



Operating Guide

VLT[®] AutomationDrive FC 301/302

0.25–75 kW





Danfoss A/S

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EU DECLARATION OF CONFORMITY

Danfoss A/S
Danfoss Drives A/S

declares under our sole responsibility that the

Product category: Frequency Converter

Type designation(s): FC-301PXXXYY*****

Where:

Character XXX: K25, K37, K55, K75, 1K1, 1K5, 2K2, 3K0, 3K7, 4K0, 5K5, 7K5, 11K, 15K, 18K, 22K, 30K, 37K, 45K, 55K, 75K

Character YY: T2, T4

* may be any number or letter indicating drive options which do not impact this DoC.

The meaning of the 39 characters in the type code string can be found in appendix 00729776.

Covered by this declaration is in conformity with the following directive(s), standard(s) or other normative document(s), provided that the product is used in accordance with our instructions.

Low Voltage Directive 2014/35/EU

EN61800-5-1:2007 + A1:2017 Adjustable speed electrical power drive systems – Part 5-1: Safety requirements – Electrical, thermal and energy.

EMC Directive 2014/30/EU

EN61800-3:2004 + A1:2012 Adjustable speed electrical power drive systems – Part 3: EMC requirements and specific test methods.

RoHS Directive 2011/65/EU including amendment 2015/863.

EN63000:2018 Technical documentation for the assessment of electrical and electronic products with respect to the restriction of hazardous substances

Date: 2020.09.15 Place of issue: Graasten, DK	Issued by  Signature: Name: Gert Kjær Title: Senior Director, GDE	Date: 2020.09.15 Place of issue: Graasten, DK	Approved by  Signature: Name: Michael Termansen Title: VP, PD Center Denmark
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Danfoss only vouches for the correctness of the English version of this declaration. In the event of the declaration being translated into any other language, the translator concerned shall be liable for the correctness of the translation

For products including available Safe Torque Off (STO) function according to unit typecode on the nameplate: **T at character 18 of the typecode.**

Machine Directive 2006/42/EC

EN/IEC 61800-5-2:2007
(Safe Stop function conforms with STO – Safe Torque Off, SIL 2 Capability)

Adjustable speed electrical power drive systems –
Part 5-2: Safety requirements – Functional

Other standards considered:

EN ISO 13849-1:2015
(Safe Stop function, PL d
(MTTFd=14000 years, DC=90%, Category 3)
EN/IEC 61508-1:2011, EN/IEC 61508-2:2011
(Safe Stop function, SIL 2 (PFH = 1E-10/h, 1E-8/h
for specific variants, PFD = 1E-10, 1E-4 for specific
variants, SFF>99%, HFT=0))

Safety of machinery - Safety-related parts of control
systems - Part 1: General principles for design

Functional safety of electrical/electronic/
programmable electronic safety-related systems
Part 1: General requirements

Part 2: Requirements for electrical/ electronic /
programmable electronic safety-related systems
Safety of machinery - Functional safety of safety-
related electrical, electronic and programmable
electronic control systems

EN/IEC 62061:2005 + A1:2013
(Safe Stop function, SILCL 2)

Safety of machinery - Electrical equipment of
machines - Part 1: General requirements

EN/IEC 60204-1:2006 + A1:2009
(Stop Category 0)

Further information can be found in manufacturers declarations:

EU Declaration of conformity 00730213 A.1, 00730215 A.1 and 00730217 A.1 or newer / Manufacturers
declaration 00596226 A.9 or newer.



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EU DECLARATION OF CONFORMITY

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Danfoss Drives A/S

declares under our sole responsibility that the

Product category: Frequency Converter

Type designation(s): FC-302XXXXZZ*****

Character X: N or P

Character YYY: K25, K37, K55, K75, 1K1, 1K5, 2K2, 3K0, 3K7, 4K0, 5K5, 7K5, 11K, 15K, 18K, 22K, 30K, 37K, 45K, 55K, 75K, 90K, 110, 132, 150, 160, 200, 250, 315, 355, 400, 450, 500, 560, 630, 710, 800, 900, 1M0, 1M2

Character ZZ: T2, T5, T6, T7

* may be any number or letter indicating drive options which do not impact this DoC.

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Safety requirements – Electrical, thermal and energy.

EMC Directive 2014/30/EU

EN61800-3:2004 + A1:2012

Adjustable speed electrical power drive systems – Part 3: EMC
requirements and specific test methods.

RoHS Directive 2011/65/EU including amendment 2015/863.

EN63000:2018

Technical documentation for the assessment of electrical and
electronic products with respect to the restriction of

Date: 2020.09.15 Place of issue:	Issued by  Signature: Name: Gert Kjær Title: Senior Director, GDE	Date: 2020.09.15 Place of issue:	Approved by  Signature: Name: Michael Termansen Title: VP, PD Center Denmark
Graasten, DK		Graasten, DK	

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hazardous substances

For products including available Safe Torque Off (STO) function according to unit typecode on the nameplate: **X, B or R at character 18 of the typecode.**

Machine Directive 2006/42/EC

EN/IEC 61800-5-2:2007
(Safe Stop function conforms with STO – Safe Torque Off, SIL 2 Capability)

Adjustable speed electrical power drive systems – Part 5-2: Safety requirements – Functional

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EN ISO 13849-1:2015
(Safe Stop function, PL d
(MTTFd=14000 years, DC=90%, Category 3)
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(Safe Stop function, SIL 2 (PFH = 1E-10/h, 1E-8/h for specific variants, PFD = 1E-10, 1E-4 for specific variants, SFF>99%, HFT=0))

Safety of machinery - Safety-related parts of control systems - Part 1: General principles for design

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Safety of machinery - Functional safety of safety-related electrical, electronic and programmable electronic control systems

EN/IEC 62061:2005 + A1:2013
(Safe Stop function, SILCL 2)

Safety of machinery - Electrical equipment of machines - Part 1: General requirements

EN/IEC 60204-1:2006 + A1:2009
(Stop Category 0)

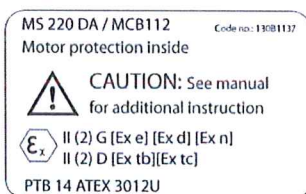
For products including ATEX option, it requires STO function in the products. The products can have the VLT PTC Thermistor Card MCB112 installed from factory (**2 at character 32 in the typecode**), or it can be separately installed as an additional part.

2014/34/EU - Equipment for explosive atmospheres (ATEX)

Based on EU harmonized standard:

EN 50495: 2010

Safety devices required for safe functioning of equipment with respect to explosion risks.



Notified Body:

PTB Physikalisch-Technische Bundesanstalt, Bundesallee 100, 38116 Braunschweig,
has assessed the conformity of the "ATEX certified motor thermal protection systems" of Danfoss FC VLT Drives with Safe Torque Off function and has issued the certificate PTB 14 ATEX 3009.

