### Revision history

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Series 90 Family of Pumps and Motors

Series 90 hydrostatic pumps and motors can be applied together or combined with other products in a system to transfer and control hydraulic power. They are intended for closed circuit applications.

- Series 90 – advanced technology
- Seven sizes of variable displacement pumps
- Proven reliability and performance
- Compact, lightweight
- Worldwide sales and service
- PLUS+1™ compliant controls and sensors

Series 90 variable displacement pumps are compact, high power density units. All models utilize the parallel axial piston/slipper concept in conjunction with a tiltable swashplate to vary the pump's displacement. Reversing the angle of the swashplate reverses the flow of oil from the pump and thus reverses the direction of rotation of the motor output.

Series 90 pumps include an integral charge pump to provide system replenishing and cooling oil flow, as well as control fluid flow. They also feature a range of auxiliary mounting pads to accept auxiliary hydraulic pumps for use in complementary hydraulic systems. A complete family of control options is available to suit a variety of control systems (mechanical, hydraulic, electric).

Series 90 motors also use the parallel axial piston/slipper design in conjunction with a fixed or tiltable swashplate. They can intake/discharge fluid through either port; they are bidirectional. They also include an optional loop flushing feature that provides additional cooling and cleaning of fluid in the working loop. For more information on Series 90 motors, refer to Series 90 Motors Technical Information 520L0604.

PLUS+1 Compliant Controls and Sensors

A wide range of Series 90 controls and sensors are PLUS+1™ compliant. PLUS+1 compliance means our controls and sensors are directly compatible with the PLUS+1 machine control architecture. Adding Series 90 pumps to your application using PLUS+1 GUIDE software is as easy as drag-and-drop. Software development that used to take months can now be done in just a few hours. For more information on PLUS+1 GUIDE, visit www.sauer-danfoss.com/plus1.

Series 90 pumps can be used together in combination with other Danfoss pumps and motors in the overall hydraulic system. Danfoss hydrostatic products are designed with many different displacement, pressure and load-life capabilities.

Go to the Danfoss website or applicable product catalog to choose the components that are right for your complete closed circuit hydraulic system.
Technical Information
Series 90 Axial Piston Pumps

General Description

Design

Series 90 pump cross-section

Series 90 pumps are also manufactured in Europe and China. Place of manufacture shown on nameplate will correspond with the actual place of manufacture.
General Description

Series 90 Pictorial Circuit Diagram

The circuit diagram shows a hydrostatic transmission using a Series 90 axial piston variable displacement pump and a Series 90 fixed displacement motor.

System schematic
## General Specifications

<table>
<thead>
<tr>
<th>Specification</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Design</strong></td>
<td>Axial piston pump of cradle swashplate design with variable displacement</td>
</tr>
<tr>
<td><strong>Direction of rotation</strong></td>
<td>Clockwise, counterclockwise</td>
</tr>
<tr>
<td><strong>Pipe connections</strong></td>
<td>Main pressure ports: ISO split flange boss Remaining ports: SAE straight thread O-ring boss</td>
</tr>
<tr>
<td><strong>Recommended installation position</strong></td>
<td>Pump installation position is discretionary, however the recommended control position is on the top or at the side, with the top position preferred. Vertical input shaft installation is acceptable. If input shaft is at the top 1 bar case pressure must be maintained during operation. The pump housing must be filled with hydraulic fluid under all conditions; including after a long period of shutdown. Before operating the machine, ensure the pump housing and case drain lines are free of air. Recommended mounting for a multiple pump stack is to arrange the highest power flow towards the input source. Consult Danfoss for nonconformance to these guidelines.</td>
</tr>
<tr>
<td><strong>Auxiliary cavity pressure</strong></td>
<td>Will be inlet pressure with internal charge pump. For reference see Operating Parameters. Will be case pressure with external charge supply. Please verify mating pump shaft seal capability.</td>
</tr>
</tbody>
</table>

## Features and Options

<table>
<thead>
<tr>
<th>Feature</th>
<th>Unit</th>
<th>Frame</th>
</tr>
</thead>
<tbody>
<tr>
<td>Torque at maximum displacement</td>
<td>N•m/bar [lbf•in/1000 psi]</td>
<td>0.67 [410] 0.88 [530] 1.19 [730] 1.59 [970] 2.07 [1260] 2.87 [1750] 3.97 [2433]</td>
</tr>
<tr>
<td>Mass moment of inertia of rotating components</td>
<td>kg•m² [slug•ft²]</td>
<td>0.0023 [0.0017] 0.0060 [0.0044] 0.0096 [0.0071] 0.0150 [0.0111] 0.023 [0.0170] 0.0380 [0.0280] 0.0650 [0.0479]</td>
</tr>
<tr>
<td>Mounting (per ISO 3019-1)</td>
<td>Flange</td>
<td>102-2 (SAE B) 127-4 (SAE C) 152-4 (SAE D) 165-4 (SAE E)</td>
</tr>
<tr>
<td>Rotation</td>
<td>Right hand or Left hand rotation</td>
<td></td>
</tr>
<tr>
<td>Main port configuration</td>
<td>Twin port Twin or side port Twin port</td>
<td></td>
</tr>
<tr>
<td>Case drain ports (SAE O-ring boss)</td>
<td>UNF thread (in.)</td>
<td>0.875–14 1.0625–12 1.0625–12 1.0625–12 1.3125–12 1.625–12 1.625–12</td>
</tr>
<tr>
<td>Other ports</td>
<td>SAE O-ring boss</td>
<td></td>
</tr>
<tr>
<td>Shafts</td>
<td>Spline, and tapered shafts available</td>
<td></td>
</tr>
<tr>
<td>Auxiliary mounting</td>
<td>SAE-A, B, C SAE-A, B, C, D SAE-A, B, C, D, E</td>
<td></td>
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</table>
## Technical Specifications

### Operating Parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Unit</th>
<th>Frame</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
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<tbody>
<tr>
<td>Input speed</td>
<td>min-1(rpm)</td>
<td></td>
<td>500</td>
<td>500</td>
<td>500</td>
<td>500</td>
<td>500</td>
<td>500</td>
<td>500</td>
</tr>
<tr>
<td>Minimum</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Rated Speed</td>
<td></td>
<td></td>
<td>4200</td>
<td>3900</td>
<td>3600</td>
<td>3300</td>
<td>3100</td>
<td>2600</td>
<td>2300</td>
</tr>
<tr>
<td>Maximum</td>
<td></td>
<td></td>
<td>4600</td>
<td>4250</td>
<td>3950</td>
<td>3650</td>
<td>3400</td>
<td>2850</td>
<td>2500</td>
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### Operating parameters

<table>
<thead>
<tr>
<th>System pressure</th>
<th>Maximum working pressure</th>
<th>bar</th>
<th>[psi]</th>
<th>450</th>
<th>[6525]</th>
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<tbody>
<tr>
<td>Maximum</td>
<td></td>
<td></td>
<td></td>
<td>480</td>
<td>[6960]</td>
</tr>
<tr>
<td>Minimum low loop pressure</td>
<td></td>
<td></td>
<td></td>
<td>45</td>
<td>[650]</td>
</tr>
<tr>
<td>Maximum low loop pressure</td>
<td></td>
<td></td>
<td></td>
<td>10</td>
<td>[145]</td>
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<tr>
<td>Charge pressure</td>
<td>Minimum</td>
<td>bar</td>
<td>[psi]</td>
<td>18</td>
<td>[261]</td>
</tr>
<tr>
<td>Maximum</td>
<td></td>
<td></td>
<td></td>
<td>34</td>
<td>[493]</td>
</tr>
<tr>
<td>Control pressure</td>
<td>Minimum (at corner power for EDC and FNR)</td>
<td>bar</td>
<td>[psi]</td>
<td>14</td>
<td>[203]</td>
</tr>
<tr>
<td>Maximum</td>
<td>Minimum (at corner power for NFPE)</td>
<td></td>
<td></td>
<td>22</td>
<td>[319]</td>
</tr>
<tr>
<td>Maximum</td>
<td></td>
<td></td>
<td></td>
<td>40</td>
<td>[580]</td>
</tr>
<tr>
<td>Charge pump inlet pressure</td>
<td>Rated</td>
<td>bar (absolute)</td>
<td>[in Hg vacuum]</td>
<td>0.7</td>
<td>[9]</td>
</tr>
<tr>
<td>Minimum (cold start)</td>
<td></td>
<td></td>
<td></td>
<td>0.2</td>
<td>[24]</td>
</tr>
<tr>
<td>Maximum</td>
<td></td>
<td></td>
<td></td>
<td>4.0</td>
<td>[58]</td>
</tr>
<tr>
<td>Case pressure</td>
<td>Rated</td>
<td>bar</td>
<td>[psi]</td>
<td>3.0</td>
<td>[44]</td>
</tr>
<tr>
<td>Maximum</td>
<td></td>
<td></td>
<td></td>
<td>5.0</td>
<td>[73]</td>
</tr>
<tr>
<td>Lip seal external pressure</td>
<td>Maximum</td>
<td>bar</td>
<td>[psi]</td>
<td>0.4</td>
<td>[5.8]</td>
</tr>
</tbody>
</table>

### Fluid Specification

#### Viscosity

| 1) | 5 [42] |
| 2) | 7 [49] |

**Recommended range**: 12 – 80 [66 – 370]

1600 [7500]

1) = Short term t < 1 min per incident and not exceeding 2 % of duty cycle based load-life.

#### Temperature

| 1) | -40°C [-40°F] |
| Rated | 104°C [220°F] |

**Recommended range**

60 – 85°C [140 – 185°F]

115°C [240°F]

1) Cold start = Short term t > 3 min, p ≤ 50 bar [725 psi], n ≤ 1000 min-1 (rpm).

2) At the hottest point, normally case drain port.
Operating Parameters

Input Speed

**Minimum speed** is the lowest input speed recommended during engine idle condition. Operating below minimum speed limits the pump’s ability to maintain adequate flow for lubrication and power transmission.

**Rated speed** is the highest input speed recommended at full power condition. Operating at or below this speed should yield satisfactory product life.

Operating conditions between rated and maximum speed should be restricted to less than full power and to limited periods of time.

**Maximum speed** is the highest operating speed permitted. Exceeding maximum speed reduces product life and can cause loss of hydrostatic power and braking capacity. For most drive systems, maximum unit speed occurs during downhill braking or negative power conditions.

---

**Warning**

Never exceed the maximum speed limit under any operating conditions.

During hydraulic braking and downhill conditions, the prime mover must be capable of providing sufficient braking torque in order to avoid pump over speed. This is especially important to consider for turbo-charged and Tier 4 engines.

For more information please see *Pressure and Speed Limits*, BLN-9884, when determining speed limits for a particular application.

Independent Braking System

**Unintended vehicle or machine movement hazard.** Exceeding maximum speed may cause a loss of hydrostatic drive line power and braking capacity. Machine manufacturer is responsible to provide a braking system, redundant to the hydrostatic transmission, sufficient to stop and hold the vehicle or machine in the event of hydrostatic drive power loss. The braking system must also be sufficient to hold the machine in place when full power is applied.

System Pressure

Hydraulic unit life depends on the speed and normal operating — or weighted average — pressure that can only be determined from a duty cycle analysis.

**System pressure** is the differential pressure between high pressure system ports. It is the dominant operating variable affecting hydraulic unit life. High system pressure, which results from high load, reduces expected life.

**Application pressure** is the high pressure relief or pressure limiter setting normally defined within the order code of the pump. This is the applied system pressure at which the drive line generates the maximum calculated pull or torque in the application.

**Maximum working pressure** is the highest recommended application pressure and is not intended to be a continuous pressure. Propel systems with application pressures at, or below this pressure should yield satisfactory unit life given proper component sizing. Application pressures above maximum working pressure will only be considered with duty cycle analysis and factory approval.

Pressure spikes are normal and must be considered when reviewing maximum working pressure.
### Operating Parameters

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Maximum pressure</strong></td>
<td>is the highest intermittent pressure allowed under any circumstances. Applications with applied pressures between rated and maximum require factory approval with complete application, duty cycle, and life expectancy analysis.</td>
</tr>
<tr>
<td><strong>Minimum low loop pressure</strong></td>
<td>must be maintained under all operating conditions to avoid cavitation. All pressure limits are differential pressures referenced to low loop (charge) pressure. Subtract low loop pressure from gauge readings to compute the differential.</td>
</tr>
</tbody>
</table>
Servo Pressure

Servo pressure is the pressure in the servo system needed to position and hold the pump on stroke. It depends on system pressure and speed. At minimum servo pressure the pump will run at reduced stroke depending on speed and pressure.

**Minimum servo pressure** at corner power holds the pump on full stroke at max speed and max pressure.

**Maximum servo pressure** is the highest pressure typically given by the charge pressure setting.

Charge Pressure

An internal charge relief valve regulates charge pressure. Charge pressure supplies the control with pressure to operate the swashplate and to maintain a minimum pressure in the low side of the transmission loop.

The charge pressure setting listed in the order code is the set pressure of the charge relief valve with the pump in neutral, operating at 1800 min\(^{-1}\) (rpm), and with a fluid viscosity of 32 mm\(^2\)/s [150 SUS].

Pumps configured with no charge pump (external charge supply) are set with a charge flow of 30 l/min [7.93 US gal/min] and a fluid viscosity of 32 mm\(^2\)/s [150 SUS].

The charge pressure setting is referenced to case pressure. Charge pressure is the differential pressure above case pressure.

**Minimum charge pressure** is the lowest pressure allowed to maintain a safe working condition in the low side of the loop. Minimum control pressure requirements are a function of speed, pressure, and swashplate angle, and may be higher than the minimum charge pressure shown in the Operating parameters tables.

**Maximum charge pressure** is the highest charge pressure allowed by the charge relief adjustment, and which provides normal component life. Elevated charge pressure can be used as a secondary means to reduce the swashplate response time.

Charge Pump Inlet Pressure

At normal operating temperature charge inlet pressure must not fall below rated charge inlet pressure (vacuum).

**Minimum charge inlet pressure** is only allowed at cold start conditions. In some applications it is recommended to warm up the fluid (e.g. in the tank) before starting the engine and then run the engine at limited speed.

**Maximum charge inlet pressure** may be applied continuously.

Case Pressure

Under normal operating conditions, the rated case pressure must not be exceeded. During cold start case pressure must be kept below maximum intermittent case pressure. Size drain plumbing accordingly.

