

NovoCon® S - High Accuracy Actuator

Description



NovoCon[®] S is a high accuracy multi-functional field bus actuator, specifically designed for use in combination with the Pressure Independent Control Valve type AB-QM in sizes from DN 10-32. The flow is modulated by the AB-QM pressure independent control valve to avoid overflow and reduced boiler and/or chiller efficiency.

The actuator with AB-QM is used to control water supply to fan coil units, chilled beams, induction units, small re-heaters, re-coolers, AHU's and other terminal units for zone control, in which heating/ chilled water is the controlled medium. Due to its accuracy, remote functionality and flow indication features, this product facilitates an accelerated commissioning process, allows easy maintenance, improves indoor comfort, increases energy savings and allows for fair cost allocation of heat/cool energy.

The high position accuracy of the actuator, together with the pressure independent and linear characteristic of the AB-QM valve, allow NovoCon® S to be used as a flow indicator.

Setup of the actuator and valve parameters are made via fieldbus. Control is achieved via field bus or via analog inputs to NovoCon[®] S.

Typical applications are:

- Radiant ceiling panels, supplied by 4 pipes (Heating supply and return and cooling supply and return).
- Fan coil units, with single coils supplied by 4 pipes (Heating supply and return and cooling supply and return).

General features:

- Remote commissioning/Pre-set/Flush features
- Flow, emission and energy indication
- High position resolution and accuracy
- Energy management algorithms
- 4/2-pipe changeover applications
- I/O applications
- LED bar displaying status and alarms
- No tools required for mounting
- Maintenance-free lifetime
- Self-positioning process
- Low-noise operation
- Plug-in halogen free cables
- Auto MAC addressing for BACnet
- Auto baud rate detection

- Intrinsic alarm reporting for BACnet
- Valve blockage alarm Broken wire detection on analog control and
- ground signal
- Choice of BACnet MS/TP or Modbus RTU in the same product
- Mis-wiring protection on any wire up to 30 V

Combined with the Actuator NovoCon® ChangeOver⁶, NovoCon® S offers a unique solution in controlling both the AB-QM valve and a 6-port motorised ball valve that performs a diverting function between two water circuits in 4-pipe changeover systems.

This diverting function, primarily used for radiant panels, also allows the cooling and heating capacity of a fan coil unit to be increased for the same compact size compared to a double coil model where the heating and cooling water circuits each have their own coil.

The 6-port diverting valve and actuator work in combination with an AB-QM PIBCV valve and NovoCon[®] S bus actuator. The AB-QM balances the flow and the NovoCon[®] S bus actuator controls the flow. NovoCon[®] S also controls the 6-port diverting valve actuator which switches between heating and cooling. This unique functionality is characterized by the following:

- There is only one single field bus and power supply connection cable to the NovoCon[®] S actuator. This powers both the NovoCon[®] S and controls the 6-port actuator. Furthermore, there is feedback from the 6-port actuator to NovoCon[®] S.
- The NovoCon[®] S actuator automatically faultdetects, by means of comparing 0-10V control & feedback signals, if the 6-port actuator is in manual operation mode, removed from the valve or if the 6-port valve is blocked.
- The NovoCon[®] S actuator has two Design Flow Rate pre-settings: one for heating and another for cooling.
- The NovoCon[®] S actuator indicates power emission and logs energy usage for heating and cooling energy based on flow, supply and return pipe temperature measurement.
- While in maintenance mode, the 6-port actuator is able to fully close the valve and prevent any leakage, thereby saving on stop valves.
- Logic contained within the NovoCon[®] S actuator, ensures that only one actuator in each pair (NovoCon[®] S and 6-port valve actuator) drives. This ensures that 2 actuators in the pair never drive at the same time. This reduces voltage booster demands in daisy chains.
- The NovoCon[®] S actuator detects if the 6-port actuator cable is disconnected. If this is the case an alarm is initiated.

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Description (continued)

Features CO6:

- NovoCon[®] S + ChangeOver⁶ actuator represents only ONE device on the fieldbus network needing no physical I/O
- No cross-flow between heating and cooling
- Simple connection and control
- Feedback for position status and alarms
- Quiet and reliable operation
- Maintenance free
 Teflon seal and polished chrome valve ball to prevent valve sticking
- Blocked valve alarm
- Manual override

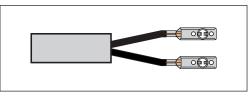
Features Energy:

- Supply and return temperature measurement
- Power/emission indication reading
- Energy Management functionality for both heating and cooling e.g. minimum delta t management
- Energy logging of both heating and cooling

Features I/O:

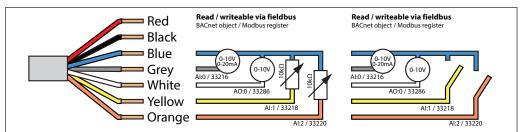
- Connect to other devices and present them on the field bus, e.g. room thermostat, window contact, CO2 sensor, humidity sensors, fan control, 0-10V actuator etc.
- Select temperature units, Ohms or use as





potential free contacts. Closed circuit <900 Ω , open circuit 100k Ω .

Available connections: 1 x analog output (V), 1 x analog input (V/mA) and 2 x resistance based inputs (°C/°F/Ohms)



Ordering

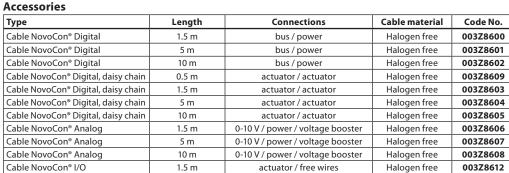


Туре

NovoCon[®] S







Note! Cables are not included with actuator and must be ordered separately.



| Cable NovoCon® Energy | 1.5 m | Plug-in cable with PT1000 surface temperature sensors | PVC | 003Z8610 |
|-----------------------------------|----------------------------|---|------------------------------------|----------|
| Cable NovoCon® Energy | 1.5 m | Plug-in cable with PT1000 Immersed /universal temperature sensors | PVC | 003Z8611 |
| Cable NovoCon® Temperature I/O | 1 m / Temp. sensor 1.5m | Plug-in cable with PT1000 surface temperature sensors and free wires for input, output and power | Halogen free. Sensor cables PVC | 003Z8613 |

Note! If separate PT1000 temperature sensors are needed, Danfoss has an array of PT1000 sensors that can be used with NovoCon[®] S. See Danfoss PT1000 sensors ESMT, ESM-10, ESM-11, ESMB-12, ESMC and ESMU.

ChangeOver6 actuators

| Actuator NovoCon ChangeOver ⁶ | 1 m | Plug-in | Halogen free | 003Z8520 |
|---|---------------------------|---|-----------------------------------|----------|
| Actuator NovoCon ChangeOver ⁶ Energy | 1 m Temp. sensor 1.5 m | Plug-in incl. PT1000 surface temperature sensors | Halogen free Sensor cables PVC | 003Z8521 |
| Actuator NovoCon ChangeOver ⁶ Flexible | 1.5 m | Actuator / open wires | Halogen free | 003Z8522 |

Code No.

003Z8504

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NovoCon[®] S - High Accuracy Actuator

Ordering (continued)

| Туре | DN | Fire load class ¹⁾ | Code No. |
|-------------------------------------|----|-------------------------------|----------|
| ChangeOver ⁶ insulation | 15 | B2 | 003Z3159 |
| ¹⁾ According to D/N 4102 | | | |

Service kit - combination with old AB-QM

| Туре | Code No. |
|---|----------|
| NovoCon [®] adapter for AB-QM, DN 10-32 (5 pcs.) | 003Z0239 |

CE

| | Туре | DN | k_{vs} (m³/h) | Connection | Code No. |
|--|-------------------------------|----|---------------------------------|------------|----------|
| | ChangeOver ⁶ valve | 15 | 2,4 | Rp ½ | 003Z3150 |
| | | 20 | 3,8 | Rp ¾ | 003Z3151 |

RoHS Directive 2011/65/EU

| Accessories and | snare narte | (Cable No | voCon® Enerav) |
|-----------------|-------------|-----------|----------------|
| Accessories and | spare part | | VOCON LINEIGY) |

| Туре | Designation | Code No. |
|--|--|----------|
| Pockets for Cable | Immersion brass pockets, 40 mm, t6.0 pair | 087G6061 |
| NovoCon® Energy (003Z8611) | Immersion brass pockets, 85 mm, t6.0 pair | 087G6062 |
| Heat conducting paste, 3.5 cm ² | | 041E0110 |

Approvals

Technical data

| Power supply range | 24 V AC/DC, 50 / 60 Hz * |
|---|--|
| Power consumption | Operating: 2.7 VA@24VAC / 1.2 W@24VDC Standby: 1.8 VA@24VAC / 0.7 W@24VDC |
| Protection class | III safety extra-low voltage |
| Control signal NovoCon [®] S | BACnet MS/TP, Modbus RTU 0-10 VDC, 0-5 VDC, 2-10 VDC, 5-10 VDC, 2-6 VDC, 6-10 VDC, 0-20 mA, 4-20 mA |
| lus un adaman | Rin Al:0 >100 kΩ (V); 500 Ω (mA) |
| Impedance | Rout AO: 1500 Ω |
| Actuator speed selections (open to close) | 3 sec/mm, 6 sec/mm, 12 sec/mm, 24 sec/mm, Constant Time |
| Stroke | 7 mm |
| Force | 90 N |
| Position accuracy | ± 0.05 mm |
| Ambient temp. range | –10° C to 50° C |
| Ambient humidity | 98% r.h., non-condensing (according to EN 60730-1) |
| Max. medium temp. | 120° C |
| Storage temp. range | –40 to 70 °C |
| Grade of enclosure | IP 54 (IP 40 upside down) |
| Weight | 0.4 kg |

EMC Directive 2014/30/EU, EN 60730-2-14:1997, EN 60730-2-14/A1:2001, EN60730-1:2011

* NovoCon[®] S is designed to operate at power deviations up to $\pm 25\%$.

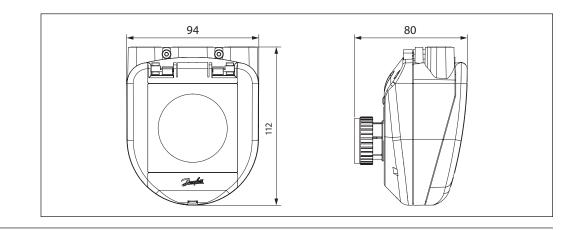
BACnet data

| Туре | Description |
|-----------------------------|--|
| BACnet device profile | BACnet Application Specific Controller (B-ASC) |
| BACnet protocol | BACnet Master Slave / Token Passing (MS/TP) |
| BACnet baud rates supported | Auto baud rate detection* / 9600 bps / 19200 bps / 38400 bps / 56700 bps / 76800 bps / 115200bps |

Modbus RTU data

| Supported baud rates | Auto baud rate detection* / 9600 bps / 19200 bps / 38400 bps / 56700 bps / 76800 bps / 115200bps |
|------------------------------|---|
| Supported transmission modes | Parity: None (1-8-N-2) / Odd (1-8-O-1) / Even (1-8-E-1) / None (1-8-N-1) / Auto parity* Data format: Parity (Start bit - Data bits - Parity - Stop bits) |
| * Default | |

Dimensions



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Pre-setting

Pre-setting of flow (maximum allowable flow though the valve) is achieved electronically with the NovoCon[®] S actuator. The pre-set scale on the AB-QM valve is not used under normal operation.

Normal operation

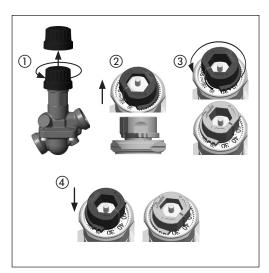
Leave valve at default factory pre-set (100 %).

High flow operation

In order to achieve a more efficient flush and enable pre-setting of the valve more than 100%, it is recommended to manually pre-set the AB-QM valve to maximum flow. This is done by turning the pre-set scale counter-clockwise until it stops. See drawing.

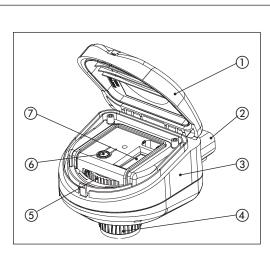
etails about AR-OM pre-setti

Details about AB-QM pre-setting can be found in the AB-QM data sheet.



Design

- 1 Removable lid
- (2) Bus and power connections
- (3) LED window
- (4) Locking ring
- 5 Manual override
- 6 Reset button
- 7 DIP switches

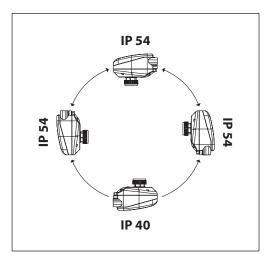


Mounting Orientation

NovoCon[®] S can be mounted in any position. However, mounting orientation affects the IP classification. Using NovoCon[®] S upside down in cooling applications is not recommend due to the risk condensation brings. See illustration.

Note!

IP classification is only valid when cable or plugs are present in all connections.

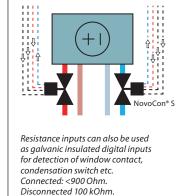


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Application principle NovoCon[®] S I/O

Data sheet

When combining the NovoCon® S and the Cable NovoCon® I/O, many options are possible



Operation example (DDC command)

| Object /Register Write value | | Description |
|------------------------------|-----|--|
| AV:1 / 33280 | 85 | DDC writes % opening value of the AB-QM valve |
| AO:0/33286 | 5.5 | DDC writes level of voltage on NovoCon® S analog output, which is sent to the connected remote device |

Read on the BMS example

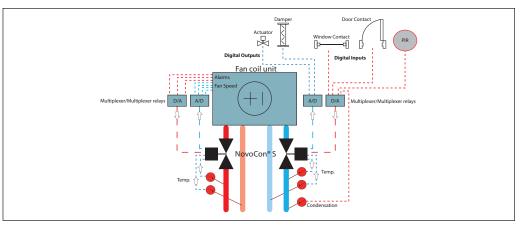
| Object /Register Read value | | Description |
|---|------|---|
| AO:0/33286 5.5 | | Voltage output from NovoCon® S to remote device |
| Al:0 / 33216 | 6.5 | Voltage level on the analog control input measured by the actuator (may also be mA) |
| AI:1 / 33218 | 1160 | Resistance value (Ohm) received from remote device 1 |
| Al:2 / 33220 1263 Resistance value (Ohm) received from remote | | Resistance value (Ohm) received from remote device 2 |

Application principle NovoCon[®] I/O and Multiplexers/Relays

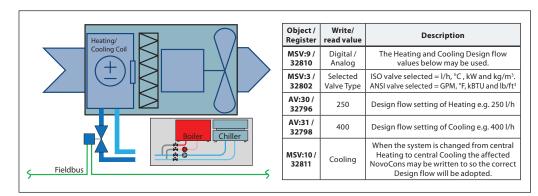
Multiplexers and relays (analog-digital-analog convertors) in combination with NovoCon[®] S, may be used to gather information on, or control on/off devices.

Using NovoCon's 0-10V output signal (AO:0 / 33286), multiplexer relays convert this signal in order to switch devices on or off e.g. 7V signal from NovoCon® S is converted inside the multiplexer so device1=on, device 2=on, device3=off. E.g. 4V signal from NovoCon® S is converted inside the multiplexer so the device1=on, device 2=off, device3=off.

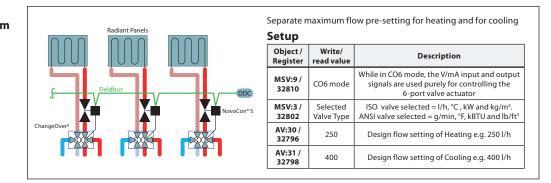
Using NovoCon's 0-10V input signal (AI:0 / 33216) received from the multiplexers, the DDC can decipher the meaning of the voltage signal e.g. 7V signal to NovoCon[®] S from the multiplexer is deciphered by the DDC as meaning device1=on, device 2=on, device3=off. 4V signal to NovoCon[®] S from the multiplexer is deciphered by the DDC as meaning device1=on, device 2=off, device3=off.







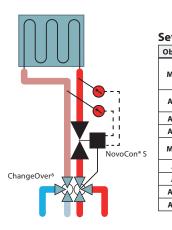
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ChangeOver⁶ - 4 pipe system

Application principle

Application principle ChangeOver⁶ Energy

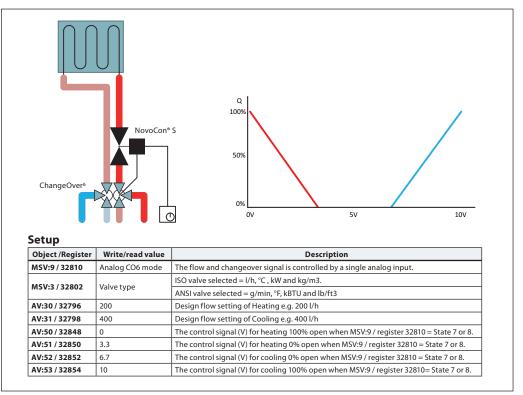


| Setup | | |
|-------------------------|------------------------|---|
| Object /Register | Write/read value | Description |
| MSV:9 / 32810 | CO6 mode | While in CO6 mode, the V/mA input and output signals are used purely for controlling the 6-por valve actuator |
| AV:32 / 33288 | Power emission | Calculates energy based on values from flow feedback (AV:2) and temperature (AI:1 and AI:2) |
| AV:33 / 33290 | Heating Energy Counter | Accumulate Energy counter for heating |
| AV:34 / 33292 | Cooling Energy Counter | Accumulate Energy counter for cooling |
| MSV:3 / 32802 | Selected Valve Type | ISO valve selected = I/h, °C , kW and kg/m ³ . ANSI valve selected = g/min, °F, kBTU and lb/ft ³ |
| AI:1 / 33218 | Temperature | Select between temperature units or ohms |
| AI:2 / 33220 | Temperature | Select between temperature units or ohms |
| AV:30 / 32796 | 250 | Design flow setting of Heating e.g. 250 l/h |
| AV:31 / 32798 | 400 | Design flow setting of Cooling e.g. 400 l/h |

Application principle Analog CO6 mode

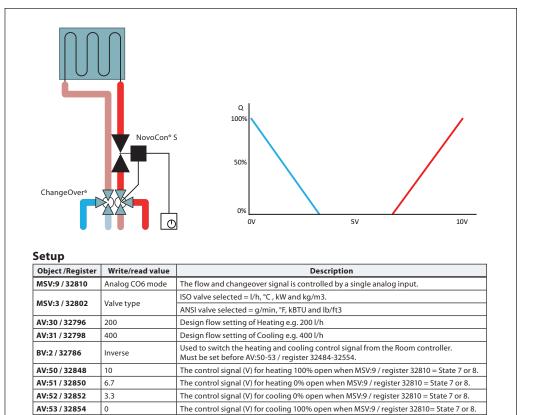
With the Object MSV:9 / register 32810 state 7 or 8 both NovoCon[®] S and the NovoCon[®] ChangeOver6 can be controlled by a single voltage output from a room controller.

