

VACON[®] NX

AC DRIVES

**ENDAT/SSI, SIN-COS OPTION BOARD, OPTBE
SIN-COS OPTION BOARD, OPTAK
SIN-COS WITH PULSE OUTPUT OPTION BOARD, OPTAR
USER MANUAL**

VACON[®]

INDEX

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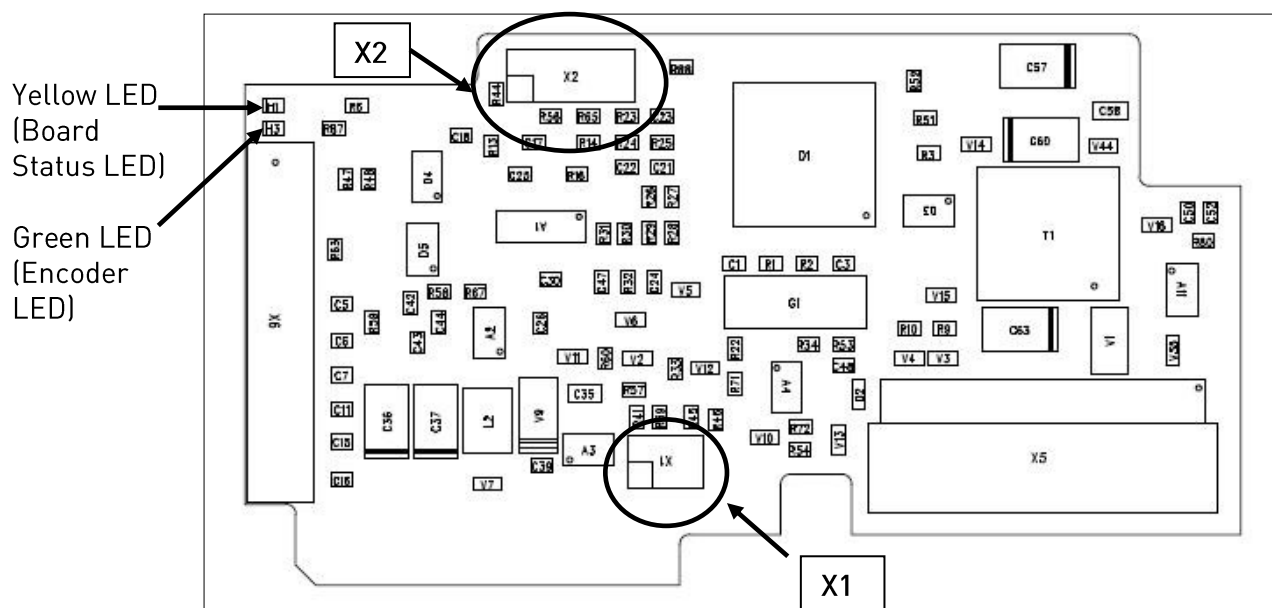
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NOTE! You can download the English and French product manuals with applicable safety, warning and caution information from <https://www.danfoss.com/en/service-and-support/>.

REMARQUE Vous pouvez télécharger les versions anglaise et française des manuels produit contenant l'ensemble des informations de sécurité, avertissements et mises en garde applicables sur le site <https://www.danfoss.com/en/service-and-support/>.

1. ENDAT/SSI, SIN-COS OPTION BOARD OPTBE

1.1 OPTBE layout and description



Description: Encoder board for **VACON® NXP** with an input for *EnDat/SSI* absolute encoder and *Sin/Cos* type encoder.

Allowed slots: C, D, E (Sin/Cos signals can only be used in slot C)

Type ID: 16965

Terminals: One terminal block; Screw terminals (M2.6); No coding.

Jumpers: X1 and X2 (see page 5)

Board parameters: Yes (see page 7)

An **absolute encoder** is a type of encoder capable of specifying its absolute position. The position data is retained even during a power failure or breakdown. The position data carried by the absolute encoder can be used by the AC drive in motor control and position control applications.

