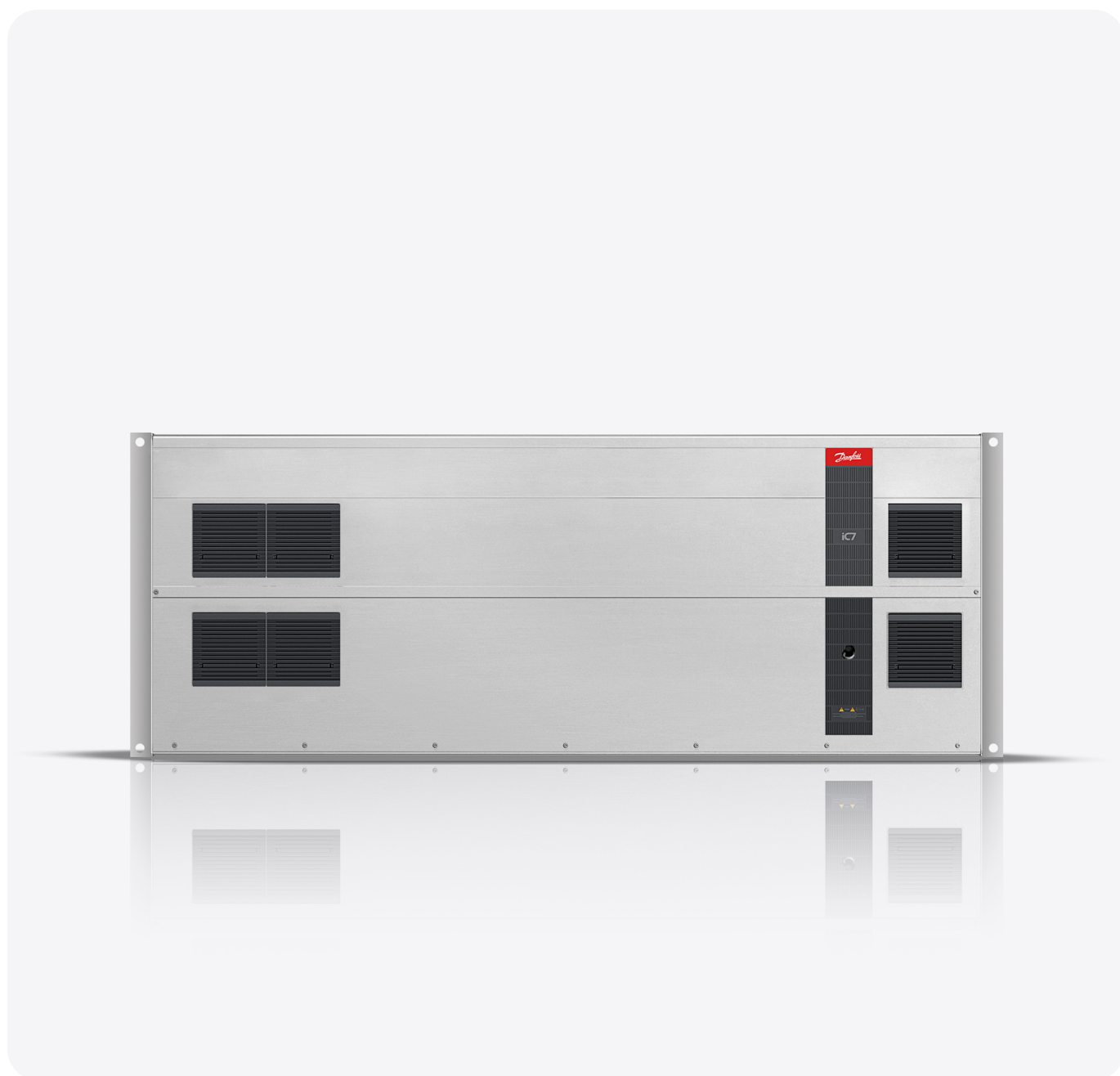




iC7-HVACR Horizontal Frequency Converter

FB12h (893–1260 A)



1 Installation

1.1 Safety and Installation Awareness

An installation guide and a safety guide are provided with the drive. Before installing the drive, read all safety guidelines and precautions in the safety guide (BH319740379644). For details on cybersecurity, see *Security Features* in the *iC7 Series HVACR Application Guide* (AB493837940842). More documentation – including a design guide and fieldbus operating guide – can be accessed by scanning the QR code on the front cover.

1.2 Required Tools

- Lifting aid
- Measuring tape
- Wrench with extensions and 8, 13, 17, 19 mm sockets
- Torx and slotted screwdrivers (T20, T25, SL1, and SL2)
- Wire crimper
- Sheet metal punch and/or pliers for cable entry plate

1.3 Verifying the Shipment and Its Contents

Make sure that the items supplied and the information on the product label correspond to the order confirmation. The product label is placed on the lower right corner of the exterior door and also on the interior of the drive. Use a Data Matrix ECC 200 compatible barcode reader to obtain the model code, code number, serial number, and manufacture date from the 2D code on the product label.

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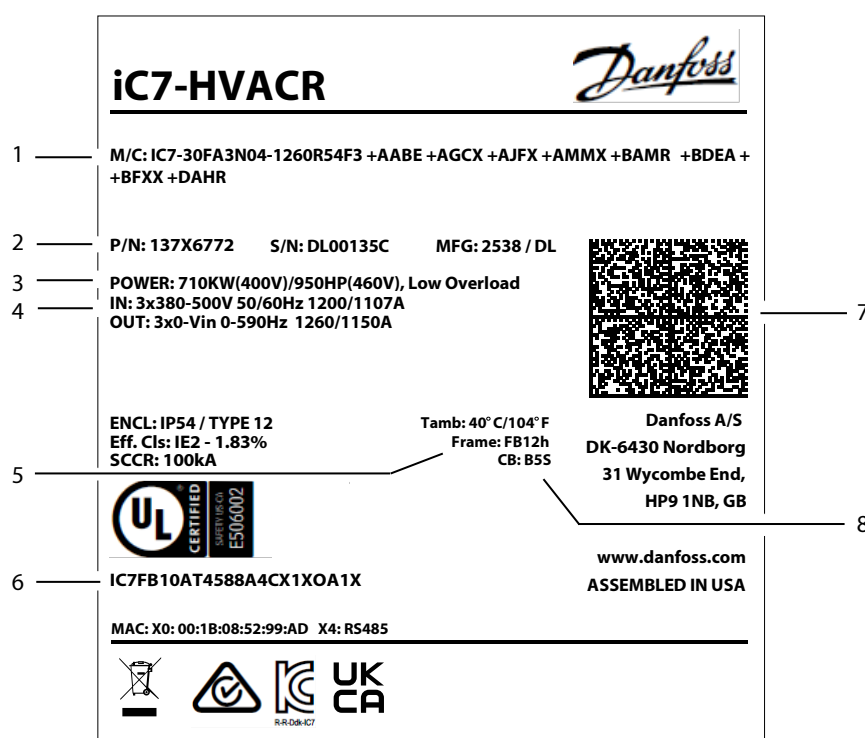


Figure 1: Example of a Product Label

1	Model code (2D code shows the full model code)	2	Code number, serial number, manufacture date (YYWW)
3	Power rating	4	Input and output voltage, frequency, current

5	Frame designation	6	Compliance code used on certificate
7	2D code	8	Control board designation

1.4 Installing the Drive

Installation location is important. Full output current is available when the following installation conditions are met. For temperatures and altitudes outside this range, consult the *Derating* section in the design guide.

- Maximum ambient temperature for low-overload operation: 40 °C (104 °F) average over 24 hrs and 45 °C (113 °F) for 1 hr. For high-overload, maximum ambient temperature: 45 °C (113 °F) average over 24 hrs and 50 °C (122 °F) for 1 hr.
- Minimum ambient air temperature: -30 °C (-22 °F).
- Altitude < 1000 m (3280 ft) above sea level.

1. Identify the frame and control board designations. See [Figure 1](#).
2. Ensure that the operating environment and electrical installation meet the following standards.
 - a. Indoor unconditioned/pollution degree 2.
 - b. Overvoltage category 3.
3. Review the wiring diagram based on the control board designation. See step 1 in the *Illustrations* section.

All wiring must comply with local and national regulations regarding cross-section and ambient temperature requirements. Loose connections can cause equipment faults or reduced performance. Tighten the terminals according to the proper torque value in step 8 in the *Illustrations* section.

4. Review the fuse specifications. See step 2 in the *Illustrations* section.

This product is suitable for use on a circuit capable of delivering up to 100 kA short-circuit current rating (SCCR) at the respective drive voltage rating. For details, see the product label. For the short-circuit current rating for variants with built-in disconnect, see the design guide. For IEC installations with semiconductor fuses, use suitable branch circuit protection according to local regulations.

5. Review the power cable specifications. See step 3 in the *Illustrations* section.

Use copper wire with a minimum 70 °C (158 °F) rating. For aluminum wire, see the design guide.

6. Install the drive following the numbered steps in the *Illustrations* section. Certain illustrations/steps pertain to specific frame designations, such as FB12h (R54) and (L54). The label R54 indicates that the drive is mounted on its right side, and L54 indicates that the drive is mounted on its left side.
 - a. Remove or open the front panel/door using a T25 driver.
 - b. Remove any touch guard panels.
 - c. Attach the components from the accessory bag to the drive. See step 4 in the *Illustrations* section.

For this step, accessory bag components are shown shaded within the illustration.

- d. Mount the drive on or against a solid, non-combustible mounting surface such as concrete or metal. See step 5 in the *Illustrations* section.
- e. Ensure proper cooling by providing necessary clearance around the drive. The drive requires 225 mm (8.9 in) end clearance.
- f. Create the openings in the cable entry plate. Cable entry can be made at the end of the unit and through the back of the unit, as shown by the shaded areas in step 6 in the *Illustrations* section.