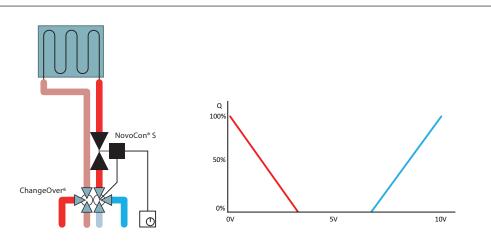
NovoCon[®] S can be customized to match the voltage values outputted by any room controller to both changeover and control the flow. This is done by configuring the objects AV:50-53 / register 32848-32854.





Application principle Analog CO6 mode (continued)





Setup

| Object /Register | Write/read value | Description |
|-------------------------|-----------------------------|--|
| MSV:9 / 32810 | Analog inverted CO6 mode | The flow and changeover signal is controlled by a single analog input. |
| MCV/-2 / 22002 | | ISO valve selected = I/h , °C , kW and kg/m3. |
| MSV:3 / 32802 | Valve type | ANSI valve selected = g/min, °F, kBTU and lb/ft3 |
| AV:30 / 32796 | 200 | Design flow setting of Heating e.g. 200 l/h |
| AV:31 / 32798 | 400 | Design flow setting of Cooling e.g. 400 l/h |
| BV:2 / 32786 | Direct | Used to switch the heating and cooling control signal from the Room controller. Must be set before AV:50-53 / register 32484-32554. |
| AV:50 / 32848 | 10 | The control signal (V) for heating 100% open when MSV:9 / register 32810 = State 7 or 8. |
| AV:51 / 32850 | 6.7 | The control signal (V) for heating 0% open when MSV:9 / register 32810 = State 7 or 8. |
| AV:52 / 32852 | 3.3 | The control signal (V) for cooling 0% open when MSV:9 / register 32810 = State 7 or 8. |
| AV:53 / 32854 | 0 | The control signal (V) for cooling 100% open when MSV:9 / register 32810= State 7 or 8. |

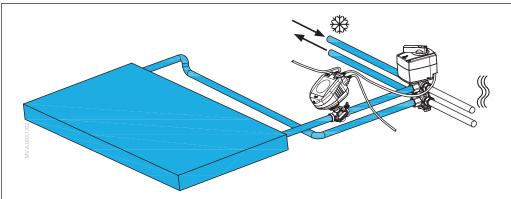
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Application principle ChangeOver⁶

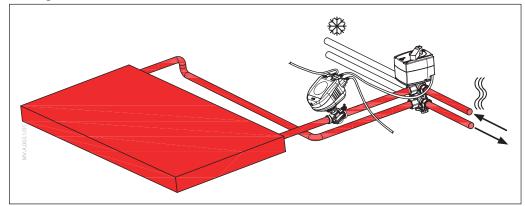
Anti-sticking requirements:

To reduce the risk of the ball valve sticking due to water quality, the valve must be partially rotated at least every 7 days. This is a factory default setting and is handled by the object MSV:11 / register 32812. The ChangeOver⁶ is a 6-port valve with a rotary actuator that switches the flow between heating and cooling. An AB-QM pressure independent balancing and control valve with an actuator is used to balance the system and modulate the flow. When using the NovoCon[®] S for flow control, both NovoCon[®] S and the Actuator NovoCon[®] ChangeOver⁶ are represented on the fieldbus network and need no physical I/O for control.

Cooling:

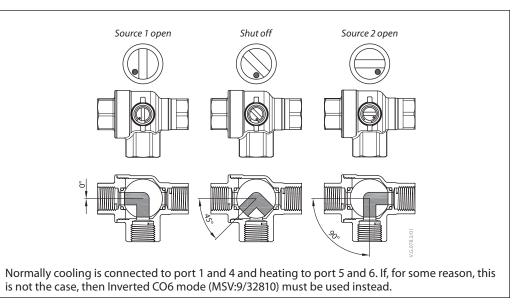


Heating:





No mixing and shut off

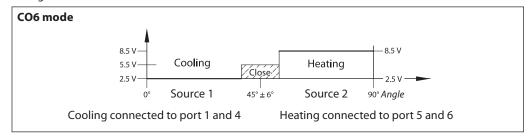


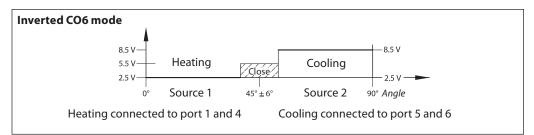
CO6, contrary to other ball valves, includes a shut off function. This function should only be used during maintenance and not during operation. This replaces the need for four ball valves. The Shut off command can only be performed when the Flow Rate Setpoint (AV:1/33280) is 0.

MSV:9 / 32810 Application mode

State 3: CO6 Mode

Normally cooling is connected to ports 1 and 4 and heating to ports 5 and 6. If that is not possible, then this may be switched and state **4: Inverted CO6 Mode** must be selected. NovoCon[®] S and the ChangeOver⁶ actuator communicate with voltage control and feedback signal. Whole functionality is available by using simple bus commands. For easier technical understanding, please see below detailed explanation of the communication between NovoCon[®] S and the ChangeOver⁶ actuator.





Signal from NovoCon[®] S to the Actuator NovoCon[®] ChangeOver⁶

| | Stop the motor | Cooling | Shut-off | Heating |
|-------------------|----------------|---------|----------|---------|
| CO6 mode | 1.0 V | 2.5 V | 5.5 V | 8.5 V |
| Inverted CO6 mode | 1.0 V | 8.5 V | 5.5 V | 2.5 V |

Feedback signal from the Actuator NovoCon® ChangeOver⁶

| Unable to move | Cooling | Moving direction: Cooling to Heating | Shut-off | Moving direction: Heating to Cooling | Heating |
|----------------|---------|---|----------|---|---------|
| 1.0 V | 2.5 V | 4.0 | 5.5 V | 7.0 V | 8.5 V |

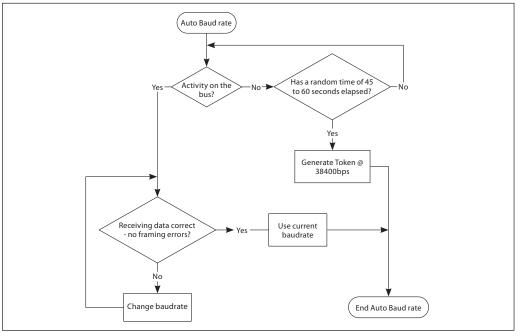
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Auto baud rate

NovoCon[®] S should be connected after, or at the same time as, other BACnet devices. NovoCon[®] S will then adapt to it's network's baud rate automatically.

Baud rate MSV:6 / 32804 must be set to 1 (default).

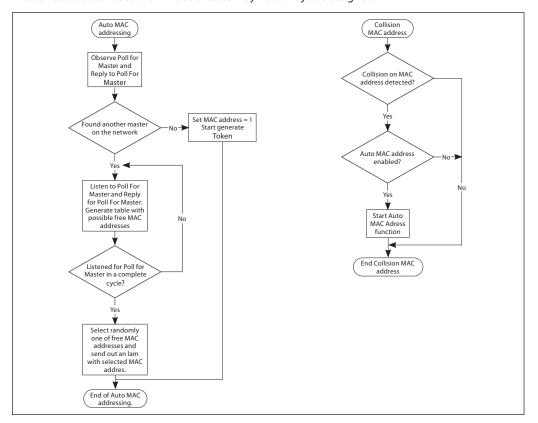
If the NovoCon[®] S observes activity on the bus within 45 seconds after powering up, then it adopts the baud rate presently used on the network by other BACnet devices. If the actuator does not see activity on the network within this time, it generates a token and sends the token out at the default baud rate of 38400bps.



Auto MAC Addressing - BACnet only

MAC address assignment method MSV:5 must be set to 1 (default).

The NovoCon[®] S actuator observes for occupied MAC addresses on the sub-network and then automatically assigns an available MAC address to the actuator only on first Power up. Assuming the address has not already been manually selected by DIP Switches. If a MAC address collision arises an Auto MAC addressing is enabled. This function will start the search for an available MAC address again. When an available MAC address is found, an "I-Am" notification will be sent out via BACnet. Please note that consecutive MAC addresses may not always be assigned.

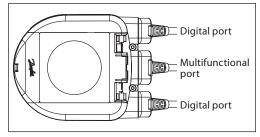


Wiring



The wiring of BACnet MS/TP or Modbus RTU (*RS485*) must be carried out in accordance with applicable standard ANSI/TIA/EIA-485-A-1998. **Galvanic separation shall be provided for** segments crossing buildings. **Common ground shall be used for all devices** on the same network inclusive router, gateways etc.

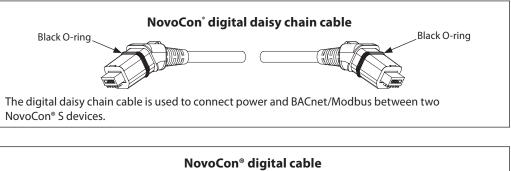
All BACnet bus connections in the cables are made with twisted wires.

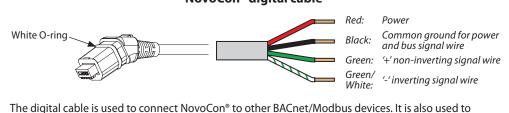


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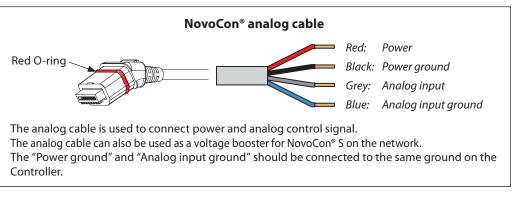
The cable type used for NovoCon[®] analog, digital and I/O cables is AWG22/0.32mm². If other cables are used to extend the length, always use twisted pair wire for bus signal and include ground for the bus signal. The recommended cable type is AWG22/0.32 mm². If used for longer distances please use a AWG20/0.5mm² or AWG18/0.75mm² cable. The cable's impedance characteristic shall be between 100-130 Ω . The capacitance between conductors shall be less than 100 pf per meter. The length of the cables influence on the communication speed. Longer cable lengths should result in lower baud rates. The total maximum cable length allowed per network is 1200m.

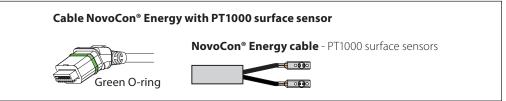
Use a minimum 20 cm distance between 110V/230V/400V power line cables and bus cables. NovoCon[®] S has mis-wiring protection on up to 30 V AC/DC on all wires, but be aware that if 30V AC are connected to the Analog input, the external power supply will see this as a short circuit and blow the fuse in the external power supply.





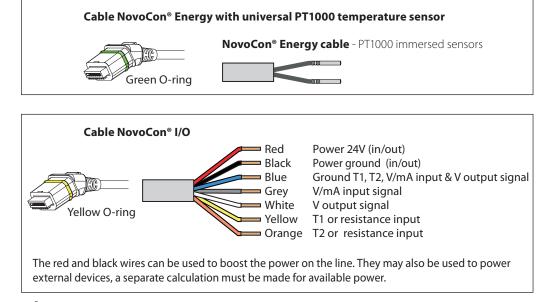
The digital cable is used to connect NovoCon® to other BACnet/Modbus devices. It is also used to connect NovoCon to a longer length of power/communication cable other than standard sales codes.



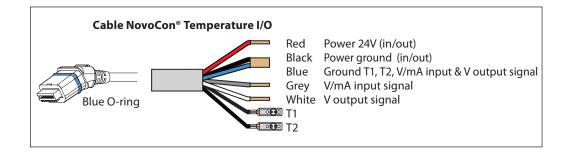


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Wiring (continued)



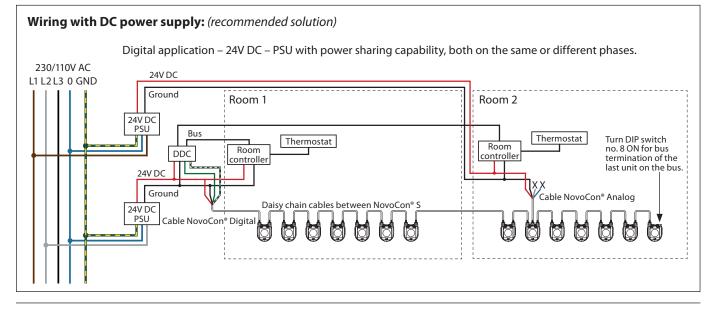
To avoid electrical short-circuiting, ensure that loose cable-ends have been connected or isolated before inserting the plug-in connector to the NovoCon[®] S actuator.

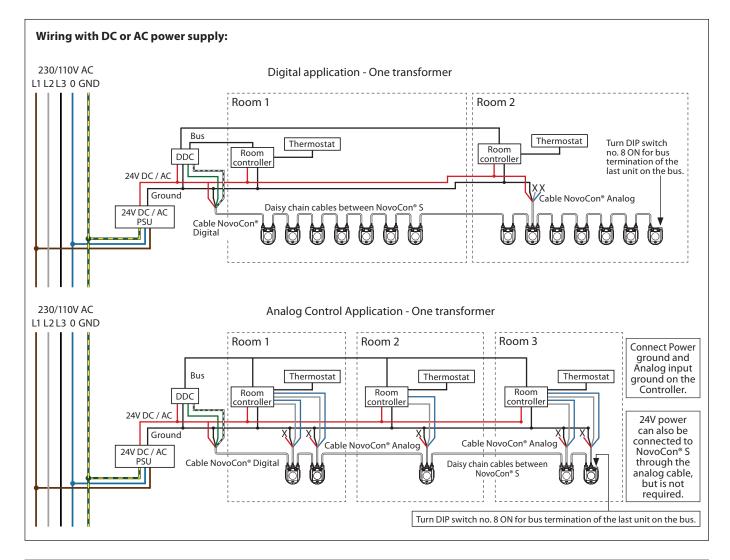


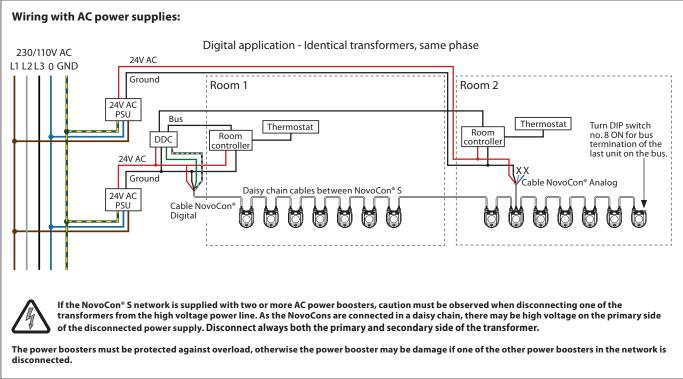
Wiring considerations

The important factors here are:

- Common ground
- 24VDC power supply is recommended
- In case more 24VAC power supplies are used always separate the 24VAC power supplies if different types of power supplies are used and
- different types of power supplies are used and / or different phases are used.

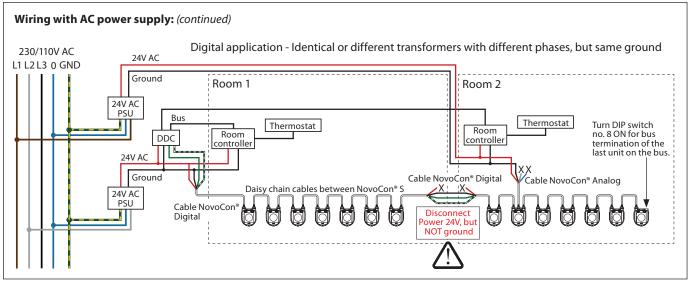




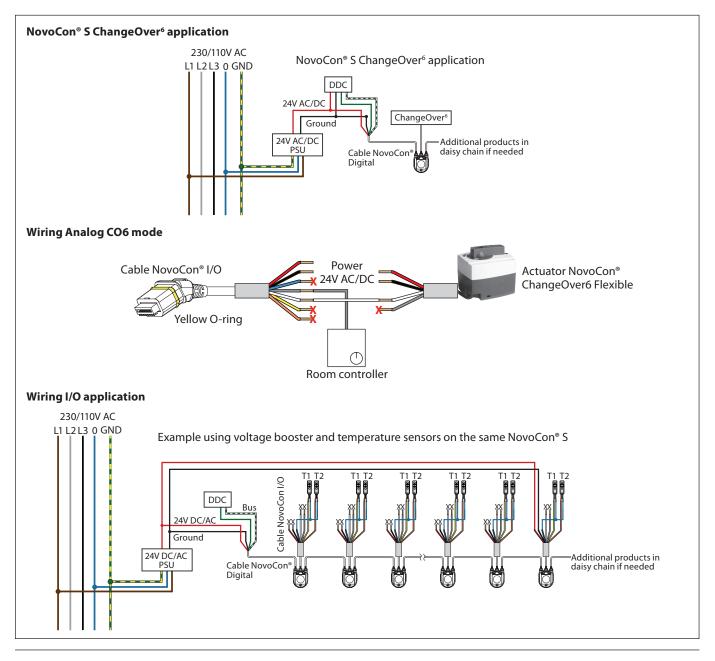


Wires that ends in an "X" must be properly terminated.

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Wires that ends in an "X" must be properly terminated.



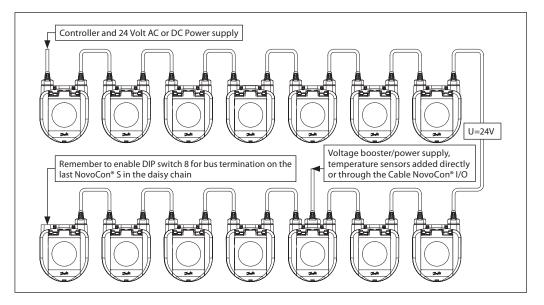
Daisy chain

DC Power supply (recommended)

When daisy chaining with 10m NovoCon[®] cables and using a 24V DC power supply, additional voltage boosters/power supply is needed when 12 NovoCons in series is exceeded. See table below.

AC Power supply

When daisy chaining with 10m NovoCon[®] cables and using a 24V AC power supply, additional voltage boosters/power supply is needed when 7 NovoCons in series is exceeded. *See table below.* Important: The power supply used must be able to deliver 60% more power than the nominal rating of NovoCon[®] S.