Sin/Cos encoder produces a pair of analog sinusoidal signals. There are several sine cycles (for example 1024 or 2048) per mechanical revolution.

| | |
|-----------------------------------|--|
| Encoder cable | Heidenhain cable Max. length 100m It is recommended to use a cable which contains individual shield for each twisted pair. |
| Encoder voltage | 5V, 12V or 15V Max. current consumption 300mA |
| Measuring steps/ revolution | 4.2 billion (max. 32bit) |
| Distinguishable revolutions | 0—65535 (max. 16bit) |
| Sin/Cos signal periods/revolution | 1—65535 |
| EnDat and SSI data transfer rate | 200 kHz |

EnDat is a bidirectional synchronous serial interface for encoders. For example, the absolute encoder position data can be read and encoder parameters can be set via the EnDat connection. It also forwards the messages related to the encoder functions. All EnDat connections are available in terminal X6. The board uses EnDat version 2.1.

SSI (Synchronous Serial Interface) is a single directional interface for transmitting absolute position value.




The absolute position value beginning with the Most Significant Bit (MSB first) is transferred on the DATA lines in synchronism with a CLOCK signal transmitted by the control. The SSI standard data word length for single turn absolute encoders is 13 bits, and for multiturn absolute encoders 25 bits.

More information on EnDat/SSI: <http://www.heidenhain.com>.


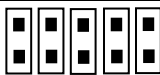
1.2 OPTBE jumpers

NOTE! It is recommended to use a 12 V or 15 V supply voltage instead of 5 V. OPTBE interface does not support "sense" function to compensate voltage drop with a long cabling. Therefore with 5 V supply voltage the cable length limit is about 60 meters with 0.5 mm² wire section. With 5 V supply voltage it is recommended to use two or more wires in parallel for the supply connection.

Jumper X1 selects encoder supply voltage on the OPTBE board, see jumper settings below:

| | | |
|---|---|---|
|  |  |  |
| 5V (Default) | 12V | 15V |

Jumper X2 selects Sin/Cos signals connection on the OPTBE board, see jumper settings below:

| | |
|---|---|
|  |  |
| Sin/Cos signals connected Note! This setting can only be used in slot C | Sin/Cos signals not connected (Default) Note! This setting must be used in slots B, D and E |

NOTE! Be careful with the jumper settings, wrong settings may damage the encoder.

1.3 OPTBE LEDs

There are two LEDs on the OPTBE board:

- 1) Yellow LED (Board Status LED)
Slow blinking -> Board state is ready
Fast blinking -> Board state is faulted
- 2) Green LED (Encoder LED)
ON -> Encoder serial communication is OK
OFF -> No serial connection to encoder

1.4 I/O terminals on OPTBE, encoder terminal X6

| Terminal | | Heidenhain colour code | Technical data |
|----------|-----------------|------------------------|--|
| 1 | DATA+ | Grey | Data line 120Ω/RS-485 |
| 2 | DATA- | Pink | |
| 3 | CLOCK+ | Violet | Clock line 120Ω/RS-485 (200kHz) |
| 4 | CLOCK- | Yellow | |
| 5 | A+, COS+ | Green/black | 1Vpp (±0.5V); impedance 120Ω; Max. input 350 kHz |
| 6 | A-, COS- | Yellow/black | |
| 7 | B+, SIN+ | Blue/black | 1Vpp (±0.5V); impedance 120Ω; Max. input 350 kHz |
| 8 | B-, SIN- | Red/black | |
| 9 | GND | White/green | Input ground |
| 10 | Encoder voltage | Brown/green | Selectable encoder voltages: 5V, 12V and 15V Max. current consumption 300mA |

Analog Sin/Cos signals deserve some more precautions for noise immunity than pulse encoders. It is recommended to use a cable which contains individual shield for each twisted pair. Use one pair for SIN+/SIN- signals, another pair for COS+/COS- signals, another pair for DATA+/DATA- signals and another pair for CLOCK+/CLOCK- signals.

1.5 OPTBE Parameters

Notes for selecting Operating Mode:

In modes "EnDat + Sin/Cos" and "SSI+Sin/Cos" Sin/Cos signals and absolute serial information are used:

- Modes can be used in VACON® NXP option board slot C.
- Closed loop motor control mode can be used.
- Jumper X2 is installed into OPTBE board because Sin/Cos signals are used.

In modes "Endat Only" and "SSI Only", only the absolute serial information is used:

- Modes can be used in VACON® NXP option board slots C, D and E.
- Closed loop motor control mode cannot be used. Usage of closed loop in these modes causes Fault 43 (Encoder fault) with Subcode 10.
- Jumper X2 is removed from OPTBE board because Sin/Cos signals are not used.