- g. Identify the terminals for functional extensions, fieldbus, power, and ground connections. See step 7 in the *Illustrations* section.
 - h. Install the motor, mains, and PE ground wiring. See step 8 in the *Illustrations* section.
 - i. Install the control wiring. See step 9 in the *Illustrations* section.
 - j. Route the control cables to the left side of the enclosure using the cable clips or zip ties.
 - k. Replace the touch guard panels.
7. Securely fasten the cover to the drive using a T25 driver. Torque the fasteners to 2.3 Nm (20 in-lb).
 8. Perform initial drive and motor setup. Consult the *iC7 Series Aqua Application Guide* or the *iC7 HVACR Application Guide*.
 9. Configure the fieldbus. Consult the appropriate iC7 fieldbus operating guide.

1.5 Functional Safety (Safe Torque Off)

The drive is shipped with all safe inputs de-energized. Without extra wiring to the safe I/O terminal blocks (X31 and X32), the STO function is always active and the motor will not turn. For more information, refer to the *iC7-Aqua and iC7-HVACR Functional Safety Operating Guide* (AQ540338948377).

- To disable the STO function, install jumper wires to terminals X31 and X32. See step 9 in the *Illustrations* section.
- To use the STO function, wire a safety device to 1 or both of the safe I/O terminal blocks. See step 1 in the *Illustrations* section. To avoid erroneous faults or warnings from occurring, any unused safe I/O terminal blocks must be disabled using jumper wires or a jumper clip. One jumper clip is included in the accessory bag.

WARNING

RESIDUAL ROTATION

The STO function can be used for any type of motors. 2 faults can occur in the power semiconductor of the drive. A residual rotation can result from the faults. The rotation can be calculated to $\text{angle} = 360 / (\text{number of pole pairs})$.

- Ensure that this residual rotation does not pose a safety risk. The situation is not relevant for induction motors.

NOTICE

A successful commissioning test of the STO function is required after the initial installation and after each subsequent change to the installation or application involving the STO.

Commissioning test

There are 2 types of commissioning tests based on whether the STO parameter is configured for manual restart (M) or automatic restart (A). For more information on the STO parameter, see the application guide.

- If Parameter **7.3.1 Safe Torque Off Response = Fault - reset required**, perform the steps marked with an "M".
- If Parameter **7.3.1 Safe Torque Off Response = Warning - no reset required**, perform the steps marked with an "A".

Table 1: Commissioning Test for STO Functionality

Type of test	Commissioning steps	X
M/A	Power on the frequency converter.	
M/A	Verify that no safety faults are present.	
M/A	Start the motor.	
M/A	Without interrupting the mains supply, remove the 24 V DC voltage supply to both STO input terminals using the safety device.	
M/A	Verify that the motor coasts. This process can take some time.	

Table 1: Commissioning Test for STO Functionality - (continued)

Type of test	Commissioning steps	X
M/A	Verify that STO activated is shown on the control panel or in the event log.	
M/A	If the STO feedback is used, verify that STO is activated by checking the state of the STO Feedback.	
M/A	Reapply 24 V DC supply to both the STO input terminals.	
M/-	Verify that the motor remains in the coasted state and any connected relays remain activated.	
M/-	Send a reset signal via fieldbus, digital I/O, or the control panel.	
M/A	Verify that the motor starts up and runs within the original speed range.	

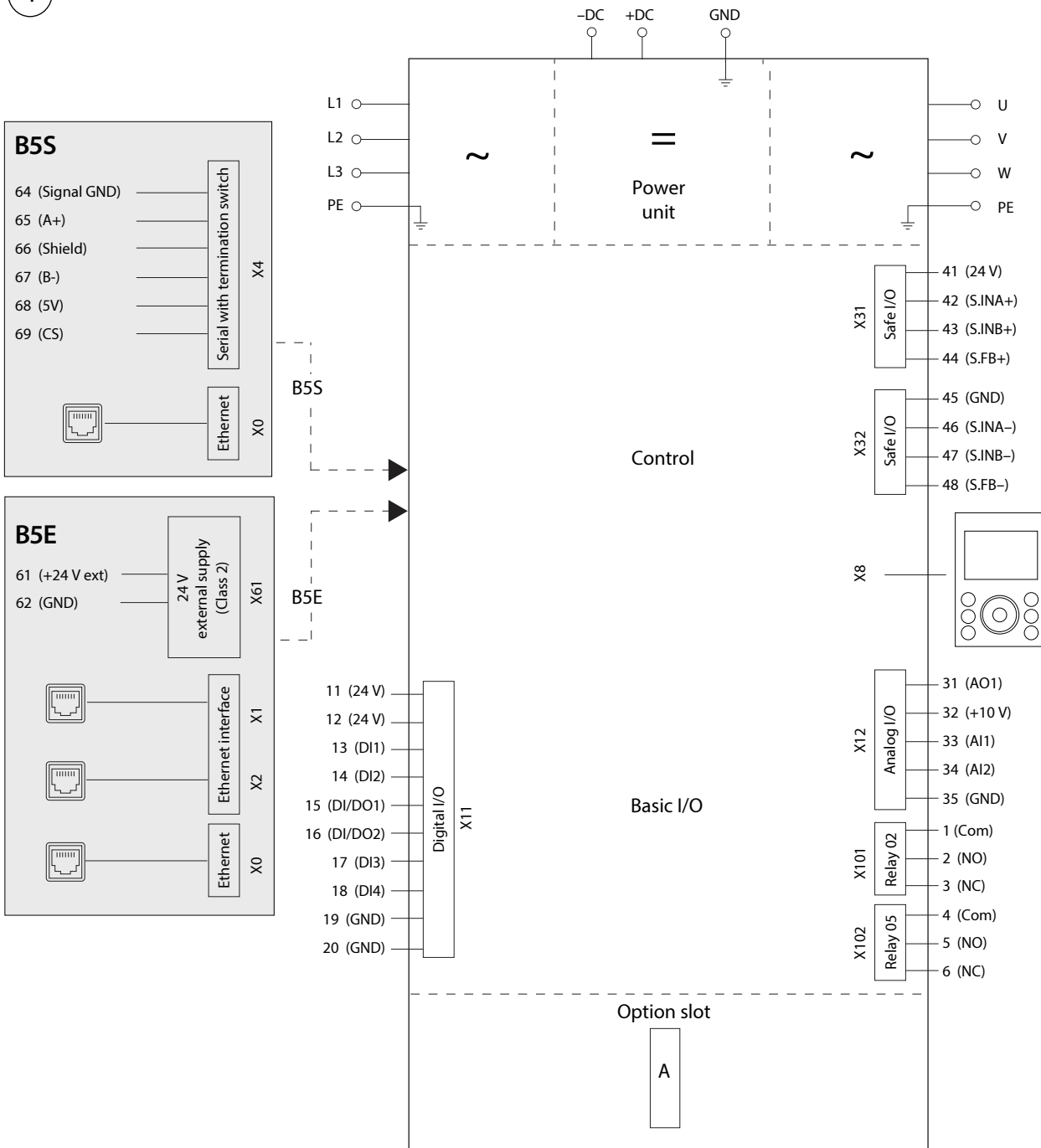
1.6 Power Losses and Efficiency

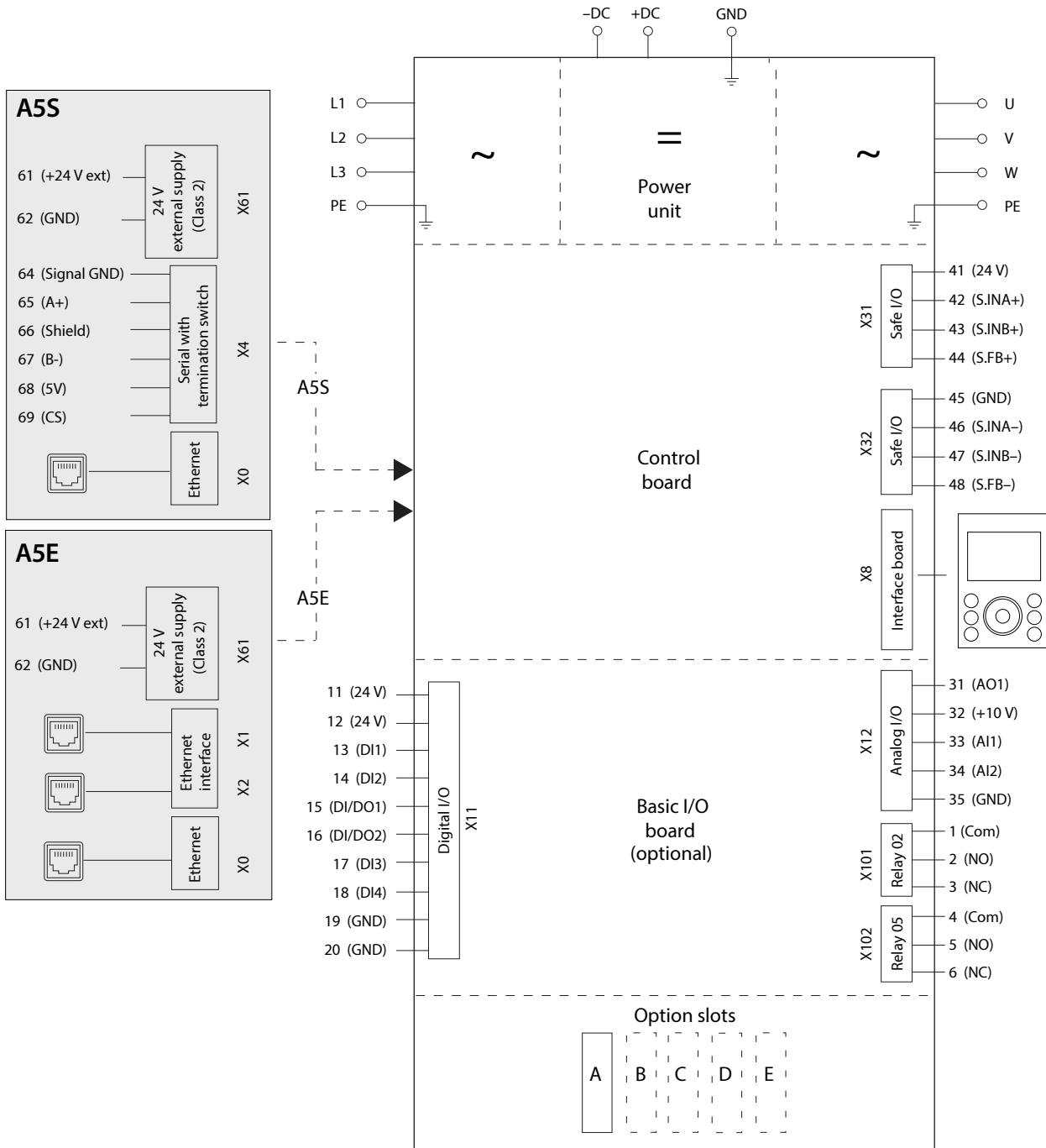
For power loss data including part load losses, see <https://energy.mydrive.danfoss.com>.