The auxiliary pad cavity of axial pumps configured without integral charge pumps is referenced to case pressure. Units with integral charge pumps have auxiliary mounting pad cavities referenced to charge inlet (vacuum).

Possible component damage or leakage.

Operation with case pressure in excess of stated limits may damage seals, gaskets, and/or housings, causing external leakage. Performance may also be affected since charge and system pressure are additive to case pressure.
Operating Parameters

External Shaft Seal Pressure

In certain applications the input shaft seal may be exposed to external pressure. In order to prevent damage to the shaft seal the maximum differential pressure from external sources must not exceed 0.4 bar (5.8 psi) over pump case pressure.

The case pressure limits of the pump must also be followed to ensure the shaft seal is not damaged.

Caution

Regardles of the differential pressure across the shaft seal, the shaft seal has been known to pump oil from the external source (e.g. gear box) into the pump case.

Temperature

The high temperature limits apply at the hottest point in the transmission, which is normally the motor case drain. The system should generally be run at or below the quoted rated temperature.

The maximum intermittent temperature is based on material properties and should never be exceeded.

Cold oil will generally not affect the durability of the transmission components, but it may affect the ability of oil to flow and transmit power; therefore temperatures should remain 16 °C [30 °F] above the pour point of the hydraulic fluid.

The minimum temperature relates to the physical properties of component materials.

Size heat exchangers to keep the fluid within these limits. Danfoss recommends testing to verify that these temperature limits are not exceeded.

Viscosity

For maximum efficiency and bearing life, ensure the fluid viscosity remains in the recommended range.

The minimum viscosity should be encountered only during brief occasions of maximum ambient temperature and severe duty cycle operation.

The maximum viscosity should be encountered only at cold start.
**Filtration System**

To prevent premature wear, ensure only clean fluid enters the hydrostatic transmission circuit. A filter capable of controlling the fluid cleanliness to ISO 4406 class 22/18/13 (SAE J1165) or better, under normal operating conditions, is recommended.

These cleanliness levels can not be applied for hydraulic fluid residing in the component housing/case or any other cavity after transport.

The filter may be located on the pump (integral) or in another location (remote).

The integral filter has a filter bypass sensor to signal the machine operator when the filter requires changing. Filtration strategies include suction or pressure filtration. The selection of a filter depends on a number of factors including the contaminant ingestion rate, the generation of contaminants in the system, the required fluid cleanliness, and the desired maintenance interval. Filters are selected to meet the above requirements using rating parameters of efficiency and capacity.

Filter efficiency can be measured with a Beta ratio¹ (βX). For simple suction-filtered closed circuit transmissions and open circuit transmissions with return line filtration, a filter with a β-ratio within the range of $\beta_{35-45} = 75$ ($\beta_{10} \geq 2$) or better has been found to be satisfactory. For some open circuit systems, and closed circuits with cylinders being supplied from the same reservoir, a considerably higher filter efficiency is recommended. This also applies to systems with gears or clutches using a common reservoir.

For these systems, a charge pressure or return filtration system with a filter β-ratio in the range of $\beta_{15-20} = 75$ ($\beta_{10} \geq 10$) or better is typically required.

Because each system is unique, only a thorough testing and evaluation program can fully validate the filtration system. Please see Design Guidelines for Hydraulic Fluid Cleanliness Technical Information, 520L0467 for more information.

¹ Filter βx-ratio is a measure of filter efficiency defined by ISO 4572. It is defined as the ratio of the number of particles greater than a given diameter (“x” in microns) upstream of the filter to the number of these particles downstream of the filter.

---

**Warning**

Clogged filters can cause cavitation, which damages the charge pump. We recommend a filter bypass with a filter bypass sensor to prevent damage due to blocked suction filters.

---

**Filtration Options**

**Suction filtration – Option S**

The suction filter is placed in the circuit between the reservoir and the inlet to the charge pump, as shown below.

The use of a filter contamination monitor is recommended.

**Suction filtration**

![Suction filtration diagram](image-url)
System Design Parameters

Charge pressure filtration (partial charge pump flow)

Two types of pressure filtration exist for most Series 90 pumps. The two types are: remote pressure filtration (filter remotely mounted on vehicle) and integral pressure filtration (filter mounted to the endcap). Verify option availability in the size specific technical information.

In either case the filtration circuit is the same with the filter element situated in the circuit downstream the charge pump and upstream of the charge relief valve such that full charge flow is continuously filtered, as shown in the accompanying illustrations. Charge pressure filtration can mitigate high inlet vacuum in cold start-ups and provides fluid filtration immediately prior to entrance to the loop and the control system. Pressure filtration provides a higher level of filtering efficiency than suction filtration.

Filters used in charge pressure filtration circuits must be rated to at least 35 bar [508 psi] pressure. A 100 – 125 μm screen located in the reservoir or in the charge inlet line is recommended when using charge pressure filtration.

Technical data according to ISO 16889

<table>
<thead>
<tr>
<th>Nominal flow at 30mm²/s and ΔP 0.5 bar [7.3 psi] (clean filter element only)</th>
<th>Minimum β-ratio</th>
</tr>
</thead>
<tbody>
<tr>
<td>Short</td>
<td>60 l/min</td>
</tr>
<tr>
<td>Long</td>
<td>105 l/min</td>
</tr>
</tbody>
</table>

Remote charge pressure filtration

A special adapter head is available to allow for the charge filter to be located conveniently for easy service and replacement. Care should be taken to minimize the hydraulic pressure drops associated with long connecting lines, small diameter hoses, or restrictive port adaptors at the filter head or endcap. Ensure the normal operating pressure drop across the remote filtration in and out ports is sufficiently below the crack pressure setting of the recommended filter bypass valve.

Charge pressure filtration

⚠️ Warning

Remote filter heads without bypass and poor plumbing design can encounter excessive pressure drops that can lead to charge pump damage in addition to contaminants being forced through the filter media and into the transmission loop.

Fluid Selection

Ratings and performance data are based on operating with hydraulic fluids containing oxidation, rust and foam inhibitors. These fluids must possess good thermal and hydrolytic stability to prevent wear, erosion, and corrosion of pump components.

Never mix hydraulic fluids of different types.

Reservoir

The hydrostatic system reservoir should accommodate maximum volume changes during all system operating modes and promote de-aeration of the fluid as it passes through the tank. A suggested
System Design Parameters

Minimum total reservoir volume is \( \frac{5}{8} \) of the maximum charge pump flow per minute with a minimum fluid volume equal to \( \frac{1}{2} \) of the maximum charge pump flow per minute. This allows 30 seconds fluid dwell for removing entrained air at the maximum return flow. This is usually adequate to allow for a closed reservoir (no breather) in most applications.

Locate the reservoir outlet (charge pump inlet) above the bottom of the reservoir to take advantage of gravity separation and prevent large foreign particles from entering the charge inlet line. A 100-125 μm screen over the outlet port is recommended. Position the reservoir inlet (fluid return) to discharge below the normal fluid level, toward the interior of the tank. A baffle (or baffles) will further promote de-aeration and reduce surging of the fluid.

Case Drain

All single S90 pumps are equipped with multiple drain ports. Port selection and case drain routing must enable the pump housing to maintain a volume of oil not less than half full and normal operating case pressure limits of the unit are maintained. Case drain routing and design must consider unit case pressure ratings.

A case drain line must be connected to one of the case outlets to return internal leakage to the system reservoir.

Do not over torque the fitting on case drain port L2 (located on the side cover). The proper torque is 100 N•m [74 lbf•ft] maximum. Over torquing the fitting may change the neutral position of the swashplate.

Pump Life

Pump life depends on several factors, such as speed, pressure, and swashplate angle. For detailed product life calculation, please contact your Danfoss representative.

Charge Pump

Charge flow is required on all Series 90 pumps applied in closed circuit installations. The charge pump provides flow to make up internal leakage, maintain a positive pressure in the main circuit, provide flow for cooling and filtration, replace any leakage losses from external valving or auxiliary systems, and to provide flow and pressure for the control system.

Many factors influence the charge flow requirements and the resulting charge pump size selection. These factors include system pressure, pump speed, pump swashplate angle, type of fluid, temperature, size of heat exchanger, length and size of hydraulic lines, control response characteristics, auxiliary flow requirements, hydrostatic motor type, etc. When initially sizing and selecting hydrostatic units for an application, it is frequently not possible to have all the information necessary to accurately evaluate all aspects of charge pump size selection.

Unusual application conditions may require a more detailed review of charge pump sizing. Charge pressure must be maintained at a specified level under all operating conditions to prevent damage to the transmission. Danfoss recommends testing under actual operating conditions to verify this.

Charge pump sizing/selection

In most applications a general guideline is that the charge pump displacement should be at least 10% of the total displacement of all components in the system. Unusual application conditions may require a more detailed review of charge flow requirements. Refer to Selection of Drive line Components, BLN-9885, for a detailed procedure.

System features and conditions which may invalidate the 10% guideline include (but are not limited to):
System Design Parameters

- Continuous operation at low input speeds (< 1500 min⁻¹ (rpm))
- High shock loading and/or long loop lines
- High flushing flow requirements
- Multiple Low Speed High Torque motors
- High input shaft speeds

Bearing Loads and Life

In vehicle propel drives with no external shaft loads, and where the system pressure and swashplate angle are changing direction and magnitude regularly, the normal L20 bearing life (80% survival) will exceed the hydraulic life of the unit.

In non-propel drives, such as vibratory drives, conveyor drives and fan drives, the operating speed and pressure are often nearly constant and the swashplate angle is predominantly at maximum. These drives have a distinct duty cycle compared to a propulsion drive. In these types of applications, a bearing life review is recommended.

For bearing life, speed, pressure, swashplate angle, plus external loads will be considered. Other factors that affect bearing life include fluid type, viscosity, and cleanliness.

Applications with external shaft loads

External loads are found in applications where the pump is driven with a side/thrust load (belt drive or gear drive) as well as in installations with misalignment and improper concentricity between the pump and drive coupling. All external loads act to reduce bearing life.

In applications where you cannot avoid external radial shaft loads, orient the load to 0° or 180° position. Use tapered output shafts or clamp-type couplings where radial shaft loads are present.

In addition, external thrust loads can reduce bearing life in systems with low delta pressure or in combination with external radial loads/bending moments.

\[ \text{Re} = \frac{\text{Me}}{L} \]

\( \text{Me} = \) Shaft moment  
\( \text{L} = \) Flange distance  
\( \text{Re} = \) External force

Radial load position

<table>
<thead>
<tr>
<th>Parameter</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
</tr>
</thead>
</table>

* no tapered shaft available
System Design Parameters

If continuous applied external radial loads are 25% of the maximum allowable or more or thrust loads/bending moments known to occur, contact your Danfoss representative for an evolution of bearing life.

Avoid external thrust loads in either direction.

Understanding and Minimizing System Noise

Noise is transmitted in fluid power systems in two ways: as fluid borne noise, and structure borne noise.

Fluid-borne noise (pressure ripple or pulsation) is created as pumping elements discharge oil into the pump outlet. It is affected by the compressibility of the oil, and the pump's ability to transition pumping elements from high to low pressure. Pulsations travel through the hydraulic lines at the speed of sound (about 1400 m/s [4600 ft/sec] in oil) until there is a change (such as an elbow) in the line. Thus, amplitude varies with overall line length and position.

Structure born noise is transmitted wherever the pump casing connects to the rest of the system. The way system components respond to excitation depends on their size, form, material, and mounting.

System lines and pump mounting can amplify pump noise.

Follow these suggestions to help minimize noise in your application:

- Use flexible hoses.
- Limit system line length.
- If possible, optimize system line position to minimize noise.
- If you must use steel plumbing, clamp the lines.
- If you add additional support, use rubber mounts.
- Test for resonants in the operating range; if possible avoid them.

Sizing Equations

The following equations are helpful when sizing hydraulic pumps. Generally, the sizing process is initiated by an evaluation of the machine system to determine the required motor speed and torque to perform the necessary work function. Refer to Selection of drive line components, BLN-9885, for a more complete description of hydrostatic drive line sizing. First, the motor is sized to transmit the maximum required torque. The pump is then selected as a flow source to achieve the maximum motor speed.

**SI Units**

\[
\text{Output flow } Q = \frac{V_g \cdot n \cdot \eta_v}{1000} \quad (l/min.)
\]

\[
\text{Input torque } M = \frac{V_g \cdot \Delta p}{20 \cdot \pi \cdot \eta_m} \quad (N\cdot m)
\]

\[
\text{Input power } P = \frac{M \cdot n \cdot \pi}{30000} = \frac{Q \cdot \Delta p}{600 \cdot \eta_t} \quad (kW)
\]

**US Units**

\[
\text{Output flow } Q = \frac{V_g \cdot n \cdot \eta_v}{231} \quad (US \text{ gal/min.})
\]

\[
\text{Input torque } M = \frac{V_g \cdot \Delta p}{2 \cdot \pi \cdot \eta_m} \quad (lb\cdot \text{in.})
\]

\[
\text{Input power } P = \frac{M \cdot n \cdot \pi}{198000} = \frac{Q \cdot \Delta p}{1714 \cdot \eta_t} \quad (hp)
\]

Mounting Flange Loads

Adding tandem mounted auxiliary pumps and/or subjecting pumps to high shock loads may result in excessive loading of the mounting flange.
System Design Parameters

Applications which experience extreme resonant vibrations or shock may require additional pump support. The overhung load moment for multiple pump mounting may be estimated using the formula below.

Overhung load example

![Diagram showing overhung load example]

Estimated maximum and rated acceleration factors for some typical applications are shown in the table below.

<table>
<thead>
<tr>
<th>Application</th>
<th>Calculation factor</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Rated (vibratory)</td>
</tr>
<tr>
<td></td>
<td>(vibratory)</td>
</tr>
<tr>
<td></td>
<td>(shock)</td>
</tr>
<tr>
<td></td>
<td>G&lt;sub&gt;R&lt;/sub&gt;</td>
</tr>
<tr>
<td></td>
<td>G&lt;sub&gt;S&lt;/sub&gt;</td>
</tr>
<tr>
<td>Skid Steer Loader</td>
<td>8</td>
</tr>
<tr>
<td>Trencher (rubber tires)</td>
<td>3</td>
</tr>
<tr>
<td>Asphalt Paver</td>
<td>2</td>
</tr>
<tr>
<td>Windrower</td>
<td>2</td>
</tr>
<tr>
<td>Aerial Lift</td>
<td>1.5</td>
</tr>
<tr>
<td>Turf Care Vehicle</td>
<td>1.5</td>
</tr>
</tbody>
</table>

Use these values for a rough load estimation in the absence of specific data.
System Design Parameters

Typical G loads for various applications (continued)

<table>
<thead>
<tr>
<th>Application</th>
<th>Calculation factor</th>
<th>Rated (vibratory) acceleration $G_R$</th>
<th>Maximum (shock) acceleration $G_S$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Vibratory Roller</td>
<td>6</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>T000 165E</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Allowable overhung load moment values are shown in the following table.