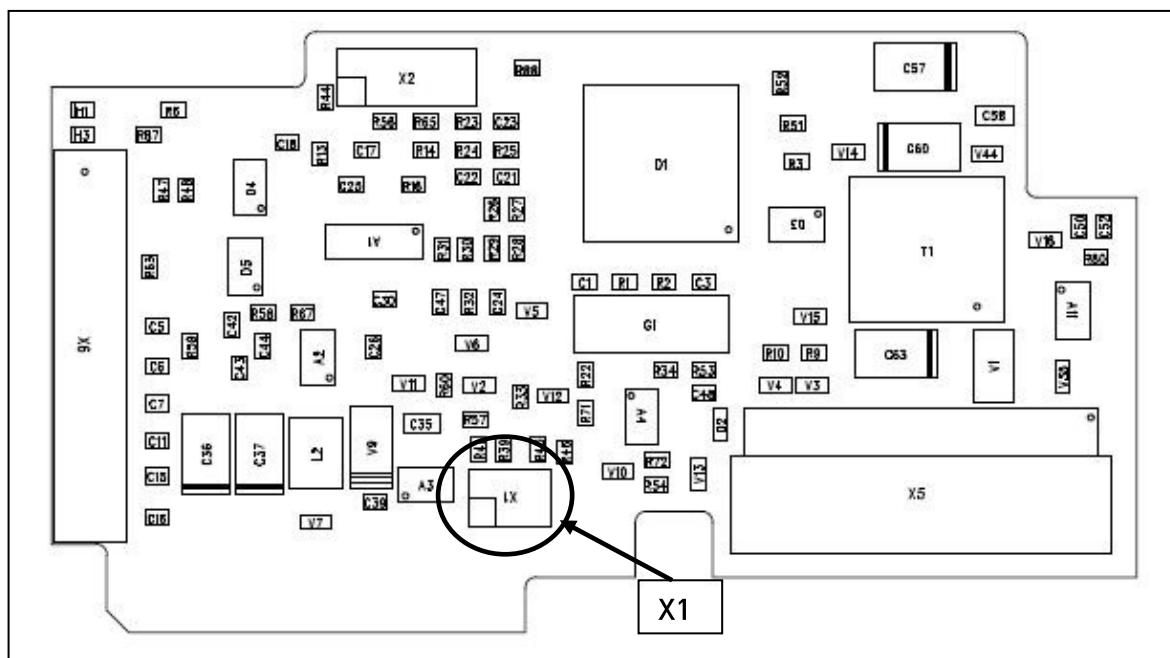
| Number | Parameter | Min | Max | Default | Note |
|---------|------------------|-----|-------|---------|--|
| 7.x.1.1 | Operating Mode | 4 | 8 | 4 | 4= EnDat + Sin/Cos (default) 5= EnDat Only 6= SSI+Sin/Cos 7= SSI Only 8= Sin/Cos Only |
| 7.x.1.2 | Pulse/revolution | 1 | 65535 | 1024 | |
| 7.x.1.3 | Invert direction | 0 | 1 | 0 | 0 = No 1 = Yes |
| 7.x.1.4 | Reading rate | 0 | 4 | 1 | Time used to calculate speed actual value. Note: Use value 1 in Closed Loop mode. 0 = No 1 = 1 ms 2 = 5 ms 3 = 10 ms 4 = 50 ms |
| 7.x.1.5 | Interpolation | 0 | 1 | 0 | If activated, the sinusoidal incremental pulses are used to calculate the polar angle in order to optimize the encoder accuracy 0=No 1=Yes |
| 7.x.1.6 | SSI data coding | 0 | 1 | 1 | 0=Binary 1=Gray |
| 7.x.1.7 | SSI total bits | 0 | 55 | 13 | |
| 7.x.1.8 | SSI revol bits | 0 | 16 | 0 | |

1.6 OPTBE monitored values

| Code | Monitored value | Unit | Description |
|---------|---------------------------|------|---|
| 7.x.2.1 | Encoder frequency | Hz | Encoder frequency in Hz |
| 7.x.2.2 | Encoder speed | rpm | Encoder Speed in rpm |
| 7.x.2.3 | Com Counter | | Message counter for serial encoder communication 0-65535 |
| 7.x.2.4 | Revolution counter | | In case multiturn encoders this monitored value counts the revolutions. 0-65535 |
| 7.x.2.5 | Absolute position Hi word | | absolute position up from 16 bits to 32bits |
| 7.x.2.6 | Absolute position Lo word | | absolute position up to 16 bits |

2. SIN-COS OPTION BOARD OPTAK

2.1 OPTAK layout and description



Description: Encoder board for **VACON® NXP** with an input for *Sin/Cos* type encoder. Programmable control voltage.