2 Illustrations

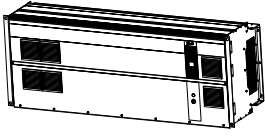


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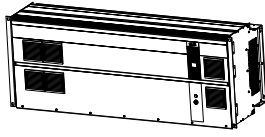
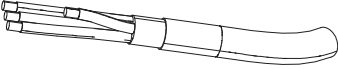


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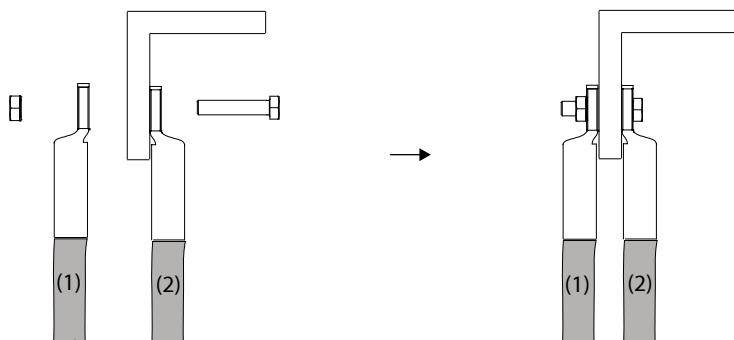
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	05-1000	170M7309	170M7309
	05-1120	170M7340	170M7340
	05-1260	170M7340	170M7340

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3

 FB12h	L1/L2/L3 U/V/W  [mm ² (AWG)]	
	05-893A	3x240 (3x500), 4x185 (4x350 mcm)
	05-1000	4x185 (4x350), 5x150 (5x300 mcm)
	05-1120	4x240 (4x500), 5x185 (5x350 mcm)
	05-1260	4x240 (4x500), 5x185 (5x350 mcm)

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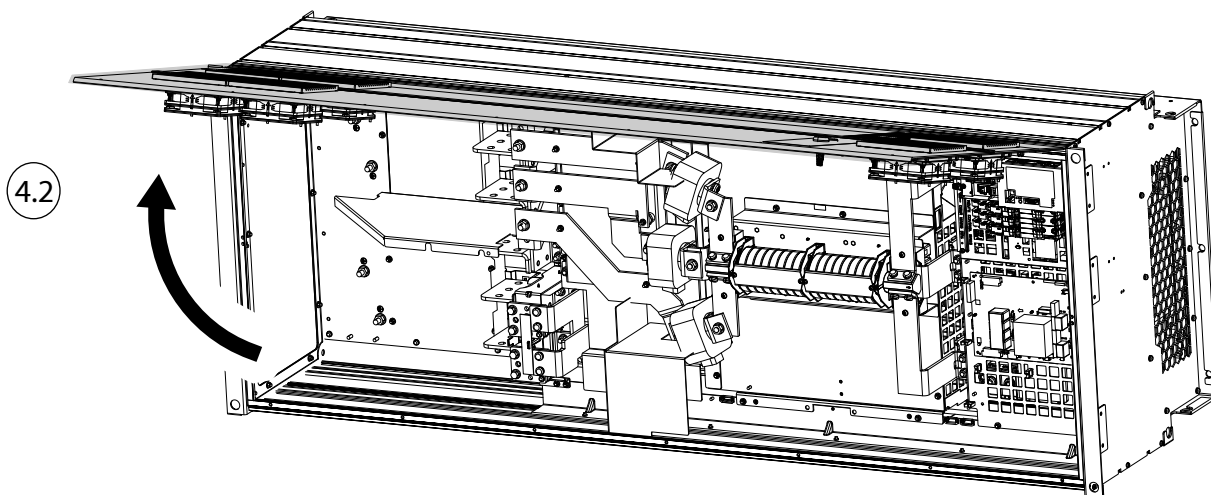
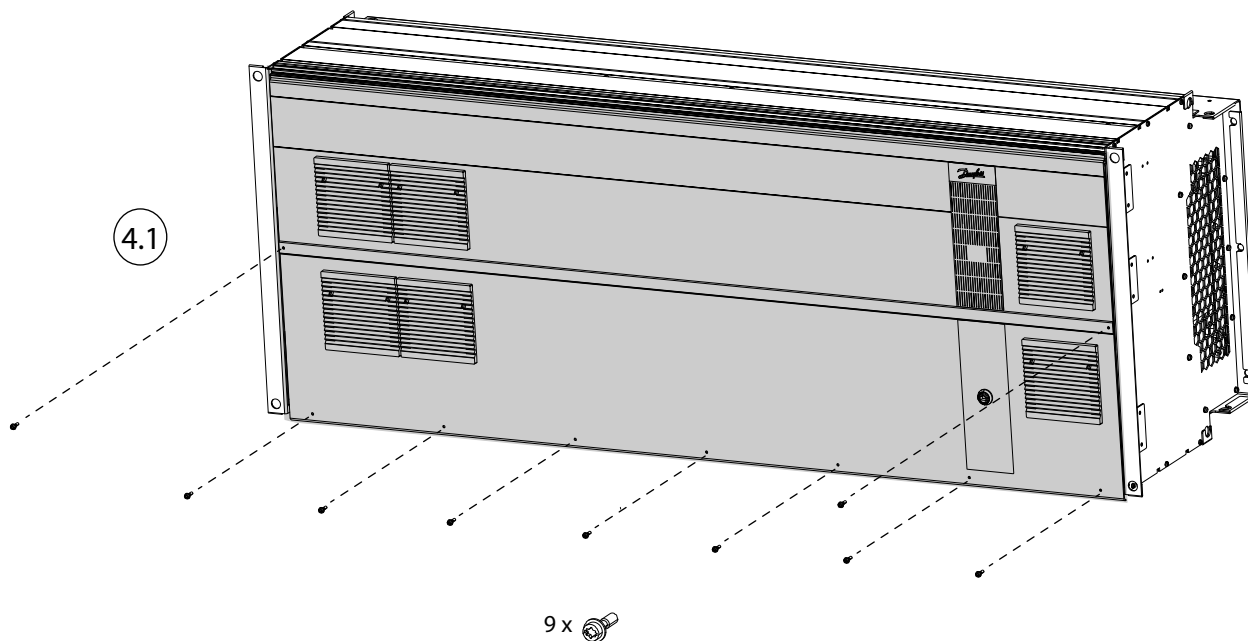