Allowable overhung load moments

<table>
<thead>
<tr>
<th>Frame size</th>
<th>Rated moment (MR)</th>
<th>Shock load moment (MS)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>N•m</td>
<td>lbf•in</td>
</tr>
<tr>
<td>042</td>
<td>860</td>
<td>7600</td>
</tr>
<tr>
<td>055</td>
<td>1580</td>
<td>14 000</td>
</tr>
<tr>
<td>075</td>
<td>1580</td>
<td>14 000</td>
</tr>
<tr>
<td>100</td>
<td>1580</td>
<td>14 000</td>
</tr>
<tr>
<td>130</td>
<td>3160</td>
<td>28 000</td>
</tr>
<tr>
<td>180</td>
<td>6070</td>
<td>54 000</td>
</tr>
<tr>
<td>250</td>
<td>6070</td>
<td>54 000</td>
</tr>
</tbody>
</table>
## Master Model Code

### Series 90 Master Model Code Breakdown

<table>
<thead>
<tr>
<th>R</th>
<th>Size</th>
<th>M</th>
<th>P</th>
<th>J</th>
<th>G</th>
<th>N</th>
<th>F</th>
<th>L</th>
<th>H</th>
<th>T</th>
<th>W</th>
<th>Y</th>
<th>Z</th>
<th>K</th>
</tr>
</thead>
<tbody>
<tr>
<td>S90</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### S90 Rotation and Size Options

#### R – Rotation

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
</tr>
</thead>
<tbody>
<tr>
<td>R</td>
<td>Right hand [CW]</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>L</td>
<td>Left hand [CCW]</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>

#### Size

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
</tr>
</thead>
<tbody>
<tr>
<td>042</td>
<td>42 cc [2.56 in(^3)] max displacement per revolution</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>055</td>
<td>55 cc [3.36 in(^3)] max displacement per revolution</td>
<td></td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>075</td>
<td>75 cc [4.58 in(^3)] max displacement per revolution</td>
<td></td>
<td></td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>100</td>
<td>100 cc [6.10 in(^3)] max displacement per revolution</td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>130</td>
<td>130 cc [7.93 in(^3)] max displacement per revolution</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td></td>
<td></td>
</tr>
<tr>
<td>180</td>
<td>180 cc [10.98 in(^3)] max displacement per revolution</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>250</td>
<td>250 cc [15.26 in(^3)] max displacement per revolution</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
</tr>
</tbody>
</table>
## Master Model Code

### S90 Control Options

#### M – Controls

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
<th>042</th>
<th>044</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
</tr>
</thead>
<tbody>
<tr>
<td>CA</td>
<td>Cover plate without feedback link, no control</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>DC</td>
<td>3 position F-N-R solenoid control (12V, DC) DIN connector</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>DD</td>
<td>3 position F-N-R solenoid control (24V, DC) DIN connector</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>HF</td>
<td>HDC 2, std. porting, 3, 0-11 bar [44-160 psi]</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>KA</td>
<td>EDC, MS connector, std. porting, dual coil (14-85 mA)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>KN</td>
<td>EDC, MS connector, std. porting, 643 Ohm single coil (14-85 mA)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>KT</td>
<td>EDC DEUTSCH connector, std. porting, dual coil (14-85 mA)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>KP</td>
<td>EDC, Weatherpack connector, std. porting, dual coil (14-85 mA)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>MA</td>
<td>MDC with neutral start switch</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>MB</td>
<td>MDC with neutral start switch</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>FA</td>
<td>NFPE control with 12V Amp connector; proportional solenoid with pressure reducing valve (25 bar)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FB</td>
<td>NFPE control with 24V Amp connector; proportional solenoid with pressure reducing valve (25 bar)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FC</td>
<td>NFPE control with 12V Amp connector; proportional solenoid with pressure reducing valve (32 bar)</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FD</td>
<td>NFPE control with 24V Amp connector; proportional solenoid with pressure reducing valve (32 bar)</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FG</td>
<td>NFPE control with 12V Amp connector; proportional solenoid with pressure reducing valve (32 bar) fast response</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FH</td>
<td>NFPE control with 24V Amp connector; proportional solenoid with pressure reducing valve (32 bar) fast response</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>FK</td>
<td>NFPE control with 12V Amp connector; proportional solenoid with pressure reducing valve (25 bar)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
</tr>
<tr>
<td>FL</td>
<td>NFPE control with 24V Amp connector; proportional solenoid with pressure reducing valve (25 bar)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
</tr>
<tr>
<td>FM</td>
<td>NFPE control with 12V Amp connector; proportional solenoid with pressure reducing valve (32 bar) fast response</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
</tr>
<tr>
<td>FN</td>
<td>NFPE control with 24V Amp connector; proportional solenoid with pressure reducing valve (32 bar)</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
</tr>
</tbody>
</table>
### S90 Pressure, Aux Mounting, Ports, Filtration, Displacement Limitation

**P – High pressure regulation**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Pressure limiter for port A and B (140-450 bar)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>2</td>
<td>High pressure relief valves for port A and B (90-450 bar)</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>

**J – Auxiliary Mounting Pad**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
</tr>
</thead>
<tbody>
<tr>
<td>AB</td>
<td>SAE-A with sealed cover, 9 teeth coupling</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>BB</td>
<td>SAE-B with sealed cover, 15 teeth coupling</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>BC</td>
<td>SAE-B with sealed cover, 13 teeth coupling</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>CD</td>
<td>SAE-C with sealed cover, 4 bolt adapter, 14 teeth coupling</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>DE</td>
<td>SAE-D with sealed cover, 13 teeth coupling</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>EF</td>
<td>SAE-E with sealed cover, 13 teeth coupling</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
<tr>
<td>NN</td>
<td>No auxiliary mounting pad</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
</tr>
</tbody>
</table>

**G – Endcap ports**

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
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**N – Filtration**

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**F – Displacement limitation**

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<th>130</th>
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<th>250</th>
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### Master Model Code

#### S90 Shaft and Charging System

**L – Shaft Options**

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**H – Charging System**

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<td>External charge pump with internal charge pressure relieve valve for units with auxiliary mounting pad</td>
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<td>N</td>
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# Master Model Code

## S90 Control Orifice Options

### T – Control Orifice Options for MDC

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<th>Drain TB</th>
<th>Servo A</th>
<th>Servo B</th>
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* No orifice installed in control; orifice hole in control spool

### T – Control Orifice Options for EDC

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<th>Servo A</th>
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### T – Control Orifice Options for FNR

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### T – Control Orifice Options for HDC

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<th>Drain TB</th>
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### T – Control Orifice Options for NFPE

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### Master Model Code

**S90 Special Hardware and Pressure Settings**

#### W – Special Hardware Features

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<th>130</th>
<th>180</th>
<th>250</th>
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<td>GCA</td>
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<td>GLA</td>
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</tbody>
</table>

#### Y – High Pressure Setting A

<table>
<thead>
<tr>
<th></th>
<th></th>
<th>26</th>
<th>32</th>
<th>35</th>
<th>38</th>
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<th>42</th>
</tr>
</thead>
<tbody>
<tr>
<td>26</td>
<td>260 bar</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>32</td>
<td>320 bar</td>
<td></td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
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</tr>
<tr>
<td>35</td>
<td>350 bar</td>
<td></td>
<td></td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>38</td>
<td>380 bar</td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td>X</td>
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</tr>
<tr>
<td>40</td>
<td>400 bar</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
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<tr>
<td>42</td>
<td>420 bar</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
</tr>
</tbody>
</table>

#### Z – High Pressure Setting B

<table>
<thead>
<tr>
<th></th>
<th></th>
<th>26</th>
<th>32</th>
<th>35</th>
<th>38</th>
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</tr>
</thead>
<tbody>
<tr>
<td>26</td>
<td>260 bar</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>32</td>
<td>320 bar</td>
<td></td>
<td>X</td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>35</td>
<td>350 bar</td>
<td></td>
<td></td>
<td>X</td>
<td>X</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>38</td>
<td>380 bar</td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>40</td>
<td>400 bar</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
<td></td>
</tr>
<tr>
<td>42</td>
<td>420 bar</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>X</td>
</tr>
</tbody>
</table>

#### K – Charge Pressure Setting

<table>
<thead>
<tr>
<th></th>
<th></th>
<th>20</th>
<th>22</th>
<th>24</th>
<th>26</th>
<th>28</th>
<th>30</th>
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</thead>
<tbody>
<tr>
<td>20</td>
<td>200 bar</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>22</td>
<td>220 bar</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>24</td>
<td>240 bar</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>26</td>
<td>260 bar</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>28</td>
<td>280 bar</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>30</td>
<td>300 bar</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>32</td>
<td>320 bar</td>
<td>X</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>34</td>
<td>340 bar</td>
<td>X</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

---

Technical Information

Series 90 Axial Piston Pumps
Control Features

3-Position (FNR) Electric Control - DC, DD

The 3-Position (FNR) control uses an electric input signal to switch the pump to a full stroke position. To use the FNR control in a PLUS+1 Guide application, download HWD file 10106826 from www.Danfoss.com/PLUS+1.

⚠️ Warning

Avoid designing a system which places the swashplate into full stroke when control operation is blocked by contamination.

Solenoid connector

Solenoid plug face for DIN 43650 connector

DANFOSS
matting parts kit
Part No. K09129

Voltage between terminals 1 and 2

Pump displacement vs. electrical signal

<table>
<thead>
<tr>
<th>Code</th>
<th>Voltage</th>
<th>Current</th>
<th>Connector</th>
</tr>
</thead>
<tbody>
<tr>
<td>DC</td>
<td>12 Vdc</td>
<td>340 mA</td>
<td>DIN 46350</td>
</tr>
<tr>
<td>DD</td>
<td>24 Vdc</td>
<td>170 mA</td>
<td>DIN 46350</td>
</tr>
</tbody>
</table>
Response time

The time required for the pump to change from zero to full flow (acceleration), or full flow to zero (deceleration), is a function of the size of the orifice, the charge pressure, valve plates and other vehicle dynamics.

A range of orifice sizes are available for the Series 90 FNR Control to assist in matching the rate of swashplate response to the acceleration and deceleration requirements of the application. Testing should be carried out to determine the proper orifice selection for the desired response. For more information regarding response time for individual orifices, please contact your Danfoss representative.

Pump output flow direction vs. control signal

<table>
<thead>
<tr>
<th>Input shaft rotation</th>
<th>CW</th>
<th>CCW</th>
</tr>
</thead>
<tbody>
<tr>
<td>Signal at solenoid</td>
<td>A</td>
<td>B</td>
</tr>
<tr>
<td>Port A flow (M1)</td>
<td>Out</td>
<td>In</td>
</tr>
<tr>
<td>Port B flow (M2)</td>
<td>In</td>
<td>Out</td>
</tr>
<tr>
<td>Servo cylinder (side)</td>
<td>M5 (2)</td>
<td>M4 (1)</td>
</tr>
</tbody>
</table>

⚠️ Warning

Avoid designing a system which puts the swashplate into full stroke when control operation is blocked by contamination.

Electric Displacement Control (EDC), Options KA, KP, KT

The electric displacement control uses an electrohydraulic Pressure Control Pilot (PCP) valve to control the pilot pressure. The PCP converts an electrical input signal to a hydraulic input signal to operate a 4-way servo valve, which ports hydraulic pressure to either side of a double acting servo piston. The servo piston tilts the cradle swashplate, thus varying the pump’s displacement from full displacement in one direction to full displacement in the opposite direction.

The control has a mechanical feedback mechanism which moves the servo valve in relation to the input signal and the angular position of the swashplate. The electrical displacement control is designed so the angular rotation of the swashplate (pump displacement) is proportional to the electrical input signal. Due to normal operating force changes, the swashplate tends to drift from the position preset by the machine operator. Drift, sensed by feedback linkage system connecting the swashplate to the control valve, will activate the valve and supply pressure to the servo piston, maintaining the swashplate in its preset position.

Features and Benefits

- The electric displacement control is a high gain control: With only a small change of the input current, the servo valve moves to a full open position thus porting maximum flow to the servo cylinder.
- Oil filled PCP case lengthens control life by preventing moisture ingestion and dampening component vibrations.
- All electrical displacement controls are equipped with dual coil PCPs. The user has the option of using a single coil or both coils (in series or parallel).
Control Features

- Internal mechanical stops on the servo valve allow rapid changes in input signal voltages without damaging the control mechanism.
- Precision parts provide repeatable accurate displacement settings.
- The swashplate is coupled to a feedback mechanism. The control valve drains the ends of the servo piston when an electric input signal is not present.

Benefits

- Pump returns to neutral after prime mover shuts down
- Pump returns to neutral if external electrical input signal fails or if there is a loss of charge pressure

Electric displacement control schematic

Cross-section

To use the EDC control in a PLUS+1 Guide application, download HWD file 10106626 from www.Danfoss.com/Plus1.
Control Features

Electrical Characteristics

<table>
<thead>
<tr>
<th>PUMP SHAFT ROTATION</th>
<th>One of Dual Coils</th>
<th>Dual Coils in Parallel</th>
<th>Dual Coils in Series</th>
<th>Produces Flow Out of Pump Port</th>
</tr>
</thead>
<tbody>
<tr>
<td>Clockwise</td>
<td>A or C</td>
<td>A and C</td>
<td>A</td>
<td>A</td>
</tr>
<tr>
<td>Clockwise</td>
<td>B or D</td>
<td>B and D</td>
<td>D</td>
<td>C</td>
</tr>
<tr>
<td>Counterclockwise</td>
<td>A or C</td>
<td>A and C</td>
<td>A</td>
<td>B</td>
</tr>
<tr>
<td>Counterclockwise</td>
<td>B or D</td>
<td>B and D</td>
<td>D</td>
<td>A</td>
</tr>
<tr>
<td>Start Current</td>
<td>A/B 14 mA±3 mA</td>
<td>14 mA with 0.13 Vdc</td>
<td>7 mA with 0.25 Vdc</td>
<td></td>
</tr>
<tr>
<td>Full Stroke Current</td>
<td>A/B 85 mA±11 mA</td>
<td>85 mA with 0.75 Vdc</td>
<td>43 mA with 1.55 Vdc</td>
<td></td>
</tr>
<tr>
<td>Start Current</td>
<td>C/D 14 mA±3 mA</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Full Stroke Current</td>
<td>C/D 85 mA±11 mA</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

The EDC is designed to be controlled from a DC current source or voltage source. Pulse width modulation (PWM) is not required. If a PWM signal is used to carry frequency greater than 200 Hz, do not use a pulse current of more than 120% of that required for full output.