When all devices on the sub-network are NovoCon® S, refer to the examples below for guidance.

| | 1 2 | 3 | 4 | 5 6 | 7 | 8 | 9 1 | 01 | 1 12 | 13 | 14 | 151 | 613 | 7 18 | 19 | 202 | 12 | 22 | 3 24 | 125 | 26 | 272 | 82 | 930 | 31 | 32 | 333 | 435 | 536 | 37 | 38 | 394 | 04 | 1 42 | 43 | 44 | 454 | 64 | 748 | 49 | 50 | 51 | 525 | 354 | 455 | 56 | 57 | 585 | 960 | 61 | 626 | 364 |
|--------------|-----|-----|------|-------|-------|-----------|------|------|------|-----------|------|------|------|----------|----|----------|----|----|------|-----|----|-----|----|----------|-----------|----|-----|-----|----------|-----------|-----------|-----|----|----------|--------------|-----------|-----|----|----------|-----------|-----------|----|-----|----------|-----|----|----------|-----|----------|-----------|-----|-----|
| 1 | | | | | T | П | | | | | | | | 1 | П | | | T | | 1 | | | T | 1 | П | | | | 1 | | | | T | | | П | | | | | | | | T | T | П | | | 1 | Π | | П |
| 24 Volt DC | | | | | | | | | | | | | | | | | Ι | Ι | | | | | Ι | | | | | Ι | | | | | | L | | | | | | | | | | I | Γ | | | | | | | |
| 1 | | - | - | - | T | | - | - | - | | | - | - | — | | _ | - | Т | | | | - | - | — | П | | - | - | <u> </u> | | | - | - | — | \mathbf{T} | | - | - | — | | | - | - | — | T | | | - | — | П | - | - |
| 24 Volt DC | | t. | | | ÷ | H | | ÷ | | | | ÷ | | 1 | | | | t | | | | ÷ | ÷ | 1 | | | | | t | | \square | + | + | ╈ | | \vdash | + | + | + | | \square | + | + | + | ┢ | H | \vdash | + | + | \vdash | + | ++ |
| 24 101000 | | | | | | | | | | | | | | _ | | | | _ | | | | | | _ | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| | | | | T | | | | Т | | | | | | | | | Τ | Ι | | | | | Τ | | | | | Τ | | | | | | T | | | | | | | | | | Τ | Γ | | | | | | | |
| 24 Volt DC | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | Ц |
| | | T | -r | T | T | П | - | | T | \square | | T | - | T | П | T | Т | Т | | | | T | Т | T | П | | - | Т | T | \square | П | -r | | T | n | П | - | | | \square | П | T | T | T | T | П | Г | - | T | П | - | |
| 24 Volt DC | • | | | | 1 | H | | | | | | | | 1 | | | | t | | | H | | | 1 | | | | | ÷ | | H | | | | | | | | | | H | | | | ÷ | H | | | | H | ÷ | |
| | _ | | _ | | | _ | _ | | | | | _ | | | _ | _ | | | | | | | | | | _ | _ | | | _ | | _ | | | | | _ | | | _ | | _ | _ | | | _ | | | | _ | _ | |
| | 4 | | _ | | - | Ц | _ | _ | | | | _ | _ | | | | | 1 | - | | | | + | | | | | | | | | _ | _ | _ | | | _ | _ | | | | _ | _ | _ | | | | | | | _ | |
| 24 Volt DC | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | |
| 1 | | Т | T | Т | T | П | T | Т | Т | \square | | | Т | T | П | | Т | Т | Т | Т | | Т | Т | T | П | | T | Т | Т | | | Т | Т | Т | \square | П | T | Т | Т | | | | T | Т | T | Π | | Т | Т | П | Т | Т |
| 24 Volt AC | | | | | 1 | H | | | 1 | Г | | | | | П | | | 1 | 1 | 1 | Н | | 1 | | H | | | 1 | 1 | Н | | | | | | H | | | 1 | Н | | | | | 1 | П | H | | 1 | H | + | + |
| | - | - | _ | - | | | _ | - | | _ | _ | | - | | _ | _ | - | - | | | | - | - | | | _ | _ | | | _ | | - | - | - | | _ | _ | - | | _ | | _ | - | - | | _ | | _ | - | | _ | - |
| 0.000 10 4.0 | | - | - | - | - | Ц | - | + | - | | _ | + | + | - | | | + | ╀ | + | ┢ | | + | ╇ | + | \square | | + | + | + | | \square | + | + | + | | \square | + | + | + | | \square | + | + | + | ┢ | Н | \vdash | + | + | \square | + | + |
| 24 Volt AC | | | | | | | | | | | | | | | | | | | _ | I | | | | 1 | | | | | _ | | | | | | | | | | _ | | | | | _ | 1 | | | | | | | Щ |
| 1 1 | | Т | Т | Т | Τ | П | Т | Т | Т | | | | Т | Т | Π | Т | Т | Т | Т | Т | | Т | | | П | Т | Т | Т | Т | | | Т | Т | Т | | | Т | Т | Т | | | Т | Т | Т | Т | Π | | Т | Т | Π | Т | П |
| 24 Volt AC | | | | | | | | | | | | | | | | | | T | | | | | П | | | | | | | | | | | | | | | | | | | | | | T | | | | | | | |
| | | - | - | - | | | | - | - | _ | | - | - | - | - | | | - | - | - | _ | - | - | - | - | _ | | | | | | - | - | - | - | _ | | - | - | | | - | - | - | - | - | | - | - | | _ | |
| 24 Volt AC | 4 | | - | | | \square | + | + | + | | | ÷ | | | H | | | ╋ | | | | ÷ | | - | | | | | | | | + | | | | | - | + | + | | H | ÷ | ÷ | | + | | | | | | | |
| 24 VOIL AC | | - | _ | _ | _ | | _ | | _ | | | | | _ | | | _ | - | _ | - | | _ | _ | _ | | _ | _ | _ | _ | | | _ | | _ | _ | | _ | | _ | | | _ | | _ | _ | | | _ | _ | | | |
| | | Bus | con | ımu | inic | atio | on f | ron | n th | e ci | ont | roll | er | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | | _ |
| 1 | | Pow | er s | upp | oly v | with | n da | isy | cha | ain f | fron | n co | onti | roll | er | | _ | _ | | | _ | | _ | | | | | | | _ | | | | | | | | | | | | _ | | | | | | | | | | _ |
| | | Usa | ge o | of ar | nalo | g c | abl | e as | vo | ltag | je b | 000 | ster | r | _ | | | | | | | | | | | | | | | _ | | | | | | _ | | | | _ | | | | | | _ | _ | | | | | |
| | | Nov | oČc | n® s | s | | | | | | | | | | _ | | | | | | | _ | | | | _ | | | | | | | | _ | _ | _ | | | | | | | | | _ | _ | | | _ | | | |

If NovoCon[®] S is used to power external devices, a separate calculation must be made for power booster amount and location.

Jantos

NovoCon® S - High Accuracy Actuator

Daisy chain (continued)

T-junctions

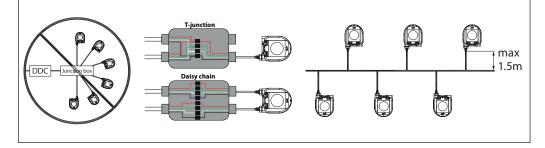
T-junction connections (stub lines) are not recommended.

In the event of T-Junction connections being used the following limitations must be adhered to:

- max T-junction cable length 1.5m (shortest standard digital cable)
- total length of Network max 640m (+ 100m stub length)
- max baud rate 76 kb/s¹⁾
- max number of devices on network 64¹⁾
- main cable should be standard RS485 bus, twisted pair, min thickness AWG22 / 0.32mm2.
- ¹⁾ When using less than 32 devices you may attempt to raise the speed to 115 kb/s.

Star topology

Star topology is not according to RS485 standard and should not be used with NovoCon[®] S.



If the supply voltage to the first device in the daisy chain is lower than 24V AC/DC, or long thin cables other than NovoCon[®] cables are used, then the quantity of devices in the daisy chain may have to be reduced.

The recommended maximum quantities of NovoCon[®] S are 64 pcs in one daisy chain connection. If other BACnet devices are added with NovoCon[®] S in the same daisy chain connection, Danfoss recommends a maximum of 32 pcs. to ensure sufficient network speed.

Danfoss recommends that NovoCon[®] S should be used on its own sub-network for optimal performance.

General requirements and recommendations:

- Use Danfoss daisy chain cable to connect two NovoCon® S devices.
- Use Danfoss digital cable to connect NovoCon[®] S with another BACnet device.
- The current in cables should not exceed 3Arms at 30°C.
- Use the termination resistor (DIP switch 8) at the end of daisy chain.
- Voltage boosting may be achieved via any port.
- Generally, one power supply is preferred.
- If two power supplies are used, they must have the same polarity and the same common ground.
- A common ground must be used for all devices on the same sub-network, including routers and gateways.
- Galvanic separation shall be provided for segments crossing buildings.
- Total maximum sub-network cable length is 1200m.

Optimize BACnet network speed

Reducing Unnecessary PollforMaster Traffic

The MAX_MASTER setting in NovoCon[®] S can be set above the number of the highest used MAC address in the MS/TP sub network. The MAX_MASTER property is found in the Device object and has a default value of 127. If used, it should be noted that the MAX_MASTER property value should be adjusted accordingly at a later stage prior to adding more devices to the network when the highest MAC address exceeds the MAX_MASTER property value.

Important: Before MAX_MASTER can be set, ensure **ALL** network device MAC addresses are below the intended MAX_MASTER property value. Failure to do this may result in network communication problems.

Allocating Correct INFO_FRAMES

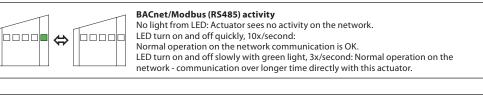
Setting for Controller:

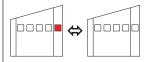
Network Routers and Controller devices that transport traffic in the MS/TP network require a higher number of INFO_FRAMES than NovoCon[®] S. Therefore, these devices should have a higher value than NovoCon[®] S. A general rule of thumb for the sub network router's MAX_INFO_FRAMES property value is equal to the amount of MS/TP devices in the router's sub network. The MAX_INFO_FRAMES property is found in the Device object of MS/TP devices. NovoCon's default MAX_INFO_FRAMES value is 1.

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LED Display

BACnet/Modbus (RS485) activity





BACnet/Modbus (RS485) activity with ERRORS

LED turns on and off slowly, 3x/second, with RED color: Actuator sees activity, but with errors. LED turn on and off quickly, 10x/second, with RED color: Communication is OK, EXCEPT that another device may be using the same MAC address.

Position of valve/actuator



AB-QM is open 1-24% of Design Flow.



AB-QM is open 25-49% of Design Flow.

|--|

AB-QM is open 50-74% of Design Flow.



AB-QM is open 75-99% of Design Flow.



AB-QM valve is open 100% of Design Flow.

| Flush is active All LEDs turns on/off with specific period. |
|--|
|--|

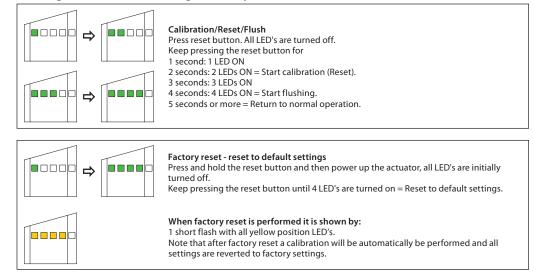
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| LED Display (continued) | Movement of valve/actuate | or |
|-------------------------|--------------------------------|--|
| | | NovoCon[®] S is closing the valve All green LEDs are turned ON, then turned OFF one at the time (repeatedly). |
| | | NovoCon[®] S is opening the valve All green LEDs are turned OFF, then turned ON one at the time (repeatedly). |
| | | NovoCon[®] S is calibrating Green light moves forward and backwards, one by one. |
| | | De-air is active Yellow LEDs are turned ON one by one, then turned OFF one by one (repeatedly). |
| | Information from actuator | |
| | | Blinking function , all green LEDs turns on/off. Used to physically identify individual actuator on the bus. |
| | | Error during closing Debris might be trapped under the AB-QM valve cone. Flushing may solve the problem. |
| | | Temperature inside NovoCon® S is out of the recommended range LEDs change between showing the alarms and showing normal operation. Ambient temperature has likely exceeded 60°C. |
| | | Internal NovoCon [®] S error LEDs change between showing the alarms and showing normal between operation. Try: A: Re-calibrate. B: Turn power off and on. C: If the error does not disappear actuator replacement can be necessary. |
| | | Error during NovoCon® S calibration LEDs change between showing the alarms and showing normal operation. Verify if the NovoCon® S is correctly attached to the valve and recalibrate. |
| | | Power supply is outside limits LEDs change between showing the alarms and showing normal operation. Use analog cables as voltage booster. |
| | | No Control Signal In analog control the broken control wire is detected. In CO6 mode or Inverted CO6 mode the ChangeOver ⁶ actuator is not connected or damaged. |
| | | ChangeOver⁶ actuator The ChangeOver ⁶ actuator is in manual override or unable to reach position. |
| | LEDs change between showing th | e alarms and showing normal operation. |

Pantos

LED Display (continued)

Pressing the reset button during normal operation



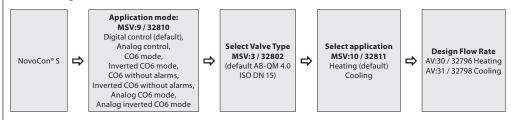
BACnet objects and Modbus registers usage

- Design flow rate setting

General

There are simple BACnet and Modbus settings that are essential to the basic setup configuration of NovoCon[®] S in order to communicate and control. These are contained in the BACnet objects or in decimal format Modbus registers.

Initial configuration



BACnet objects and Modbus registers usage

- Advanced configuration and features If the default setup of the actuator isn't suitable, special attention has to be payed to the following objects:

| MSV:9 / 32810 | Application mode |
|----------------|------------------------------------|
| MSV:3 / 32802 | Selected Valve Type |
| AV:30 / 32796 | Design Flow Rate Heating |
| AV:31 / 32798 | Design Flow Rate Cooling |
| MSV:10 / 32811 | Application command & status |
| Al:1 / 33218 | Temperature T1 or resistance input |
| AI:2 / 33220 | Temperature T2 or resistance input |
| AV:32 / 33288 | Power Emission |
| MSV:13 / 32815 | Energy management |
| | |

Application mode:

The default Application mode is Digital Control. In this mode the NovoCon[®] S is controlled via fieldbus and the the voltage inputs and outputs are available to connect other devices. Alternatively, in Analog Control mode the NovoCon[®] S is expecting an analog control signal.

If the CO6 functionality is needed the Application mode must be changed to CO6 mode. This is where the NovoCon[®] S actuator is ready to be used with the Actuator NovoCon[®] ChangeOver⁶. If the heating and cooling pipes are connected inverted to that shown on the data sheet, then CO6 Inverted mode must be selected. The object/register MSV:9 / 32810 Application mode is used to select this. Analog Control is also possible if reguired.

Select if the application is Heating, Cooling or CO6 in Application command & status MSV:10 / 32811.

Selection of AB-QM valve type:

After selecting Application mode (see above), it is then necessary to select the AB-QM valve type that the actuator is mounted on. This is done with the object MSV:3 / 32802 Selected Valve Type. The present value of MSV:3 / 32802 may be set to values between 1 and 30. Each number represents a specific AB-QM valve type, which can be found in the table: Valve type selection. The default value for MSV:3 / 32802 is 2 i.e. ABQM 4.0 ISO DN15 valve.

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BACnet objects and Modbus registers usage

- Advanced configuration and features (continued)

Selection and setting of engineering units:

NovoCon[®] S - High Accuracy Actuator

If there is a need to change the default engineering units, this is done in BACnet via the object's engineering units property or in separate objects, and in Modbus via separate registers. Se the BACnet and Modbus tables for more details.

Setting the Design Flow Rate:

The designed maximum flow rate of the controlled system should be set if the nominal flow of the valve does not correspond to the designed maximum flow rate. The Design Flow Rate is set by changing the present value of:

- MSV:30 / 32796 Design Flow Rate for Heating
- MSV:31 / 32798 Design Flow Rate for Cooling

Note: If the Design Flow Rate is set to more than the nominal flow value of the valve, the mechanical pre-setting on the valve must be set to maximum open i.e. fully opening the mechanical pre-setting wheel on the AB-QM valve (100% open is the default mechanical pre-setting from our factory).

Changing from Heating to cooling in CO6 and Inverted CO6 mode:

The object / register MSV:10 / 32811 CO6 command & status is used to change from heating function to cooling function as well as giving feedback as to the ball position status. A more detailed description of this is found in the tables for BACnet objects / Modbus registers.

Temperature measurements:

Al:1 / 33218 Temperature T1 or resistance input and Al:2 / 33220 Temperature T2 or resistance input are used to measure the temperature with temperature sensors. The resistance value may also be shown directly if selected, allowing these inputs to be used for other purposes than measuring temperature e.g. window contacts or other potential free contacts. Closed circuit <900 Ω , open circuit 100k Ω .

Power emission:

AV:32 / 33288 Power Emission is used to show the present hydronic power emission of the terminal unit, based on calculations from water flow rate and the temperature difference between supply and return pipes.

Energy Counter:

Either the Cooling or Heating hydronic energy used is counted and logged under AV:33 / 33290 or AV:34 / 33292. This function is enabled and disabled with MSV:12 / 32814.

Flushing a system:

Actuator Mode and Special Features MSV:0 / 33284 has an option which allows the user to flush the system via the field bus. To start flushing the system, set MSV:0 / 33284 to 3, Flush. The actuator will then open up the AB-QM valve completely. Flush will end when:

- MSV:0 / 33284 is set back to 1 = Normal operation
- Or the power is cycled.
- Or the flush function times-out after 1 hour.

When flushing ends, the actuator returns to normal operation.

De-Airing of a system:

With MSV:0 / 33284, is it also possible to start the De-Air function in the actuator. This function will open and close the AB-QM valve a number times, helping getting rid of trapped air in the hydronic system. Start De-Air by setting MSV:0 / 33284 to 4. De-air will run undisturbed until it ends. The state of the actuator will then go back to normal operation i.e. MSV:0 / 33284 = 1, Normal.

Controlling the actuator:

Under normal operation of the actuator, where the flow through the AB-QM valve is to be controlled, the object Flow Rate Setpoint AV:1 / 33280 is used. The default setting for the Flow Rate Setpoint engineering unit is %.

This is the most suitable setting as the controller does not need to know anything about the Design Flow Rate setting of the actuator. The output signal from the controller needs only to be set up so it regulates from 0 to 100% of the Heating Design Flow Rate AV:30 / 32796 or Cooling Design Flow Rate AV:31 /32798. Alternative Design Flow Rate AV:0 / 32768 can be used.

To change the flow rate through the valve, the present value of AV:1 / 33280 is written-to, in the range 0 - 100%.

If the engineering unit selected for AV:1 / 33280 must be l/h, the Flow Rate Setpoint through the valve must be written-to in integers representing l/h. An example of this could be a controller writing values to the actuator in the range 0 to 450 l/h for a DN15 valve.

Alarms and warnings:

System issues can be detected by using BACnet object values BV:10 to BV:24 or Modbus register 33536, see BACnet and Modbus tables for more details.

MSV:9 / 32810 has also a state called "CO6 without alarms" meaning that essentially the same CO6 functionality is present (2 Design flows and the changeover signal) without alarms, so the analog input signal may be used to connect other devices if required.