Contents

1 Introduction	3
1.1 Purpose of the Manual	3
1.2 Additional Resources	3
1.3 Manual and Software Version	3
1.4 Product Overview	3
1.5 Type Approvals and Certifications	5
2 Safety	6
2.1 Safety Symbols	6
2.2 Qualified Personnel	6
2.3 Safety Precautions	6
3 Mechanical Installation	8
3.1 Unpacking	8
3.1.1 Items Supplied	8
3.2 Installation Environments	8
3.3 Mounting	9
4 Electrical Installation	10
4.1 Safety Instructions	10
4.2 EMC-compliant Installation	10
4.3 Grounding	10
4.4 Wiring Schematic	12
4.5 Motor Connection	14
4.6 AC Mains Connection	15
4.7 Control Wiring	15
4.7.1 Safe Torque Off (STO)	15
4.7.2 Mechanical Brake Control	15
4.8 Installation Check List	17
5 Commissioning	18
5.1 Safety Instructions	18
5.2 Local Control Panel Operation	19
5.3 System Set-up	20
6 Basic I/O Configuration	21
7 Maintenance, Diagnostics, and Troubleshooting	23
7.1 Maintenance and Service	23

7.2 Warning and Alarm Types	23
7.3 List of Warnings and Alarms	24
8 Specifications	33
8.1 Electrical Data	33
8.1.1 Mains Supply 200–240 V	33
8.1.2 Mains Supply 380–500 V	36
8.1.3 Mains Supply 525–600 V (FC 302 only)	39
8.1.4 Mains Supply 525–690 V (FC 302 only)	42
8.2 Mains Supply	45
8.3 Motor Output and Motor Data	45
8.4 Ambient Conditions	46
8.5 Cable Specifications	46
8.6 Control Input/Output and Control Data	46
8.7 Fuses and Circuit Breakers	50
8.8 Connection Tightening Torques	58
8.9 Power Ratings, Weight, and Dimensions	59
9 Appendix	65
9.1 Symbols, Abbreviations, and Conventions	65
9.2 Parameter Menu Structure	65
Index	75

1 Introduction

1.1 Purpose of the Manual

This operating guide provides information for safe installation and commissioning of the frequency converter.

The operating guide is intended for use by qualified personnel. Read and follow the instructions to use the frequency converter safely and professionally, and pay particular attention to the safety instructions and general warnings. Always keep this operating guide available with the frequency converter.

VLT® is a registered trademark.

1.2 Additional Resources

Other resources are available to understand advanced frequency converter functions and programming.

- The *VLT® AutomationDrive FC 301/FC 302 Programming Guide* provides greater detail on working with parameters and shows many application examples.
- The *VLT® AutomationDrive FC 301/FC 302 Design Guide* provides detailed information about capabilities and functionality to design motor control systems.
- Instructions for operation with optional equipment.

Supplementary publications and manuals are available from Danfoss. See www.danfoss.com/en/search/?filter=type%3Adocumentation%2Csegment%3Adds for listings.

1.3 Manual and Software Version

This manual is regularly reviewed and updated. All suggestions for improvement are welcome. *Table 1.1* shows the manual version and the corresponding software version.

Edition	Remarks	Software version
MG33ATxx	Error correction. Changing minimum cable cross-section to 10 mm ² (7 AWG)	8.1x, 48.20 (IMC)

Table 1.1 Manual and Software Version

1.4 Product Overview

1.4.1 Intended Use

The frequency converter is an electronic motor controller intended for:

- Regulation of motor speed in response to system feedback or to remote commands from external controllers. A power drive system consists of the frequency converter, the motor, and equipment driven by the motor.
- System and motor status surveillance.

The frequency converter can also be used for motor overload protection.

Depending on the configuration, the frequency converter can be used in standalone applications or form part of a larger appliance or installation.

The frequency converter is allowed for use in residential, industrial, and commercial environments in accordance with local laws and standards.

NOTICE!

In a residential environment, this product can cause radio interference, in which case supplementary mitigation measures can be required.

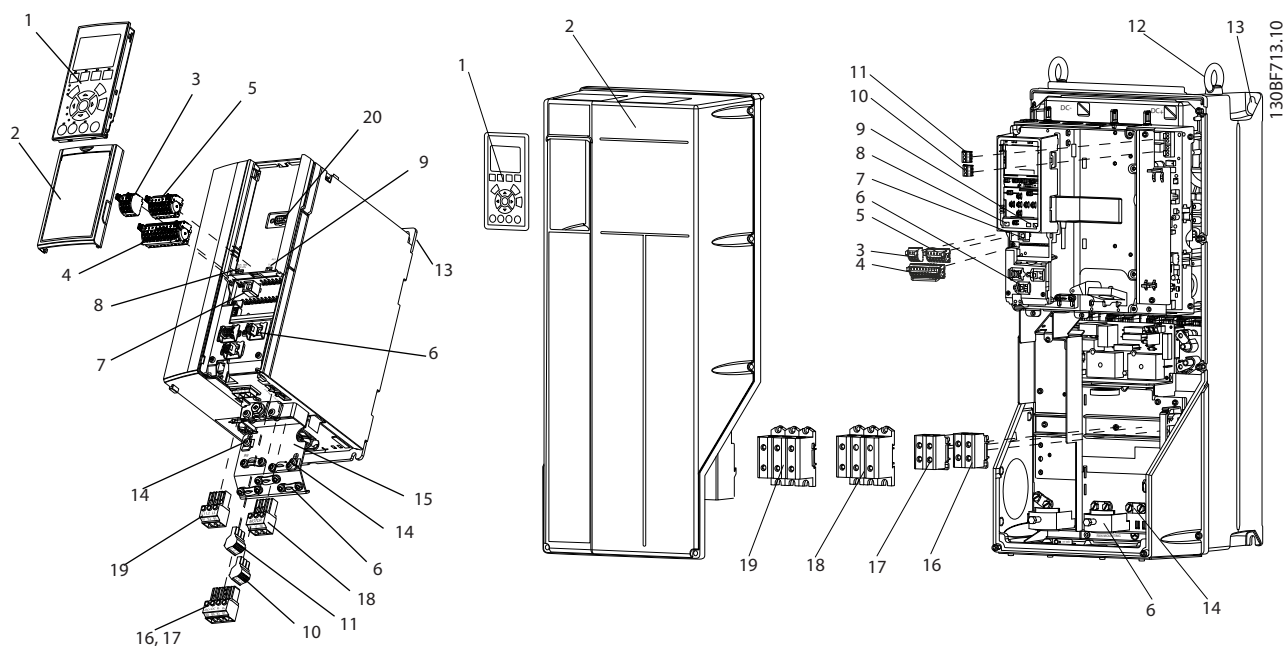
Foreseeable misuse

Do not use the frequency converter in applications which are non-compliant with specified operating conditions and environments. Ensure compliance with the conditions specified in *chapter 8 Specifications*.

NOTICE!

The output frequency of the frequency converter is limited to 590 Hz. For demands exceeding 590 Hz, contact Danfoss.