Control signal requirements

Recommended PWM signal is 200 Hz, avoid exceeding 440 Hz.

⚠️ Warning

Maximum input current under any condition: 250 mA
PWM frequency: 200 Hz
Coil resistance at 24°C [75°F]:
A-B coil 20 Ω
C-D coil 16 Ω

MS connector (option KA) MS 3102C-14S-2P

Danfoss mating parts kit
Part no. K01588
Ident No. 615062
Control Features

Packard® Weather-Pack (option KP) 4-way shroud connector

Danfoss mating parts kit
Part no. K03384
(female terminals)

Pump displacement vs. control current

Deutsch DT Series connector (option KT)

4 pin Deutsch® Plug DT Series Connector

Response time

The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a function of the size of the orifice in the control flow passage, charge pressure, valve plate and other vehicle dynamics.

A range of orifice sizes is available for the Series 90 Electric Displacement Control to assist in matching the rate of swashplate response to the acceleration and deceleration requirements of the application. Testing should be carried out to determine the proper orifice selection for the desired response.

For more information regarding response times for individual orifices, contact your Danfoss representative.
Control Features

Pump output flow direction vs. control current

**EDC using a single coil or dual coils in parallel (A and C common, B and D common)**

<table>
<thead>
<tr>
<th>Input shaft rotation</th>
<th>CW</th>
<th>CCW</th>
</tr>
</thead>
<tbody>
<tr>
<td>Positive current to term</td>
<td>A or C</td>
<td>B or D</td>
</tr>
<tr>
<td>Port A flow (M1)</td>
<td>Out</td>
<td>In</td>
</tr>
<tr>
<td>Port B flow (M2)</td>
<td>In</td>
<td>Out</td>
</tr>
<tr>
<td>Servo cylinder (side)</td>
<td>M5 (2)</td>
<td>M4 (1)</td>
</tr>
</tbody>
</table>

**EDC using a dual coil in series (B and C common)**

<table>
<thead>
<tr>
<th>Input shaft rotation</th>
<th>CW</th>
<th>CCW</th>
</tr>
</thead>
<tbody>
<tr>
<td>Positive current to term</td>
<td>A</td>
<td>D</td>
</tr>
<tr>
<td>Port A flow (M1)</td>
<td>Out</td>
<td>In</td>
</tr>
<tr>
<td>Port B flow (M2)</td>
<td>In</td>
<td>Out</td>
</tr>
<tr>
<td>Servo cylinder (side)</td>
<td>M5 (2)</td>
<td>M4 (1)</td>
</tr>
</tbody>
</table>

Refer to *Installation Drawings* for port locations.

For further information on EDC controls, refer to *Electrical Displacement Control For Series 90 Pumps, BLN-95-9060*.

Manual Over Ride (MOR)

EDC controls are available with a Manual Over Ride (MOR) which is intended for temporary actuation of the control to aid in pump diagnostics.

⚠️ **Warning**

Using the MOR to control the pump will not result in proportional control.

Refer to the control flow table in the size specific technical information manual for the relationship of solenoid to direction of flow.

⚠️ **Warning**

The vehicle must always be in a safe condition (i.e. vehicle lifted off the ground) when using the MOR function. The MOR lever has a must be manually actuated to be engaged. Moving the plunger mechanically moves the pilot stage armature which allows the pump to go on stroke. The MOR should be engaged anticipating a full stroke response from the pump.

<table>
<thead>
<tr>
<th>Pump Phasing With EDC Manual Operator (MOR)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pump Rotation</td>
</tr>
<tr>
<td>----------------</td>
</tr>
<tr>
<td>CW CCW</td>
</tr>
<tr>
<td></td>
</tr>
</tbody>
</table>
Control Features

![Control Features Image]

**Warning**

Unintended MOR operation will cause the pump to go into stroke.

Hydraulic Displacement Control (HDC), Option HF

**Warning**

Avoid designing a system which puts swashplate into full stroke when control operation is blocked by contamination.

**Operation**

The hydraulic displacement control uses a hydraulic input signal to operate a 4-way servo valve, which ports hydraulic pressure to either side of a double acting servo piston. The servo piston tilts the cradle swashplate, thus varying the pump’s displacement from full displacement in one direction to full displacement in the opposite direction.

The control has a mechanical feedback mechanism which moves the servo valve in relation to the input signal and the angular rotation of the swashplate. The hydraulic displacement control is designed so the angular position of the swashplate (pump displacement) is proportional to the hydraulic input signal pressure. Due to normal operating force changes, the swashplate tends to drift from the position preset by the machine operator. Drift, sensed by feedback linkage system connecting the swashplate to the control valve, activates the valve to supply pressure to the servo piston, maintaining the swashplate in its preset position.

**Features and Benefits**

- The hydraulic displacement control is a high gain control: With only small change of the input signal, the servo valve moves to a full open position porting maximum flow to the servo cylinder.
- Internal mechanical stops on the servo valve allow rapid changes in input signal pressure without damaging the control mechanism.
- Precision parts provide repeatable, accurate displacement settings with a given input signal.
- The swashplate is coupled to a feedback mechanism. The control valve drains the ends of the servo piston when an input signal is not present.

**Benefits:**
Control Features

- Simple - low cost design.
- Pump returns to neutral after prime mover shuts down.
- Pump returns to neutral if there is a loss of input signal pressure or if there is a loss of charge pressure.

Hydraulic displacement control schematic

Cross-section

⚠️ Warning

Maximum allowable signal pressure is 60 bar [870 psi]. Exceeding allowable signal pressure will cause damage to the control.

Response time

The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a function of the size of the orifice in the control flow passage, charge pressure, valve plates and other vehicle dynamics.

A range of orifice sizes are available for the Series 90 hydraulic displacement control to assist in matching the rate of swashplate response to the acceleration and deceleration requirements of the application. Testing should be carried out to determine the proper orifice selection for the desired response.

For more information regarding response time for individual orifices, please contact your Danfoss representative.
Control Features

Pump displacement vs. signal pressure

Hydraulic signal pressure range*

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>a</td>
<td>3 ± 0.5 bar</td>
<td>[43 ± 6 psi]</td>
</tr>
<tr>
<td>b</td>
<td>11 ± 0.5 bar</td>
<td>[160 ± 6 psi]</td>
</tr>
</tbody>
</table>

Pump output flow direction vs. control pressure

<table>
<thead>
<tr>
<th></th>
<th>CW</th>
<th>CCW</th>
</tr>
</thead>
<tbody>
<tr>
<td>Control pressure to port</td>
<td>X1</td>
<td>X2</td>
</tr>
<tr>
<td>Port A flow (M1)</td>
<td>Out</td>
<td>In</td>
</tr>
<tr>
<td>Port B flow (M2)</td>
<td>In</td>
<td>Out</td>
</tr>
<tr>
<td>Servo cylinder (side)</td>
<td>M5 (2)</td>
<td>M4 (1)</td>
</tr>
</tbody>
</table>

Refer to Installation Drawings, for port locations.

Manual Displacement Control (MDC), Options MA, MB

⚠️ Warning

Avoid designing a system which puts swashplate into full stroke when control operation is blocked by contamination.

The manual displacement control converts a mechanical input signal to a hydraulic signal that tilts the cradle swashplate through an angular rotation varying the pump's displacement from full displacement in one direction to full displacement in the opposite direction.

The manual displacement control has a mechanical feedback mechanism which moves a servo valve in the proper relationship to the input signal and the angular position of the swashplate. The control is designed so that the angular rotation of the swashplate is proportional to the mechanical input signal. The control is designed with an internal override mechanism which allows the mechanical input to be moved at a faster rate than the movement of the swashplate without damage to the control.
## Control Features

### Features and benefits

- Precision parts provide repeatable, accurate displacement settings with a given input signal.
- The manual displacement control is a high gain control: With only small movement of the control handle (input signal), the servo valve moves to full open position porting maximum flow to the servo cylinder. This is a high response system with low input force.
- The integral override mechanism allows rapid changes in input signal without damaging the control mechanism.
- Precision parts provide repeatable, accurate displacement settings with a given input signal.
- The double-acting servo piston is coupled to a spring centering mechanism. The servo control valve is spring centered such that with no input signal the servo valve is open centered and thus no fluid is ported to the servo cylinder.

### Benefits:

- Pump returns to neutral after prime mover shuts down.
- Pump returns to neutral if external control linkage fails at the control handle or if there is a loss of charge pressure.

### Manual displacement control schematic

![Schematic diagram](Image)

### Cross-section

![Cross-section](Image)

### External control handle requirements

- Torque required to move handle to maximum displacement is 0.68 to 0.9 N-m [6 to 8 lbf-in].
- Torque required to hold handle at given displacement is 0.34 to 0.57 N-m [3 to 5 lbf-in].
- Torque required to overcome the override mechanism is 1.1 to 2.3 N-m [10 to 20 lbf-in] with the maximum torque required for full forward to full reverse movement.
- Maximum allowable input torque is 17 N-m [150 lbf-in].

Pump displacement vs. control lever rotation
Control Features

Control lever rotation range

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>a</td>
<td>0.5° - 4.5°</td>
</tr>
<tr>
<td>b</td>
<td>24° - 30°</td>
</tr>
</tbody>
</table>

Volumetric efficiencies of the system will have impacts on the start- and end input- commands.

Response Time

The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a function of the size of the orifice and charge pressure in the control, charge pressure, valve plates and other vehicle dynamics.

A range of orifice sizes is available for the Series 90 manual displacement control to assist in matching the rate of swashplate response to the acceleration and deceleration requirements of the application. Testing should be carried out to determine the proper orifice selection for the desired response. For more information regarding response time for individual orifices, please contact your Danfoss representative.

Pump output flow direction vs. control handle rotation

MDC handle rotation parameters

<table>
<thead>
<tr>
<th>Input shaft rotation</th>
<th>CW</th>
<th>CCW</th>
</tr>
</thead>
<tbody>
<tr>
<td>Handle rotation</td>
<td>A</td>
<td>A</td>
</tr>
<tr>
<td></td>
<td>B</td>
<td>B</td>
</tr>
<tr>
<td>Port A flow (M1)</td>
<td>Out</td>
<td>In</td>
</tr>
<tr>
<td>Port B flow (M2)</td>
<td>In</td>
<td>Out</td>
</tr>
<tr>
<td>Servo cylinder (side)</td>
<td>M5 (2)</td>
<td>M4 (1)</td>
</tr>
</tbody>
</table>

Refer to **Installation Drawings** for handle connection requirements.
Control Features

Neutral start switch (NSS) for MDC

The neutral start switch is an optional feature available with the MDC. When connected properly with the vehicle’s electrical system, the neutral start switch ensures that the prime mover can start only when the control is in neutral position.

Non Feedback Proportional Electric Control (NFPE)

The Non Feedback Proportional Electric (NFPE) control is an electrical automotive control in which an electrical input signal activates one of two proportional solenoids that port charge pressure to either side of the pump servo cylinder. The NFPE control has no mechanical feedback mechanism.

The pump displacement is proportional to the solenoid signal current, but it also depends upon pump input speed and system pressure. This characteristic also provides a power limiting function by reducing the pump swashplate angle as system pressure increases.

Control response

Series 90 controls are available with optional control passage orifices to assist in matching the rate of swashplate response to the application requirements (e.g. in the event of electrical failure). Software ramp or rate limiting should be used to control vehicle response in normal operation. The time required for the pump output flow to change from zero to full flow (acceleration) or full flow to zero (deceleration) is a net function of spool porting, orifices, charge pressure, valve plates and other vehicle dynamics. A swashplate response table is available for each frame indicating available swashplate response times. Testing a prototype system to verify the software and orifice selection provide the desired response.

Series 90 pumps have many orificing combinations, however, software is the best means of controlling the swashplate response in normal operating conditions. Mechanical servo orifices should be used only for fail-safe return to neutral in the event of an electrical failure.

Pump Displacement vs. Input Signal
**Control Features**

*NFPE Schematic*

**NFPE control used with a Danfoss microcontroller**

- Creep mode
- Two automotive control ramps via mode switch
- Engine overspeed protection
- Electric control
- Anti-stall function
- Smooth operation
- Electronic ramp control is superior to hydraulic control with orifices

**Input signal requirements**

The NFPE control requires a pulse-width-modulated (PWM) input current to optimize performance. The recommended PWM frequency is 100 Hz. The minimum PWM frequency is 80 Hz.