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| Energy management MSV:13 / 32815 | Whilst under NovoCon® control, the valve will no contained within its algorithms, although an exter the valve. If the energy limitation settings are un- will be activated to inform the user that the set- p will not automatically relinquish control of the flor external device e.g. DDC differs greatly with that This information may be used by the user to imp General Information - Energy Control States: For all 'control' states within MSV:13/32815, Novo the AB-QM valve and will not accept a control sig control, the valve will not be fully closed at any t | varning will be activated and made visible on the control of the flow rate through the AB-QM valve. t be closed at any time i.e. closing % constraints are ernal device's control signal will always be able to clo obtainable without NovoCon® closing itself, a warnin oint value is 'out of range'. Please note that NovoCor w rate as soon as the set-point is achieved if the of NovoCon's® calculated flow rate/opening %. TIP: rove the external control device's PID. |
|-------------------------------------|--|---|
| Power Manager | State 1: Not active Energy management applications are disabled. State 2: Power limitation (chilled water exam NovoCon [®] S calculates the instantaneous hydror the DDC control signal and limit the flow rate / h in object / register AV:35 or 36 / 32832 or 32834. | |
| | for both Cooling Power and Heating Power. Whe bit 23 in register 33536 will be set to 'on'. Application example: When the "Power" is limite consumption (during peak load) and save mone | on this limitation is active, the warning object BV:23 / d in this way we are able to prevent over y. |
| | √Energy saving 2kW limit setting | MSV:9/ District NovoCon/AB-QM opening degree |
| | | MSV:3 / Digital Rowconnand via BUS MSV:3 / Selected ISO valve selected = I/h, °C , kW and kg/m³. |
| | Time | 32802 Valve Type ANSI valve selected = g/min, °F and kBTU. |
| | I/h | |
| | DDC NovoCon DDC | /32815 Limitation that NovoCon will not exceed e.g. 2kW |
| | Control Control Control | AV:36 Cooling max. The value that NovoCon will ensure T2 /32834 power value will not fall below e.g. 13°C |
| | State 3: Power control | |
| Power Manager | valve is controlled by the Flow Rate setpoint AV: based on the flowrate and temperature inputs w | hich are used to calculate the power consumption. |
| Power Manager Delta T Manager | valve is controlled by the Flow Rate setpoint AV: based on the flowrate and temperature inputs w Application example: Tempering a space (e.g. in output constant. State 4: Min. Delta T limitation (heating wate NovoCon [®] S, when required, overrides the DDC co difference between the flow and return temperat defined minimum delta T is not achieved. As the f calculated minimum set-point for the return temp transfer to the FCU irrespective of the flow tempe will apply the appropriate value whilst in cooling, For heating, the delta T value is set in object / reg limitation to be activated, the warning object BV | I in kW or kBTU/h (selected in MSV:21 / 32788) and is which are used to calculate the power consumption. storage hall) where we can set and keep the energy r example) ontrol signal and maintains a minimum temperature sures by starting to close the valve when the user flow temperature increases/decreases, so will the berature. This always ensures a minimum energy wrature. This state may also be used in CO6 mode and wheating mode. gister AV:37 / 32836. When conditions allow for this 1:23 / bit 23 in register 33536 will be set to 'on'. prove the efficiency of boiler/chiller we can define th |
| | valve is controlled by the Flow Rate setpoint AV: based on the flowrate and temperature inputs w Application example: Tempering a space (e.g. in output constant. State 4: Min. Delta T limitation (heating wate NovoCon® S, when required, overrides the DDC co difference between the flow and return temperat defined minimum delta T is not achieved. As the f calculated minimum set-point for the return temp transfer to the FCU irrespective of the flow tempee will apply the appropriate value whilst in cooling, For heating, the delta T value is set in object / ree limitation to be activated, the warning object BW Application example: When we would like to imp Minimum Delta T in the system with respect to c | I in kW or kBTU/h (selected in MSV:21 / 32788) and is which are used to calculate the power consumption. storage hall) where we can set and keep the energy r example) ontrol signal and maintains a minimum temperature cures by starting to close the valve when the user flow temperature increases/decreases, so will the berature. This always ensures a minimum energy erature. This always ensures a minimum energy trating mode. gister AV:37 / 32836. When conditions allow for this '23 / bit 23 in register 33536 will be set to 'on'. prove the efficiency of boiler/chiller we can define the butside temperatures. |
| | valve is controlled by the Flow Rate setpoint AV: based on the flowrate and temperature inputs w Application example: Tempering a space (e.g. in output constant. State 4: Min. Delta T limitation (heating wate NovoCon [®] S, when required, overrides the DDC co difference between the flow and return temperat defined minimum delta T is not achieved. As the f calculated minimum set-point for the return temp transfer to the FCU irrespective of the flow tempe will apply the appropriate value whilst in cooling, For heating, the delta T value is set in object / re- limitation to be activated, the warning object BW Application example: When we would like to imp Minimum Delta T in the system with respect to c | I in kW or kBTU/h (selected in MSV:21 / 32788) and is which are used to calculate the power consumption. storage hall) where we can set and keep the energy r example) pontrol signal and maintains a minimum temperature tures by starting to close the valve when the user flow temperature increases/decreases, so will the berature. This always ensures a minimum energy wrature. This state may also be used in CO6 mode and wheating mode. gister AV:37 / 32836. When conditions allow for this with 23 in register 33536 will be set to 'on'. prove the efficiency of boiler/chiller we can define the stutistide temperatures. Object/ Write/ MSV:9 Digital NovoCon/AB-QM opening degree |
| | valve is controlled by the Flow Rate setpoint AV: based on the flowrate and temperature inputs w Application example: Tempering a space (e.g. in output constant. State 4: Min. Delta T limitation (heating wate NovoCon® S, when required, overrides the DDC co difference between the flow and return temperat defined minimum delta T is not achieved. As the f calculated minimum set-point for the return temp transfer to the FCU irrespective of the flow tempee will apply the appropriate value whilst in cooling, For heating, the delta T value is set in object / ree limitation to be activated, the warning object BW Application example: When we would like to imp Minimum Delta T in the system with respect to c | I in kW or kBTU/h (selected in MSV:21 / 32788) and is which are used to calculate the power consumption. storage hall) where we can set and keep the energy r example) pontrol signal and maintains a minimum temperature sures by starting to close the valve when the user flow temperature increases/decreases, so will the berature. This always ensures a minimum energy wrature. This state may also be used in CO6 mode and wheating mode. gister AV:37 / 32836. When conditions allow for this i:23 / bit 23 in register 33536 will be set to 'on'. prove the efficiency of boiler/chiller we can define the butside temperatures. |
| | valve is controlled by the Flow Rate setpoint AV: based on the flowrate and temperature inputs w Application example: Tempering a space (e.g. in output constant. State 4: Min. Delta T limitation (heating wate NovoCon® S, when required, overrides the DDC co difference between the flow and return temperat defined minimum delta T is not achieved. As the f calculated minimum set-point for the return temp transfer to the FCU irrespective of the flow tempe will apply the appropriate value whilst in cooling, For heating, the delta T value is set in object / ref limitation to be activated, the warning object BV Application example: When we would like to imp Minimum Delta T in the system with respect to c | I in kW or kBTU/h (selected in MSV:21 / 32788) and is which are used to calculate the power consumption. storage hall) where we can set and keep the energy r example) ontrol signal and maintains a minimum temperature ures by starting to close the valve when the user flow temperature increases/decreases, so will the berature. This always ensures a minimum energy wrature. This state may also be used in CO6 mode and theating mode. gister AV:37 / 32836. When conditions allow for this '23 / bit 23 in register 33536 will be set to 'on'. prove the efficiency of boiler/chiller we can define the butside temperatures. |
| | valve is controlled by the Flow Rate setpoint AV: based on the flowrate and temperature inputs w Application example: Tempering a space (e.g. in output constant. State 4: Min. Delta T limitation (heating wate NovoCon [®] S, when required, overrides the DDC co difference between the flow and return temperat defined minimum delta T is not achieved. As the t calculated minimum set-point for the return temperat defined minimum set-point for the return temperat mill apply the appropriate value whilst in cooling, For heating, the delta T value is set in object / re- limitation to be activated, the warning object BV Application example: When we would like to imp Minimum Delta T in the system with respect to c | I in kW or kBTU/h (selected in MSV:21 / 32788) and is thich are used to calculate the power consumption. storage hall) where we can set and keep the energy r example) pontrol signal and maintains a minimum temperature tures by starting to close the valve when the user flow temperature increases/decreases, so will the berature. This always ensures a minimum energy trature. This state may also be used in CO6 mode and 'heating mode. gister AV:37 / 32836. When conditions allow for this '23 / bit 23 in register 33536 will be set to 'on'. prove the efficiency of boiler/chiller we can define the butside temperatures. |

DDC

NovoC

DDC control No

Constantly ensures the flow and return temperature difference do not fall below a specified value

The delta T value that NovoCon will not fall below e.g. 20°C

MSV:13 / 32815

AV:37 / 32836

DDC control Min. Delta T limitation

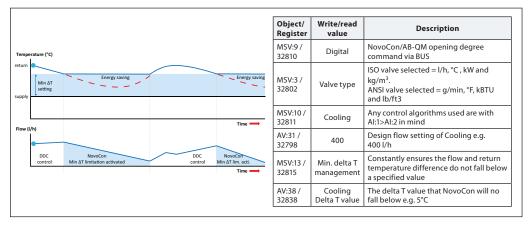
Heating Delta T value

Dantoss

Energy management MSV:13 / 32815 (continued)

State 4: Min. Delta T limitation (chilled water example)

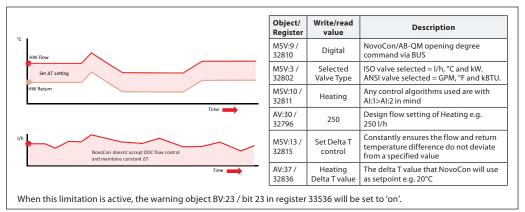
Application example: When we would like to improve the efficiency in the system we can define the Minimum Delta T in the system.



State 5: Set Delta T control (heating water example)

NovoCon[®] S constantly overrides the DDC control signal when activated and maintains a constant temperature difference between the flow and return temperatures by opening and closing the valve. When the flow temperature increases/decreases, so will the calculated delta T set-point for the return temperature. This always ensures a constant delta T across the FCU irrespective of the flow temperature. This state may also be used in CO6 mode and will apply the appropriate value whilst in cooling/heating mode.

The constant delta T for heating is set in object / register AV:37 / 32836 and for cooling AV:38 / 32838. Application example: Tempering a space (e.g. in storage hall) where we can set and keep a constant Delta T.

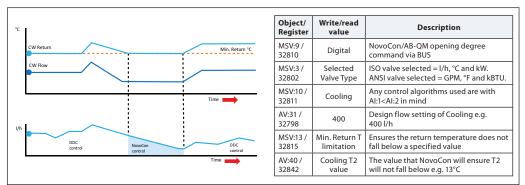


State 6: Min. Return T limitation (chilled water example)

NovoCon® S ensures the min. return temp. which is set in register / object AV:40 / 32842. This function will mainly be used for a Cooling application where the return temperature is higher than the flow temperature. NovoCon® S overrides the DDC control signal when activated and maintains a minimum return temperature by starting to close the valve when the user defined minimum return temperature is not achieved. When conditions allow for this limitation to be active, the warning object BV:23 / bit 23 in register 33536 will be set to 'on'.

Application example:

To improve chiller efficiency and ensure proper flow temperature for cooling systems, we can prescribe minimum return temperature to avoid COP reduction as well as low Delta T syndrome.



Jantos

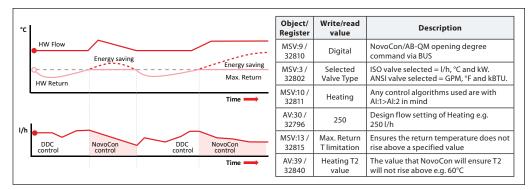
Energy management MSV:13 / 32815 (continued)

State 6: Return T limitation (heating water example)

NovoCon[®] S ensures the max return temp. set in register / object AV:39 / 32840.

This function will mainly be used for a Heating application where the return temperature is lower than the flow temperature. NovoCon[®] S overrides the DDC control signal when activated and maintains a maximum return temperature by starting to close the valve when the user defined maximum return temperature is not achieved. When conditions allow for this limitation to be active, the warning object BV:23 / bit 23 in register 33536 will be set to 'on'.

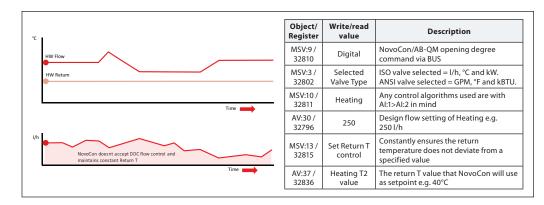
Application example: Heating systems that require a maximum return temperature for efficient heat source generation e.g. condensing boilers and heat pumps.



State 7: Set Return T control (heating water example)

A constant return temperature T2 value is set in object / register AV:37 / 32836 and/or AV:38 / 32838. NovoCon® S constantly overrides the DDC control signal and maintains a constant return temperature by opening and starting to close the valve when the user defined Return T is exceeded or not achieved. When the flow temperature increases/decreases, the Return T set-point remains the same. This will ensure a constant return temperature back to the energy source.

Application example: When we intend to use the return water for secondary usage e.g. pre-heat on a AHU or a standalone terminal unit in which the T2 value is used as the temperature set-point to be maintained.



Danfoss

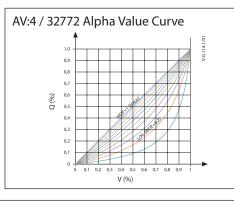
BACnet Objects - Analog Value

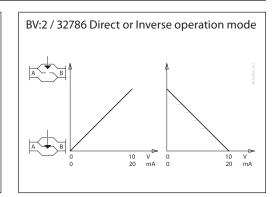
| Ident | Object / Parameter name | Unit | Read/ Write | Min | Max | Default | Resolution | Description | Persistent Yes/No |
|----------------|--|---|----------------|--|---|---|------------|---|----------------------|
| | Parameter name | | write | | | | | Recommended to use AV:30 for Heating and/or AV:31 for cooling. | Yes/NO |
| AV:0 | Design Flow Rate | 98: % 136: L/h 89: GPM | R/W | Recommended 20% of nominal flow | Setting Range Maximum from Valve table | Nominal value from the Valve table in L/h | 0.1 | Per-set value for the Design Flow Rate when control signal is at 100%, if the Application mode is Analog or Digital control otherwise not used. Units can be changed via the object's engineering units property and/or MSV:20. The units L/h (ISO valves) or GPM (ANSI valves) comes from the object MSV:3 Selected Valve type. | Yes |
| AV:1 | Flow Rate Setpoint | 98: % 136: L/h 89: GPM 48: kW 157: kBTU/h | R/W | 0 | 100% or Design Flow value | 100% | 0.01 | The Flow Rate Setpoint (max. flow rate) through the AB-QM valve. Units can be changed via the object's engineering units property and/or MSV:21. NOTE: For kW or kBTU/h to become active, MSV:13 Power Controller (state:3) must be chosen. | No |
| AV:2 | Actual Flow Rate feedback | %, L/h, GPM | R | 0 | If L/h (GPM) is selected then the valve flow rate is set to the selected valve's (MSV:3) maximum value. Otherwise 100% | L/h or GPM depending on the selected valve | 0.001 | Flow rate indication based on the position of the Actuator stem. Units can be changed via the object's engineering units property and/or MSV222. This object is supported by COV. | No |
| AV:3 | Control Fallback Time | 72: Minutes | R/W | 0 | 60 | 10 | 1 | Time before actuator reacts to a missing analog control signal. i.e. when MSV:9=1 Analog control and not receiving an analog control signal. | Yes |
| AV:4 | Alpha Value | 95: No units | R/W | 0.05 | 1.0 | 1,0 | 0.01 | Value used for shaping the curve in Manual Defined Function (MDF) mode to fit the characteristic curve of a heat exchanger. Linear setting: MDF=1. See curve below table. If AV:1 is in L/h in Digital mode, the alpha setting is ignored. See Alpha value diagram. | Yes |
| AV:5 | Valve closing or opening time | 73: Seconds | R/W | 18 | 700 | na | 1 | The time the actuator needs to move from 0% to 100% of Design Flow Rate. Use with MSV:4. | Yes |
| AV:6 | Rectified voltage measured by the actuator | Volts | R | 12 | 50 | na | 0.01 | Too mate: Ose winking powers the actuator. Rectified voltage which powers the actuator. Too low voltage: 16.1-17.5V. Too high voltage: 38.3-43.4V. Use to check power booster numbers an layout. | No |
| AV:7 | MAC Address | 95: No units | R/W | 1 | 126 | na | 1 | MAC Address used for BACnet communication. | Yes |
| AV:8 | Temperature in the Actuator | °C, °F | R | -20 | 100 | °C | 0.5 | Temperature measured inside the actuator. Units can be changed via the object's engineering units property. | No |
| AV:9 | Total Operating Hours | Hours | R | 0 | MAX | na | 1 | Total Operating Hours of the actuator. | Yes |
| AV:10 | Minutes since last power-up | Minutes | R | 0 | MAX | na | 1 | Minutes since the last power-up of the actuator. | No |
| AV:11 | Minutes since last calibration | Minutes | R | 0 | MAX | na | 1 | Minutes since the last time the actuator was calibrated to an AB-QM valve. | Yes |
| AV:12 | Minutes since fully closed | Minutes | R | 0 | MAX | na | 1 | Minutes since the last time the AB-QM valve was fully closed. | Yes |
| AV:13 | Minutes Since fully Opened | Minutes | R | 0 | MAX | na | 1 | Minutes since the last time the AB-QM valve was fully opened. | Yes |
| AV:14 | Lifetime estimate | na | R | 0 | МАХ | na | 0.01 | Calculated percentage of expended lifetime. At 100% the valve and actuator have reached the estimated minimum lifetime. Replacement of valve and actuator is recommended. | Yes |
| AV:15 | Server Message Count | na | R | 0 | MAX | na | 1 | Server Message Count | No |
| AV:16 | Server Message Received | na | R | 0 | MAX | na | 1 | Server Message Received | No |
| AV:17 AV:18 | Server Error Count Server Message sent | na na | R | 0 | MAX | na na | 1 | Server Error Count Server Message sent | No No |
| AV:19 | Server Timeout Error | na | R | 0 | MAX | na | 1 | Server Timeout Error | No |
| AV:20 | Serial Number of the actuator | na | R | na | na | na | 1 | Description of this object holds the serial number of the actuator - programmed at the time of production. | na |
| AV:21 | The name of the Selected valve is shown here | L/h or GPM, Unit type comes from MSV:3 Selected Valve Type | R | na | na | na | 1 | Nominal flow of the selected AB-QM valve is shown in the present value. | na |
| AV:22 | Valve position at nominal flow | Millimetre | R | na | na | na | 1 | Position in mm for nominal flow of the selected AB-QM valve. | na |
| AV:23 | Maximum value for the Design Flow Rate | % 136: L/h or 89: GPM. | R | na | Setting Range Maximum from Valve table | % | 1 | Maximum level the Design Flow Rate can be increased to for the selected AB-QM valve. Name and Nominal Flow for the User Defined Valve. | na |
| AV:24 | The name of the User Defined Valve is shown here | Unit type written here is copied to the Valve Table. Default: L/h | R/W | 1 | 5000 | 600 | 0.1 | This Object is used only if NovoCon [®] S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible. | Yes |
| AV:25 | Valve position at nominal flow for User Defined Valve | 30: Millimetre | R/W | 1.5 | 5.8 | 4 | 0.01 | Position in mm for nominal flow of the User Defined Valve. This Object is used only if NovoCon ⁺ S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible. | Yes |
| AV:26 | Maximum value for the Design Flow in the User Defined Valve | 98:% | R/W | 100 | 150 | 100 | 1 | Maximum level the Design Flow can be increased to for the User Defined Valve. This Object is used only if NovoCon* 5 is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the | Yes |
| AV:27 | Alarm summary count | 95: No units | R | na | na | 0 | na | desired connection is possible. Numerical overview about pending errors detected. Coding for AV:27 Alarm summary count is: If BV:10 is active then AV:27 is 1.0. If BV:11 is active then AV:27 is 2.0. If BV:13 is active then AV:27 is 2.0. If BV:13 is active then AV:27 is 3.0. If BV:15 is active then AV:27 is 3.0. If BV:16 is active then AV:27 is 3.0. If BV:16 is active then AV:27 is 3.0. If BV:17 is active then AV:27 is 3.0. If BV:18 is active then AV:27 is 54.0. If BV:19 is active then AV:27 is 52.0. If BV:20 is active then AV:27 is 512.0. If BV:21 is active then AV:27 is 50.0. If BV:22 is active then AV:27 is 50.0. If BV:23 is active then AV:27 is 50.0. If BV:23 is active then AV:27 is 50.0. If BV:24 is active then AV:27 is 50.0. If BV:23 is active then AV:27 is 50.0. If BV:24 is active then AV:27 is 50.0. If BV:24 is active then AV:27 is 50.0. This object is supported by COV. | No |
| AV:30 | Heating Design Flow Rate | 98: % 136: L/h 89: GPM | R/W | Recommended 20% of nominal flow | Setting Range Maximum from Valve table | Nominal value from the Valve table in L/h | 0.1 | Pre-set value for the Design Flow Rate in heating mode, when the control signal is at 100%. MSV:10 must be set to Heating. The units L/h (ISO valves) or GPM (ANSI valves) comes from the object MSV:3 Selected Valve type | Yes |
| AV:31 | Cooling Design Flow Rate | 98: % 136: L/h 89: GPM | R/W | Recommended 20% of nominal flow | Setting Range Maximum from Valve table | Nominal value from the Valve table in L/h | 0.1 | Pre-set value for the Design Flow Rate in cooling mode, when the control signal is at 100%. MSV:10 must be set to Cooling. The units L/h (ISO valves) or GPM (ANSI valves) comes from the object MSV:3 Selected Valve type. | Yes |
| AV:32 | Power emission | 48: kW 157: kBTU/h | R | 0 | na | na | 0.01 | The hydronic power emission of the terminal unit, based on calculations from water flow rate and the temperature difference between suppl (Ati:) and return (At:2) pipes. If AV:41 Glycol correction is used, Power emission will be adjusted accordingly. Units can be changed via the object's engineering units property. | No |