1.4.2 Exploded Views



1	Local control panel (LCP)	11	Relay 2 (04, 05, 06)
2	Cover	12	Lifting ring
3	RS485 fieldbus connector	13	Mounting slot
4	Digital input/output connector	14	Ground connection (PE)
5	Digital input/output connector	15	Cable shield connector
6	Shielded cable grounding and relief	16	Brake terminal (-81, +82)
7	USB connector	17	Load sharing terminal (-88, +89)
8	RS485 termination switch	18	Motor terminals 96 (U), 97 (V), 98 (W)
9	DIP switch for A53 and A54	19	Mains input terminals 91 (L1), 92 (L2), 93 (L3)
10	Relay 1 (01, 02, 03)	20	LCP connector

Figure 1.1 Exploded View Enclosure Size A, IP20 (left), and Enclosure Size C, IP55/IP66 (right)

1.5 Type Approvals and Certifications

The following list is a selection of possible type approvals and certifications for Danfoss frequency converters:



NOTICE!

The specific approvals and certification for the frequency converter are on the nameplate of the frequency converter. For more information, contact the local Danfoss office or partner.

For more information on UL 508C thermal memory retention requirements, refer to the section *Motor Thermal Protection* in the product-specific *design guide*.

For more information on compliance with the European Agreement concerning International Carriage of Dangerous Goods by Inland Waterways (ADN), refer to the section *ADN-compliant Installation* in the product-specific *design guide*.

2

2 Safety

2.1 Safety Symbols

The following symbols are used in this guide:

⚠ WARNING

Indicates a potentially hazardous situation that could result in death or serious injury.

⚠ CAUTION

Indicates a potentially hazardous situation that could result in minor or moderate injury. It can also be used to alert against unsafe practices.

NOTICE!

Indicates important information, including situations that can result in damage to equipment or property.

2.2 Qualified Personnel

Correct and reliable transport, storage, installation, operation, and maintenance are required for the trouble-free and safe operation of the frequency converter. Only qualified personnel are allowed to install and operate this equipment.

Qualified personnel are defined as trained staff, who are authorized to install, commission, and maintain equipment, systems, and circuits in accordance with pertinent laws and regulations. Also, the qualified personnel must be familiar with the instructions and safety measures described in this manual.

2.3 Safety Precautions

⚠ WARNING

HIGH VOLTAGE

Frequency converters contain high voltage when connected to AC mains input, DC supply, or load sharing. Failure to perform installation, start-up, and maintenance by qualified personnel can result in death or serious injury.

- Only qualified personnel must perform installation, start-up, and maintenance.
- Before performing any service or repair work, use an appropriate voltage measuring device to make sure that there is no remaining voltage on the frequency converter.

⚠ WARNING

UNINTENDED START

When the frequency converter is connected to AC mains, DC supply, or load sharing, the motor may start at any time. Unintended start during programming, service, or repair work can result in death, serious injury, or property damage. The motor can start via an external switch, a fieldbus command, an input reference signal from the LCP, or after a cleared fault condition.

To prevent unintended motor start:

- Disconnect the frequency converter from the mains.
- Press [Off/Reset] on the LCP before programming parameters.
- Completely wire and assemble the frequency converter, motor, and any driven equipment before connecting the frequency converter to AC mains, DC supply, or load sharing.

⚠WARNING

DISCHARGE TIME

The frequency converter contains DC-link capacitors, which can remain charged even when the frequency converter is not powered. High voltage can be present even when the warning LED indicator lights are off. Failure to wait the specified time after power has been removed before performing service or repair work can result in death or serious injury.

- Stop the motor.
- Disconnect AC mains and remote DC-link power supplies, including battery back-ups, UPS, and DC-link connections to other frequency converters.
- Disconnect or lock PM motor.
- Wait for the capacitors to discharge fully. The minimum waiting time is specified in *Table 2.1* and is also visible on the product label on top of the frequency converter.
- Before performing any service or repair work, use an appropriate voltage measuring device to make sure that the capacitors are fully discharged.

Voltage [V]	Minimum waiting time (minutes)		
	4	7	15
200–240	0.25–3.7 kW (0.34–5 hp)	–	5.5–37 kW (7.5–50 hp)
380–500	0.25–7.5 kW (0.34–10 hp)	–	11–75 kW (15–100 hp)
525–600	0.75–7.5 kW (1–10 hp)	–	11–75 kW (15–100 hp)
525–690	–	1.5–7.5 kW (2–10 hp)	11–75 kW (15–100 hp)

Table 2.1 Discharge Time

⚠WARNING

LEAKAGE CURRENT HAZARD

Leakage currents exceed 3.5 mA. Failure to ground the frequency converter properly can result in death or serious injury.

- Ensure the correct grounding of the equipment by a certified electrical installer.

⚠WARNING

EQUIPMENT HAZARD

Contact with rotating shafts and electrical equipment can result in death or serious injury.

- Ensure that only trained and qualified personnel perform installation, start-up, and maintenance.
- Ensure that electrical work conforms to national and local electrical codes.
- Follow the procedures in this guide.

⚠WARNING

UNINTENDED MOTOR ROTATION

WINDMILLING

Unintended rotation of permanent magnet motors creates voltage and can charge the unit, resulting in death, serious injury, or equipment damage.

- Ensure that permanent magnet motors are blocked to prevent unintended rotation.

⚠CAUTION

INTERNAL FAILURE HAZARD

An internal failure in the frequency converter can result in serious injury when the frequency converter is not properly closed.

- Ensure that all safety covers are in place and securely fastened before applying power.

3 Mechanical Installation

3

3.1 Unpacking

3.1.1 Items Supplied

Items supplied vary according to product configuration.

- Make sure that the items supplied and the information on the nameplate correspond to the order confirmation.
- Check the packaging and the frequency converter visually for damage caused by inappropriate handling during shipment. File any claim for damage with the carrier. Retain damaged parts for clarification.

NOTICE!

Do not remove the nameplate from the frequency converter (loss of warranty).

Ensure that the requirements for storage are fulfilled. Refer to *chapter 8.4 Ambient Conditions* for further details.

3.2 Installation Environments

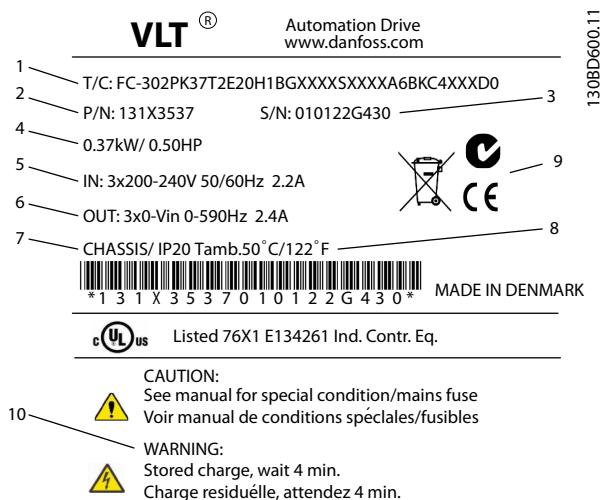
NOTICE!