**Solenoid data**

<table>
<thead>
<tr>
<th>Option</th>
<th>FA</th>
<th>FB</th>
<th>FC</th>
<th>FD</th>
<th>FK</th>
<th>FL</th>
<th>FM</th>
<th>FN</th>
<th>FG</th>
<th>FH</th>
</tr>
</thead>
<tbody>
<tr>
<td>Frame Size</td>
<td>42cc, 55cc, 100cc</td>
<td>75cc</td>
<td>75cc, 100cc, 130cc, 180cc</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Voltage [V]</td>
<td>12</td>
<td>24</td>
<td>12</td>
<td>24</td>
<td>12</td>
<td>24</td>
<td>12</td>
<td>24</td>
<td>12</td>
<td>24</td>
</tr>
<tr>
<td>Maximum Current [mA]</td>
<td>1500</td>
<td>750</td>
<td>1500</td>
<td>750</td>
<td>1500</td>
<td>750</td>
<td>1500</td>
<td>750</td>
<td>1500</td>
<td>750</td>
</tr>
<tr>
<td>Start Current [mA]</td>
<td>440</td>
<td>220</td>
<td>440</td>
<td>220</td>
<td>440</td>
<td>220</td>
<td>440</td>
<td>220</td>
<td>440</td>
<td>220</td>
</tr>
<tr>
<td>End Current [mA]</td>
<td>1290</td>
<td>645</td>
<td>1290</td>
<td>645</td>
<td>1290</td>
<td>645</td>
<td>1290</td>
<td>645</td>
<td>1290</td>
<td>645</td>
</tr>
<tr>
<td>Coil Resistance [Ohm]</td>
<td>4.72±5%</td>
<td>20.8±5%</td>
<td>5.3±5%</td>
<td>21.2±5%</td>
<td>4.72±5%</td>
<td>4.72±5%</td>
<td>4.72±5%</td>
<td>4.72±5%</td>
<td>4.98±3%</td>
<td>20.6±3%</td>
</tr>
<tr>
<td>PWM Range [Hz]</td>
<td>70-200</td>
<td>70-200</td>
<td>70-200</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>PWM Prefered [Hz]</td>
<td>200</td>
<td>200</td>
<td>200</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Protection Class</td>
<td>up to IP6K6/IPX7/IPX9K</td>
<td>up to IP6K6/IPX7/IPX9K</td>
<td>IP65 DIN 40050</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Connector</td>
<td>Amp Junior Timer</td>
<td>AMP Junior Timer</td>
<td>Amp Junior Timer</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Control Features

* PWM Signal Required for Optimum Control Performance.

To use the NFPE control in a PLUS+1 application, download the appropriate file from www.Danfoss.com/PLUS+1.

**NFPE pump displacement vs. input signal**

<table>
<thead>
<tr>
<th>Shaft rotation</th>
<th>CW</th>
<th>CCW</th>
</tr>
</thead>
<tbody>
<tr>
<td>Active solenoid</td>
<td>1 and A</td>
<td>2 and B</td>
</tr>
<tr>
<td>Port A flow</td>
<td>Out</td>
<td>In</td>
</tr>
<tr>
<td>Port B flow</td>
<td>In</td>
<td>Out</td>
</tr>
<tr>
<td>Servo cylinder</td>
<td>M5</td>
<td>M4</td>
</tr>
</tbody>
</table>

The NFPE control uses an AMP® Junior Power Timer connector. The solenoids are compatible with Danfoss microcontrollers and joysticks.

![Amp Junior Power Timer 2 Pin Connector](image-url)
Overpressure protection

The Series 90 pumps are designed with a sequenced pressure limiting system and high pressure relief valves. When the preset pressure is reached, the pressure limiter system acts to rapidly de-stroke the pump to limit the system pressure. For unusually rapid load application, the high pressure relief valve is also available to limit the pressure level. The pressure limiter sensing valve acts as the pilot for the relief valve spool, such that the relief valve is sequenced to operate above the pressure limiter level.

Both the pressure limiter sensing valves and relief valves are built into the multi-function valves located in the pump endcap. The sequenced pressure limiter/high pressure relief valve system in the Series 90 provides an advanced design of overpressure protection.

The pressure limiter avoids system overheating associated with relief valves and the sequenced relief valves are available to limit pressure spikes which exist in severe operating conditions.

Because the relief valves open only during extremely fast pressure spike conditions, heat generation is minimized during the short time that they might be open. For some applications, such as dual path vehicles, the pressure limiter function may be defeated such that only the relief valve function remains. The relief response is approximately 20 ms whether used with or without the pressure limiter function.

Pressure limiting function

When set pressure is exceeded, the pressure sensing valve (A) flows oil through passage (B) and across an orifice in the control spool raising pressure on the servo which was at low pressure. Servo pressure relief valves (C) limit servo pressure to appropriate levels. The pressure limiter action cancels the input command of the displacement control and tends to equalize servo pressure. Swashplate moments assist to change the displacement as required to maintain system pressure at the set point. The HPRV is always set 30 bar above the pressure limiter setting.

HPRVs are factory set at a low flow condition. Any application or operating condition which leads to elevated HPRV flow will cause a pressure rise with flow above a valve setting. Consult factory for application review. Excessive operation of the HPRV will generate heat in the closed loop and may cause damage to the internal components of the pump.

Multifunction valve, pressure limiter, pressure regulation, option 1
Features and Options

Bypass Function

In some applications it is desirable to bypass fluid around the variable displacement pump when pump shaft rotation is either not possible or not desired. For example, an inoperable vehicle may be moved to a service or repair location or winched onto a trailer without operating the prime mover. To provide for this, Series 90 pumps are designed with a bypass function.

The bypass is operated by mechanically rotating the bypass hex on both multifunction valves three (3) turns counterclockwise (CCW). This connects working loop A and B and allows fluid to circulate without rotating the pump and prime mover.

⚠️ Warning

Excessive speeds and extended load/vehicle movement must be avoided while moving in bypass function. The load or vehicle should be moved not more than 20% of maximum speed and for a duration not exceeding 3 minutes. Damage to drive motor(s) is possible. When the bypass function is no longer needed care should be taken to re-seat the HPRV hex plugs to the normal operating position.

⚠️ Warning

Possible pump and/or motor damage.

Bypass valves are intended for moving a machine or vehicle for very short distances at very slow speeds. They are NOT intended as tow valves.

Auxiliary Mounting Pads

Auxiliary mounting pad specifications

<table>
<thead>
<tr>
<th>Mounting pad</th>
<th>Option code</th>
<th>Spline coupling</th>
<th>Frame size/Maximum torque N•m [lbf•ft]</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>042</td>
</tr>
<tr>
<td>SAE D</td>
<td>DE</td>
<td>13T 8/16</td>
<td>n/a</td>
</tr>
<tr>
<td>SAE E</td>
<td>EF</td>
<td>13T 8/16</td>
<td>n/a</td>
</tr>
<tr>
<td>SAE E</td>
<td>EG</td>
<td>27T 16/32</td>
<td>n/a</td>
</tr>
</tbody>
</table>

Mating pump requirements

The accompanying drawing provides the dimensions for the auxiliary pump mounting flange and shaft. Pump mounting flanges and shafts with the dimensions noted below are compatible with the auxiliary mounting pads on the Series 90 pumps. An O-ring is required when a pump is bolted to an aux pad. Refer to outline drawings for more details and O-ring dimensions.
Features and Options

**Auxiliary pump mounting flange and shaft**

![Diagram showing auxiliary pump mounting flange and shaft specifications](image)

**Auxiliary pump dimensions**

<table>
<thead>
<tr>
<th>Flange size</th>
<th>Units</th>
<th>P diameter</th>
<th>B maximum</th>
<th>D</th>
<th>F minimum</th>
</tr>
</thead>
<tbody>
<tr>
<td>SAE A</td>
<td>mm [in]</td>
<td>82.55 [3.25]</td>
<td>7.4 [0.29]</td>
<td>32</td>
<td>13.5 [0.53]</td>
</tr>
<tr>
<td>SAE B</td>
<td>101.6 [4.00]</td>
<td>10.7 [0.42]</td>
<td>41</td>
<td>14.2 [0.56]</td>
<td></td>
</tr>
<tr>
<td>SAE B-B</td>
<td>101.6 [4.00]</td>
<td>10.7 [0.42]</td>
<td>46</td>
<td>16.1 [0.63]</td>
<td></td>
</tr>
<tr>
<td>SAE C</td>
<td>127.0 [5.00]</td>
<td>14.3 [0.56]</td>
<td>56</td>
<td>18.3 [0.72]</td>
<td></td>
</tr>
<tr>
<td>SAE D</td>
<td>152.4 [6.00]</td>
<td>14.3 [0.56]</td>
<td>75</td>
<td>20.8 [0.82]</td>
<td></td>
</tr>
<tr>
<td>SAE E 13 teeth</td>
<td>165.1 [6.50]</td>
<td>18.0 [0.71]</td>
<td>75</td>
<td>20.8 [0.82]</td>
<td></td>
</tr>
<tr>
<td>SAE E 27 teeth</td>
<td>165.1 [6.50]</td>
<td>18.0 [0.71]</td>
<td>75</td>
<td>27.0 [1.06]</td>
<td></td>
</tr>
</tbody>
</table>

**Displacement Limiter**

All Series 90 pumps are designed with optional mechanical displacement (stroke) limiters. The maximum displacement of the pump can be set independently for forward and reverse using the two adjustment screws.

⚠️ **Warning**

Adjusting the displacement limiter with the machine running may result in leakage. If backed out too far, the adjustment screw will come completely out of its threaded bore.

**Displacement limiter location**

<table>
<thead>
<tr>
<th>Pump rotation</th>
<th>Displacement limiter mounted on servo side</th>
<th>Displacement limitation at high pressure side</th>
</tr>
</thead>
<tbody>
<tr>
<td>Right [CW]</td>
<td>1</td>
<td>A</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>B</td>
</tr>
<tr>
<td>Left [CCW]</td>
<td>1</td>
<td>B</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td>A</td>
</tr>
</tbody>
</table>
**Shaft Torque**

**Shaft torque and spline lubrication**

The **rated torque** is a measure of tooth wear and is the torque level at which a normal spline life of 2x10^9 shaft revolutions can be expected. The rated torque presumes a regularly maintained minimum level of lubrication via a moly-disulfide grease in order to reduce the coefficient of friction and to restrict the presence of oxygen at the spline interface. It is also assumed that the mating spline has a minimum hardness of Rc 55 and full spline depth. The rated torque is proportional to the minimum active spline length.

**Maximum torque** ratings are based on torsional fatigue strength considering 100,000 full load reversing cycles. However, a spline running in oil-flooded environment provides superior oxygen restriction in addition to contaminant flushing. The rated torque of a flooded spline can increase to that of the maximum published rating. A flooded spline would be indicative of a pump driven by a pump drive or plugged into an auxiliary pad of a pump.

Maintaining a spline engagement at least equal to the Pitch Diameter will also maximize spline life. Spline engagements of less than ¾ Pitch Diameter are subject to high contact stress and spline fretting.

**Shaft torque for tapered shafts**

The **rated torque** is based on the contact pressure between the shaft and hub surfaces with poor surface contact areas. With an increased quality of the contact areas, the contact pressure between the shaft and hub is increased and allows higher torque to be transmitted.

When a key is used for orientation of the hub on the shaft in conjunction with poor quality contact surfaces, the transmitted torque will drop significantly. This is due to the key carrying the torque, which limits the shaft torque carrying capability.

**Maximum torque** rating is based on an ideal contact area of 100 % and the retaining nut properly torqued. This allows for the highest contact pressure between the shaft and the hub.
Shaft Availability and Torque Ratings

Alignment between the mating spline's pitch diameters is another critical feature in determining the operating life of a splined drive connection. Plug-in, or rigid spline drive installations can impose severe radial loads on the shafts. The radial load is a function of the transmitted torque and shaft eccentricity. Increased spline clearance will not totally alleviate this condition; but, increased spline clearance will prevent mechanical interference due to misalignment or radial eccentricity between the pitch diameters of the mating splines. Spline life can be maximized if an intermediate coupling is introduced between the bearing supported splined shafts.

For multiple pump installations, consider load of the entire pump stack. All torques are additive. Include charge pumps loads when calculating torques.

Refer to the outline drawings for shaft dimensions.

Torque required by auxiliary pumps is additive. Ensure requirements don't exceed shaft torque ratings.

### Shaft availability and maximum input torque - splined shafts

<table>
<thead>
<tr>
<th>Option code</th>
<th>Customer end</th>
<th>Frame size/Maximum torque N-m [lbf-ft]</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>042</td>
</tr>
<tr>
<td>C3</td>
<td>1ST 16/32</td>
<td>548 [404]</td>
</tr>
<tr>
<td>C6</td>
<td>21ST 16/32</td>
<td>1287 [949]</td>
</tr>
<tr>
<td>C7</td>
<td>23ST 16/32</td>
<td>n/a</td>
</tr>
<tr>
<td>C8</td>
<td>27ST 16/32</td>
<td>n/a</td>
</tr>
<tr>
<td>G1</td>
<td>25ST 20/40</td>
<td>n/a</td>
</tr>
<tr>
<td>F1</td>
<td>13ST 8/16</td>
<td>n/a</td>
</tr>
<tr>
<td>S1</td>
<td>14ST 12/24</td>
<td>n/a</td>
</tr>
</tbody>
</table>

### Shaft availability and maximum input torque - tapered shafts

<table>
<thead>
<tr>
<th>Option code</th>
<th>Customer end</th>
<th>Maximum nut torque</th>
<th>Maximum Torque transmitted through joint</th>
<th>Frame size/Maximum shaft torque N-m [lbf-ft]</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>SD supplied nut ¹</td>
<td>customer supplied nut ²</td>
<td></td>
</tr>
<tr>
<td>T8</td>
<td>Taper 1&quot; - lock nut*</td>
<td>190 [140]</td>
<td>357 [263]</td>
<td>Must be determined by customer</td>
</tr>
<tr>
<td>T1</td>
<td>Taper 1.375&quot; - crowned nut**</td>
<td>210 [155]</td>
<td>704 [519]</td>
<td>Must be determined by customer</td>
</tr>
</tbody>
</table>
### Features and Options

**Shaft availability and maximum input torque - tapered shafts (continued)**

<table>
<thead>
<tr>
<th>Option code</th>
<th>Customer end</th>
<th>Maximum nut torque SD supplied nut 1</th>
<th>Maximum Torque transmitted through joint</th>
<th>Frame size/Maximum shaft torque N-m [lbf-ft]</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>customer supplied nut 2</td>
<td>n/a</td>
<td>042</td>
</tr>
<tr>
<td>T6</td>
<td>Taper 1.5&quot; - lock nut*</td>
<td>525 [390]</td>
<td>882 [650]</td>
<td>n/a</td>
</tr>
<tr>
<td>T4</td>
<td>Taper 1.75&quot; - crowned nut**</td>
<td>400 [295]</td>
<td>1391 [1026]</td>
<td>n/a</td>
</tr>
</tbody>
</table>

* without key
** with woodruff key

⚠️ **Warning**

1. Exceeding the maximum torque value for SD supplied nut may result in nut failure.

2. Customer may supply a stronger nut. Exceeding the maximum torque value for customer supplied nut may result in shaft failure.