4 FB12h (R54)

iC7-HVACR 

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+BFXX +DAHR

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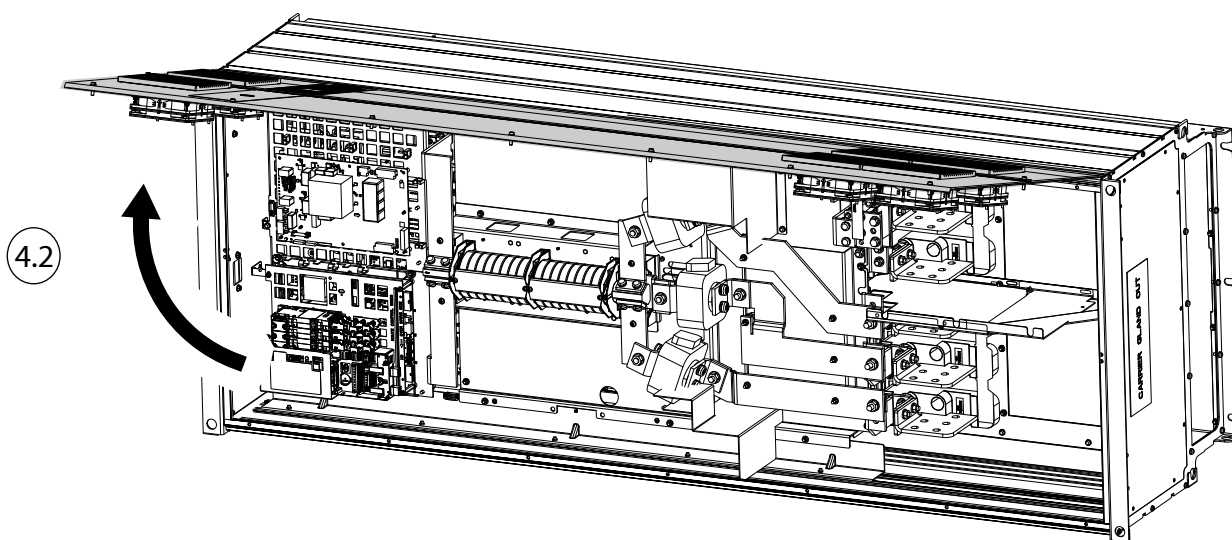
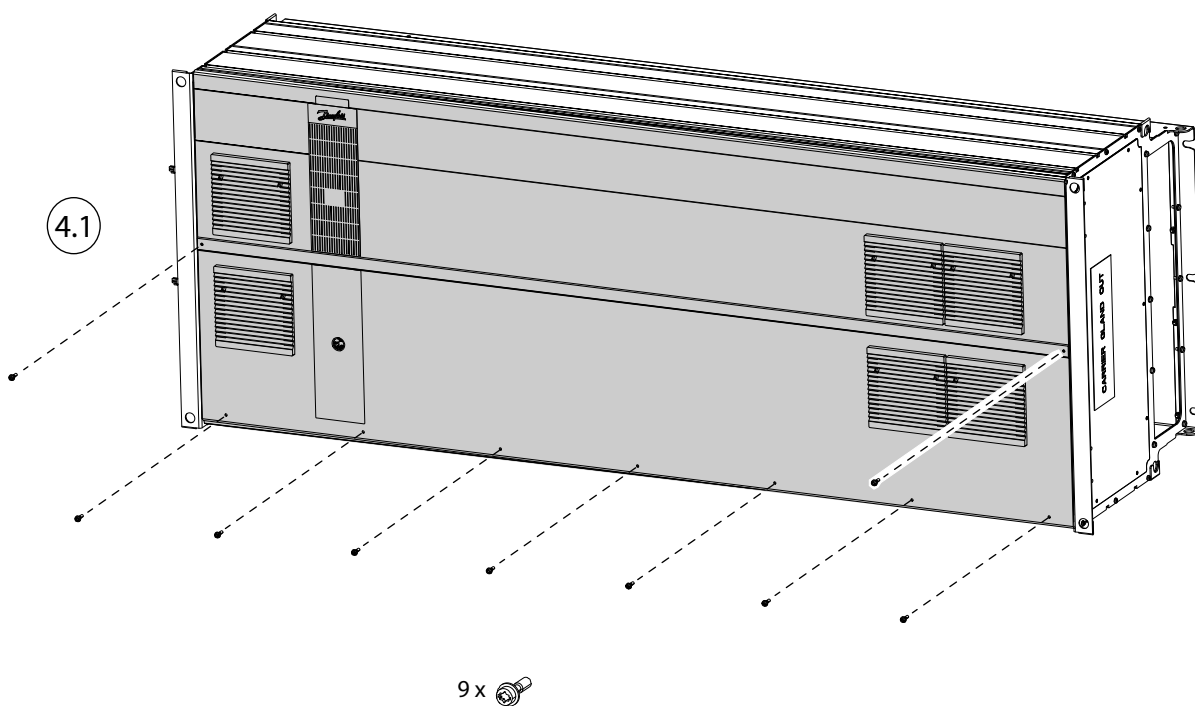
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iC7-HVACR



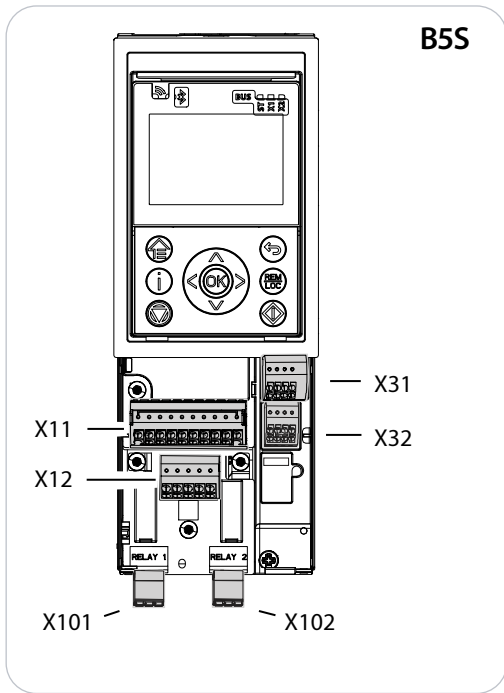
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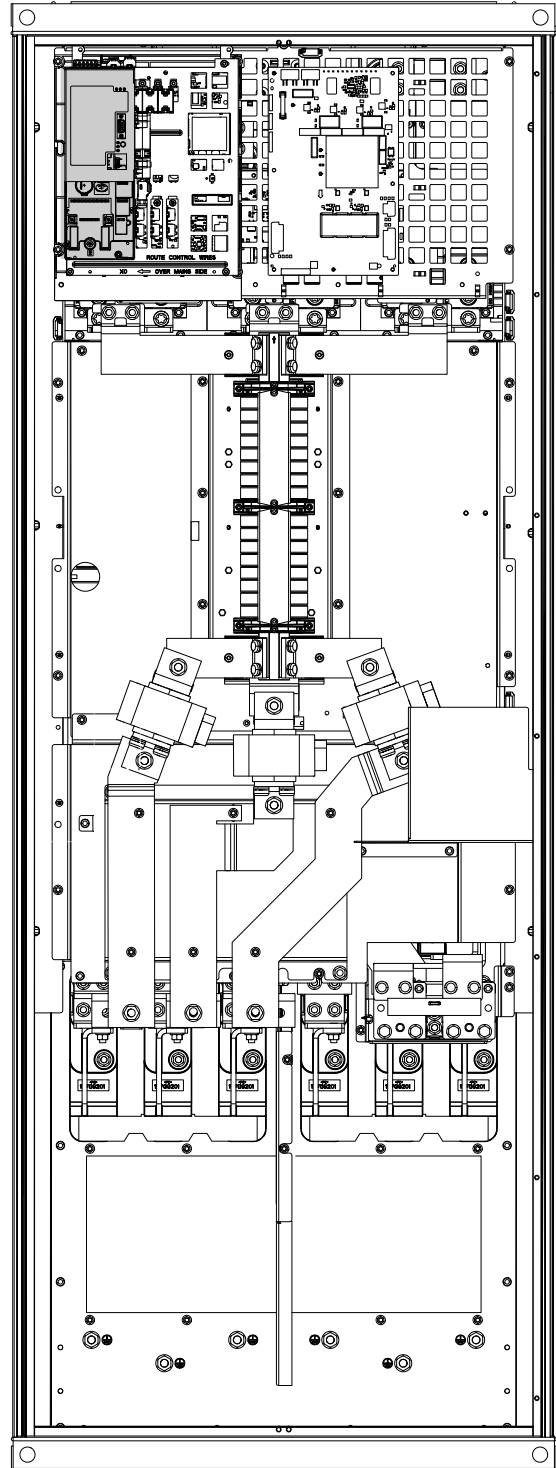
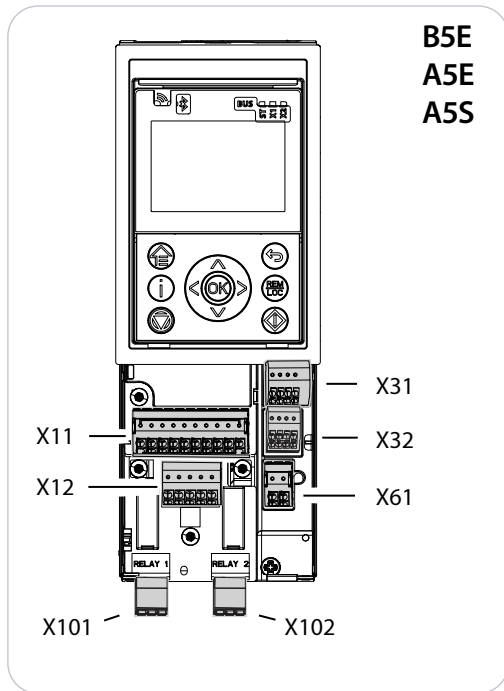