In environments with airborne liquids, particles, or corrosive gases, ensure that the IP/type rating of the equipment matches the installation environment. Failure to meet requirements for ambient conditions can reduce the lifetime of the frequency converter. Ensure that requirements for air humidity, temperature, and altitude are met.

Vibration and shock

The frequency converter complies with requirements for units mounted on the walls and floors of production premises, and in panels bolted to walls or floors.

For detailed ambient conditions specifications, refer to *chapter 8.4 Ambient Conditions*.



1	Type code
2	Code number
3	Serial number
4	Power rating
5	Input voltage, frequency, and current (at low/high voltages)
6	Output voltage, frequency, and current (at low/high voltages)
7	Enclosure size and IP rating
8	Maximum ambient temperature
9	Certifications
10	Discharge time (Warning)

Figure 3.1 Product Nameplate (Example)

3.3 Mounting

NOTICE!

Improper mounting can result in overheating and reduced performance.

Cooling

- Ensure that top and bottom clearance for air cooling is provided. See *Figure 3.2* for clearance requirements.

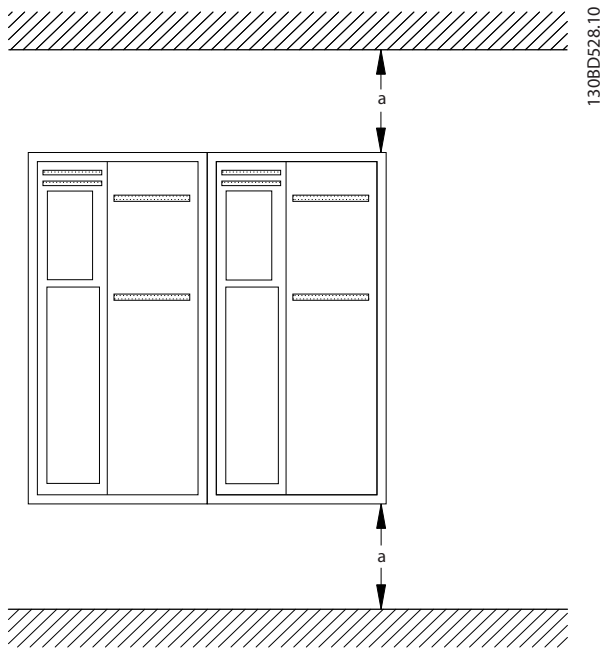


Figure 3.2 Top and Bottom Cooling Clearance

Enclosure	A1–A5	B1–B4	C1, C3	C2, C4
a [mm (in)]	100 (3.9)	200 (7.8)	200 (7.8)	225 (8.9)

Table 3.1 Minimum Airflow Clearance Requirements

Lifting

- Ensure that the lifting device is suitable for the task.
- If necessary, plan for a hoist, crane, or forklift with the appropriate rating to move the unit.
- For lifting, use hoist rings on the unit, when provided.

WARNING

HEAVY LOAD

Unbalanced loads can fall and loads can tip over. Failure to take proper lifting precautions increases risk of death, serious injury, or equipment damage.

- Never walk under suspended loads.
- To guard against injury, wear personal protective equipment such as gloves, safety glasses, and safety shoes.
- Be sure to use lifting devices with the appropriate weight rating. To determine a safe lifting method, check the weight of the unit, see *chapter 8.9 Power Ratings, Weight, and Dimensions*.
- The angle from the top of the drive module to the lifting cables has an impact on the maximum load force on the cable. This angle must be 65° or greater. Attach and dimension the lifting cables properly.

Mounting

1. Ensure that the strength of the mounting location supports the unit weight. The frequency converter allows side-by-side installation.
2. Locate the unit as near to the motor as possible. Keep the motor cables as short as possible.
3. Mount the unit vertically to a solid flat surface or to the optional backplate to provide cooling airflow.
4. Use the slotted mounting holes on the unit for wall mount, when provided.

Mounting with mounting plate and railings

A mounting plate is required when mounted on railings.

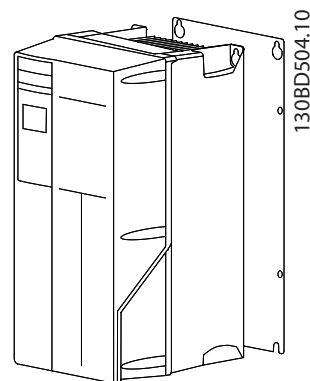


Figure 3.3 Proper Mounting with Mounting Plate

4 Electrical Installation

4.1 Safety Instructions

See *chapter 2 Safety* for general safety instructions.

⚠ WARNING

INDUCED VOLTAGE

Induced voltage from output motor cables that run together can charge equipment capacitors even with the equipment turned off and locked out. Failure to run output motor cables separately or use shielded cables or metal conduits could result in death or serious injury.

- Run output motor cables separately, or
- Use shielded cables or metal conduits.

⚠ CAUTION

SHOCK HAZARD

The frequency converter can cause a DC current in the PE conductor. Failure to follow the recommendation may lead to the RCD not providing the intended protection.

- When a residual current-operated protective device (RCD) is used for protection against electrical shock, only an RCD of Type B is allowed on the supply side.

NOTICE!

The frequency converter is supplied with Class 20 motor overload protection.

Overcurrent protection

- Extra protective equipment, such as short-circuit protection or motor thermal protection between frequency converter and motor, is required for applications with multiple motors.
- Input fusing is required to provide short-circuit and overcurrent protection. If not factory-supplied, the installer must provide fuses. See maximum fuse ratings in *chapter 8.7 Fuses and Circuit Breakers*.

Wire type and ratings

- All wiring must comply with local and national regulations regarding cross-section and ambient temperature requirements.
- Power connection wire recommendation: Minimum 75 °C (167 °F) rated copper wire.

See *chapter 8.1 Electrical Data* and *chapter 8.5 Cable Specifications* for recommended wire sizes and types.

4.2 EMC-compliant Installation

To obtain an EMC-compliant installation, follow the instructions provided in *chapter 4.3 Grounding*, *chapter 4.4 Wiring Schematic*, *chapter 4.5 Motor Connection*, and *chapter 4.7 Control Wiring*.

4.3 Grounding

⚠ WARNING

LEAKAGE CURRENT HAZARD

Leakage currents exceed 3.5 mA. Failure to ground the frequency converter properly could result in death or serious injury.

- Ensure the correct grounding of the equipment by a certified electrical installer.

For electrical safety

- Ground the frequency converter in accordance with applicable standards and directives.
- Use a dedicated ground wire for input power, motor power, and control wiring.
- Do not ground 1 frequency converter to another in a daisy-chain fashion (see *Figure 4.1*).
- Keep the ground wire connections as short as possible.
- Follow motor manufacturer wiring requirements.
- Minimum cable cross-section for the ground wires: 10 mm² (7 AWG).
- Separately terminate individual ground wires, both complying with the dimension requirements.