### Tapered Shaft Customer Acknowledgement

⚠️ **Warning**

The customer is responsible for proper analysis, design, and quality of the mating female coupling, key, and applied torque on the nut. Torque must be transmitted by the taper fit between the shaft and mating coupling, not the key. Failure to properly analyze the nut torque required to create a robust joint could result in transmitting torque through the key which may lead to premature shaft failure.

The specified torque rating of the tapered shaft is based on the cross-sectional diameter of the shaft through the keyway and assumes proper clamp and fit between shaft and coupling. Danfoss guarantees the design and manufactured quality of the tapered shaft.

Danfoss has made provisions for the key in accordance to the ISO specification with the understanding that the key is solely to assist in the installation of the mating coupling.

### Charge Pump

Charge flow is required on all Series 90 pumps applied in closed circuit installations. The charge pump provides flow to make up internal leakage, maintain a positive pressure in the main circuit, provide flow for cooling and filtration, replace any leakage losses from external valving or auxiliary systems, and to provide flow and pressure for the control system.

Many factors influence the charge flow requirements. These factors include system pressure, pump speed, pump swashplate angle, type of fluid, temperature, size of heat exchanger, length and size of hydraulic lines, control response characteristics, auxiliary flow requirements, hydrostatic motor type, etc.

Unusual application conditions may require a more detailed review of charge pump sizing. Charge pressure must be maintained at a specified level under all operating conditions to prevent damage to the transmission. Danfoss recommends testing under actual operating conditions to verify this.

### Charge pump sizing/selection

In most applications a general guideline is that the charge pump displacement should be at least 10% of the total displacement of all components in the system. Unusual application conditions may require a
Features and Options

more detailed review of charge flow requirements. Refer to Selection of Drive line Components BLN-9885, for a detailed procedure.

System features and conditions which may invalidate the 10% guideline include (but are not limited to):
• Continuous operation at low input speeds (< 1500 min\(^{-1}\) (rpm))
• High shock loading
• Excessively long system lines (> 3m [9.8 ft])
• Auxiliary flow requirements
• Use of low speed high torque motors
• High flushing flow

Contact your Danfoss representative for application assistance if your application includes any of these conditions.

Available charge pump sizes and speed limits

<table>
<thead>
<tr>
<th>Code</th>
<th>Charge pump size cm(^3) [in(^3)]</th>
<th>Rated speed min(^{-1}) (rpm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>B</td>
<td>11 [0.69]</td>
<td>4200</td>
</tr>
<tr>
<td>C</td>
<td>14 [0.86]</td>
<td>4200</td>
</tr>
<tr>
<td>D</td>
<td>17 [1.03]</td>
<td>3900</td>
</tr>
<tr>
<td>E</td>
<td>20 [1.20]</td>
<td>3600</td>
</tr>
<tr>
<td>F</td>
<td>26 [1.60] (only for 130cc)</td>
<td>3300</td>
</tr>
<tr>
<td>H</td>
<td>34 [2.07]</td>
<td>3100</td>
</tr>
<tr>
<td>J</td>
<td>47 [2.82] (only for 180cc)</td>
<td>2600</td>
</tr>
<tr>
<td>K</td>
<td>65 [3.90]</td>
<td>2300</td>
</tr>
</tbody>
</table>

Charge pump flow and power curves

Charge pressure: 20 bar [350 psi]
Case drain: 80 °C (8.2 cSt) 180 °F (53 SUS)
Reservoir temperature: 70 °C (11 cSt) 160 °F (63 SUS)
Features and Options

Charge pump output flow

Charge pump power requirements

Speed Sensor

An optional speed sensor for direct measurement of speed is available.

A special magnetic ring is pressed onto the outside diameter of the cylinder block and a Hall effect sensor is located in the housing. The sensor accepts supply voltage and outputs a digital pulse signal in response to the speed of the ring. The output changes its high/low state as the north and south poles of the permanently magnetized speed ring pass by the face of the sensor. The digital signal is generated at frequencies suitable for microprocessor based controls. The sensor is available with different connectors.

To use the speed sensor in a PLUS+1 Guide application, download HWD file 10106825 from www.Danfoss.com/Plus1. To identify the sensors that are PLUS+1 compliant, please contact your Danfoss representative.
Features and Options

**Electrical data**

<table>
<thead>
<tr>
<th>Description</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply voltage (two ranges)</td>
<td>4.5 to 8.5 Vdc Regulated</td>
</tr>
<tr>
<td></td>
<td>7 to 32 Vdc Battery</td>
</tr>
<tr>
<td>Maximum operating current</td>
<td>20 mA at 1 Hz and 5 Vdc supply</td>
</tr>
<tr>
<td>Required current</td>
<td>12 mA at 5 Vdc (no load)</td>
</tr>
<tr>
<td>Output voltage</td>
<td>High state</td>
</tr>
<tr>
<td></td>
<td>Supply voltage minus 0.5 Vdc minimum (no load)</td>
</tr>
<tr>
<td></td>
<td>Low state</td>
</tr>
<tr>
<td></td>
<td>0.5 Vdc, maximum (no load)</td>
</tr>
<tr>
<td>Maximum frequency</td>
<td>15 kHz</td>
</tr>
<tr>
<td>Load</td>
<td>Ground</td>
</tr>
<tr>
<td></td>
<td>15 kHz</td>
</tr>
<tr>
<td></td>
<td>Supply</td>
</tr>
<tr>
<td></td>
<td>15 kHz</td>
</tr>
<tr>
<td>Peak transient voltage</td>
<td>4.5 to 8.5 Vdc</td>
</tr>
<tr>
<td></td>
<td>80 Vdc for 2 milliseconds</td>
</tr>
<tr>
<td></td>
<td>7 to 32 Vdc</td>
</tr>
<tr>
<td></td>
<td>300 Vdc for 2 milliseconds</td>
</tr>
<tr>
<td></td>
<td>200 Vdc for 100 milliseconds</td>
</tr>
<tr>
<td>Peak reverse voltage</td>
<td>4.5 to 8.5 Vdc</td>
</tr>
<tr>
<td></td>
<td>-15 Vdc continuous</td>
</tr>
<tr>
<td></td>
<td>7 to 32 Vdc</td>
</tr>
<tr>
<td></td>
<td>-32 Vdc continuous</td>
</tr>
</tbody>
</table>

**Environmental data**

<table>
<thead>
<tr>
<th>Description</th>
<th>Data</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating and storage temperature</td>
<td>-40° to 110° C [-40° to 230° F]</td>
</tr>
</tbody>
</table>

For more information on the speed sensor, refer to *KPP Pulse Pickup (PPU) Technical Information 11029257*.

**Warning**

Do not energize the 4.5 to 8.5 Vdc sensor with 12 Vdc battery voltage. Use a regulated power supply. If you need to energize the sensor with battery voltage, contact your Danfoss representative for a special sensor.

**Pulse frequency**

<table>
<thead>
<tr>
<th>Pulse per revolution</th>
<th>042</th>
<th>055</th>
<th>075</th>
<th>100</th>
<th>130</th>
<th>180</th>
<th>250</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>48</td>
<td>52</td>
<td>58</td>
<td>63</td>
<td>69</td>
<td>77</td>
<td>85</td>
</tr>
</tbody>
</table>
Features and Options

Connector Pin Assignments

3 pin Deutsch Plug DT Series connector

4 pin Deutsch® Plug DT Series Connector

3 or 4 pin Delphi Connector

Packard Weather-Pack
4 pin
(Supplied Connector)
Mating Connector
No.: K03379

4 pin Turck Eurofast connector

Turck Eurofast Connector
4 pin
(Supplied Connector)
Mating Connector
straight
No.: K14956
right angle
No.: K14957
Installation Drawings

Frame Size 042

Manual displacement control (MDC), endcap twin ports, option 80

---

**Manual displacement control handle dimensions**

- Torque applied to control handle shaft not to exceed 17 Nm (150 lb-ft)
- Neutral position
- Maximum displacement

---

**Technical Information**

Series 90 Axial Piston Pumps

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Installation Drawings

**Auxiliary mounting pad – options AB, BC, BB**

**Coupling spline data:**
- Pitch diameter: 14.288 [0.5625]
- Pressure angle: 30°
- Number of teeth: 9
- Pitch: 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline: 33.5 [1.32]

**SAE B-B, option BB**

**SAE A, option AB**

**SAE B, option BC**

**View “X”**

**Technical Information**

Series 90 Axial Piston Pumps

Installation Drawings

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BC152886483413en-000907
Installation Drawings

**Shaft dimensions**

**Option T8**

- Cone flange must not protrude beyond this point
- Self-lock nut (DIN 985)
- Refer to (torque - tapered shafts) table page 42 for torque information
- Washer DIN EN ISO 7089-300

**Option C3** ISO 3019-1 Flange Outer
- Diameter 25mm ±4mm (SAE B-B, 15 tooth)
- Coupling must not protrude beyond this surface

* Minimum active spline length for the specified torque ratings
Installation Drawings

Frame Size 055

Manual displacement control (MDC), endcap side ports, option 60

Gauge port M2
System pressure B
9/16-18UNF-2B

Gauge port M1
System pressure A
9/16-18UNF-2B

Approximate center of gravity

Port S
288.8
[11.33]

Approximate center of gravity

View "Y"

Gauge port M2
System pressure B
9/16-18UNF-2B

Port L1
Case drain
Use highest port as outlet
1-1/16-12UN-2B

Port A and B
1.00 - 6000 psi
Split flange boss
Per SAE 3518
(Code 62)

Gauge port M4
Servo pressure
7/16-20UNF-2B

Gauge port M5
Servo pressure
7/16-20UNF-2B

231.9
[9.13]

168.9
[6.65]

72.9
[2.87]

57.15
[2.25]

22.76
[0.90]

Manual Displacement Control Handle Dimensions

Torque applied to control handle shaft not to exceed 17 Nm [150 lb•in]

Maximum displacement

Neutral position

Maximum displacement
Installation Drawings

Manual displacement control (MDC) endcap twin ports, option 80

Gauge port M2: system pressure B
9/16-18UNF-2B

Port S: charge
pump inlet
1-5/16-12UN-2B

Gauge port M1: system pressure A
9/16-18UNF-2B

Ports A and B
1 – 6000 psi
split flange boss
per SAE J518
(Code 62)
7/16-14UNC-2B
21 [0.83]
minimum full thread

Control MDC, option MA

View “Y”
Installation Drawings

**Auxiliary mounting pad – options AB, BC, CD, BB**

**Coupling spline data:**
- Pitch diameter = 14.288 [0.5625]
- Pressure angle = 30°
- Number of teeth = 9
- Pitch = 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 37.13 [1.46]

**SAE A, option AB**

- View "X"

**SAE B, option BC**

- View "X"

**SAE C, option CD**

- View "X"

For O-ring
- Ø 92.2 x 2.62
- [Ø 3.63 x 0.103]

For O-ring
- Ø 94.52 x 2.62
- [Ø 3.73 x 0.103]

For O-ring
- Ø 120.32 x 2.62
- [Ø 4.73 x 0.103]
Installation Drawings

Auxiliary mounting pad – options AB, BC, CD, BB

Coupling spline data:
- Pitch diameter = 23.8125 [0.9375]
- Pressure angle = 30°
- Number of teeth = 15
- Pitch = 16/32
- ANSI B92.1-1970, class 6
- Fillet root side fit
- Length of spline = 24.43 [0.96]

View “X”

Shaft dimensions

Option S1 ISO 3019-1
Flange Outer Diameter 32mm - 4mm (SAE C, 14 tooth)

7.9 [0.311]

Coupling must not protrude beyond this surface

Shaft spline data:
- Pitch diameter = 29.633 [1.167]
- Pressure angle = 30°
- Number of teeth = 14
- Pitch = 12/24
- ANSI B92.1
- Fillet root side fit

* Minimum active spline length
for the specified torque ratings

Option T1 ISO 38.3
Diameter 34.9 mm Taper 1:8

Woodruff key [0.375 x 1.5]

Wrench size 38 mm
Refer to (torque - tapered shafts) table
page 42 for torque information

Shaft/cone 1:8 SAE standard J501

Option C6 ISO 3019-1
Flange Outer Diameter 32mm - 4mm (SAE C, 21 tooth)

7.9 [0.311]

Coupling must not protrude beyond this surface

Shaft spline data:
- Pitch diameter = 33.338 [1.3125]
- Pressure angle = 30°
- Number of teeth = 21
- Pitch = 16/32
- ANSI B92.1
- Fillet root side fit

* Minimum active spline length
for the specified torque ratings

Woodruff key [0.375 x 1.5]
**Installation Drawings**

**Frame Size 075**

*Manual Displacement Control (MDC) Endcap Side Ports, Option 60*

---

**View “Y”**

- **Control MDC, option MA**

**View “Z”**

- **Gauge port M2**
  - System pressure B
  - 9/16-18UNF-2B

- **Gauge port M1**
  - System pressure A
  - 9/16-18UNF-2B

- **Approximate center of gravity**

**View “X”**

- **Multifunction valve**
  - Charge pressure relief valve

- **Gauge port M4**
  - Servo pressure
  - 9/16-18UNF-2B

- **Gauge port M5**
  - Servo pressure
  - 9/16-18UNF-2B

- **Port L2**
  - Case drain
  - 1-1/16-12UN-2B

- **Port S**
  - Charge pump inlet
  - 1-5/16-12UN-2B

**External charge plug**
- 1 5/16-12 UNF

**Approximate center of gravity**

**Neutral position**

**Maximum displacement**

**Maximum displacement**

**Neutral position**

**Maximum displacement**

**Torque applied to control handle shaft**
- Not to exceed 17 N•m [150 lbf•in]

---

**Technical Information**

**Series 90 Axial Piston Pumps**

**Installation Drawings**

**Frame Size 075**

*Manual Displacement Control (MDC) Endcap Side Ports, Option 60*

---

**View “Y”**

- **Control MDC, option MA**

**View “Z”**

- **Gauge port M2**
  - System pressure B
  - 9/16-18UNF-2B

- **Gauge port M1**
  - System pressure A
  - 9/16-18UNF-2B

- **Approximate center of gravity**

**View “X”**

- **Multifunction valve**
  - Charge pressure relief valve

- **Gauge port M4**
  - Servo pressure
  - 9/16-18UNF-2B

- **Gauge port M5**
  - Servo pressure
  - 9/16-18UNF-2B

- **Port L2**
  - Case drain
  - 1-1/16-12UN-2B

- **Port S**
  - Charge pump inlet
  - 1-5/16-12UN-2B

**External charge plug**
- 1 5/16-12 UNF

**Approximate center of gravity**

**Neutral position**

**Maximum displacement**

**Maximum displacement**

**Neutral position**

**Maximum displacement**

**Torque applied to control handle shaft**
- Not to exceed 17 N•m [150 lbf•in]

---

**Technical Information**

**Series 90 Axial Piston Pumps**

**Installation Drawings**

**Frame Size 075**

*Manual Displacement Control (MDC) Endcap Side Ports, Option 60*
Installation Drawings