Danfoss

BACnet Objects - Analog Value (continued)

| | Object / | | Read/ | | | | | | Persistent |
|-------|----------------------------------|---------------------------------|-------|-----|-----|---------|--|---|------------|
| Ident | Parameter name | Unit | Write | Min | Max | Default | Description | Information | Yes/No |
| AV:33 | Heating Energy counter | 19: kWh 126: MJ 147: kBTU | R/W | 0 | na | na | Accumulative Energy counter for heating. | Activated/Deactivated via MSV:12. Units set via MSV:27. If AV:41 Glycol correction is used, Heating Energy counter will be adjusted accordingly. | Yes |
| AV:34 | Cooling Energy counter | 19: kWh 126: MJ 147: kBTU | R/W | 0 | na | na | Accumulative Energy counter for cooling. | Activated/Deactivated via MSV:12. Units set via MSV:27. If AV:41 Glycol correction is used, Cooling Energy counter will be adjusted accordingly. | Yes |
| AV:35 | Heating max. Power | 48: kW 157: kBTU/h | R/W | 0 | na | 0 | Pre-set value for the design flow rate, in heating mode. | When using MSV:13 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the heating power through the terminal unit. | Yes |
| AV:36 | Cooling max. power | 48: kW 157: kBTU/h | R/W | 0 | na | 0 | Pre-set value for the design flow rate, in cooling mode. | When using MSV:13 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the cooling power through the terminal unit. | Yes |
| AV:37 | Heating Delta T | 62: °C 64 °F | R/W | na | na | 15 | Set-point value for the temperature difference between the flow and return pipes | For MSV:13 state Min. delta T management and Set Delta T control, this is the value the control is based on for heating. | Yes |
| AV:38 | Cooling Delta T | 62: °C 64 °F | R/W | na | na | 5 | Set-point value for the temperature difference between the flow and return pipes | For MSV:13 state Min. delta T management and Set Delta T control, this is the value the control is based on for cooling. | Yes |
| AV:39 | Heating T2 | 62: °C 64 °F | R/W | na | na | 35 | Set-point value for Heating T2 (Heating return pipe temperature) | For MSV:13 state Max. Return T management and Set return T control, this is the value the control is based on for heating. | Yes |
| AV:40 | Cooling T2 | 62: °C 64 °F | R/W | na | na | 13 | Set-point value for Cooling T2 (Cooling return pipe temperature) | For MSV:13 state Min. Return T management and Set return T control, this is the value the control is based on for cooling. | Yes |
| AV:41 | Glycol Factor | na | R/W | 0.5 | 2 | 1 | Glycol correction factor | Select appropriate factor from 0.5-2 if a glycol mixture is used. | Yes |
| AV:50 | Analog CO6 Heating point 100% | 95: No units | R/W | 0 | 10 | 0 | Signal point for Analog CO6 mode | The control signal for heating 100% open when MSV:9 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |
| AV:51 | Analog CO6 Heating point 0% | 95: No units | R/W | 0 | 10 | 3.3 | Signal point for Analog CO6 mode | The control signal for heating 0% open when MSV:9 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |
| AV:52 | Analog CO6 Cooling point 0% | 95: No units | R/W | 0 | 10 | 6.7 | Signal point for Analog CO6 mode | The control signal for cooling 0% open when MSV:9 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |
| AV:53 | Analog CO6 Cooling point 100% | 95: No units | R/W | 0 | 10 | 10 | Signal point for Analog CO6 mode | The control signal for cooling 100% open when MSV:9 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |





BACnet Objects

- Multi State Value

| Ident | Object / Parameter name | Read/ Write | State Text | Default State | Description | Persistent Yes/No |
|-------|--|----------------|---|---|--|------------------------------------|
| MSV:0 | Actuator Mode and special features | R/W | 1: Normal 2: Calibration 3: Flush ¹⁾ 4: De-Air ²⁾ 5: Alarm | 1: Normal | Shows present mode of actuator. Calibration, flushing and de-air may be started from here. | Yes, except state 3,4 & 5 |
| MSV:1 | Analog Control signal type and range | R/W | 1: 0-5 VDC 2: 0-10 VDC 3: 2-10 VDC 4: 5-10 VDC 5: 2-6 VDC 6: 6-10 VDC 7: 0-20 mA 8: 4-20 mA | 2: 0-10 VDC | Used to select the analog control signal input type and range. | Yes |
| MSV:2 | Missing Control Signal Fallback Action | R/W | 1: No action 2: CLOSE 3: OPEN 4: 50% of Design Flow | 1: No action | The action that the actuator will commence upon a missing analog control signal when MSV:9=1. | Yes |
| MSV:3 | Selected Valve Type | R/W | See table "Valve Type Selection" | 2: AB-QM 4.0 ISO DN 15 | This is the AB-QM valve type that the actuator is set-up to control. | Yes |
| MSV:4 | Actuator Speed | R/W | 1: 3 sec/mm 2: 6 sec/mm 3: 12 sec/mm 4: 24 sec/mm 5: Constant Time | 4: 24 sec/mm | The amount of time the actuator takes to move 1mm or alternatively, a specified constant time function (see AV:5). The Constant Time value range is 18-700 seconds. | Yes |
| MSV:5 | MAC Address assignment method | R/W | 1: DIP Switch Settings or Auto Addressing 2: User configuration over BACnet or Auto Addressing | 1: DIP Switch Settings or Auto Addressing | Method used to set the BACnet MAC address. If the MAC address is not set by DIP Switch, the actuator will automatically assign itself an available MAC address. | Yes |
| MSV:6 | Baud Rate | R/W | 1: Auto Baud Rate Detection 2: 9600 bps 3: 19200 bps 4: 38400 bps 5: 57600 bps 6: 76800 bps 7: 115200 bps | 1: Auto Baud Rate Detection | Baud Rate used for BACnet communication. | Yes |
| MSV:7 | LED Control | R/W | 1: Normal LED mode 2: Show alarms only 3: All LED's OFF 4: Blink | 1: Normal LED mode | Used to select the LED display required. | Yes |

¹⁾ Opens the valve fully for one hour or until a new state is selected
²⁾ Opens and closes the valve 5 times at maximum speed



NovoCon[®] S - High Accuracy Actuator

| B | ACne | t Obje | ects |
|---|-------|--------|-------|
| - | Multi | State | Value |

(continued)

| Ident | Object / Parameter name | Read/ Write | State Text | Default State | Description | Persisten Yes/No |
|--------|--|-------------------------|--|--------------------|--|---------------------|
| MSV:8 | Select field bus protocol | R/W | 1: DIP switch 2: BACnet 3: Modbus | 1: DIP switch | Selection of field bus protocol. See also the DIP Switch Settings section of the data sheet. When the protocol is changed, a power cycle is required to make the actuator adopt the newly selected protocol. | Yes |
| MSV:9 | Application mode | R/W | 1: Analog control 2: Digital control 3: CO6 mode 4: Inverted CO6 mode 5: CO6 without alarms 6: Inverted CO6 without alarms 7: Analog CO6 mode 8: Analog inverted CO6 mode | 2: Digital control | Select the actuator application mode. State 1: Analog Control. Flow is controlled with an analog signal e.g. 0-10V. Design Flow Rate set via AV:30 Heating and/or AV:31 Cooling. Alternative AV:0 can be used. State 2: Digital Control. AV:1 is used to control the flow. Design Flow Rate set via AV:30 Heating and/or AV:31 Cooling. Alternative AV:0 can be used. State 3: CO6 mode. AV:1 is used to control the flow. Design Flow Rate set via AV:30 Heating and/or AV:31 Cooling. Design Flow Rate. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. Heating to sonnected to the CO6 valve to ports 5 & 6 and cooling to ports 1 & 4. State 4: Inverted CO6 mode. AV:1 is used to control the flow. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. Ports are inverted in relation to State 3. State 5: CO6 without alarms. AV:1 is used to control the flow. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. This state may be used if the Analog input is required to be used other than CO6 feedback. Be aware that in this state the status for the CO6 valve is not shown. State 5: CO6 valve is not shown. State 5: Co6 valve is not shown. State 5: Analog CO6 mode. The flow is controlled from the Room controller via the analog input signal. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. BV:2 is in this case used to switch the control signal. Be aware that in this state the status for the CO6 valve is not shown. State 5: Analog CO6 mode. The flow is controlled from the Room controller via the analog inverted CO6 wole. Sin this case used to switch the control signal. Be aware that in this state the status for the CO6 valve is not shown. State 3: Analog CO6 mode. The flow is controlled from the Room controller via the analog input signal. Heating Design Flow Rate set via AV:30 and AV:31 for Cooling Design Flow Rate. In this state the Cooling and heating is connected opposite of state 7. When changing to this | Yes |
| MSV:10 | Application command & status | R/W (1-4) R (5-9) | 1: Heating 2: Cooling 3: CO6 Shut Off ¹⁰ 4: CO6 Start exercise 5: CO6 Moving towards Cooling 6: CO6 Moving towards Heating 7: CO6 Alam 8: CO6 Exercising | 1: Heating | States 1 to 4 are commands for the Actuator NovoCon* ChangeOver ⁴ and impact Energy Management Application MSV13. States 5 to 8 are feedback from the Actuator NovoCon* ChangeOver ⁴ . State 3, shut-off mode may only be used for maintenance and is only possible when the Flow Rate Setpoint is 0%. In Central ChangeOver applications, state 1 and 2 are used to command heating or cooling. | Yes |
| MSV:11 | CO6 auto exercise | R/W | 1: ON 2: OFF | 1: ON | ON: The ChangeOver ⁴ valve will be moved from current position to shut off and back again once per week to maintain free movement, if CO6 mode is selected. OFF: Exercising the valve should be handled by BMS. | Yes |
| MSV:12 | Energy counter activation | R/W | 1: Off 2: On | 1: Off | Enable or disable energy counter | Yes |
| MSV:13 | Energy management | R/W | 1: Not active Power Manager: 2: Power Imitation 3: Power control Delta T Manager: 4: Min. Delta T limitation 5: Set Delta T control 6: Return T limitation 7: Set Return T control | 1: Not used | Activate functions to optimize system performance. State 2: If yower is above the set value in AV:35/36, NovoCon will regulate to the specified limit AV:35 and/or AV:36. When this limitation is active, the warning BV:23 will be set to 'on'. State 3: The flowrate through the valve is controlled by AV:1 in %, kW or kBTU/h (selected in MSV:26) and is based on the flowrate and temperature inputs calculation. State 4: If delta T value in AV:37 and/or AV:38 is exceeded, NovoCon will begin to close the valve until the AV:37 and/or AV:38 will be set to 'on'. State 5: The constant delta T is set in AV:37 and/or AV:38 and NovoCon will regulate within these limits. When this limitation is active, the warning BV:23 will be set to 'on'. State 6: NovoCon ensures the min. or max. return temp. T2 set in AV:39 & AV:40. In MSV:10 / 32811 Heating/cooling application must be selected. When this limitation is active, the warning BV:23 will be set to 'on'. State 7: A constant T2 value is set in AV:39 and/or AV:40. NovoCon will regulate to maintain these values constant. | Yes |
| MSV:14 | Temperature Sensor type | R/W | 1: NTC10k Type 2 2: NTC10k Type 3 3: PT1000 | 3: PT1000 | Select the type of Temperature sensor connected. | Yes |
| MSV:20 | Units used to set Design Flow Rate | R/W | 1: L/h 2: % 3: GPM | 1: L/h | Engineering Units used for the Design Flow AV:0, AV:30 and AV:31 | Yes |
| MSV:21 | Units used to set Flow Rate Setpoint | R/W | 1: L/h 2: % 3: GPM 4: kW 5: kBTU/h | 2:% | Engineering Units used for the desired Flow AV:1. NOTE: If kW or kBTU/h chosen then MSV:13 Power Controller (state:3) also becomes active | Yes |
| MSV:22 | Units used to set Actual Flow feedback | R/W | 1: L/h 2: % 3: GPM | 1: L/h | Engineering Units used for AV:2 | Yes |
| MSV:23 | Units used to set Temperature | R/W | 1: °C 2: °F | 1: ℃ | Engineering Units used for AV:8, AV:37-40 | Yes |
| MSV:24 | Units used to set T1 | R/W | 1: ℃ 2: °F 3: Ohm | 1: °C | Engineering Units used for Al:1 | Yes |
| MSV:25 | Units used to set T2 | R/W | 1: ℃ 2: °F 3: Ohm | 1: °C | Engineering Units used for Al:2 | Yes |
| MSV:26 | Units used to set Power | R/W | 1: kW 2: kBTU/h | 1: kW | Engineering Units used for AV:32 | Yes |
| | Units used to set | | 1: kWh 2: MJ | 1: kWh | Engineering Units used for AV:33 and AV:34 | Yes |

¹⁾ A zero Flow Rate Setpoint command (AV:1) closes the AB-QM, so that there is neither heating nor cooling. Do not use the CO6 maintenance shut-off function for this purpose.



The CO6 valve shut-off function should only be used for maintenance and only when the water temperature in terminal unit is equal to ambient temperature or the terminal unit is not mounted. A water temperature change inside of a closed coil could result in rising pressure and possible damage of to the terminal unit.