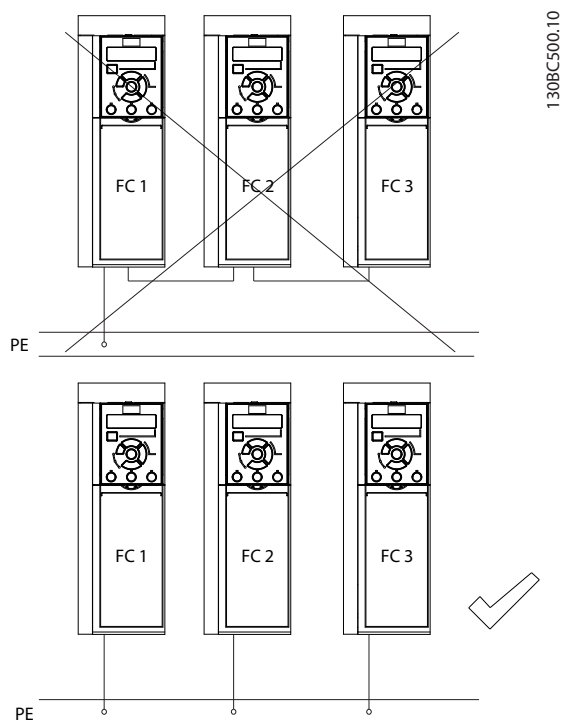


Figure 4.1 Grounding Principle

For EMC-compliant installation

- Establish electrical contact between the cable shield and the frequency converter enclosure by using metal cable glands or by using the clamps provided on the equipment (see *chapter 4.5 Motor Connection*).
- Use high-strand wire to reduce burst transient.
- Do not use pigtailed.

NOTICE!

POTENTIAL EQUALIZATION

Risk of burst transient when the ground potential between the frequency converter and the control system is different. Install equalizing cables between the system components. Recommended cable cross-section: 16 mm² (6 AWG).

4.4 Wiring Schematic

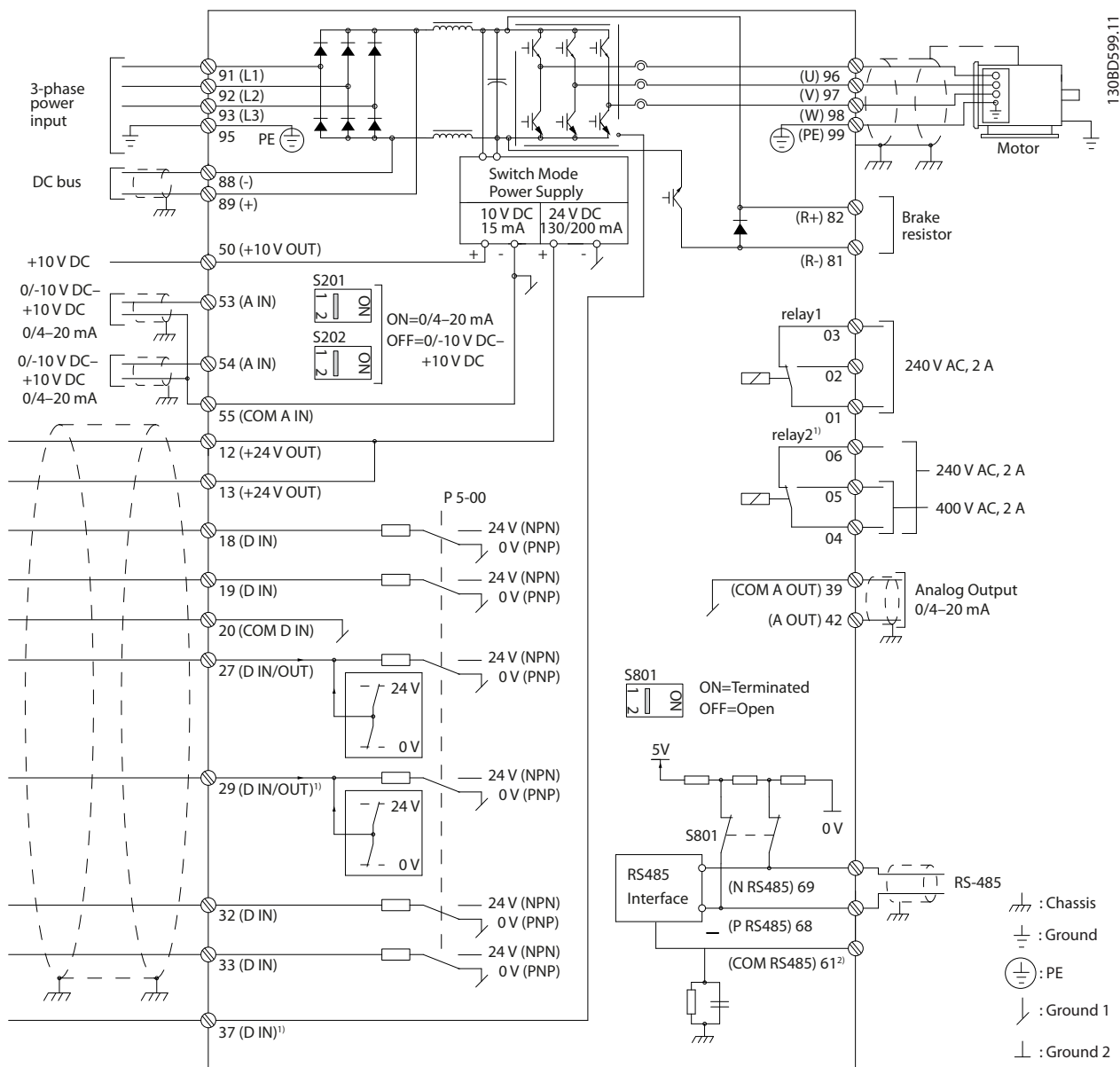
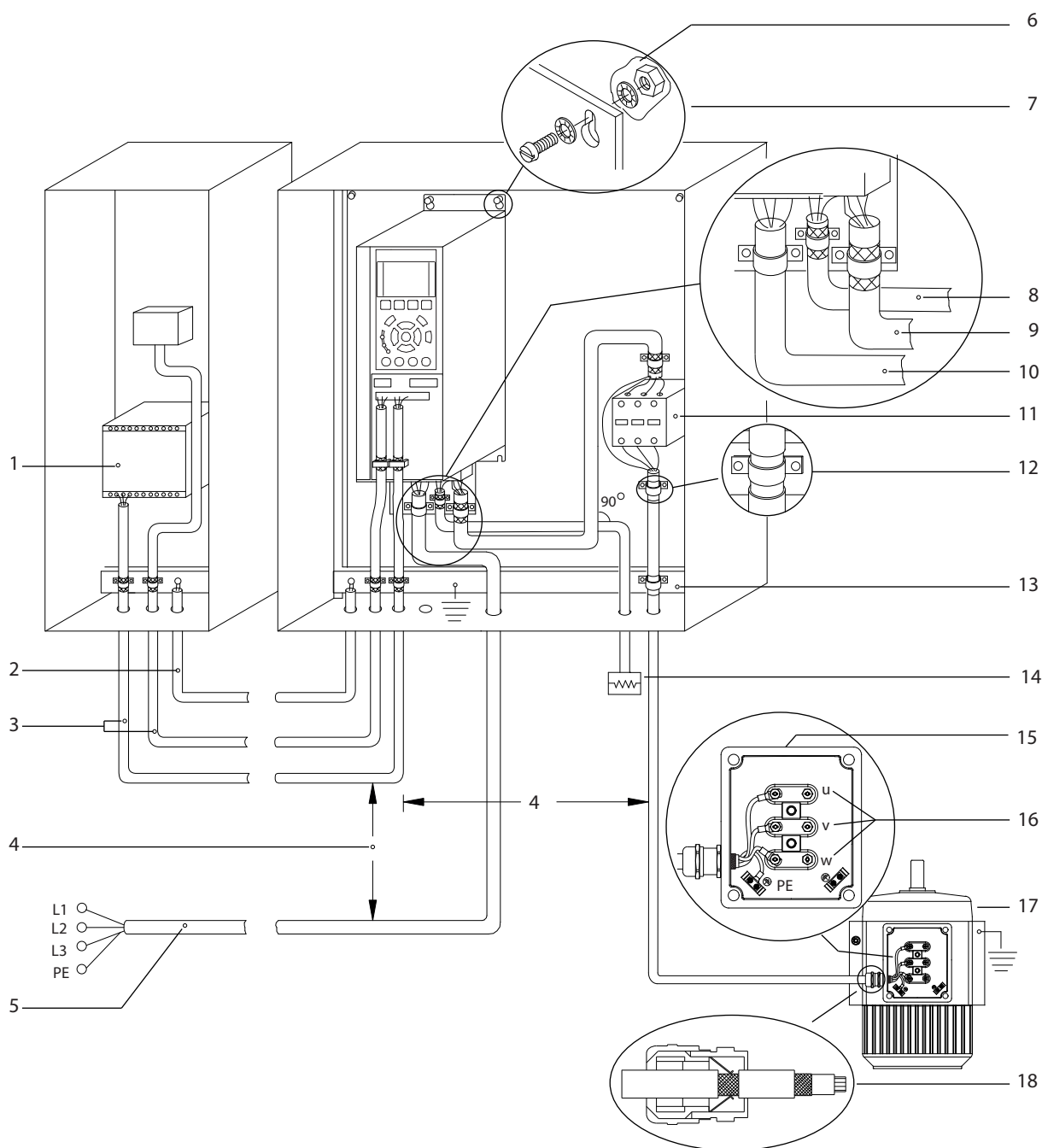