Manual Displacement Control (MDC), endcap twin ports, option 80

Gauge port M2: system pressure B
9/16-18UNF-2B

Port S: charge pump inlet
1-5/16-12UN-2B

Gauge port M1: system pressure A
9/16-18UNF-2B

Ports A and B
1 - 6000 psi
split flange boss
per SAE J518
(Code 62)
7/16-14UNC-2B
except 20.8 [0.82]
minimum full thread

Control MDC, option MA

View "Y"
Installation Drawings

**Auxiliary mounting pad – Options AB, BC, CD, BB**

**Coupling spline data:**
- Pitch diameter = 14.288 [0.5625]
- Pressure angle = 30°
- Number of teeth = 9
- Pitch = 16/32
- ANSI B92.1-1970, class 6
- Length of spline = 37.13 [1.46]

**SAE A, option AB**

**Coupling spline data:**
- Pitch diameter = 20.6375 [0.8125]
- Pressure angle = 30°
- Number of teeth = 13
- Pitch = 16/32
- ANSI B92.1-1970, class 6
- Length of spline = 29.51 [1.16]

**SAE B, option BC**

**Coupling spline data:**
- Pitch diameter = 29.6333 [1.167]
- Pressure angle = 30°
- Number of teeth = 14
- Pitch = 12/24
- ANSI B92.1-1970, class 6
- Length of spline = 18.97 [0.747]

**SAE C, option CD**

**For O-ring**
- Ø 82.22 x 2.62
  - [Ø 3.237 x 0.103]

**SAE A, option AB**

**For O-ring**
- Ø 94.92 x 2.62
  - [Ø 3.737 x 0.103]

**SAE B, option BC**

**For O-ring**
- Ø 120.32 x 2.62
  - [Ø 4.737 x 0.103]
Installation Drawings

Auxiliary mounting pad – options AB, BC, CD, BB

Coupling spline data:
- Pitch diameter = 23.8125 [0.9375]
- Pressure angle = 30°
- Number of teeth = 15
- Pitch = 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 24.43 [0.96]

For O-ring
- Ø 94.92 x 2.62 [Ø 3.737 x 0.103]

Connector
- AMP Junior Typ A

Frame Size 075 NFPE Options FK, FL, FM, FN

Integrated NFPE control, endcap side ports

System pressure B
- Gage port M2
- 9/16-18UNF-2B

Gage port M1
- 9/16-18UNF-2B

Approx center of gravity

Charge pump inlet M10
- 9/16-18UNF-2B

Case drain L1
- 1-1/16-12UN-2B

Case drain L2
- 1-1/16-12UN-2B

System pressure A
Integrated NFPE control, endcap side ports (continued)
Integrated NFPE control, endcap twin ports
Technical Information
Series 90 Axial Piston Pumps

Installation Drawings

Shaft dimensions

7.9
[0.311]

Coupling must not protrude beyond this surface
**Shaft dimensions**

<table>
<thead>
<tr>
<th>Shaft Option</th>
<th>Undercut Diameter</th>
<th>Full Spline Diameter</th>
<th>Major Diameter</th>
<th>Pitch Diameter</th>
<th>Length</th>
<th>Number of Teeth</th>
<th>Pitch</th>
<th>Pressure Angle</th>
<th>Spline</th>
</tr>
</thead>
<tbody>
<tr>
<td>S1</td>
<td>24.9 [0.98]</td>
<td>27.9 [1.10]</td>
<td>31.4 [1.23]</td>
<td>29.633 [1.1667]</td>
<td>47.6 [1.875]</td>
<td>14</td>
<td>112/24</td>
<td>30 Degrees</td>
<td>ANSI B92.1 Side fit, Fillet Root</td>
</tr>
</tbody>
</table>

* Minimum active spline length for the specified torque ratings
**Manual Displacement Control (MDC), endcap side ports, option 60**

**Gauge port M1**
- System pressure: A
- 9/16-18UNF-2B

**Gauge port M2**
- System pressure: B
- 9/16-18UNF-2B

**Gauge port M3**
- Charge pressure
- 9/16-18UNF-2B

**Gauge port M4**
- Servo pressure
- 9/16-18UNF-2B

**Gauge port M5**
- Servo pressure
- 9/16-18UNF-2B

**Multifunction valve**

**External charge plug**
- 1 5/16-12 UNF

**Port S**
- Charge pump inlet
- 1-5/8-12UN-2B

**View "X"**
- View of frame size 100

**View "Y"**
- Approximate center of gravity

**View "Z"**
- Coupling may not protrude beyond this surface

**Technical Information**

**Series 90 Axial Piston Pumps**

**Installation Drawings**

**Frame Size 100**
Manual Displacement Control (MDC), endcap twin ports, option 80

Gauge port M1: system pressure A
9/16-18UNF-2B

Gauge port M2: system pressure B
9/16-18UNF-2B

Port S: charge pump inlet
1-5/8-12UN-2B

Ports A and B: 1 - 6000 psi
split flange boss per SAE J518
(Code 62)
7/16-14UNC-2B
21 [0.83]
minimum full thread

View "Y"
Installation Drawings

**Auxiliary mounting pads, SAE AB, SAE BC, SAE CD**

**SAE A, Option AB**

**SAE B, Option BC**

**SAE C, Option CD**
Installation Drawings

Auxiliary mounting pad, SAE BB

Coupling Spline Data:
- Pitch Dia = 23.8125 (0.9375)
- Pressure Angle = 30
- Number of teeth = 15
- Pitch = 16/32
- ANSI B92.1-1970, Class 6
- Fillet Root Side Fit
- Length of spline = 24.43 (.96)

Shaft dimensions
- 7.9 [0.311]
- Coupling must not protrude beyond this surface

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Shaft dimensions

<table>
<thead>
<tr>
<th>Shaft Option</th>
<th>Undercut Diameter</th>
<th>Full Spline Diameter</th>
<th>Major Diameter</th>
<th>Pitch Diameter</th>
<th>Length</th>
<th>Number of Teeth</th>
<th>Pitch Pressure Angle</th>
<th>Spline</th>
</tr>
</thead>
<tbody>
<tr>
<td>C7</td>
<td>32.3 [1.27]</td>
<td>38.9 [1.53]</td>
<td>37.59 [1.48]</td>
<td>36.513 [1.4375]</td>
<td>47.6 [1.875]</td>
<td>23</td>
<td>16/3 2</td>
<td>30 Degrees ANSI B92.1 Side fit, Fillet Root</td>
</tr>
<tr>
<td>F1</td>
<td>34.5 [1.36]</td>
<td>49.5 [1.95]</td>
<td>43.94 [1.73]</td>
<td>41.275 [1.625]</td>
<td>66.7 [2.625]</td>
<td>13</td>
<td>8/16 3</td>
<td>30 Degrees ANSI B92.1 Side fit, Fillet Root</td>
</tr>
<tr>
<td>C6</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>30 Degrees ANSI B92.1 Side fit, Fillet Root</td>
<td></td>
</tr>
</tbody>
</table>

* Minimum active spline length for the specified torque ratings
Manual Displacement Control (MDC), end cap twin ports, option 80

---

**Manual displacement control handle dimensions**

- **Torque applied to control handle shaft**: not to exceed 17 N•m [150 lbf•in]
- **Approximate center of gravity**
- **Gauge port**: M2, System pressure B 9/16-18UNF-2B
- **Gauge port**: M4, Servo pressure 9/16-18UNF-2B
- **Gauge port**: M5, Servo pressure 9/16-18UNF-2B
- **Port L1**: Case drain, Use highest port as outlet 1-5/16-12UN-2B
- **Port L2**: Case drain 1-5/16-12UN-2B
- **Approximate center of gravity**

---

**Technical Information**

**Series 90 Axial Piston Pumps**

**Installation Drawings**

**Frame Size 130**

P102 052
Installation Drawings

Auxiliary mounting pad - options AB, BC, CD, DE, BB

Coupling spline data:
- Pitch diameter: 14.288 [0.5625]
- Pressure angle: 30°
- Number of teeth: 9
- Pitch: 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline: 22.4 [0.88]

For O-ring
Ø 94.92 x 2.62
[Ø 3.737 x 0.103]

Coupling spline data:
- Pitch diameter: 14.288 [0.5625]
- Pressure angle: 30°
- Number of teeth: 9
- Pitch: 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline: 22.4 [0.88]

For O-ring
Ø 94.92 x 2.62
[Ø 3.737 x 0.103]

Coupling spline data:
- Pitch diameter: 14.288 [0.5625]
- Pressure angle: 30°
- Number of teeth: 13
- Pitch: 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline: 28.77 [1.1]

For O-ring
Ø 82.22 x 2.62
[Ø 3.237 diameter x 0.103]

Coupling spline data:
- Pitch diameter: 20.6375 [0.8125]
- Pressure angle: 30°
- Number of teeth: 13
- Pitch: 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline: 28.77 [1.1]

For O-ring
Ø 82.22 x 2.62
[Ø 3.237 diameter x 0.103]

Coupling spline data:
- Pitch diameter: 29.6333 [1.167]
- Pressure angle: 30°
- Number of teeth: 14
- Pitch: 12/24
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline: 29.97 [1.18]

For O-ring
Ø 120.32 x 2.62
[Ø 4.737 x 0.103]
Installation Drawings

Auxiliary mounting pad - options AB, BC, CD, DE, BB

Coupling spline data:
- Pitch diameter = 41.275 [1.625]
- Pressure angle = 30°
- Number of teeth = 13
- Pitch = 8/16
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 25.22 [0.993]

View "X"

SAE B-B, option BB

Coupling spline data:
- Pitch diameter = 31.25 [1.232]
- Pressure angle = 30°
- Number of teeth = 13
- Pitch = 8/16
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 24.59 [0.965]

View "X"

SAE D, option DE

Coupling spline data:
- Pitch diameter = 41.275 [1.625]
- Pressure angle = 30°
- Number of teeth = 13
- Pitch = 8/16
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 25.22 [0.993]

View "X"

Shaft dimensions

Option C8 ISO 3019-1 (27 tooth)
- Coupling must not protrude beyond this surface
- Shaft spline data:
  - Pitch diameter = 42.862 [1.687]
  - Pressure angle = 30°
  - Number of teeth = 27
  - Pitch = 16/32
  - ANSI B92.1
  - Fillet root side fit

Option F1 ISO 3019-1 (13 tooth)
- Coupling must not protrude beyond this surface
- Shaft spline data:
  - Pitch diameter = 41.275 [1.625]
  - Pressure angle = 30°
  - Number of teeth = 13
  - Pitch = 8/16
  - ANSI B92.1
  - Fillet root side fit

* Minimum active spline length for the specified torque ratings

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Cone flange must not protrude beyond this surface.

Wrench size 46 mm
Refer to (torque - tapered shafts) table page 42 for torque information.

Woodruff key

11.06 x 63.5 [0.4355 x 2.75]

Gauge Diameter
Installation Drawings

Frame Size 180

Manual Displacement Control (MDC), end cap twin ports, option 80

Manual displacement control handle dimensions

Torque applied to control handle shaft not to exceed 17 Nm [150 lb·in]

Maximum displacement

"B"

Null position

"A"

Maximum displacement

R 30.8 [R 2.0]

R 25.4 [R 1.0]

Ø 6.73 [Ø 0.265] 2x

Gauge port M5

Charge pressure

1 5/8-12 UNF-2B

External charge plug

Multifunction valve

Port S: charge

pump inlet

1-5/8-12UN-2B

Gauge port M2

System pressure B

9/16-18UNF-2B

Gauge port M1

System pressure A

9/16-18UNF-2B

Ports A and B

1-7/8 - 6000 psi

split flange boss

per SAE J518

(Code 62)

1/2-13UNC-2B

0.960

minimum full thread

Gauge port M4

Servo pressure

9/16-18UNF-2B

Gauge port M3

Charge pressure

9/16-18UNF-2B

Multifunctional valve

P102 057
Installation Drawings

Auxiliary mounting pad - options AB, BC, CD, DE, EF, EG, BB

**SAE A, option AB**

Coupling spline data:
- Pitch diameter = 20.288 [0.8013]
- Pressure angle = 30°
- Number of teeth = 9
- Pitch = 16.32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 17.8 [0.70]

**SAE B, option BC**

Coupling spline data:
- Pitch diameter = 14.288 [0.5625]
- Pressure angle = 30°
- Number of teeth = 9
- Pitch = 16.32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 17.8 [0.70]

**SAE C, option CD**

Coupling spline data:
- Pitch diameter = 16.333 [0.6425]
- Pressure angle = 30°
- Number of teeth = 14
- Pitch = 12.24
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 22.1 [0.87]

---

**Technical Information**

Series 90 Axial Piston Pumps

Installation Drawings

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BC15286483413en-000907
Auxiliary mounting pad - options AB, BC, CD, DE, EF, EG, BB

Coupling spline data:
- SAE D, option DE
  - Pitch diameter = 41.275 [1.625]
  - Pressure angle = 30°
  - Number of teeth = 13
  - Pitch = 5/16
  - ANSI B92.1-1970, class 6, fillet root side fit
  - Length of spline = 25.9 [1.02]

View "X"

Coupling spline data:
- SAE E, option EF
  - Pitch diameter = 41.275 [1.625]
  - Pressure angle = 30°
  - Number of teeth = 13
  - Pitch = 5/16
  - ANSI B92.1-1970, class 6, fillet root side fit
  - Length of spline = 25.9 [1.02]

View "X"

Coupling spline data:
- SAE E, option EG
  - Pitch diameter = 42.862 [1.687]
  - Pressure angle = 30°
  - Number of teeth = 27
  - Pitch = 16/32
  - ANSI B92.1-1970, class 6, fillet root side fit
  - Length of spline = 28.5 [1.12]

View "X"
Installation Drawings

**Auxiliary mounting pad - options AB, BC, CD, DE, EF, EG, BB**

**Coupling spline data:**
- Pitch diameter = 23.8125 [0.9375]
- Pressure angle = 30°
- Number of teeth = 15
- Pitch = 16/32
- ANSI B92.1-1970, class 6, fillet root side fit
- Length of spline = 24.49 [0.96]

**Shaft dimensions**

Coupling must not protrude beyond this surface.