BACnet Objects - Binary Value

| Ident | Object / Parameter name | Read/ Write | Active Text (1) | Inactive Text (0) | Default | Description | Persistent Yes/No |
|-------|---|----------------|--------------------|----------------------|----------|---|----------------------|
| BV:2 | Direct or Inverse operation Mode | R/W | Inverse | Direct | Direct | Selection between Direct and Inverse operation mode. See Direct/Inverse diagram. For the states Analog CO6 mode and Inverted Analog CO6 mode this object is used to switch the control signal. | Yes |
| BV:3 | Analog feedback signal | R/W | Active | Inactive | Inactive | By activating this feature, the analog output signal (AO:0) and the position of the valve opening become linked. The voltage output type and range is linked to the MSV:1 present value. This feature may be used for FCU fan control for example and is only made available when MSV:9 Application Mode are in State 1: Analog control or State 2: Digital control. If BV:3 is active and the analog output signal (AO:0) is written to manually it must be relinquished i.e. write 'NULL' to return to the original setting of BV:3. | Yes |
| BV:10 | Warning: Temperature of the actuator is out of recommended range | R | ON | OFF | na | The Temperature inside the Actuator is out of the recommended range. | No |
| BV:11 | Alarm: No Control Signal | R | ON | OFF | na | The actuator has detected that it has no analog control signal. | No |
| BV:12 | Alarm: Error during Closing | R | ON | OFF | na | The actuator is unable to reach it's intended closing position. Check for valve blockages. | No |
| BV:13 | Warning: Pre-set Conflict | R | ON | OFF | na | Conflict between the Mechanical AB-QM valve setting and the NovoCon [®] S. The mechanical valve setting must be 100% or above. The warning will also be activated if the Selected Valve Type has different stroke than the actually valve used. Validated during calibration. | No |
| BV:14 | Warning: Voltage of power supply is too high | R | ON | OFF | na | Voltage of power supply is measured to be too high. When the measured voltage exceeds 43.4V the alarm will be turned ON for too high voltage. When the measured voltage is once more below 38.3V, the alarm will be turned OFF. | No |
| BV:15 | Warning: Voltage of power supply is too low | R | ON | OFF | na | Voltage of power supply is measured to be too low. When the measured voltage level drops below 16.5V the alarm will be activated for too low voltage. When the measured voltage level drops below 16.1V the motor will also be turned off. When the measured voltage is once more above 17.5V, the motor will be activated again. | No |
| BV:16 | Alarm: Error during Calibration | R | ON | OFF | na | There was an error during calibration of the actuator. E.g. the NovoCon® S actuator is not mounted on the valve or the valve is stuck. | No |
| BV:17 | Warning: BACnet MAC-address Conflict was Detected | R | ON | OFF | na | Two or more devices on the same BACnet sub-network have the same MAC-address. | No |
| BV:18 | Warning: Faults on the BACnet was detected | R | ON | OFF | na | Problems with communication on the network are detected. | No |
| BV:19 | Alarm: An internal Error has been detected | R | ON | OFF | na | Re-calibrate or power cycle actuator to reset - actuator replacement may be necessary | No |
| BV:20 | Alarm: CO6 in manual override or CO6 unable to move | R | ON | OFF | na | ChangeOver ⁶ actuator is in manual override or is unable to reach position. When the reason for the alarm is removed it may take up to 2 minutes before the alarm is cleared. | No |
| BV:21 | Alarm: CO6 actuator not connected or damaged | R | ON | OFF | na | The ChangeOver ⁶ actuator is not connected or is damaged. | No |
| BV:22 | Warning: Temp. sensors are missing or interchanged | R | ON | OFF | na | Temp. sensors are missing or interchanged | No |
| BV:23 | Warning: Energy limitation is active | R | ON | OFF | na | Limitation is active. E.g. Power limitation, min. delta T or min/max return T management limitation. | No |
| BV:24 | Warning: Energy management controller out of range | R | ON | OFF | na | Power, delta T or return T setpoint out of range or the setpoint can't be achieved. Action: Check that setpoint is achievable with the given flow rates and temperatures. | No |

BACnet Objects - Device Object

List with some selected important Device Object properties.

| Property | Value | Read / Write | Description | Persistent Yes/No |
|--|---|--------------|--|----------------------|
| Object ID | Instance Range: 0 to 4194302 | R/W | This property is normally called Device Instance number or Unique ID. | Yes |
| Object-Name Combination of "NovoCon S" + Type and Object ID | | R/W | Product name. Max. 25 characters. | Yes |
| Firmware revision | Current firmware version | R | BACnet software revision. | Yes |
| Application S/W version | Current Application SW version | R | Actuator Application Software version. | Yes |
| Location This string is empty when actuator is new. | | R/W | R/W Free text can be used to describe location etc. Max. 50 characters. | |
| Description | Danfoss NovoCon actuator with BACnet MS/TP | R/W | Product description. Max. 50 characters. | Yes |
| Segmentation-supported | SEGMENTATION | R | Able to transmit and receive segmented messages. | Yes |
| Max-master | Default: 127 Range: 0-127 | R/W | The MAX_master setting in NovoCon® S can be set above the highest used MAC address in the MS/TP sub network. | Yes |
| Max ADPU length | 480 | R | Maximum allowed ADPU length. | Yes |
| Max segments accepted | 5 | R | Max segments accepted | Yes |

| BACnet Objects - Analog Input | Ident | Object / Parameter name | Unit | Read / Write | Min | Max | Default units | Description | Persistent Yes/No |
|--|-------|--|------------------------------|-----------------|-----------------------|------------------------|------------------|---|----------------------|
| ······································ | AI:0 | Voltage or Current on analog input | 5: Volts 2: mA | R | 0 | 10V 20mA | Volts | Voltage(V) or Current(mA) level on the analog control input, measured by the actuator. Units comes from MSV:1 Analog Control signal type and range. This object is supported by COV. In CO6 and Inversed CO6 mode mA cannot be selected. | No |
| | AI:1 | T1 or resistance input | | | | | | Temperature/resistance measured from connected sensors. For Power emission AV:32, AI:1 is temperature on the flow pipe and AI:2 is temperature on the return pipe. When used as potential free contacts: Closed circuit <900Ω, | |
| | AI:2 | T2 or resistance input | 62: °C 64: °F, 4: Ohms | R | -10°C 10°F 900Ω | 120°C 250°F 10kΩ | °C | open circuit 100kΩ. Recommended max. cable length 2m. Units can be changed via the object's engineering units property or via objects MSV:24 and MSV:25. The upper temperature limit for NTC 10k Type 2 sensors is 90°C/194°F. The upper temperature limit for NTC sensor 10k Type 3 is 95°C/203°F. This object is supported by COV. | No |

| BACnet Objects - Analog Output | Ident | Object / Parameter name | Unit | Read / Write | Min | Max | Default units | Description | Persistent Yes/No |
|-----------------------------------|-------|-----------------------------|-------|-----------------|-----|-----|------------------|---|----------------------|
| 5. | AO:0 | Voltage on analog output | Volts | R/W | 0 | 10 | Volt | Output Voltage value. Note: In CO6 modes the present value is not writeable. | No |



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NovoCon® S - High Accuracy Actuator

BACnet Objects - Notification class

| Ident | Object / Parameter name | Description |
|-------|---|--|
| NC:0 | Alarm Notifier, Subscribe here for alarms | Subscribe devices for receiving alarms |

NC:0 is an object where other BACnet devices can subscribe to be informed directly from this device if an alarm or warning is activated or cleared. A maximum of 4 devices can subscribe to this service. Subscribers of this object will be informed if any of the Warning or Alarms BV:10 to BV:24 is activated or cleared.

When the notification class NC:0 is going to be used to notify about changes with status of Warnings and Alarms (BV:10 – BV24), is it necessary to subscribe for notifications for the entire day and week: From 00:00:000 to 23:59:59:99 and all 7 days of the week. This is because the actuator does not have a clock built in and will therefore not be able to handle notifications with respect to time.

BACnet Objects - Averaging

| Ident | Object / Parameter name | Min. Value | Average value | Max. Value | Window Interval | Window Sample | Description | Persistent Yes/No |
|-------|--|--------------------------|------------------|---------------|--------------------|------------------|--|----------------------|
| AVO:0 | Average rectified voltage measured by the actuator | Updated acc measureme | J | ual | 1 Day | 24 | Average of the rectified voltage that powers the actuator. | No |

Valve Type Selection



Values for flow are valid for water applications. For glycol mixtures, please use correction factor.

| Index | Name | Nominal Flow | Units | Valve position for nominal flow [mm] | Setting Range Maximum [%] |
|------------------|-----------------------|--------------|-------|--------------------------------------|---------------------------|
| 1 | AB-QM 4.0 ISO DN 15LF | 200 | L/h | 4 | 100 |
| 21) | AB-QM 4.0 ISO DN 15 | 600 | L/h | 4 | 100 |
| 3 | AB-QM 4.0 ISO DN 15HF | 1200 | L/h | 4 | 100 |
| 4 | AB-QM 4.0 ISO DN 20 | 1200 | L/h | 4 | 100 |
| 5 | AB-QM 4.0 ISO DN 20HF | 2200 | L/h | 4 | 100 |
| 6 | AB-QM 4.0 ISO DN 25 | 2200 | L/h | 4 | 100 |
| 7 | AB-QM 4.0 ISO DN 25HF | 4200 | L/h | 4 | 100 |
| 8 | AB-QM 4.0 ISO DN 32 | 4200 | L/h | 4 | 100 |
| 9 | AB-QM 4.0 ISO DN 32HF | 6000 | L/h | 4 | 100 |
| 10 | AB-QM ISO DN 10LF | 150 | L/h | 2.25 | 120 |
| 11 | AB-QM ISO DN 10 | 275 | L/h | 2.25 | 120 |
| 12 | AB-QM ISO DN 15LF | 275 | L/h | 2.25 | 120 |
| 13 | AB-QM ISO DN 15 | 450 | L/h | 2.25 | 120 |
| 14 | AB-QM ISO DN 15HF | 1135 | L/h | 4 | 110 |
| 15 | AB-QM ISO DN 20 | 900 | L/h | 2.25 | 120 |
| 16 | AB-QM ISO DN 20HF | 1700 | L/h | 4 | 110 |
| 17 | AB-QM ISO DN 25 | 1700 | L/h | 4.5 | 110 |
| 18 | AB-QM ISO DN 25HF | 2700 | L/h | 4.5 | 110 |
| 19 | AB-QM ISO DN 32 | 3200 | L/h | 4.5 | 110 |
| 20 | AB-QM ISO DN 32HF | 4000 | L/h | 4.5 | 110 |
| 21 | AB-QM ANSI 1/2" LF | 1.2 | GPM | 2.25 | 100 |
| 22 | AB-QM ANSI 1/2" | 2 | GPM | 2.25 | 100 |
| 23 | AB-QM ANSI 1/2" HF | 5 | GPM | 4 | 100 |
| 24 | AB-QM ANSI ¾" | 4 | GPM | 2.25 | 100 |
| 25 | AB-QM ANSI ¾" HF | 7.5 | GPM | 4 | 100 |
| 26 | AB-QM ANSI 1" | 7.5 | GPM | 4.5 | 100 |
| 27 | AB-QM ANSI 1" HF | 12 | GPM | 4.5 | 100 |
| 28 | AB-QM ANSI 11/4" | 14.1 | GPM | 4.5 | 100 |
| 29 | AB-QM ANSI 11/4" HF | 17.5 | GPM | 4.5 | 100 |
| 30 ²⁾ | User Defined Valve | NF | UF | VPNF | SRM |

¹⁾ Default ²¹ The "User Defined Valve" is used only if NovoCon[®] S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible. When an ANSI valve is selected the units for flow and temperature are default changed from I/h to GPM and Celsius to Fahrenheit, and vice versa

when an ISO valve is selected.

BACnet BIBBs services

| Service | BIBBs | Init/Exe |
|----------------------------------|-----------|----------|
| ReadProperty | DS-RP-B | exe |
| WriteProperty | DS-WP-B | exe |
| Who-Is | DM-DDB-A | init |
| Who-Is | DM-DDB-B | exe |
| I-Am | DM-DDB-B | init |
| I-Am | DM-DDB-A | exe |
| Who-Has | DM-DOB-B | exe |
| I-Have | DM-DOB-B | init |
| DeviceCommunicationControl | DM-DCC-B | exe |
| ReinitializeDevice ¹⁾ | DM-RD-B | exe |
| ConfirmedEventNotification | AE-N-I-B | init |
| UnconfirmedEventNotification | AE-N-I-B | init |
| AcknowledgeAlarm | AE-ACK-B | exe |
| GetEventInformation | AE-INFO-B | exe |

| Service | BIBBs | Init/Exe |
|-----------------------|-----------|----------|
| GetAlarmSummary | AE-ASUM-B | exe |
| GetEnrollmentSummary | AE-ESUM-B | exe |
| AddListElement | DM-LM-B | exe |
| RemoveListElement | DM-LM-B | exe |
| ReadPropertyMultiple | DS-RPM-B | exe |
| WritePropertyMultiple | DS-WPM-B | exe |
| SubscribeCOV 2) | DS-COV-B | exe |
| Restart | DM-R-B | exe |
| AtomicWriteFile | na | exe |

¹⁾ NovoCon[®] S supports BACnet warm reset (power cycle) and Cold reset (factory reset). Note that after Cold/factory reset a calibration will be automatically performed and all settings will

be reverted to factory settings. ²⁷ COV is implemented for the following: Analog Inputs Al:0, Al:1 and Al:2, and for the following Analog Values AV:2 and AV:27.

DIP Switch Settings

BACnet: Auto MAC addressing is default. For manual MAC addressing, use DIP Switches. Modbus: Manual MAC addressing is default. Automatic addressing is not available for Modbus. However, if an address has been assigned in BACnet before switching to Modbus, the address will also be used in Modbus if the DIP switches are left in the default positions.

| DIP Switch | Configuration name | OFF state (default) | ON state |
|---|--|----------------------------|--------------------------------------|
| 1 2 3 4 5 6 7 8 9 10 1 ON OFF | BACnet address / Modbus unit ID bit 0 | Logic '0' | Logic '1' |
| 1 2 3 4 5 6 7 8 9 10 2. | BACnet address / Modbus unit ID bit 1 | Logic '0' | Logic '1' |
| 1 2 3 4 5 6 7 8 9 10 3. | BACnet address / Modbus unit ID bit 2 | Logic '0' | Logic '1' |
| 4. 4 5 6 7 8 9 10 ON OFF | BACnet address / Modbus unit ID bit 3 | Logic '0' | Logic '1' |
| 5. 1 2 3 4 5 6 7 8 9 10 5. 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | BACnet address / Modbus unit ID bit 4 | Logic '0' | Logic '1' |
| 6. 1 2 3 4 5 6 7 8 9 10 ON OFF | BACnet address / Modbus unit ID bit 5 | Logic '0' | Logic '1' |
| 1 2 3 4 5 6 7 8 9 10 7. | BACnet address / Modbus unit ID bit 6 | Logic '0' | Logic '1' |
| 8. 1 2 3 4 5 6 7 8 9 10 ON OFF | Termination resistor (120Ω) | No termination | Termination resistor enabled $^{1)}$ |
| 9. 1 2 3 4 5 6 7 8 9 10 9. 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | | Not used | |
| 1 2 3 4 5 6 7 8 9 10 10. 10. 10 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 | - | BACnet MS/TP ²⁾ | Modbus RTU ²⁾ |

¹⁾ The actuator possesses a resistor, DIP switch no. 8, that can be activated in the last actuator on the bus for correct termination of the bus. ²⁾ When the protocol is changed on DIP switch no. 10, a power cycle is required to make the actuator adopt the newly selected protocol.

DIP Switch Settings - Manual Addressing

BACnet MAC address/Modbus Slave ID is set by DIP switch 1 to 7. $0=\mathsf{OFF},\,1=\mathsf{ON}$

| | | | | | | | DIP s 1, 2, | witch 3, 4 | | | | | | | | DIP switch 5,6,7 |
|------|------|------|------|------|------|------|----------------|---------------|------|------|------|------|------|------|------|---------------------|
| 0000 | 1000 | 0100 | 1100 | 0010 | 1010 | 0110 | 1110 | 0001 | 1001 | 0101 | 1101 | 0011 | 1011 | 0111 | 1111 | 5,0,7 |
| 0* | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | 000 |
| 16 | 17 | 18 | 19 | 20 | 21 | 22 | 23 | 24 | 25 | 26 | 27 | 28 | 29 | 30 | 31 | 100 |
| 32 | 33 | 34 | 35 | 36 | 37 | 38 | 39 | 40 | 41 | 42 | 43 | 44 | 45 | 46 | 47 | 010 |
| 48 | 49 | 50 | 51 | 52 | 53 | 54 | 55 | 56 | 57 | 58 | 59 | 60 | 61 | 62 | 63 | 110 |
| 64 | 65 | 66 | 67 | 68 | 69 | 70 | 71 | 72 | 73 | 74 | 75 | 76 | 77 | 78 | 79 | 001 |
| 80 | 81 | 82 | 83 | 84 | 85 | 86 | 87 | 88 | 89 | 90 | 91 | 92 | 93 | 94 | 95 | 101 |
| 96 | 97 | 98 | 99 | 100 | 101 | 102 | 103 | 104 | 105 | 106 | 107 | 108 | 109 | 110 | 111 | 011 |
| 112 | 113 | 114 | 115 | 116 | 117 | 118 | 119 | 120 | 121 | 122 | 123 | 124 | 125 | 126 | 127* | 111 |

* Addresses no. 0 and 127 must not be used.

Example

| Setting | MAC | addre | ss to 37: | |
|---------|-----|-------|-----------|--|
| | | | | |

| 7: | DIP 1 | DIP 2 | DIP 3 | DIP 4 | DIP 5 | DIP 6 | DIP 7 |
|----|-------|-------|-------|-------|-------|-------|-------|
| | ON | OFF | ON | OFF | OFF | ON | OFF |

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Modbus registers - Configuration

| Modbus register | Read/ Write | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Unit | Description of usage | Persistent Yes/No |
|--------------------|----------------|--------------------|---------------------|--|--|--|--|---|----------------------|
| 0x8000 32768 | R/W | 3,4 & 16 | FLOAT | Design Flow Rate | Recommended to use 32796 for Heating and/or 32798 for cooling. Pre-set value for the Design Flow Rate when control signal is at 100%. Unit follows 32787 | Nominal value from the Valve table in L/h | %, L/h, GPM | Design Flow Rate in Liters per hour i.e. 150450 correspond to 150450 L/h or in percent, i.e. 20 100 correspond to 20 100%. The maximum setting range is depending on the selected valve. See Valve Type Selection. | Yes |
| 0x8002 32770 | R/W | 3,4 & 6 | WORD | Control Fallback Time | Time before actuator reacts to a missing analog control signal | 10 | Minutes | Control Fallback Time in minutes, i.e 0 60 correspond to 0 60 minutes | Yes |
| 0x8004 32772 | R/W | 3,4 & 16 | FLOAT | Alpha Value | Value used for shaping the curve in Manual Defined Function (MDF) mode to fit the characteristics curve of a heat exchanger. If 33280 is in L/h in Digital mode, the alpha setting is ignored. | 1.0 | na | Alpha Value curve, i.e. 0.05 1.00 correspond to 0.05 1.00. Alpha = 1.00 is liniar. Alpha = 0.2 is equal to the LOG function. See Alpha value diagram. | Yes |
| 0x8006 32774 | R/W | 3,4 & 16 | WORD | Valve closing or opening time | The time the actuator needs to move from 0% to 100% of Design Flow Rate. Use with 32803. | na | Seconds | Valve closing or opening time in seconds i.e 18 700 correspond to 18 700 seconds | Yes |
| 0x8008 32776 | R | 3,4 & 6 | FLOAT | Nominal Flow of the user defined valve | The Nominal flow of the user defined valve is shown here. This Object is used only if NovoCon ^o S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible. | na | L/h or GPM, Unit type comes from Valve Table | Nominal flow e.g. in Liters per hour i.e. 0600 correspond to 0600 L/h | Yes |
| 0x800A 32778 | R | 3&4 | FLOAT | Valve position at nominal flow for User Defined Valve | Position in mm for nominal flow of the User Defined Valve. This Object is used only if NovoCon [®] S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible. | 4 | Millimetre | Valve position for nominal flow in millimetre, i.e. 0.5 5.8 correspond to 0.5 5.8 millimetre | Yes |
| 0x800C 32780 | R/W | 3,4 & 6 | FLOAT | Maximum value for the Design Flow in the User Defined Valve | Maximum level the Design Flow Rate can be increased to for the User Defined Valve. This Object is used only if NovoCon* S is not used with an AB-QM valve. Please contact your Danfoss representative to verify if the desired connection is possible. | 100 | Unit type follows 32787 selection: % or (L/h or GPM) | i.e. 100150 correspond to 100150 % | Yes |
| 0x8012 32786 | R/W | 3,4 & 6 | WORD | Direct or Inverse operation Mode | Selection between Direct and Inverse operation mode. See Direct/Inverse diagram. | 0: Direct | 0: Direct 1: Inverse | Selection between Direct and Inverse operation mode. See Direct/Inverse diagram. | Yes |
| 0x8013 32787 | R/W | 3,4 & 6 | WORD | Units used to set and display the Design Flow Rate | Units used to set and display the Design Flow Rate. Units for L/h & GPM comes from Selected Valve Type. | 0: L/h | 0: L/h 1: % 2: GPM | Engineering Units used for the Design Flow Rate. | Yes |
| 0x8014 32788 | R/W | 3,4 & 6 | WORD | Units used to set and display Flow Rate Setpoint | Units used to set and display Flow Rate Setpoint | 1: % | 0: L/h 1: % 2: GPM 3: kW 4: kBTU/h | Engineering Units used for the desired Flow 33280. Note: If kW or kBTU/h chosen then 32815 Power Controller (state 3) also becomes active. | Yes |
| 0x8015 32789 | R/W | 3,4 & 6 | WORD | Units used to set and display the Actual Flow Rate feedback | Units used to set and display the Actual Flow Rate feedback | 0: L/h | 0: L/h 1: % 2: GPM | Engineering Units used for 33282. | Yes |
| 0x8016 32790 | R/W | 3,4 & 6 | WORD | Units used to set temperature | Select between °C or °F to set and display temperature | 0: °C | 0: °C 1: °F | Engineering Units for 33796, 32836. 32838, 32840 & 32842. | Yes |
| 0x8017 32791 | R/W | 3,4 & 6 | WORD | Units used to set and display T1 | Units used to read the temperature or | | 0: °C | Engineering Units used for 33218. | |
| 0x8018 32792 | R/W | 3,4 & 6 | WORD | Units used to set and display T2 | resistance value. | 0: °C | 1: °F 2: Ohms | Engineering Units used for 33220. | Yes |
| 0x8019 32793 | R/W | 3,4 & 6 | WORD | Units used to set Power | Units used to read the power usage. | 0: kW | 0: kW, 1: kBTU/h | Engineering Units for 33288. | Yes |
| 0x801A 32794 | R/W | 3,4 & 6 | WORD | Endian type | Byte ordering for LONG and FLOAT types | 0: Big | 0: Big 1: Little | Used endian type for float and long registers | Yes |
| 0x801C 32796 | R/W | 3,4 & 16 | FLOAT | Heating Design Flow Rate | Pre-set value for the Design Flow Rate when the control signal is at 100%. 32810 must be set to Heating or Cooling. | Nominal value from the Valve | %, L/h, GPM | Design Flow Rate in Liters per hour i.e. 150450 correspond to 150450 L/h or in percent, i.e. 20 100 correspond to 20 100%. | Yes |
| 0x801E 32798 | R/W | 3,4 & 16 | FLOAT | Cooling Design Flow Rate | Unit follows 32787 | table in L/h | | The maximum setting range is depending on the selected valve. See Valve Type Selection. | |