Figure 4.2 Basic Wiring Schematic

A=Analog, D=Digital

1) Terminal 37 (optional) is used for Safe Torque Off (STO). For installation instructions, refer to the *VLT® Safe Torque Off Operating Guide*. For FC 301, terminal 37 is only included in enclosure size A1. Relay 2 and terminal 29 have no function in FC 301.

2) Do not connect cable shield.



1	PLC.	10	Mains cable (unshielded).
2	Minimum 16 mm ² (6 AWG) equalizing cable.	11	Output contactor.
3	Control cables.	12	Cable insulation stripped.
4	Minimum 200 mm (7.9 in) between control cables, motor cables, and mains cables.	13	Common ground busbar. Follow local and national requirements for cabinet grounding.
5	Mains supply.	14	Brake resistor.
6	Bare (unpainted) surface.	15	Metal box.
7	Star washers.	16	Connection to motor.
8	Brake cable (shielded).	17	Motor.
9	Motor cable (shielded).	18	EMC cable gland.

Figure 4.3 Example of Proper EMC Installation
MG33AT22

For more information about EMC, see *chapter 4.2 EMC-compliant Installation*

NOTICE!**EMC INTERFERENCE**

Run cables for input power, motor wiring, and control wiring in 3 separate metallic conduits. Failure to isolate power, motor, and control cables can result in unintended behavior or reduced performance. Minimum 200 mm (7.9 in) clearance is required between power, motor, and control cables.

4

4.5 Motor Connection

WARNING**INDUCED VOLTAGE**

Induced voltage from output motor cables that run together can charge equipment capacitors even with the equipment turned off and locked out. Failure to run output motor cables separately or use shielded cables or metal conduits could result in death or serious injury.

- Run output motor cables separately, or
- Use shielded cables or metal conduits.
- Comply with local and national electrical codes for cable sizes. For maximum wire sizes, see *chapter 8.1 Electrical Data*.
- Follow motor manufacturer wiring requirements.
- Motor wiring knockouts or access panels are provided at the base of IP21 (NEMA1/12) and higher units.
- Do not wire a starting or pole-changing device (for example Dahlander motor or slip ring asynchronous motor) between the frequency converter and the motor.

Procedure for grounding the cable shield

1. Strip a section of the outer cable insulation.
2. Position the stripped wire under the cable clamp to establish mechanical fixation and electrical contact between the cable shield and ground.
3. Connect the ground wire to the nearest grounding terminal in accordance with the grounding instructions provided in *chapter 4.3 Grounding*, see *Figure 4.4*.
4. Connect the 3-phase motor wiring to terminals 96 (U), 97 (V), and 98 (W), see *Figure 4.4*.
5. Tighten the terminals in accordance with the information provided in *chapter 8.8 Connection Tightening Torques*.

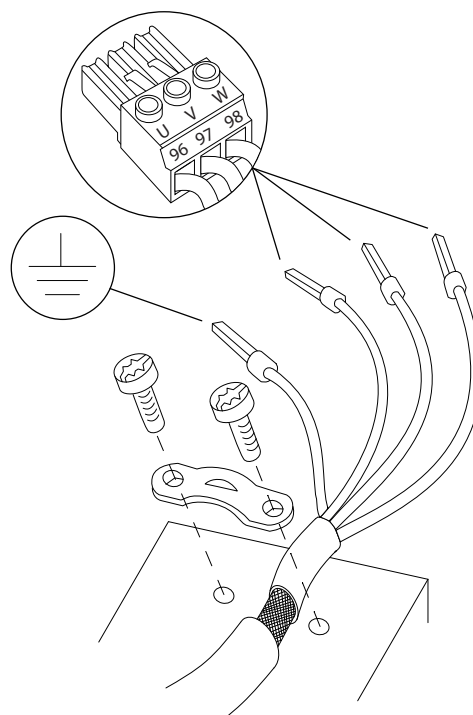


Figure 4.4 Motor Connection

Figure 4.5 shows mains input, motor, and grounding for basic frequency converters. Actual configurations vary with unit types and optional equipment.