FB12h

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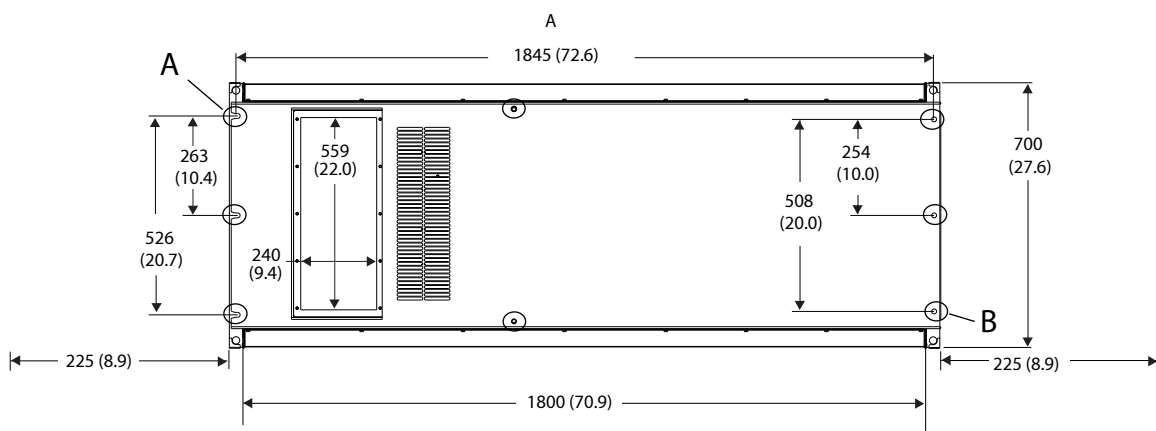
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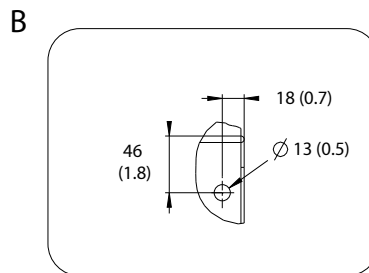
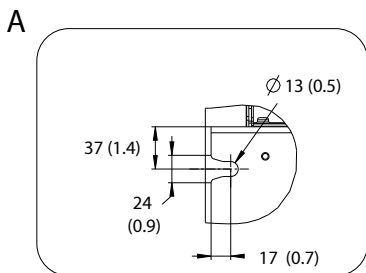
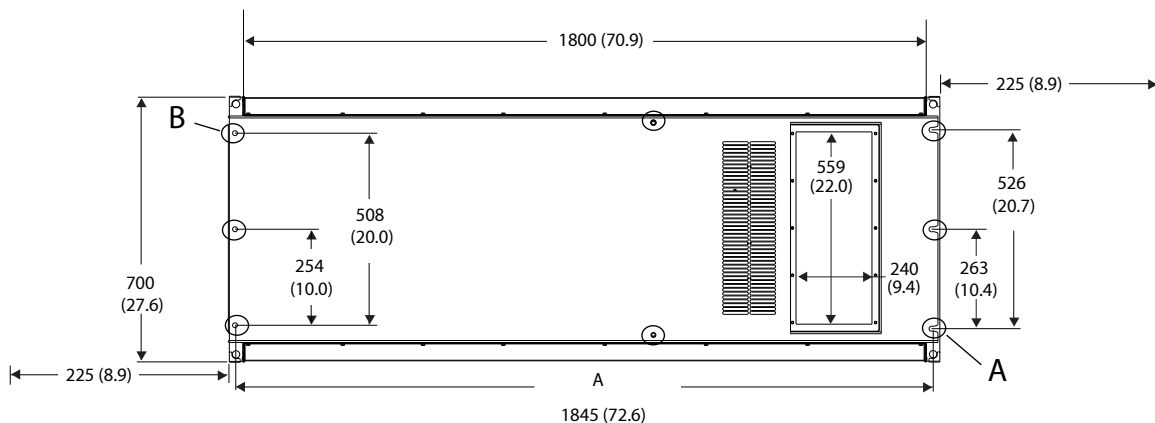
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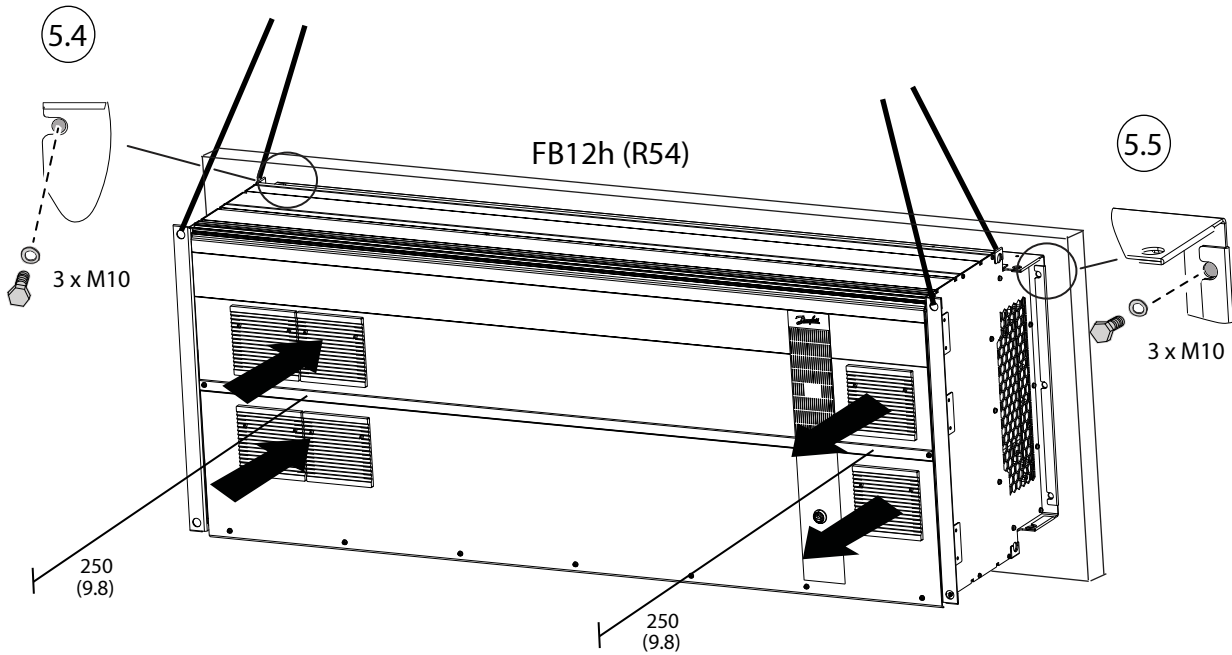
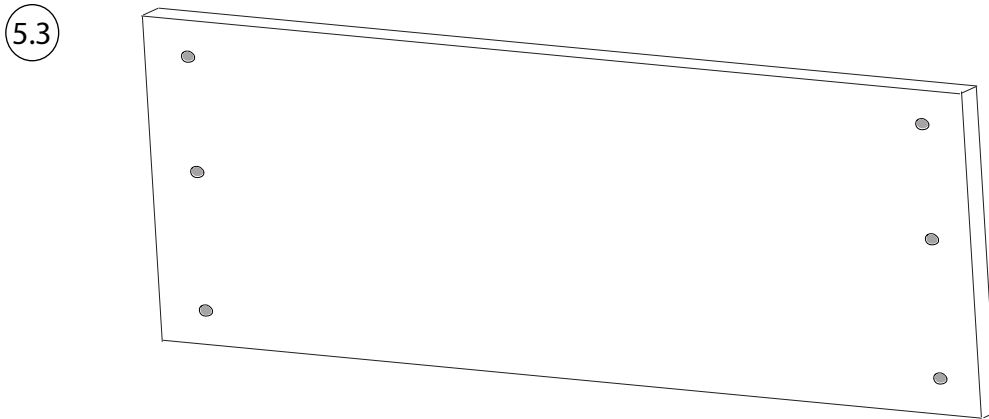
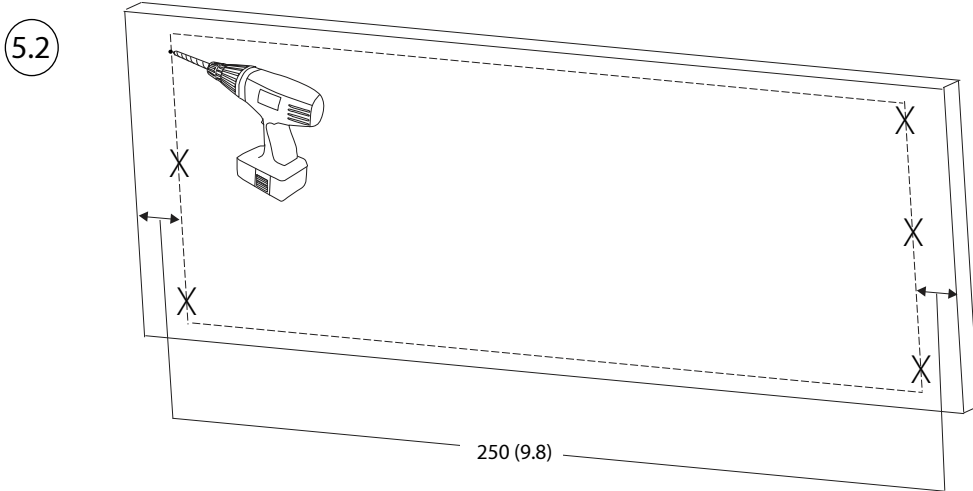
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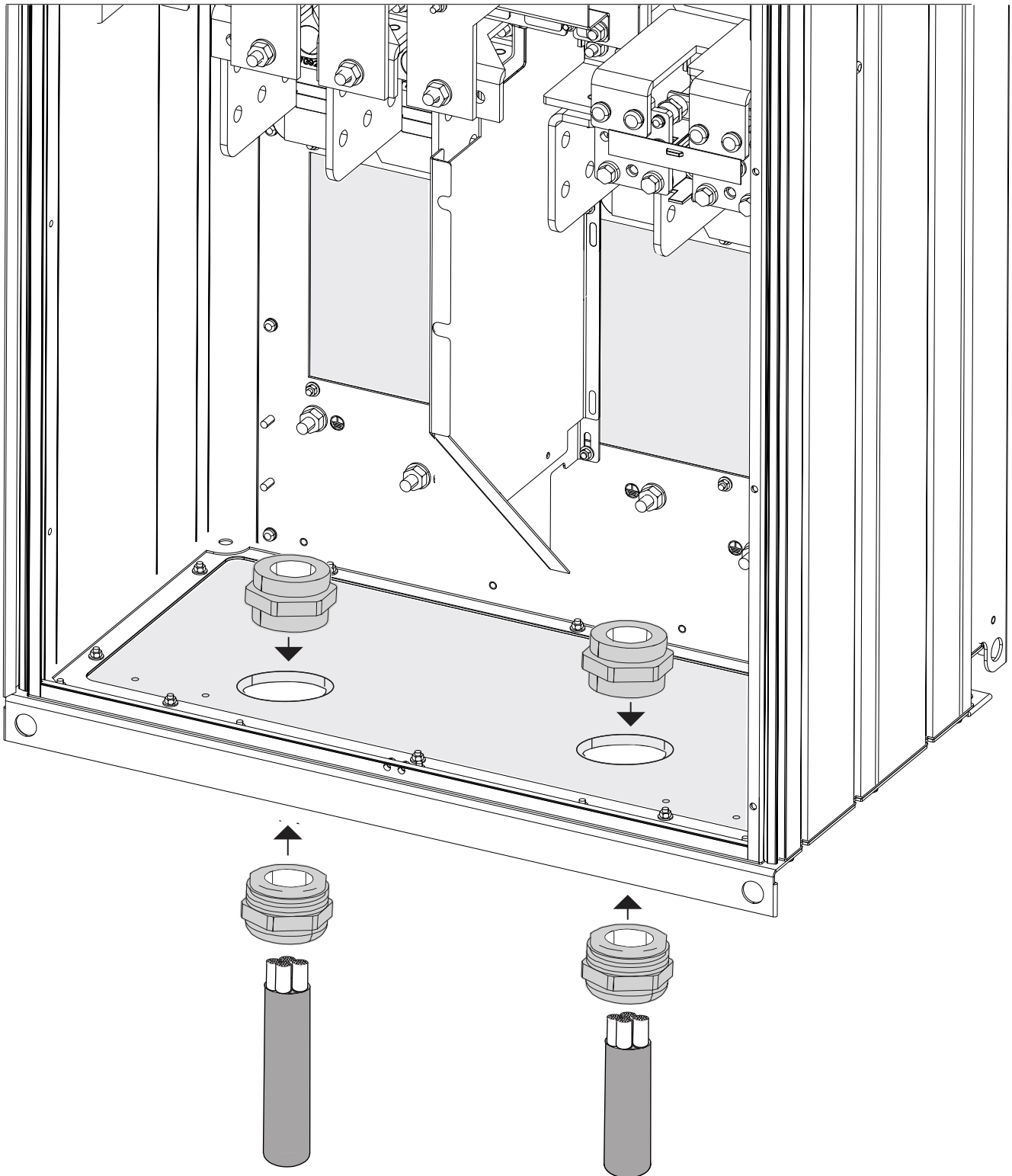
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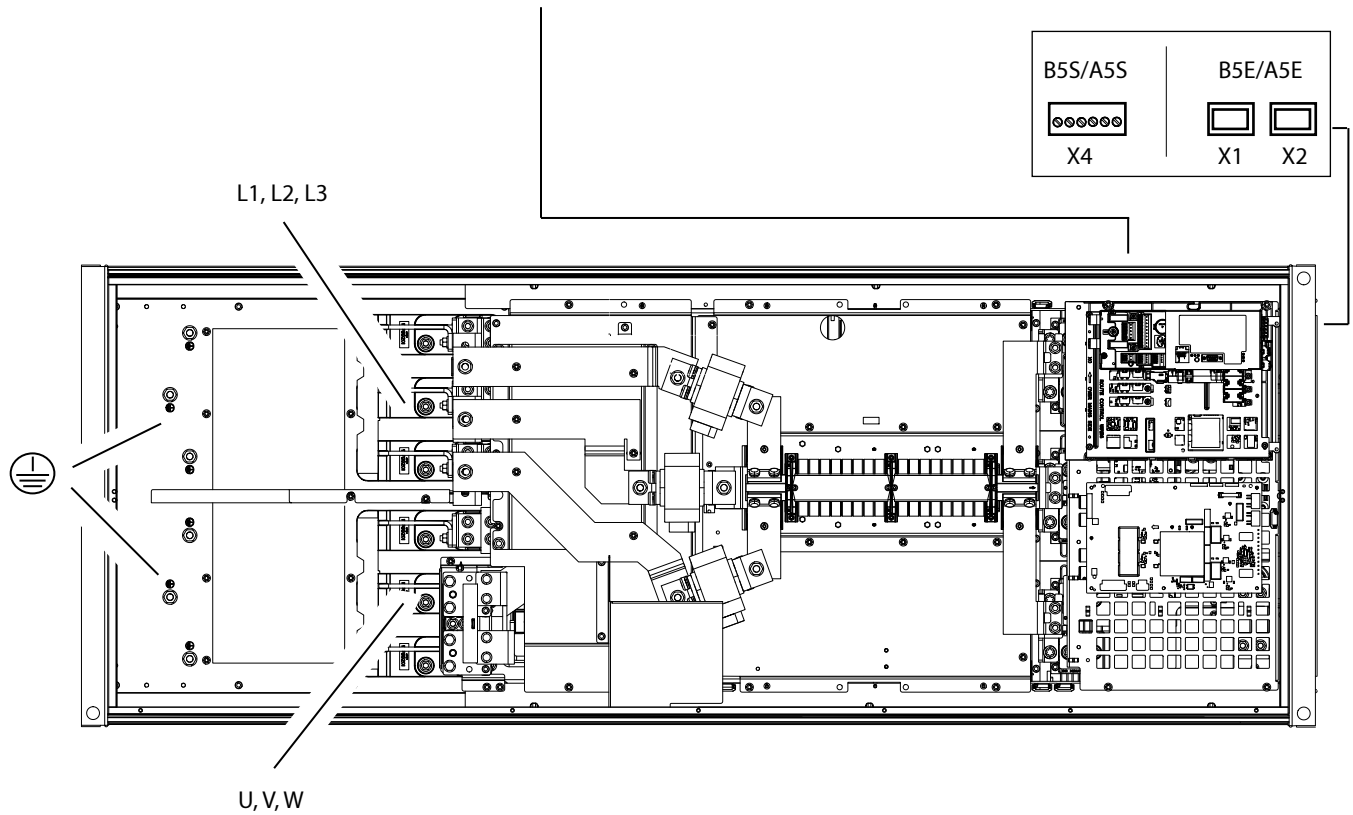
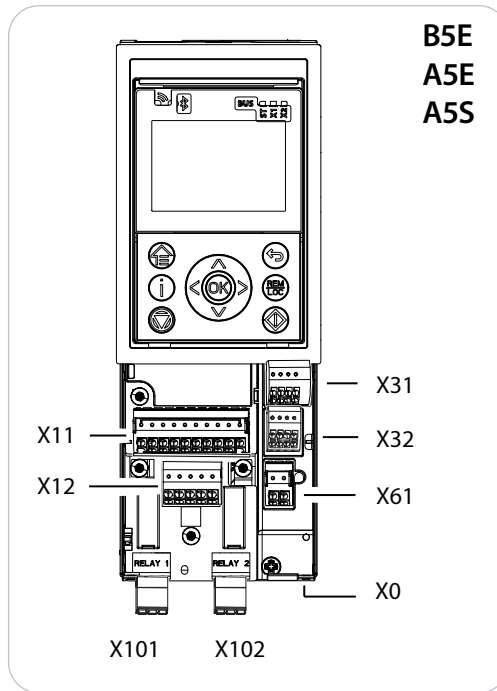
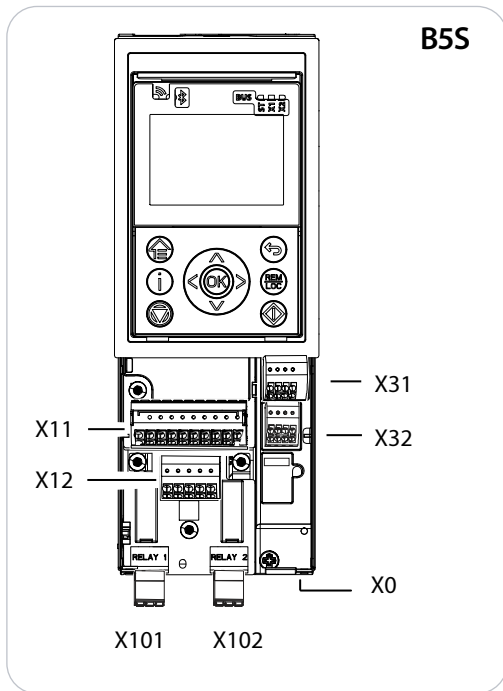
6 FB12h