Allowed slots: C (*Sin/Cos* signals can only be used in slot C)

Type ID: 16715

Terminals: One terminal block; Screw terminals (M2.6); No coding.

Jumpers: X1 (see page 9)




Board parameters: Yes (see page 10)

Sin/Cos encoder produces a pair of analog sinusoidal signals. There are several sine cycles (for example 1024 or 2048) per mechanical revolution.

2.2 OPTAK jumper settings

NOTE! It is recommended to use a 12 V or 15 V supply voltage instead of 5 V. OPTAK interface does not support "sense" function to compensate voltage drop with a long cabling. Therefore with 5 V supply voltage the cable length limit is about 60 meters with 0.5 mm² wire section. With 5 V supply voltage it is recommended to use two or more wires in parallel for the supply connection.

Jumper X1 selects encoder supply voltage on the OPTAK board, see jumper settings below:

| | | |
|---|---|---|
|  |  |  |
| 5V (Default) | 12V | 15V |

NOTE! Be careful with the jumper setting, wrong voltage may damage the encoder.

2.3 I/O terminals on OPTAK, encoder terminal X6

| Terminal | | Technical data |
|----------|-----------------|---|
| 1 | N.C. | Not Connected |
| 2 | N.C. | |
| 3 | R+ | Max 10Vpp ($\pm 5V$), Min 1Vpp ($\pm 0.5V$). Typically signal is $\sim 2.5Vpp$ ($\pm 1.25V$): at reference mark moment positive signal, other time negative signal. Impedance 120 Ω Max input 350 kHz Reference mark signal |
| 4 | R- | |
| 5 | SIN+ | 1Vpp ($\pm 0.5V$); impedance 120 Ω ; Max. input 350 kHz, |
| 6 | SIN- | |
| 7 | COS+ | 1Vpp ($\pm 0.5V$); impedance 120 Ω ; Max. input 350 kHz |
| 8 | COS- | |
| 9 | GND | Input ground |
| 10 | Encoder voltage | Selectable encoder voltages: 5V, 12V and 15V Max. current consumption 300mA |

NOTE! Analog Sin/Cos signals deserve some more precautions for noise immunity than pulse encoders. It is recommended to use a cable which contains individual shield for each twisted pair. Use one pair for SIN+/SIN- signals, another pair for COS+/COS- signals and another pair for R+/R- signals.