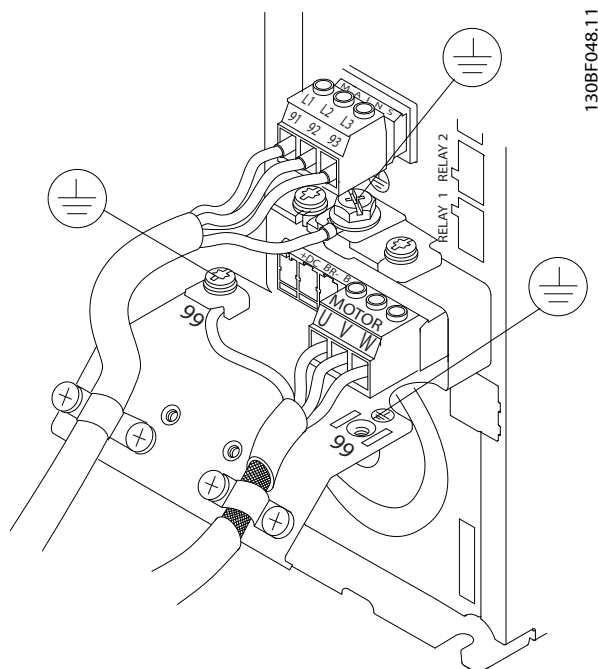


Figure 4.5 Example of Motor, Mains, and Ground Wiring

4.6 AC Mains Connection

- Size the wiring based on the input current of the frequency converter. For maximum wire sizes, see *chapter 8.1 Electrical Data*.
- Comply with local and national electrical codes for cable sizes.

Procedure

1. Connect the 3-phase AC input power wiring to terminals L1, L2, and L3 (see *Figure 4.5*).
2. Depending on the configuration of the equipment, connect the input power to the mains input terminals or the input disconnect.
3. Ground the cable in accordance with the grounding instructions provided in *chapter 4.3 Grounding*.
4. When supplied from an isolated mains source (IT mains or floating delta) or TT/TN-S mains with a grounded leg (grounded delta), ensure that *parameter 14-50 RFI Filter* is set to [0] Off. This setting prevents damage to the DC link and reduces ground capacity currents in accordance with IEC 61800-3.

4.7 Control Wiring

- Isolate the control wiring from the high-power components in the frequency converter.
- When the frequency converter is connected to a thermistor, ensure that the thermistor control wiring is shielded and reinforced/double insulated. A 24 V DC supply voltage is recommended.

4.7.1 Safe Torque Off (STO)

To run STO, more wiring for the frequency converter is required. Refer to *VLT® Frequency Converters Safe Torque Off Operating Guide* for further information.

4.7.2 Mechanical Brake Control

In hoisting/lowering applications, it is necessary to control an electro-mechanical brake.

- Control the brake using any relay output or digital output (terminal 27 or 29).
- Keep the output closed (voltage-free) as long as the frequency converter is unable to keep the motor at standstill, for example due to the load being too heavy.
- Select [32] *Mechanical brake control in parameter group 5-4* Relays* for applications with an electro-mechanical brake.
- The brake is released when the motor current exceeds the value in *parameter 2-20 Release Brake Current*.
- The brake is engaged when the output frequency is less than the frequency set in *parameter 2-21 Activate Brake Speed [RPM]* or *parameter 2-22 Activate Brake Speed [Hz]*, and only if the frequency converter carries out a stop command.

If the frequency converter is in alarm mode or in an overvoltage situation, the mechanical brake immediately closes.

NOTICE!

The frequency converter is not a safety device. It is the responsibility of the system designer to integrate safety devices according to relevant national crane/lift regulations.

4

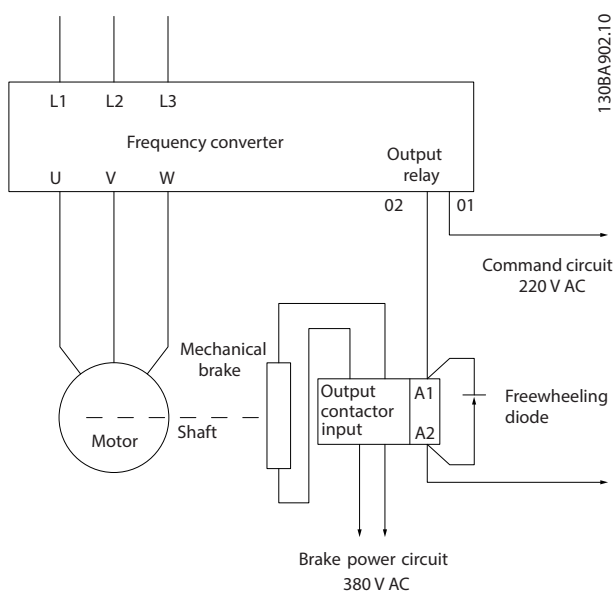


Figure 4.6 Connecting the Mechanical Brake to the Frequency Converter

4.8 Installation Check List

Before completing installation of the unit, inspect the entire installation as detailed in *Table 4.1*. Check and mark the items when completed.

Inspect for	Description	<input checked="" type="checkbox"/>
Auxiliary equipment	<ul style="list-style-type: none"> Look for auxiliary equipment, switches, disconnects, or input fuses/circuit breakers, residing on the input power side of the frequency converter, or output side to the motor. Ensure that they are ready for full-speed operation. Check the function and installation of any sensors used for feedback to the frequency converter. Remove any power factor correction caps on the motor. Adjust any power factor correction caps on the mains side and ensure that they are dampened. 	
Cable routing	<ul style="list-style-type: none"> Ensure that the motor wiring and control wiring are separated, shielded, or in 3 separate metallic conduits for high frequency interference isolation. 	
Control wiring	<ul style="list-style-type: none"> Check for broken or damaged wires and loose connections. Check that the control wiring is isolated from power and motor wiring for noise immunity. Check the voltage source of the signals, if necessary. <p>The use of shielded cable or twisted pair is recommended. Ensure that the shield is terminated correctly.</p>	
Cooling clearance	<ul style="list-style-type: none"> Ensure that the top and bottom clearance is adequate to ensure proper airflow for cooling, see <i>chapter 3.3.1 Mounting</i>. 	
Ambient conditions	<ul style="list-style-type: none"> Check that requirements for ambient conditions are met. 	
Fusing and circuit breakers	<ul style="list-style-type: none"> Check for proper fusing or circuit breakers. Check that all fuses are inserted firmly and are in operational condition, and that all circuit breakers are in the open position. 	
Grounding	<ul style="list-style-type: none"> Check for sufficient ground connections and ensure that those connections are tight and free of oxidation. Grounding to conduit, or mounting the back panel to a metal surface, is not a suitable grounding. 	
Input and output power wiring	<ul style="list-style-type: none"> Check for loose connections. Check that the motor and mains cables are in separate conduit or separated shielded cables. 	
Panel interior	<ul style="list-style-type: none"> Inspect that the unit interior is free of dirt, metal chips, moisture, and corrosion. Check that the unit is mounted on an unpainted metal surface. 	
Switches	<ul style="list-style-type: none"> Ensure that all switch and disconnect settings are in the proper positions. 	
Vibration	<ul style="list-style-type: none"> Check that the unit is mounted solidly, or that shock mounts are used, as necessary. Check for an unusual amount of vibration. 	