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Modbus registers - Configuration (continued)

| Modbus register | | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Description of usage | Persistent Yes/No |
|--------------------|-----|--------------------|---------------------|---|---|--------------|--|----------------------|
| 0x802A 32810 | R/W | 3,4 & 6 | WORD | Application mode | 1: Analog control 2: Digital control 3: CO6 mode 4: Inverted CO6 mode 5: CO6 without alarms 6: Inverted CO6 without alarms: 7: Analog CO6 mode 8: Analog inverted CO6 mode | 2: Digital | Select the actuator application mode. State 1: Analog Control. Flow is controlled with an analog signal e.g. 0-10V. Design Flow Rate set via register 32796 Heating and/or 32798 Cooling. Alternative 32738 can be used. State 2: Digital Control. Register 33280 is used to control the flow. Design Flow Rate set via register 32796 Heating and/or 32798 Cooling. Alternative 32738 can be used. State 3: CO6 mode. Register 33280 is used to control the flow. Heating Design Flow Rate set via register 32796 and register 32798 for Cooling Design Flow Rate set via register 32796 and register 32798 for Cooling Design Flow Rate. Heating is connected to the CO6 valve to ports 5 & 6 and cooling to ports 1 & 4. State 4: Inverted CO6 mode. Register 33280 is used to control the flow. Heating Design Flow Rate set via register 32796 and 32798 for Cooling Design Flow Rate. Ports are inverted in relation to State 3. State 5: CO6 without alarms. Register 33280 is used to control the flow. Heating Design Flow Rate set via register 32796 and 32798 for Cooling Design Flow Rate. This state may be used if the Analog Input is required to be used other than CO6 feedback. Be aware that in this state the status for the CO6 valve is not shown. State 6: Inverted CO6 without alarms. register 33280 is used to control the flow. Heating Design Flow Rate. Ports are inverted in relation to State 3. This state may be used if the Analog Input is required to be used other than CO6 feedback. Be aware that in this state the status for the CO6 valve is not shown. State 7: Analog CO6 mode. The flow is controlled from the Room controller via the analog input signal. Heating Design Flow Rate set via register 32796 and 32798 for Cooling Design Flow Rate set via register 32796 and 32798 for Cooling Design Flow Rate. Register 32786 is in this case used to switch the control signal. Be aware that in this state the status for the CO6 valve is not shown. State 8: Analog input signal. Heating Design Flow Rate set via regist | Yes |
| 0x802B 32811 | R/W | 3,4 & 6 | WORD | Application command & status | 1: Heating 2: Cooling 3: CO6 Shut Off ¹⁾ 4: CO6 Start exercise 5: CO6 Moving towards Cooling 6: CO6 Moving towards Heating 7: CO6 Alarm 8: CO6 Exercising | 1: Heating | States 1 to 4 are commands for the Actuator NovoCon® ChangeOver6 and impact Energy Management Application register 32815. States 5 to 8 are feedback from the Actuator NovoCon® ChangeOver6. State 3 , shut-off mode may only be used for maintenance and is only possible when the Flow Rate Setpoint is 0% . In Central ChangeOver applications, state 1 and 2 are used to command heating or cooling. | Yes |
| 0x802C 32812 | R/W | 3,4 & 6 | WORD | CO6 auto exercise | 1: ON 2: OFF | 1: ON | 1: ON: The ChangeOver6 valve will be moved from current position to shut off and back again once per week to maintain free movement, if CO6 mode is selected. 2: OFF: Exercising the valve should be handled by BMS. | Yes |
| 0x802E 32814 | R/W | 3,4 & 6 | WORD | Energy counter activation | 1: Off 2: On | 1: Off | Enable or disable energy counter | Yes |
| 0x802F 32815 | R/W | 3,4 & 6 | WORD | Energy management | 1: Not active Power Manager: 2: Power Innitation 3: Power control Delta T Manager: 4: Min. Delta T limitation 5: Set Delta T control 6: Return T limitation 7: Set Return T control | 1: Not used | Activate functions to optimize system performance. State 1: Not active. State 2: If power is above the set value in register 32832 or register 32834, NovoCon will regulate to the specified limit register 32832 and/or 32834. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'. State 3: The flowrate through the valve is controlled by register 33280 in %, kW or kBTU/h (selected in 32793) and is based on the flowrate and temperature inputs. State 4: If delta T value in register 32836 and/or 32838 is exceeded, NovoCon will begin to close the valve until the register 32836 and/or 32838 values are reached. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'. State 5: The constant delta T is set in register 32836 and/or 32838 and NovoCon will regulate within these limits. When this limitation is active, the warning bit 23 in register 32536 will be set to 'on'. State 6: NovoCon ensures the min. or max. return temp. T2 set in 32840 & 32842. In register 32811 Heating/cooling application must be selected. When this limitation is active, the warning bit 23 in register 33536 will be set to 'on'. State 7: A constant T2 value is set in 32840 and/or 32842. NovoCon will regulate to maintain these values constant. | Yes |
| 0x8020 32800 | R/W | 3,4 & 6 | WORD | Analog Control signal type and range | Used to select the analog control signal input type and range | 2: 0-10 VDC | Select 1, 2 or based on the table below: 1: 0-5 VDC 2: 0-10 VDC 3: 2-10 VDC 4: 5-10 VDC 5: 2-6 VDC 5: 2-6 VDC 6: 6-10 VDC 7: 0-20 mA 8: 4-20 mA | Yes |
| 0x8021 32801 | R/W | 3,4 & 6 | WORD | Missing Control Signal Fallback Action | The action that the actuator will commence upon a missing analog control signal. | 1: No action | Select 1, 2 or based on the table below: 1: No action 2: CLOSE 3: OPEN 4: Go to 50% of Design Flow Rate | Yes |

¹⁾ A zero Flow Rate Setpoint command (33280) closes the AB-QM, so that there is neither heating nor cooling, do not use the CO6 maintenance shut-off function for this purpose.

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The CO6 valve shut-off function should only be used for maintenance and only when the water temperature in terminal unit is equal to ambient temperature or the terminal unit is not mounted. A water temperature change inside of a closed coil could result in rising pressure and possible damage of to the terminal unit.

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Modbus registers - Configuration (continued)

| Modbus register | Read/ Write | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Unit | Description of usage | Persistent Yes/No |
|--------------------|----------------|--------------------|---------------------|--|--|-----------------------------------|----------------------------|--|----------------------|
| 0x8022 32802 | R/W | 3,4 & 6 | WORD | Selected Valve Type | This is the AB-QM valve type that the actuator is set-up to control | 2: AB-QM 4.0 ISO DN 15 | na | See table "Valve Type Selection" | Yes |
| 0x8023 32803 | R/W | 3,4 & 6 | WORD | Actuator Speed | The amount of time the actuator takes to move 1mm or alternatively, a specified constant time function (see 32774). The Constant Time value range is 18-700 seconds. | 4: 24 sec/mm | na | Select 1, 2 or based on the table below: 1: 3 sec/mm 2: 6 sec/mm 3: 12 sec/mm 4: 24 sec/mm 5: Constant Time (set by register 0x8006) | Yes |
| 0x8024 32804 | R/W | 3,4 & 6 | WORD | Baud Rate | Baud Rate used for bus communication | 1: Auto Baud Rate Detection | na | Select 1, 2 or based on the table below: 1: Auto Baud Rate Detection 2: 9600 bps 3: 19200 bps 4: 38400 bps 5: 57600 bps 6: 76800 bps 7: 115200 bps | Yes |
| 0x8025 32805 | R/W | 3,4 & 6 | WORD | Select UART mode | Supported transmission modes | 5: Auto parity | na | Select 1, 2, 3 or 4 based on the table below: 1: 1-8-N-2 2: 1-8-O-1 3: 1-8-E-1 4: 1-8-N-1 5: Auto parity Data format: (Start bit-Data bits-Parity-Stop bits) | Yes |
| 0x8026 32806 | R/W | 3,4 & 6 | WORD | Slave ID | Slave ID used for communication. | na | na | Slave ID used for communication | Yes |
| 0x8027 32807 | R/W | 3,4 & 6 | WORD | Slave ID asignment method | The Slave ID address selection method. | 1: DIP Switch Settings | na | 1: DIP Switch Settings 2: User configuration over Modbus If DIP Switches are in an invalid position the actuator will automatically check if a Slave ID is present in the User Configuration. | Yes |
| 0x8028 32808 | R/W | 3,4 & 6 | WORD | BUS protocol | Select field bus protocol to be used. See also the DIP Switch Settings section of the data sheet. When the protocol is changed, a power cycle is required to make the actuator adopt the newly selected protocol. | 1: DIP switch | na | Select 1, 2 or 3 based on the table below: 1: DIP switch 2: BACnet 3: Modbus | Yes |
| 0x8029 32809 | R/W | 3,4 & 6 | WORD | LED Control | Used to select the LED display required. | 1: Normal LED mode | na | Select 1, 2 or based on the table below: 1: Normal LED mode 2: Show alarms only 3: All LED's OFF 4: Blink (can be used to locate the actuator) | Yes |
| 0x8030 32816 | R/W | 3,4 & 6 | WORD | Units used to set Energy counter | Units used to set energy counter | 0: kWh | 0: kWh 1: MJ 2: kBTU | Engineering Units used for 33290 & 33292. | Yes |
| 0x8031 32817 | R/W | 3,4 & 6 | WORD | Analog feedback signal | Set analog output according to valve position | 0: Inactive | na | 0: Inactive 1: Active By activating this feature, the analog output signal (33286) and the position of the valve opening become linked. The voltage output type and range is linked to the 32800 present value. This feature may be used for FCU fan control for example and is only made available when 32810 Application Mode are in State 1: Analog control or State 2: Digital control. If 32817 is active and the analog output signal (33286) must be written to manually, it is necessary to change the setting of 32817 to inactive. | Yes |
| 0x8033 32819 | R/W | 3,4 & 6 | WORD | Temperature sensor type | Select the type of Temperature sensor connected. | 3: PT1000 | na | Select temperature sensor type: 1: NTC10k Type 2 2: NTC10k Type 3 3: PT1000 | Yes |
| 0x804C 32844 | R/W | 3, 4 & 16 | FLOAT | Glycol Factor | Glycol correction factor | 1 | na | Select appropriate factor from 0.5-2 if a glycol mixture is used. | Yes |
| 0x8050 32848 | R/W | 3,4 & 16 | FLOAT | Analog CO6 Heating point 100% | Signal point for Analog CO6 mode | 0 | na | The control signal for heating 100% open when register 32810 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |
| 0x8052 32850 | R/W | 3,4 & 16 | FLOAT | Analog CO6 Heating point 0% | Signal point for Analog CO6 mode | 3.3 | na | The control signal for heating 0% open when register 32810 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |
| 0x8054 32852 | R/W | 3,4 & 16 | FLOAT | Analog CO6 Cooling point 0% | Signal point for Analog CO6 mode | 6.7 | na | The control signal for cooling 0% open when register 32810 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |
| 0x8056 32854 | R/W | 3,4 & 16 | FLOAT | Analog CO6 Cooling point 100% | Signal point for Analog CO6 mode | 10 | na | The control signal for cooling 100% open when register 32810 = State 7 or 8. Overlaping heating and cooling control curves are not accepted. | Yes |
| 0x8500 34048 | w | 6 | WORD | Reset | Warm reset = Power cycle. Cold reset = Factory reset. Note that after factory reset a calibration will be automatically be performed and all settings will be reverted to factory settings. | na | na | 0x5741 / 22337: Warm reset 0x434F / 17231: Cold reset. | na |

Modbus registers - Operating

| Modbus register | Read/ Write | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Unit | Description of usage | Persistent Yes/No |
|--------------------|----------------|--------------------|---------------------|--|--|--------------|---|--|---------------------------------|
| 0x8200 33280 | R/W | 3,4 & 16 | FLOAT | Flow Rate Setpoint | The Flow Rate Setpoint through the AB-QM valve. Unit follows 32788 | 100% | %, L/h, GPM, kW, kBTU/h | Flow Rate Setpoint in percent, i.e.0 100 correspond to 0 100% | No |
| 0x8202 33282 | R | 3 & 4 | FLOAT | Actual Flow Rate feedback | Flow Rate Indication based on the position of the Actuator stem. Unit follows 32788 | na | %, L/h, GPM | Design Flow Rate feedback in percent, i.e. 0 100 correspond to 0 100%. If L/h (GPM) is selected in 32787 then the valve flow rate is set to the selected valve's 32776 maximum value. Otherwise 100% | No |
| 0x8204 33284 | R/W | 3,4 & 6 | WORD | Actuator Mode and special features | Shows present mode of actuator. Calibration, Flush and de-air may be started from here | 1: Normal | na | Select 1, 2 or based on the table below: 1: Normal 2: Calibration 3: Flush 4: De-Air 5: Alarm | Yes, except state 3,4 & 5 |
| 0x8206 33286 | R/W | 3,4 & 16 | FLOAT | Voltage on analog output | Output Voltage value in Digital and Analog mode 32810. Note: In CO6 and Inversed CO6 mode the present value is not writeable | na | Volts | Voltage level i.e. 0.00 10.00 correspond to 0.00 10.00 V | No |
| 0x8208 33288 | R/W | 3,4 & 16 | FLOAT | | The hydronic power emission of the terminal unit, based on calculations from water flow rate and the temperature difference between supply (33218) and return (33220) pipes. Positive values reflect heating power emission. Units can be changed via the object's engineering units property. | | Power in kW or kBTU/h. If register 32844 Glycol correction is used, Power emission will be adjusted accordingly. i.e1000.00 1000.00 correspond to -1000.00 1000.00 kW or in kBTU/h, i.e1000.00 1000.00 kBTU/h 1000.00 1000.00 kBTU/h | No | |

| Modbus register | Read/ Write | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Unit | Description of usage | Persistent Yes/No |
|--------------------|----------------|--------------------|---------------------|----------------------------|---|---------|------------------|---|----------------------|
| 0x820A 33290 | R/W | 3,4 & 16 | FLOAT | Heating Energy counter | Energy counter for heating | na | kWh, MJ, kBTU | Accumulative Energy counter for heating. i.e. 0.00 1000.00 correspond to 0.00 1000.00 kWh. If register 32844 Glycol correction is used, Heating Energy Counter emission will be adjusted accordingly. Activated/Deactivated via register 32814. | Yes |
| 0x820C 33292 | R/W | 3,4 & 16 | FLOAT | Cooling Energy counter | Energy counter for cooling | na | kWh, MJ, kBTU | Accumulative Energy counter for cooling. i.e. 0.00 1000.00 correspond to 0.00 1000.00 kWh. If register 32844 Glycol correction is used, Cooling Energy Counter emission will be adjusted accordingly. Activated/Deactivated via register 32814. | Yes |
| 0x8040 32832 | R/W | 3,4 & 16 | FLOAT | Heating max. Power | Pre-set value for the design power, in heating mode, when control signal is at 100% | 0 | kW, kBTU/h | When using register 32815 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the heating power through the terminal unit. i.e. 0.00 10.00 correspond to 0.00 10.00 kW | Yes |
| 0x8042 32834 | R/W | 3,4 & 16 | FLOAT | Cooling max. power | Pre-set value for the design power, in cooling mode, when control signal is at 100% | 0 | kW, kBTU/h | When using register 32815 state Power limiter this is the maximum allowed hydronic energy output. This value is intended to limit the cooling power through the terminal unit. i.e. 0.00 10.00 correspond to 0.00 10.00 kW | Yes |
| 0x8044 32836 | R/W | 3,4 & 16 | FLOAT | Heating Delta T | Set-point value for the temperature difference between the flow and return pipes | 15 | °C or °F | For register 32815 state Minimum Delta T management and Set Delta T control, this is the value the control is based on for heating. i.e. 5 50 correspont to 5°C 50°C | Yes |
| 0x8046 32838 | R/W | 3,4 & 16 | FLOAT | Cooling Delta T | Set-point value for the temperature difference between the flow and return pipes | 5 | °C or °F | For register 32815 state Minimum Delta T management and Set Delta T control, this is the value the control is based on for cooling. i.e. $5 \dots 50$ correspont to $5^{\circ}C \dots 50^{\circ}$ | Yes |
| 0x8048 32840 | R/W | 3,4 & 16 | FLOAT | Heating T2 | Set-point value for Heating T2 (Heating return pipe temperature) | 35 | °C or °F | For register 32815 state Max. Return T management and Set return T control, this is the value the control is based on for heating. i.e. 5 50 correspont to 5°C 50° | Yes |
| 0x804A 32842 | R/W | 3,4 & 16 | FLOAT | Cooling T2 | Set-point value for Cooling T2 (Cooling return pipe temperature) | 13 | °C or °F | For register 32815 state Min. Return T management and Set return T control, this is the value the control is based on for cooling. i.e. 5 50 correspont to 5°C 50° | Yes |