2.4 OPTAK parameters

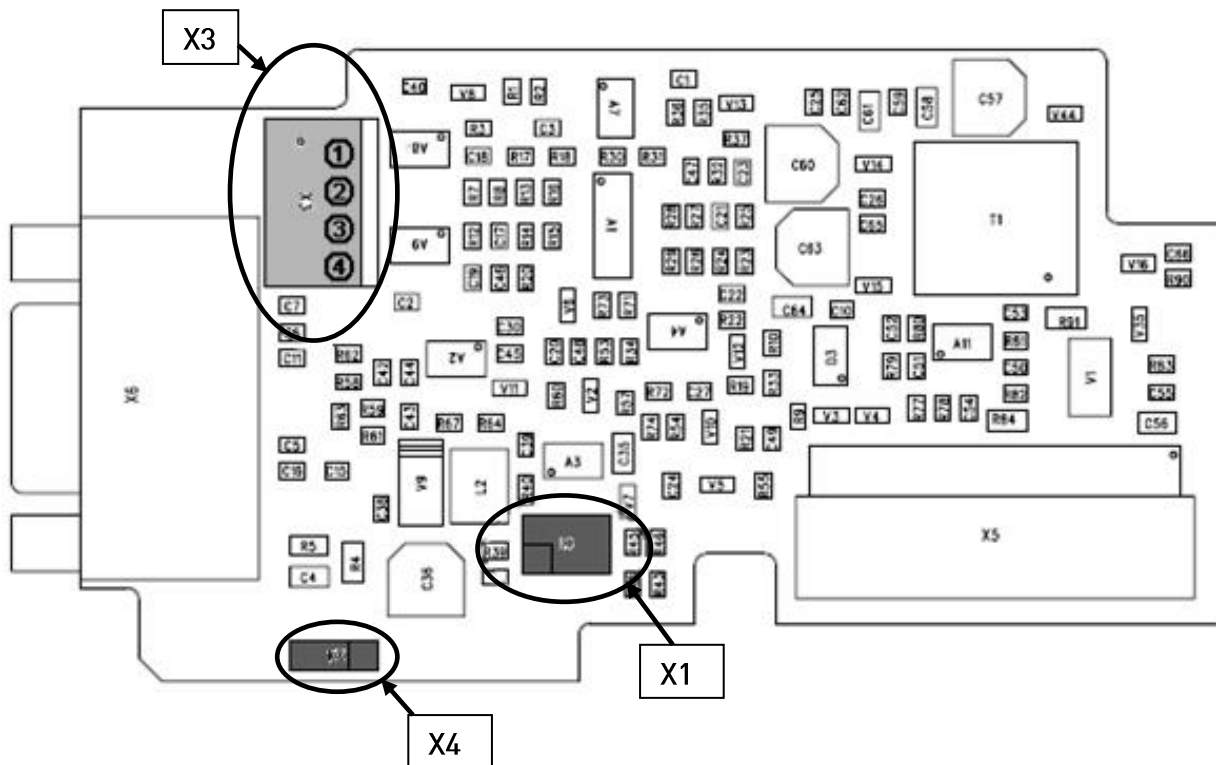
| Number | Parameter | Min | Max | Default | Note |
|---------|------------------|-----|-------|---------|--|
| 7.3.1.1 | Pulse/revolution | 1 | 65535 | 1024 | |
| 7.3.1.2 | Invert direction | 0 | 1 | 0 | 0 = No 1 = Yes |
| 7.3.1.3 | Reading rate | 0 | 4 | 1 | Time used to calculate speed actual value. Note: Use value 1 in Closed Loop mode. 0 = No 1 = 1 ms 2 = 5 ms 3 = 10 ms 4 = 50 ms |
| 7.3.1.3 | Interpolation | 0 | 1 | 0 | If activated, the sinusoidal incremental pulses are used to calculate the polar angle in order to optimize the encoder accuracy 0=No 1=Yes |

2.5 OPTAK monitored values

| Code | Monitored value | Unit | Description |
|---------|-------------------|------|-------------------------|
| 7.3.2.1 | Encoder frequency | Hz | Encoder frequency in Hz |
| 7.3.2.2 | Encoder speed | rpm | Encoder Speed in rpm |

2. SIN-COS WITH PULSE OUTPUT OPTION BOARD OPTAR

2.1 OPTAR layout and description



Description: Encoder board for **VACON® NXP** with an input for *Sin/Cos* type encoder.
Programmable control voltage for encoder. Differential two channel pulse output.

Allowed slots: C (Sin/Cos signals can only be used in slot C)

Type ID : 16722

Terminals: X6 D-sub 15-pin male connector with female screw lock for Sin/Cos input
X3 4-pin screw terminal for pulse output

Jumpers: X1 and X4 (see page 11)




Board parameters: Yes (see page 12)

A Sin/Cos encoder produces pair of analog sinusoidal signals. There are several sine cycles (for example 1024 or 2048) per mechanical revolution.

2.2 OPTAR jumper settings




NOTE! It is recommended to use a 12 V or 15 V supply voltage instead of 5 V. OPTAR interface does not support "sense" function to compensate voltage drop with a long cabling. Therefore with 5 V supply voltage the cable length limit is about 60 meters with 0.5 mm² wire section. With 5 V supply voltage it is recommended to use two or more wires in parallel for the supply connection.

Jumper X1 selects encoder supply voltage on the OPTAR board, see jumper settings below:

| | | |
|---|---|---|
|  |  |  |
| 5V (Default) Left(top-view) | 12V middle(top-view) | 15V right(top-view) |

NOTE! Be careful with the jumper setting, wrong voltage may damage the encoder.