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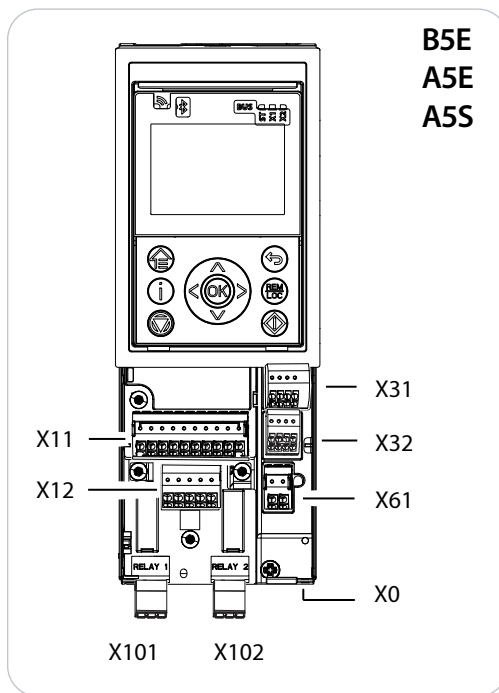
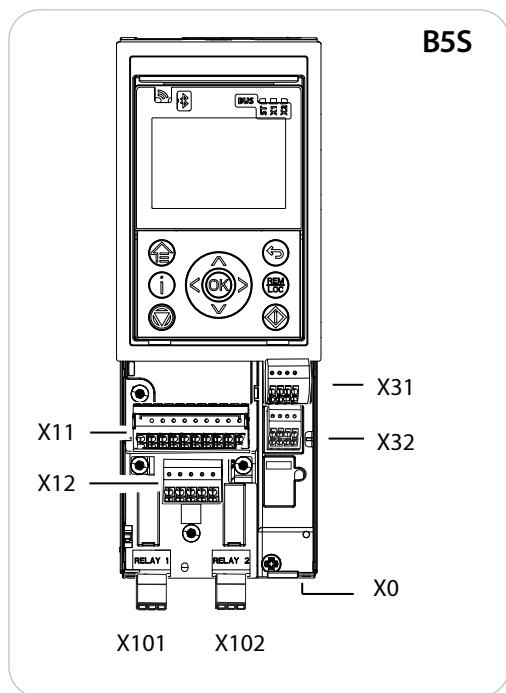
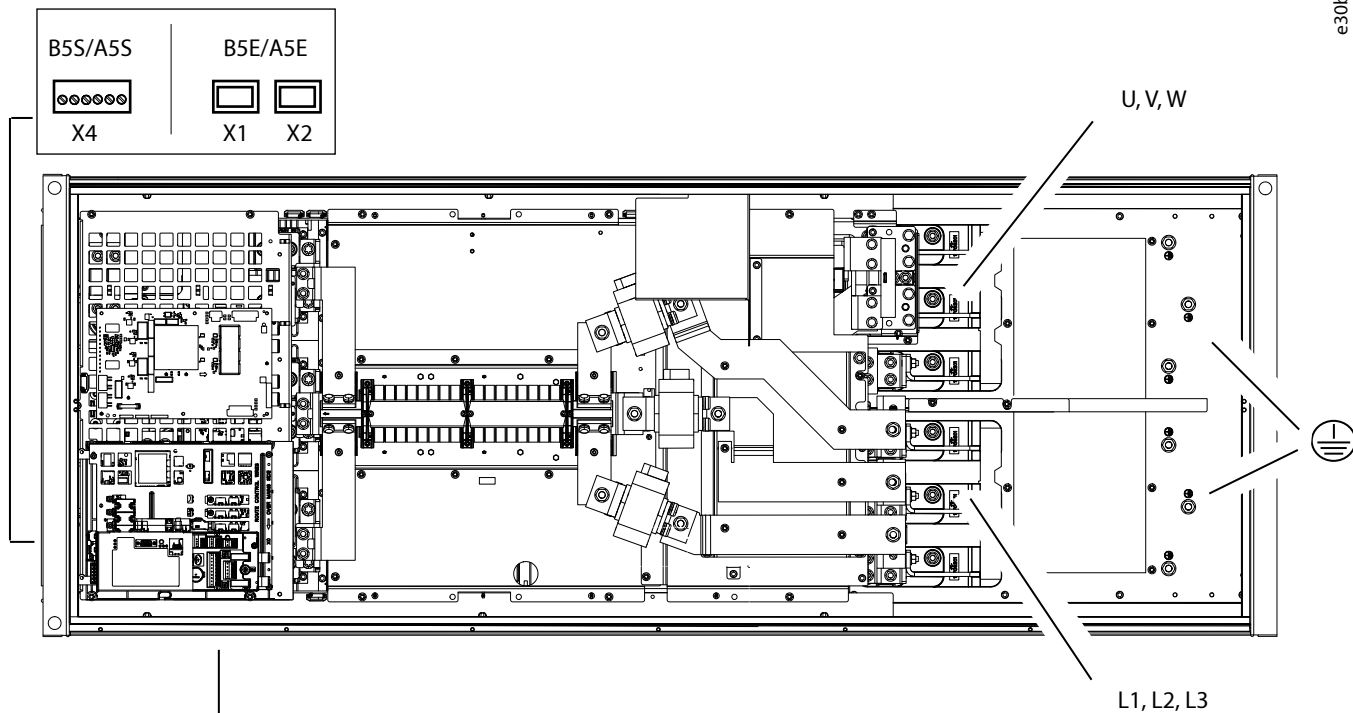
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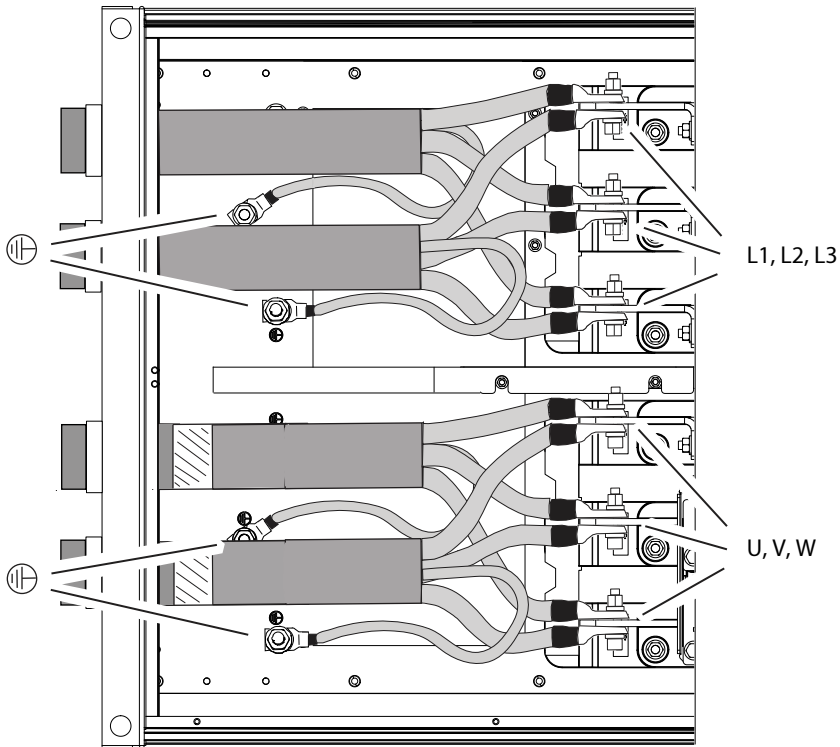
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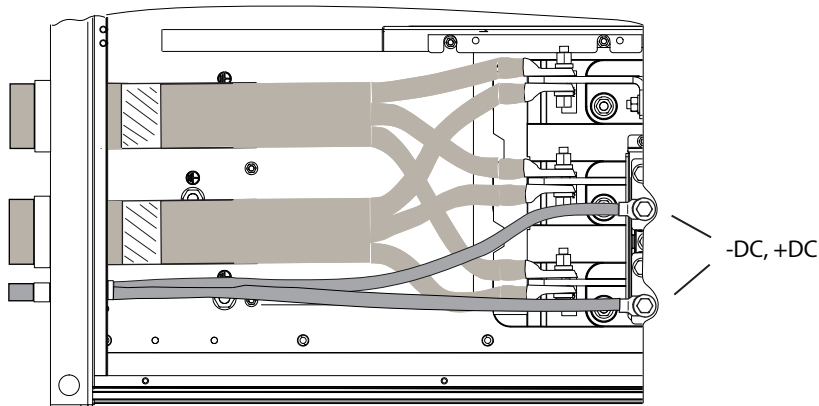