Modbus registers - Operating (continued)

Modbus registers - Information

| Modbus register | | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Unit | Description of usage | Persistent Yes/No |
|--------------------|-----|--------------------|---------------------|--|--|--|--|---|----------------------|
| 0x8100 33024 | R | 3 & 4 | FLOAT | Nominal flow of | Nominal flow of the selected valve type | 450 | L/h or GPM, Unit type comes from Valve Table | Nominal flow e.g. in Litres per hour i.e. 0450 correspond to 0450 L/h. | na |
| 0x8102 33026 | R | 3 & 4 | FLOAT | Valve position at nominal flow | Position in mm for nominal flow of the selected valve | na | Millimetre | Valve position for nominal flow in millimetre, i.e., 0.5 5.8 correspond to 0.5 5.8 millimetre. | na |
| 0x8104 33028 | R | 3 & 4 | FLOAT | Maximum value of the Design Flow Rate | Maximum level the Design Flow Rate can be increased to for the selected valve | Setting Range Maximum from Valve table | % | Maximum level of the Design Flow Rate in percent, i.e. 20 100 correspond to 20 100%. | na |
| 0x8120 33056 | R/W | 3 & 4 | STRING | Device name | Product name | NovoCon S | na | ASCII coded STRING | Yes |
| 0x8140 33088 | R | 3 & 4 | STRING | Model name | Type of the actuator | CO6 | na | ASCII coded STRING | Yes |
| 0x8160 33120 | R | 3 & 4 | STRING | Vendor name | Name of the Manufacture | Danfoss A/S | na | ASCII coded STRING | Yes |
| 0x8180 33152 | R/W | 3, 4 & 16 | STRING | Location description | Free text can be used to describe location etc. E.g. Room 1 | na | na | ASCII coded STRING. Max. 50 characters. | Yes |
| 0x81A0 33184 | R | 3, 4 | STRING | Serial number | Serial number of the actuator | na | 1 | Description of this object holds the serial number of the actuator, programmed at the production time. | Yes |
| 0x8108 33032 | R | 3, 4 | LONG | Product ID | Serial number of the actuator | na | 1 | Unique Product id. The last part of the serial number. | Yes |
| 0x810A 33034 | R | 3 & 4 | WORD | SW version | Software version of the actuator | na | na | ASCII coded WORD | Yes |
| 0x810B 33035 | R | 3 & 4 | WORD | HW version | Hardware version of the actuator | na | na | ASCII coded WORD | Yes |
| 0x81C0 33216 | R | 3 & 4 | FLOAT | Voltage or Current on analog input | Voltage(V) or Current(mA) level on the analog control input, measured by the actuator. In CO6 modes mA cannot be selected. | na | Volts / mA | Voltage level measured i.e. 0.00 10.00 correspond to 1.00 10.00 V or in mA, i.e. 0.00 20.00 correspond to 0.00 20.00 mA | No |
| 0x81C2 33218 | R | 3 & 4 | FLOAT | T1 or resistance input | Temperature/resistance measured from connected PT1000 sensors. For Power emission 33288, register 33218 is temperature on the flow pipe and 33220 is temperature on the return pipe. | °C | °C, °F, Ohms | Temperature measured in °C i.e10°C 120°C or resistance measured i.e. 900Ω 10kΩ. The upper temperature limit for NTC 10k Type 2 sensors is 90°C/194°F. The upper temperature limit for NTC sensor 10k Type 3 is 95°C/203°F. When used as potential free contacts: Closed circuit + 900Ω, open circuit 100kΩ. The upper temperature limit for NTC 10k Type 2 sensors is 90°C/194°F. The upper temperature limit for NTC sensor 10k Type 3 is 95°C/203°F. Recommended max. cable length 2m. | No |
| 0x81C4 33220 | R | 3&4 | FLOAT | T2 or resistance input | Temperature/resistance measured from connected PT1000 sensors. For Power emission 33288, register 33218 is temperature on the flow pipe and 33220 is temperature on the return pipe. | °C | °C, °F, Ohms | Temperature measured in °C i.e10°C 120°C or resistance measured i.e. 9000 10kΩ. The upper temperature limit for NTC 10k Type 2 sensors is 90°C/194°F. The upper temperature limit for NTC sensor 10k Type 3 is 95°C/203°F. When used as potential free contacts: Closed circuit (200Ω, open circuit 100kΩ. The upper temperature limit for NTC 10k Type 2 sensors is 90°C/194°F. The upper temperature limit for NTC sensor 10k Type 3 is 95°C/203°F. Recommended max. cable length 2m. | No |
| 0x8402 33794 | R | 3 & 4 | FLOAT | Rectified voltage measured by the actuator | Measured rectified voltage which powers the actuator | na | Volts | Rectified voltage which powers the actuator. Too low voltage: 16.1-17.5V Too high voltage: 38.3-43.4V | No |
| 0x8404 33796 | R | 3 & 4 | FLOAT | Temperature in the actuator | Temperature measured inside the Actuator | na | na | Temperature measured inside the actuator. Unit is decided by 32790. | No |
| 0x8406 33798 | R | 3 & 4 | LONG | Total Operating Hours | Total Operating Hours of the actuator | Hours | Hours | Total Operating Hours of the actuator | Yes |
| 0x8408 33800 | R | 3 & 4 | LONG | Lifetime estimate | Calculated percentage of expended lifetime | % | na | At 100% the valve and actuator have reached the estimated minimum lifetime. Replacement of valve and actuator is recommended. | Yes |
| 0x8410 33808 | R | 3 & 4 | LONG | Minutes since last power-up | Minutes since the last power-up of the actuator | Minutes | Minutes | Minutes since the last power-up of the actuator | No |
| 0x8412 33810 | R | 3 & 4 | LONG | Minutes since last calibration | Minutes since the last time the actuator was calibrated to an AB-QM valve | Minutes | Minutes | Minutes since the last time the actuator was calibrated to a valve | Yes |
| 0x8414 33812 | R | 3 & 4 | LONG | Minutes since fully closed | Minutes since the last time the AB-QM valve was fully closed | Minutes | Minutes | Minutes since the last time the valve was fully closed | Yes |
| 0x8416 33814 | R | 3 & 4 | LONG | Minutes Since Fully Opened | Minutes since the last time the AB-QM valve was fully opened | Minutes | Minutes | Minutes since the last time the valve was fully opened | Yes |



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Alarms & warning

| Modbus register | Read/ Write | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Description of usage | Persistent Yes/No | | | | | | | | | | | | | | | | | | | | |
|--------------------|----------------|---|---------------------|--|---|---------|-------------------------|----------------------|--|--|--|--|--|--|---|--------|--------------------|----|--|--|--|--|--|--|---|--------|---------------------|----|
| | | | | Alarm: No Control Signal | The actuator has detected that is has no analog control signal | 0: OFF | Bit 0: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Alarm: Error during Closing | The actuator is unable to reach it's intended closing position. Check for valve blockages. | 0: OFF | Bit 1: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Alarm: Error during Calibration | There was an error during calibration of the actuator. E.g. the NovoCon® S actuator is not mounted on the valve or the valve is stuck | 0: OFF | Bit 2: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Alarm: An internal Error has been detected | Re-calibrate or power cycle actuator to reset - actuator replacement may be necessary | 0: OFF | Bit 3: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | Alarm: CO6 in manual override or CO6 unable to move | ChangeOver ^e actuator is in manual override or is unable to reach position. When the reason for the alarm is removed it may take up to 2 minutes before the alarm is cleared. | 0: OFF | Bit 4: 0:OFF; 1:ON | No | | | | | | | | | | |
| | | | | Alarm: CO6 actuator not connected or damaged | The ChangeOver⁵ actuator is not connected or is damaged. | 0: OFF | Bit 5: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Alarm: Temp. sensors are missing or interchanged | Temp. sensors are missing or interchanged | 0: OFF | Bit 6: 0: OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | | | | | | | | | | | Warning: Temperature of the actuator is out of recommended range | The Temperature inside the Actuator is out of the recommended range | 0: OFF | Bit 16: 0:OFF; 1:ON | No |
| 0x8300 33536 | R | 3&4 | LONG | Warning: Pre-set Conflict | Warning: Conflict between the Mechanical AB-QM valve setting and the NovoCon [®] S. The mechanical valve setting must be 100% or above. The warning will also be activated if the Selected Valve Type has different stroke than the actually valve used. Validated during calibration. | 0: OFF | Bit 17: 0: OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Warning: Voltage of power supply is too high | Voltage of power supply is measured to be too high. When the measured voltage exceeds 43.4V the alarm will be turned ON for too high voltage. When the measured voltage is below 38.3V the alarm will be turned OFF | 0: OFF | Bit 18: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Warning: Voltage of power supply is too low | Voltage of power supply is measured to be too low. When the measured voltage level drops below 16.5V the alarm will be activated for too low voltage. When the measured voltage level drops below 16.1V the motor will also be turned off. When the measured voltage is once more above 17.5V the motor will be activated | 0: OFF | Bit 19: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Warning: Faults on communication was detected | Problems with Communication on the network are detected | 0: OFF | Bit 21: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Warning: Invalid Slave ID setting | Slave ID assignment was done incorrectly to either 0 or 127 | 0: OFF | Bit 22: 0:OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | | | Warning: Energy limitation is active | Limitation is active. E.g. Power limitation, min. delta T or min/max return T management limitation. | 0: OFF | Bit 23: 0: OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |
| | | Warning: Energy management controller out of range | | | Power, delta T or return T setpoint is out of range or the setpoint cannot be achieved. Action: Check that setpoint is achievable with the given flow rates and temperatures. | 0: OFF | Bit 24: 0: OFF; 1:ON | No | | | | | | | | | | | | | | | | | | | | |

Firmware update

Manual update

Using BACnet MS/TP

| Ident | Object / Parameter name | Read/Write | State Text | Default State | Description |
|--------|----------------------------|------------|---|---------------|--|
| MSV:19 | Firmware update | R/W | 1: Normal 2: Prepare 3: Ready 4: Error 5: Received 6: Update | 1: Normal | Commands & status for firmware update. Method used to update the firmware: • Send 'Prepare' command to MSV:19. NovoCon * S will prepare for the firmware update and change status to 'Ready'. • Send file to FIL:0. If successful, status should be 'Received'. • Send 'Update' command. NovoCon * S will reboot and update the firmware. The status should be 'Normal' after a successful firmware update. |

| Ide | nt | Object / Parameter name | Read/Write | State Text | Default State | Description |
|-----|----|----------------------------|------------|--|---------------|--|
| FIL | :0 | File | W | File used to update the firmware | na | Used to transfer the new firmware to NovoCon [®] S. |

Using Modbus RTU

| Modbus register | Read/ Write | Modbus function | Modbus Data Type | Object / Parameter name | Description | Default | Description of usage |
|--------------------|----------------|--------------------|---------------------|-------------------------------|---|-----------|--|
| 0x8501 34049 | R/W | 3, 4 & 6 | WORD | Firmware update | 1: Normal 2: Prepare 3: Ready 4: Error 5: Received 6: Update | 1: Normal | Commands & status for Firmware update. Method used to update the Firmware: Send 'Prepare' command to 34049. NovoCon * S will prepare for the firmware update and change status to 'Ready'. Send file using Modbus function 21. If successful, status should be 'Received'. Send 'Update' command. NovoCon * S will reboot and update the software. The status should be 'Normal' after a successful software update |



When using modbus function 21 (0x15) to update the firmvare in NovoCon[®] S it is nessecasy to perform the upload in smaller sections due to modbus limitations in file size, please see the modbus standard for more details.

Broadcast, update multiple NovoCon[®] S by sending the firmware to Slave Id 0, is supported in modbus. However each NovoCon[®] S must be Prepared before the firmware upload is performed.

Danfoss NovoCon[®] Configuration tool

Easy configuration, commissioning and firmware updates can be performed with the Danfoss configuration tool. Please see separate operating manual.



NovoCon[®] S - High Accuracy Actuator

Temperature sensors

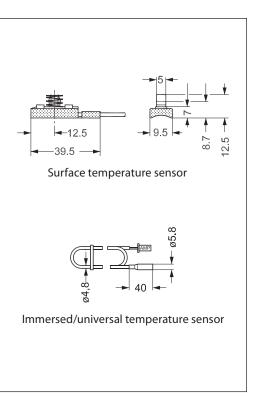
Functional description

The sensor unit consists of a platinum element, the resistance value of wich, changes proportionally with the temperature.

Pt 1000 ohm sensor (1000 ohm at 0°C). The sensor is adjusted and meets the tolerance requirements of EN 60751 Class B. The accuracy of temperature measurement is approximately 0.5° in typical operating range. It is unlikely, that during calculation of ΔT , deviation of both sensors would be summed up. Therefore, it is estimated that ΔT measurement accuracy is 0.5° when the sensors are mounted correctly.

It is not recommended to use longer wires on temperature sensors than 2m due to risk of electromagnetic interference. If long or thin wires are used it may be necessary to make an offset of the temperature reading in the BMS system.

| R (Typ.) Ohm | Temp. °C | Temp. °F | Tolerance. °C |
|-----------------|-------------|-------------|------------------|
| 1117 | 30 | 86 | 0.45 |
| 1078 | 20 | 68 | 0.40 |
| 1039 | 10 | 50 | 0.35 |
| 1000 | 0 | 32 | 0.30 |
| 961 | -10 | 14 | 0.35 |
| 922 | -20 | -4 | 0.40 |
| 882 | -30 | -22 | 0.45 |



Tender text NovoCon[®] S

Modulating, high accuracy, geared actuator with field bus (BACnet MS/TP and Modbus RTU) connectivity used to control pressure independent balancing and control valves type AB-QM DN10-32.

Control signal digital: BACnet MS/TP, Modbus RTUControl signal analog: 0-10V/2-10V, 0-20mA/4-20mA Direct connection to 6-port ball valve actuator with position feedback signal "

Direct connection to 6-port ball valve actuator with position readback signal * Direct connection to 2x PT1000 surface/immersed sensors and emission power indication ²⁾

Direct connection I/O: 2x resistance, AO and AI ³⁾

Actuator functionality is remotely accessible via the field bus:

- Design flow pre-setting

- Flushing the valve and terminal unit

- Error during closing intrinsic alarm reporting

- Alarm if CO6 6-port ball valve actuator is blocked, in manual override or disconnected ¹⁾
- Supply and return temperature readings, emission power indication²
- Energy counter (kWh, MJ, kBTU)²⁾
- Alarm high/low deltaT and temperature sensors disconnected²⁾
- Alpha characteristics setting
- Speed selection 3/6/12/24 s/mm
- Opening/closing time selection from 18s to 700s
- Auto MAC addressing (BACnet only)
- Auto Baud rate detection

- Flow indication based on measured stroke in l/h

Eu.bac interchangeability approved in combination with PIBCV valve

- Supply Voltage: 24V DC/AC 50/60Hz
- Spindle position accuracy: ±0.05mm

Cables: Halogen free plug-in available in 1.5m, 5m and 10m length

Temperature sensors: plug-in 2x PT1000 surface or immersed 1.5m length

64 actuators can be connected to the same network

Supports BACnet service Change of Value (COV)

Supports remote Firmware updates

- IP Class: 54
- Stroke: 7mm

BACnet Testing Laboratories (BTL) listed BACnet MS/TP fieldbus device

Manual override function

Configuration tool available easy configuration, commissioning and firmware updates

- Commissioning tool available for addressing, parametrization and hydronic continuous commission
- ¹⁾ CO6 application
- ²⁾ Energy application
- ³⁾ Remote I/O application

Lantos

Trouble shooting

BACnet Fieldbus check:

It is possible to check the fieldbus state by examining error messaging related to the actuator in order to verify communication and detect early potential fieldbus related problems. This is done by the object values AV:15 to AV:19.

Quality of the BACnet network:

An important thing for good operation of the actuator is a well functioning network. Some values that tell you about the quality of the network can be found in the objects AV:15 to AV:19. The most important values are AV:17 Server Error Count and AV:19 Server Timeout Error. These two values should be much lower than AV:15, AV:16 and AV:18. As a general rule, it is important that AV:17 and AV:19 are not constantly increasing their count.

Quality of power supply:

The object / register AV:6 / 33794 may be used to check if the power supply and cabling, used to supply the actuator with power, is according to specification requirements. The present value of AV:6 / 33794 represents the current voltage measured inside the actuator. This is the voltage that the actuator monitors at all times and subsequently reacts on if outside the recommended range. See in the table below how the actuator reacts at different voltage levels.

| Voltage (Present value of AV:6 / 33794 | Reaction | | |
|--|--|--|--|
| Voltage below 16.5V | Start alarm indication with LED. Initiate and alarm BV: 15 / 33536 Bit 19 and that the supply voltage is too low. | | |
| Voltage below 16.1V | Motor is stopped. The LEDs indicating alarm and actuator still initiating alarm BV:15 / 33535 Bit 19 if the voltage hasn't dropped too low. | | |
| When voltage rises above 17.5V again | Motor can run again. LED alarm indication stops and returns to normal operation. Alarm BV:15 / 33536 Bit 19 returns to normal operation. | | |
| When voltage rises above 43.4V | Start alarm indication with LED. Initiate an alarm BV:14 / 33536 Bit 18. | | |
| When voltage drops below 38.3V again | LED alarm indication stops and returns to normal operation. Alarm BV:14 / 33536 Bit 18 returns to normal operation. | | |

NB: the voltage level will be constantly changing depending on the operational activity of the entire group of actuators and other devices connected. The supply voltage will go up and down in value if:

- Power supply is not strong and stable
- If long cables are used in a daisy chain setup

A higher number of actuators running at the same time will reduce the supply voltage (for the last devices on a daisy chain cable, in particular).

The actuator's voltages are considered to be OK when all values of AV:6 / 33794 are above 18V, when all actuators are moving the motor/running. To ensure voltage in each device is OK under worst case operational conditions, the following is recommended:

- Run all the actuators on the daisy chain cable at the same time. While all are running, check each value of AV:6 / 32794. These values should still be above 18V and no previously mentioned voltage level alarms should be initiated or indicated. If LEDs indicate an alarm state or a BACnet/Modbus alarm is initiated, or a value less than 18V is observed, then cabling should be reviewed.
- Check the values of AVO:0. This BACnet object holds 3 values: Average measured voltage, Maximum measured voltage and Minimum measured voltage. The most important value here is the Minimum measured voltage. It can tell you the lowest voltage that has been measured during operation of the actuator.

Danfoss



ENGINEERING TOMORROW

Data sheet

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