Jumper X4 selects grounding mode for cable shield of encoder on the OPTAR board, see jumper settings below:

| | | |
|---|---|---|
|  |  |  |
| Left(top-view) (default, directly to ground) | Right(top-view) (Through RC-circuit to ground) | Without X4 (floating) |

2.3 I/O terminals on OPTAR, encoder terminal X6

| Terminal | | Technical data |
|---------------|-----------------|--|
| 1 | COS- | Same as SIN- |
| 2 | N.C. | |
| 3 | R+ | 1Vpp (±0.5V); impedance 120Ω; Max. input 350 kHz, Reference mark signal |
| 4 | R- | |
| 5 | SIN+ | 1Vpp (±0.5V); impedance 120Ω; Max. input 350 kHz, |
| 6 | SIN- | |
| 7 | GND | Input ground |
| 8 | COS+ | Same as SIN+ |
| 9 | Encoder voltage | Selectable encoder voltages: 5V, 12V and 15V Max. current consumption 300mA |
| 10 15 | N.C | |
| | Shield | |

NOTE! It is recommended to use a cable which contains individual shield for each twisted pair. Use one pair for SIN+/SIN- signals, another pair for COS+/COS- signals and another pair for R+/R- signals.

2.4 I/O terminals on OPTAR, pulse output X3

| Terminal | | Technical data |
|----------|----|--|
| 1 | A+ | Incremental differential pulse output square wave, signal level RS-422 Impedance 120Ω Output current max. 50mA Max. output frequency 200KHz Output short/grounding protection |
| 2 | A- | |
| 3 | B+ | Same as A+/A- |
| 4 | B- | |

2.5 OPTAR parameters

| Number | Parameter | Min | Max | Default | Note |
|---------|------------------|-----|-------|---------|--|
| 7.3.1.1 | Pulse/revolution | 1 | 65535 | 1024 | |
| 7.3.1.2 | Invert direction | 0 | 1 | 0 | 0 = No 1 = Yes |
| 7.3.1.3 | Reading rate | 0 | 4 | 1 | Time used to calculate speed actual value. Note: Use value 1 in Closed Loop mode. 0 = No 1 = 1 ms 2 = 5 ms 3 = 10 ms 4 = 50 ms |
| 7.3.1.3 | Interpolation | 0 | 1 | 0 | If activated, the sinusoidal incremental pulses are used to calculate the polar angle in order to optimize the encoder accuracy 0=No 1=Yes |

2.6 OPTAR monitored values

| Code | Monitored value | Unit | Description |
|---------|-------------------|------|-------------------------|
| 7.3.2.1 | Encoder frequency | Hz | Encoder frequency in Hz |
| 7.3.2.2 | Encoder speed | rpm | Encoder Speed in rpm |

3. INSTALLATION



WARNING!



Internal components and circuit boards are at high potential when the AC drive is connected to the power source. This voltage is extremely dangerous and may cause death or severe injury if you come into contact with it.


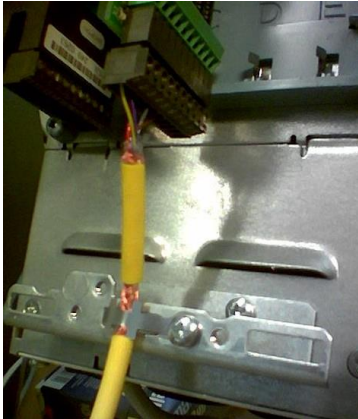
3.1 Installing option boards



Option boards OPTBE, OPTAK and OPTAR can only be used with VACON® NXP drives.

OPTAK and OPTAR can be connected to **slot C**. OPTBE board can be connected to **slots C, D or E**, but Sin/Cos signals can only be used in slot C. If OPTBE board is connected to slots D or E, the Sin/Cos signals have to be disconnected using the jumpers (see chapter 1.2).

Disconnect the drive from the mains before starting the installation.

| | |
|---|---|
| A | <p>VACON® NXP AC drive</p>  |
| B | <p>Remove the cable cover.</p>  |

| | |
|---|---|
| C | <p data-bbox="352 197 798 235">Open the cover of the control unit.</p>  |
| D | <p data-bbox="352 813 1449 929">Install the option board in correct slot on the control board of the AC drive. Make sure that the grounding plate fits tightly in the clamp. Strip the cable at such distance from the terminal that you can fix it to the frame with the grounding clamp.</p>  |

| | |
|---|--|
| E | <p>Make a sufficiently wide opening for your cable by cutting the grid as wide as necessary.</p>  |
| F | <p>Close the cover of the control unit and the cable cover.</p>  |

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