8 FB12h (R54)

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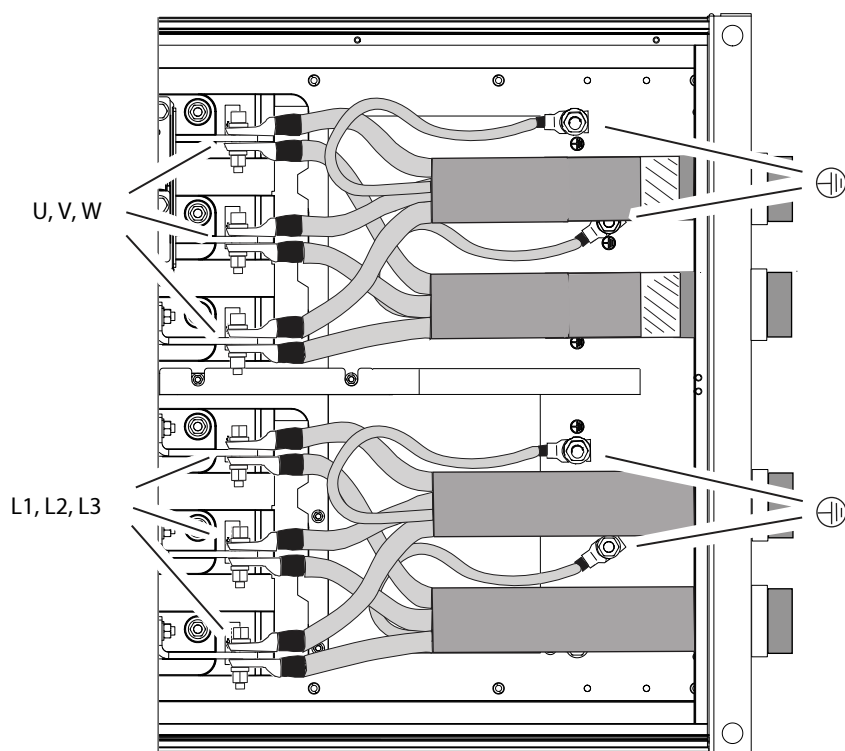
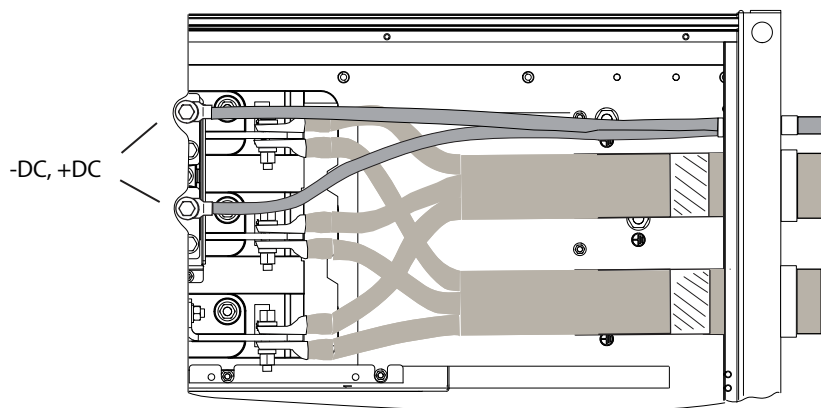


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	U, V, W		M10 [19 Nm (168 in-lb)] M12 [35 Nm (310 in-lb)]
	-DC +DC		M10 [19 Nm (168 in-lb)]
			M8 [9.6 Nm (84 in-lb)] M10 [19 Nm (168 in-lb)]