<table>
<thead>
<tr>
<th>Shaft Option</th>
<th>Undercut Diameter</th>
<th>Full Spline Diameter</th>
<th>Major Spline Diameter</th>
<th>Pitch Diameter</th>
<th>Number of Teeth</th>
<th>Pitch Angle</th>
<th>Pressure Angle</th>
<th>Spline Type</th>
</tr>
</thead>
<tbody>
<tr>
<td>T</td>
<td>39 [1.54]</td>
<td>42.5 [1.67]</td>
<td>44.35 [1.75]</td>
<td>42.8625 [1.68]</td>
<td>27</td>
<td>16/32</td>
<td>ANSI B92.1</td>
<td>Side fit, Fillet Root</td>
</tr>
<tr>
<td>F1</td>
<td>34.04 [1.34]</td>
<td>42.5 [1.67]</td>
<td>43.94 [1.73]</td>
<td>41.275 [1.625]</td>
<td>13</td>
<td>8/16</td>
<td>ANSI B92.1</td>
<td>Side fit, Fillet Root</td>
</tr>
</tbody>
</table>

* Minimum active spline length for the specified torque ratings
Installation Drawings

Frame Size 250

Manual Displacement Control (MDC), end cap twin ports, option 80

Port S: charge pump inlet
1-1/2 - 3000 psi
split flange boss per SAE J516 (Code 61)
24 [0.94] minimum
full thread

Ports A and B
1-1/2 - 6000 psi
split flange boss
per SAE J516 (Code 62)
25 [0.98] minimum
full thread

Approximate center of gravity

Manual displacement control handle dimensions

Torque applied to control handle shaft
not to exceed 17 Nm (150 lbf-in)

View "Y"

View "Z"

Gauge port M4
servo pressure
9/16-18UNF-2B
7.9 [0.31]

Gauge port M5
servo pressure
9/16-18UNF-2B
228 [8.98]

Gauge port M6
charg e pump Inlet
9/16-18UNF-2B

Port M2
system pressure B
9/16-18UNF-2B

Port N (optional), speed pick-up
9/16-18UNF-2B
Installation Drawings

Auxiliary mounting pad - options AB, BC, CD, DE, EF, EG, BB

Coupling spline data:
Pitch diameter = 14.288 [0.5625]
Pressure angle = 30°
Number of teeth = 9
Pitch = 16/32
ANSI B92.1-1970, class 6, fillet root side fit
Length of spline = 17.8 [0.70]

For O-ring
Ø 120.32 x 2.62
[Ø 4.737 x 0.103]

Coupling spline data:
Pitch diameter = 20.6375 [0.8125]
Pressure angle = 30°
Number of teeth = 13
Pitch = 16/32
ANSI B92.1-1970, class 6, fillet root side fit
Length of spline = 29.5 [1.16]

For O-ring
Ø 94.92 x 2.62
[Ø 3.737 x 0.103]

Coupling spline data:
Pitch diameter = 29.6333 [1.167]
Pressure angle = 30°
Number of teeth = 14
Pitch = 12/24
ANSI B92.1-1970, class 6, fillet root side fit
Length of spline = 22.1 [0.87]

For O-ring
Ø 82.22 x 2.62
[Ø 3.237 x 0.103]

SAE A, option AB

View "X"

SAE B, option BC

View "X"

SAE C, option CD

View "X"
Installation Drawings

Auxiliary mounting pad – options AB, BC, CD, DE EF, EG, BB

Coupling spline data:
- Pitch diameter = 41.275 [1.625] mm
- Pressure angle = 30°
- Number of teeth = 13
- Pitch = 8/16
- ANSI B92.1-1970, class 6
- Fillet root side fit
- Length of spline = 25.9 [1.02] mm

View "X"

SAE D, option DE

View "X"

SAE E, option EF

View "X"

SAE E, option EG

For O-ring
Ø 153 x 3.0
[Ø 6.02 x 0.118]

485.8 [19.13]

49.9 [1.96]

469.1 [18.47]

4 threads
3/4-10UNC-2B
41 [1.61] deep

4 threads
3/4-10UNC-2B
41 [1.61] deep

49.9 [1.96]

469.1 [18.47]

469.1 [18.47]

4 threads
3/4-10UNC-2B
41 [1.61] deep

4 threads
3/4-10UNC-2B
41 [1.61] deep

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### Installation Drawings

**Auxiliary mounting pad – options AB, BC, CD, DE, EF, EG, BB**

**Shaft dimensions**

**Option F1**
- ANSI B92.1 1970KL.5 (13 tooth)
- Coupling must not protrude beyond this surface

**Shaft spline data:**
- Pitch diameter = 41.275 [1.625]
- Pressure angle = 30°
- Number of teeth = 13
- Pitch = 8/16
- ANSI B92.1
- Fillet root side fit

* Minimum active spline length for the specified torque ratings

**Option C8**
- ANSI B92.1 1970KL.5 (27 tooth)
- Coupling must not protrude beyond this surface

**Shaft spline data:**
- Pitch diameter = 42.8625 [1.6875]
- Pressure angle = 30°
- Number of teeth = 27
- Pitch = 16/32
- ANSI B92.1
- Fillet root side fit

**Cover Plate**

**Option CA**

Displacement limiter option 4 limitation both sides
### Dimensions

<table>
<thead>
<tr>
<th>Frame size</th>
<th>C1</th>
<th>C2</th>
<th>C3</th>
<th>C4 maximum (option 4)</th>
</tr>
</thead>
<tbody>
<tr>
<td>055</td>
<td>69.2 [2.72]</td>
<td>179.4 [7.06]</td>
<td>103.6 [4.08]</td>
<td>114 [4.48]</td>
</tr>
<tr>
<td>075</td>
<td>74.2 [2.92]</td>
<td>185.7 [7.31]</td>
<td>109.4 [4.31]</td>
<td>118 [4.65]</td>
</tr>
<tr>
<td>100</td>
<td>83.3 [3.28]</td>
<td>183.3 [7.22]</td>
<td>118.3 [4.66]</td>
<td>136 [5.35]</td>
</tr>
<tr>
<td>130</td>
<td>86.6 [3.41]</td>
<td>209.3 [8.24]</td>
<td>137.2 [5.40]</td>
<td>141 [5.55]</td>
</tr>
<tr>
<td>180</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>184 [7.24]</td>
</tr>
<tr>
<td>250</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>184 [7.24]</td>
</tr>
</tbody>
</table>

### 3-Position (F-N-R) Electric Control

**Option DC & DD**

View "W"

<table>
<thead>
<tr>
<th>Frame size</th>
<th>CS maximum</th>
<th>CS.1</th>
<th>CS.2</th>
</tr>
</thead>
<tbody>
<tr>
<td>042</td>
<td>196.5 [7.74]</td>
<td>108.8 [4.28]</td>
<td>106.2 [4.18]</td>
</tr>
<tr>
<td>055</td>
<td>200.6 [7.90]</td>
<td>108.8 [4.28]</td>
<td>106.2 [4.18]</td>
</tr>
<tr>
<td>075</td>
<td>207.9 [8.19]</td>
<td>108.8 [4.28]</td>
<td>106.2 [4.18]</td>
</tr>
<tr>
<td>100</td>
<td>216.8 [8.54]</td>
<td>117.4 [4.62]</td>
<td>97.6 [3.84]</td>
</tr>
<tr>
<td>130</td>
<td>235.7 [9.28]</td>
<td>102.4 [4.03]</td>
<td>112.6 [4.43]</td>
</tr>
<tr>
<td>180</td>
<td>252.4 [9.94]</td>
<td>94.6 [7.32]</td>
<td>120.4 [4.74]</td>
</tr>
<tr>
<td>250 [option DD only]</td>
<td>210.4 [8.28]</td>
<td>94.6 [7.32]</td>
<td>120.4 [4.74]</td>
</tr>
</tbody>
</table>
Electric Displacement Control (EDC) with MS-Connector or Packard® connector

Dimensions

<table>
<thead>
<tr>
<th>Frame size</th>
<th>C6</th>
<th>C7</th>
</tr>
</thead>
<tbody>
<tr>
<td>042</td>
<td>95.3 [3.75]</td>
<td>168.6 [6.64]</td>
</tr>
<tr>
<td>055</td>
<td>95.3 [3.75]</td>
<td>141.2 [5.56]</td>
</tr>
<tr>
<td>075</td>
<td>105.2 [4.14]</td>
<td>144.8 [5.70]</td>
</tr>
<tr>
<td>100</td>
<td>114.0 [4.49]</td>
<td>153.7 [6.05]</td>
</tr>
<tr>
<td>130</td>
<td>99.1 [3.90]</td>
<td>172.7 [6.80]</td>
</tr>
<tr>
<td>180</td>
<td>93.4 [3.68]</td>
<td>190.0 [7.48]</td>
</tr>
<tr>
<td>250</td>
<td>93.4 [3.68]</td>
<td>226.2 [8.91]</td>
</tr>
</tbody>
</table>

Hydraulic Displacement Control (HDC)
Installation Drawings

**Dimensions**

<table>
<thead>
<tr>
<th>Frame size</th>
<th>C8.1 [mm]</th>
<th>C8.2 [mm]</th>
<th>C9 [mm]</th>
<th>C10 [mm]</th>
<th>C11 [mm]</th>
<th>C12 [mm]</th>
</tr>
</thead>
<tbody>
<tr>
<td>042</td>
<td>143.5 [5.65]</td>
<td>135.0 [5.31]</td>
<td>71.0 [2.79]</td>
<td>75.7 [2.98]</td>
<td>89.6 [3.52]</td>
<td>99.2 [3.90]</td>
</tr>
<tr>
<td>055</td>
<td>150.8 [5.94]</td>
<td>139.0 [5.47]</td>
<td>71.0 [2.79]</td>
<td>75.7 [2.98]</td>
<td>105.6 [4.15]</td>
<td>115.2 [4.53]</td>
</tr>
<tr>
<td>100</td>
<td>158.0 [6.22]</td>
<td>149.0 [5.86]</td>
<td>76.8 [3.02]</td>
<td>67.0 [2.63]</td>
<td>127.9 [5.03]</td>
<td>131.4 [5.17]</td>
</tr>
</tbody>
</table>

**Manual Displacement Control (MDC) with neutral start switch**

![Diagram showing Manual Displacement Control (MDC) with neutral start switch]

Neutral start switch

View “W”

**Dimensions**

<table>
<thead>
<tr>
<th>Frame size</th>
<th>C13 [mm]</th>
<th>C14 [mm]</th>
</tr>
</thead>
<tbody>
<tr>
<td>042</td>
<td>0.35 [0.014]</td>
<td>96.0 [3.78]</td>
</tr>
<tr>
<td>055</td>
<td>18.0 [0.71]</td>
<td>100.0 [3.94]</td>
</tr>
<tr>
<td>075</td>
<td>25.0 [0.98]</td>
<td>106.9 [4.21]</td>
</tr>
<tr>
<td>100</td>
<td>31.3 [1.23]</td>
<td>115.8 [4.56]</td>
</tr>
<tr>
<td>130</td>
<td>46.0 [1.81]</td>
<td>134.5 [5.29]</td>
</tr>
<tr>
<td>180</td>
<td>52.0 [2.04]</td>
<td>151.8 [5.97]</td>
</tr>
<tr>
<td>250</td>
<td>52.0 [2.04]</td>
<td>151.8 [5.97]</td>
</tr>
</tbody>
</table>
Installation Drawings

Electrohydraulic Displacement Control (NFPE) (except 075 NFPE)

Dimensions

<table>
<thead>
<tr>
<th>Frame Size</th>
<th>Option</th>
<th>&quot;X&quot;</th>
<th>&quot;Y&quot;</th>
</tr>
</thead>
<tbody>
<tr>
<td>042</td>
<td>FA, FB, FC, FD</td>
<td>169.30 [6.67]</td>
<td>140.00 [5.51]</td>
</tr>
<tr>
<td>055</td>
<td>FA, FB, FC, FD</td>
<td>207.00 [8.15]</td>
<td>145.00 [5.71]</td>
</tr>
<tr>
<td>075</td>
<td>Special version see Frame Size 075 NFPE Options FK, FL, FM, FN on page 61</td>
<td></td>
<td></td>
</tr>
<tr>
<td>100</td>
<td>FA, FB, FC, FD</td>
<td>235.00 [9.25]</td>
<td>161.10 [6.34]</td>
</tr>
<tr>
<td>100</td>
<td>FG, FH</td>
<td>176.60 [6.95]</td>
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</tr>
<tr>
<td>130</td>
<td>FG, FH</td>
<td>244.10 [9.61]</td>
<td>195.50 [7.70]</td>
</tr>
<tr>
<td>180</td>
<td>FG, FH</td>
<td>290.00 [11.42]</td>
<td>213.00 [8.39]</td>
</tr>
<tr>
<td>250</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>
**Integral Pressure Filter**

Gauge port M6
Charge pressure before filter 9.0 to 10.5 MPa

Gauge port M3
Charge pressure after filter 9.0 to 10.5 MPa

Frame size 042 – 130 = option P
Frame size 042 – 250 = option L

Remote pressure – without filter

Port E
from filter
7/8-14UN (option R)
1/16-12UN (option T)

Frame size 042 – 130 = option R
Frame size 180 – 250 = option T

Dimensions

<table>
<thead>
<tr>
<th>Frame size</th>
<th>F1</th>
<th>F2</th>
<th>F3</th>
<th>F4 maximum</th>
<th>F5 maximum</th>
<th>F6 maximum</th>
<th>F7 maximum</th>
</tr>
</thead>
<tbody>
<tr>
<td>100</td>
<td>174.5 [6.87]</td>
<td>262.6 [10.34]</td>
<td>280.7 [11.05]</td>
<td>223.0 [8.78]</td>
<td>127.7 [5.03]</td>
<td>167.7 [6.60]</td>
<td>183.0 [7.20]</td>
</tr>
</tbody>
</table>
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- PLUS+1™ sensors
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