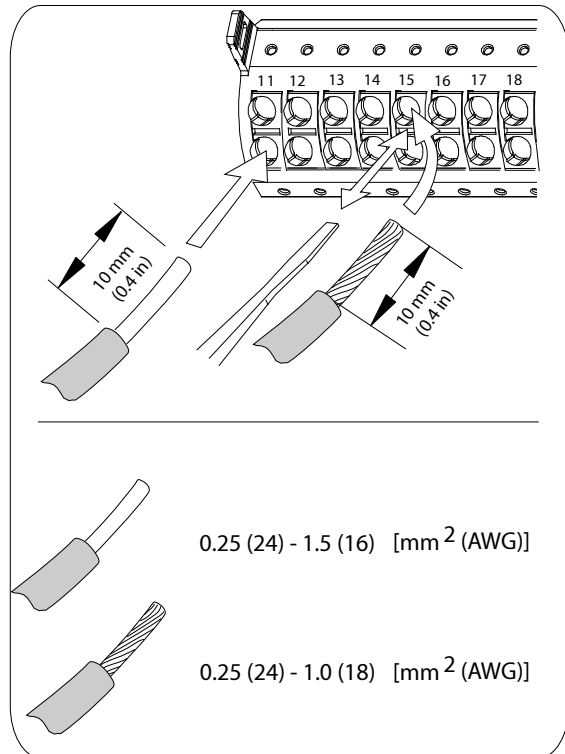
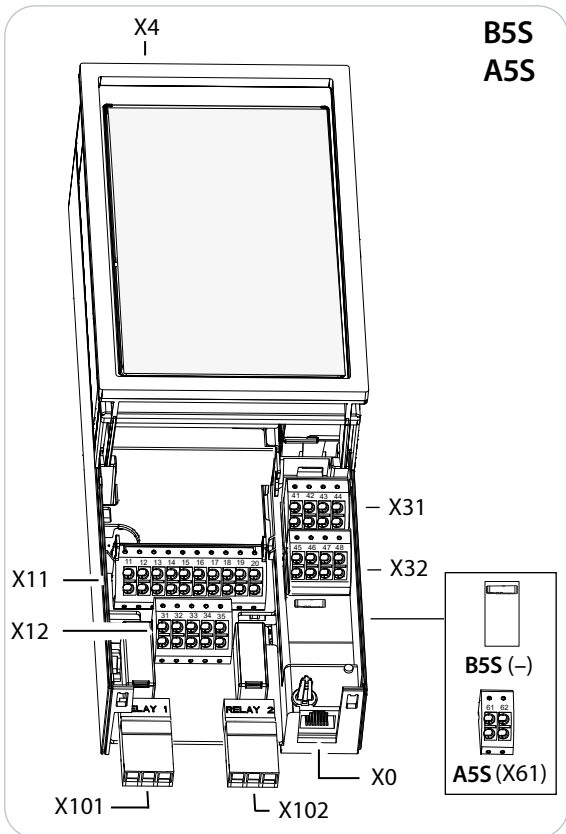
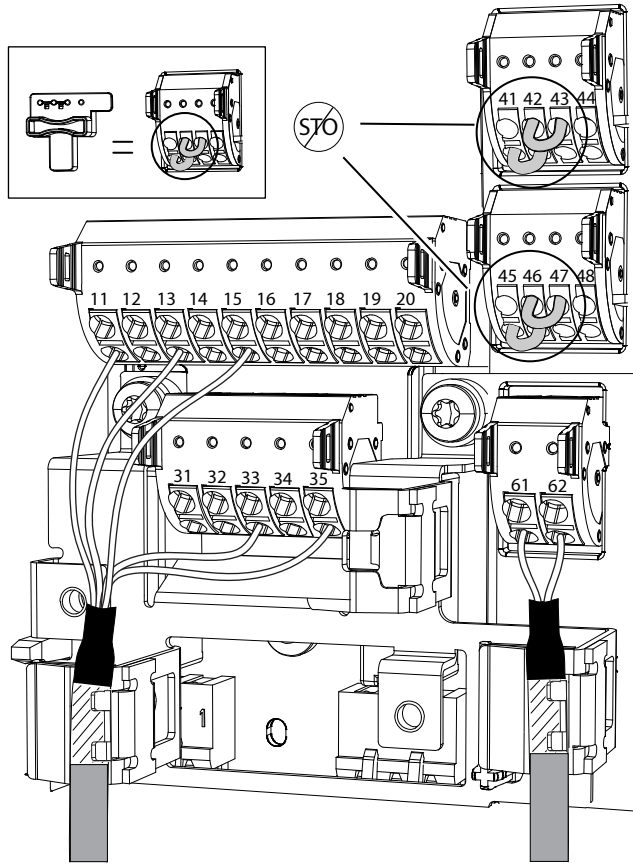
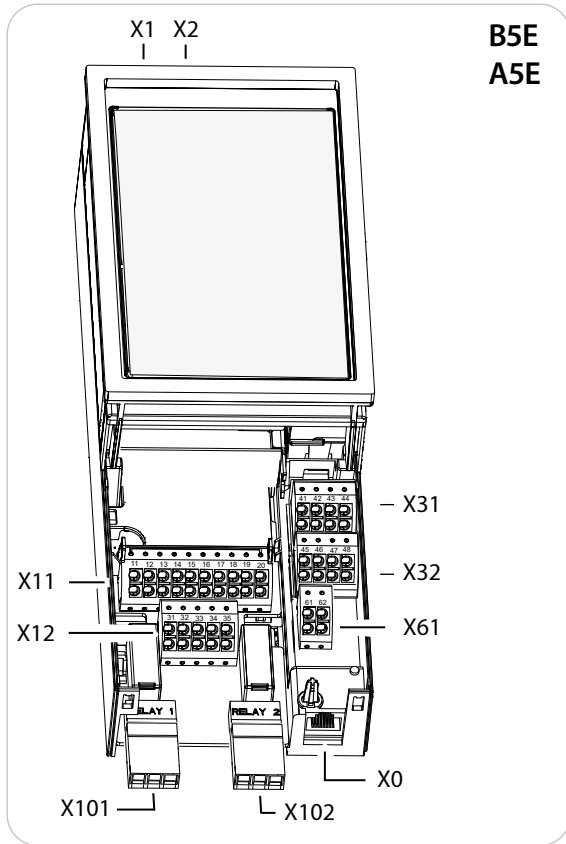
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	-DC +DC		M10 [19 Nm (168 in-lb)]
			M8 [9.6 Nm (84 in-lb)]
			M10 [19 Nm (168 in-lb)]

9



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 www.danfoss.com

EU DECLARATION OF CONFORMITY

Danfoss A/S
Danfoss Drives

declares under our sole responsibility that the

Product category: Frequency Converter, IC7-HVACR
Type designation(s): IC7YYYYYYYYYYYYYYYY**Y

Y are varying numbers or letters indicating drive configurations which impact this DoC.

- Character 4-5 (Frame type) FA, FK, FB
 - Character 6-7 (Frame size) 02, 04, 05, 06, 07, 08, 09, 10, 11, 12
 - Character 8 (Cooling type) A
 - Character 9-10 (Voltage class) H4, T4
 - Character 11-14 (Current rating) 01A3, 01A8, 02A4, 03A0, 04A0, 05A6, 07A2, 09A2, 12A5, 16A0, 24A0, 31A0, 38A0, 42A0, 61A0, 73A0, 90A0, 106A, 147A, 170A, 206A, 245A, 302A, 385A, 395A, 480A, 588A, 658A, 736A, 799A, 895A, 1000, 1120, 1260
 - Character 15 (Enclosure rating) 1, 2, 4, 5, A, B
 - Character 16 (RRI class) B, C, D, E
 - Character 17 (Brake) X, 1
 - Character 18 (Internal fuse) X, 1, 2, 3
 - Character 19 (DCterminals) X, 1
 - Character 23 (Functional Safety) X, A
- * may be any number or letter indicating drive options which do not impact this DoC.

Covered by this declaration is in conformity with the following directive(s), standard(s) or other normative document(s), provided that the product is used in accordance with our instructions.

- Low Voltage Directive 2014/35/EU** EN 61800-5-1:2007+A1:2017+A11:2021 Adjustable speed electrical power drive systems – Part 5-1: Safety requirements – Electrical, thermal and energy.
- EN IEC 61800-5-1:2023* Adjustable speed electrical power drive systems – Part 5-1: Safety requirements – Electrical, thermal and energy.
* only for F807AH4, F810AH4/e indicates A, B or X)

Date: 5 March 2026 Place of issue: Graasten, DK	Signed By: Name: Arne Fink Hansen Title: Product Owner	Date: 5 March 2026 Place of issue: Graasten, DK	Signed By: Name: Mari Haapala Title: Vice President
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Danfoss only vouches for the correctness of the English version of this declaration. In the event of the declaration being translated into any other language, the translator concerned shall be liable for the correctness of the translation.

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Page 1 of 2



Machinery Directive 2006/42/EU (only applicable for Character 23 equals A)
 EN 61800-5-2:2017 Adjustable speed electrical power drive systems - Part 5-2: Safety requirements - Functional

Character 23:
 X = no functionality
 A = 4BE61

EMC Directive 2014/30/EU
 EN IEC 61800-3:2023

Adjustable speed electrical power drive systems – Part 3: EMC requirements and specific test methods.

RoHS Directive 2011/65/EU including amendment 2015/863.
 EN IEC 63000:2018

Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances.

Commission Regulation (EU) 2019/1781 under the Ecodesign Directive 2009/125/EC including amendment in Commission Regulation (EU) 2021/341
 EN IEC 61800-9-2:2025

Adjustable speed electrical power drive systems (PDS) - Part 9-2: Ecodesign for motor systems - Energy efficiency determination and classification

Batteries Regulation 2023/1542 concerning batteries and waste batteries, amending Directive 2008/98/EC and Regulation (EU) 2019/1020 and repealing Directive 2006/66/EC
 EN 45554:2020

General methods for the assessment of the ability to repair, reuse and upgrade energy-related products

Packaging and packaging waste Regulation 2025/40/EU
 Article 5
 Requirements for substances in packaging

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Danfoss A/S
Ulsnaes 1
DK-6300 Graasten

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