Table 4.1 Installation Check List

CAUTION

POTENTIAL HAZARD IN THE EVENT OF INTERNAL FAILURE

Risk of personal injury if the frequency converter is not properly closed.

- Before applying power, ensure that all safety covers are in place and securely fastened.

5 Commissioning

5.1 Safety Instructions

See *chapter 2 Safety* for general safety instructions.

⚠ WARNING

HIGH VOLTAGE

Frequency converters contain high voltage when connected to AC mains input power. Failure to perform installation, start-up, and maintenance by qualified personnel could result in death or serious injury.

- Installation, start-up, and maintenance must be performed by qualified personnel only.

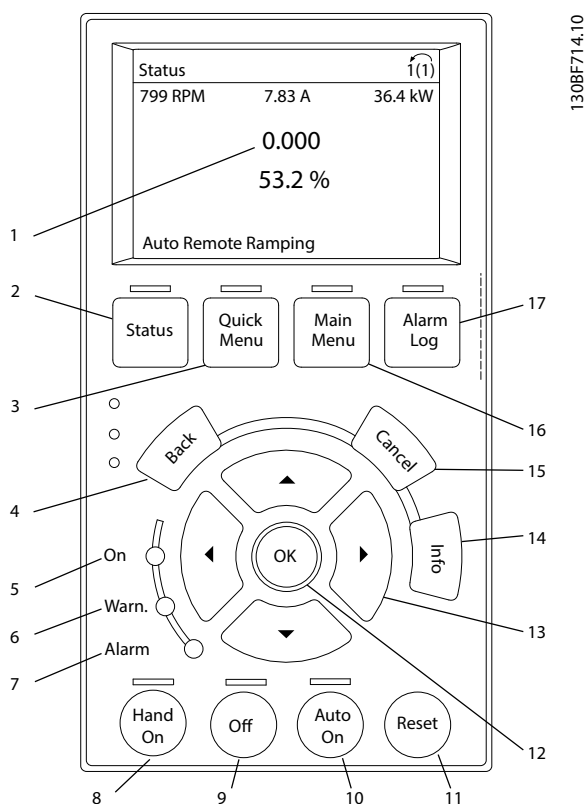
NOTICE!

The front covers with warning signs are an integrated part of the frequency converter and considered safety covers. The covers must be in place before applying power and at all times.

Before applying power:

1. Close the safety cover properly.
2. Check that all cable glands are firmly tightened.
3. Ensure that input power to the unit is off and locked out. Do not rely on the frequency converter disconnect switches for input power isolation.
4. Verify that there is no voltage on input terminals L1 (91), L2 (92), and L3 (93), phase-to-phase, and phase-to-ground.
5. Verify that there is no voltage on output terminals 96 (U), 97 (V), and 98 (W), phase-to-phase, and phase-to-ground.
6. Confirm continuity of the motor by measuring Ω values on U-V (96–97), V-W (97–98), and W-U (98–96).
7. Check for proper grounding of the frequency converter and the motor.
8. Inspect the frequency converter for loose connections on the terminals.
9. Confirm that the supply voltage matches the voltage of the frequency converter and the motor.

5.2 Local Control Panel Operation



5

Key	Function
1	The information shown in the display area depends on the selected function or menu (in this case <i>Quick Menu Q3-13 Display Settings</i>).
2	Status Shows operational information.
3	Quick Menu Allows access to programming parameters for initial set-up instructions and many detailed application instructions.
4	Back Reverts to the previous step or list in the menu structure.
5	Green indicator light. Power on.
6	Yellow indicator light. The indicator light comes on when a warning is active. A text appears in the display area identifying the problem.
7	Red indicator light. A fault condition causes the indicator light to flash, and an alarm text is shown.
8	[Hand On] Puts the frequency converter in local control mode, so that it responds to the LCP. <ul style="list-style-type: none"> An external stop signal by control input or serial communication overrides the local [Hand On].
9	Off Stops the motor but does not remove power to the frequency converter.
10	[Auto On] Puts the system in remote operational mode. <ul style="list-style-type: none"> Responds to an external start command by control terminals or serial communication.
11	Reset Resets the frequency converter manually after a fault has been cleared.
12	OK Press to access parameter groups or to enable a selection.
13	Navigation Keys Press the navigation keys to move between items in the menu.
14	Info Press for a definition of the function being shown.
15	Cancel Cancels the last change or command as long as the display mode is not changed.
16	Main Menu Allows access to all programming parameters.
17	Alarm Log Shows a list of current warnings, the last 10 alarms, and the maintenance log.

Figure 5.1 Graphic Local Control Panel (GLCP)

5.3 System Set-up

1. Perform automatic motor adaption (AMA):
 - 1a Set the following basic motor parameters as shown in *Table 5.1* before performing AMA.
 - 1b Optimize the compatibility between motor and frequency converter via *parameter 1-29 Automatic Motor Adaptation (AMA)*.
2. Check motor rotation.
3. If encoder feedback is used, perform the following steps:
 - 3a Select *[0] Speed open loop* in *parameter 1-00 Configuration Mode*.
 - 3b Select *[1] 24V encoder* in *parameter 7-00 Speed PID Feedback Source*.
 - 3c Press [Hand On].
 - 3d Press [►] for positive speed reference (*parameter 1-06 Clockwise Direction* at *[0] Normal*).
 - 3e In *parameter 16-57 Feedback [RPM]*, check that the feedback is positive.

	<i>Parameter 1-10 Motor Construction</i>		
	ASM	PM	SynRM
<i>Parameter 1-20 Motor Power [kW]</i>	X		
<i>Parameter 1-21 Motor Power [HP]</i>			
<i>Parameter 1-22 Motor Voltage</i>	X		
<i>Parameter 1-23 Motor Frequency</i>	X		X
<i>Parameter 1-24 Motor Current</i>	X	X	X
<i>Parameter 1-25 Motor Nominal Speed</i>	X	X	X
<i>Parameter 1-26 Motor Cont. Rated Torque</i>		X	X
<i>Parameter 1-39 Motor Poles</i>		X	

Table 5.1 Basic Parameters to be checked before AMA

6 Basic I/O Configuration

The examples in this section are intended as a quick reference for common applications.

- Parameter settings are the regional default values unless otherwise indicated (selected in *parameter 0-03 Regional Settings*).
- Parameters associated with the terminals and their settings are shown next to the drawings.
- Required switch settings for analog terminals A53 or A54 are also shown.

NOTICE!

When using the optional Safe Torque Off (STO) feature, a jumper wire may be required between terminal 12 (or 13) and terminal 37 for the frequency converter to operate with factory default programming values.

6.1 Application Examples

6.1.1 Motor Thermistor

CAUTION

THERMISTOR INSULATION

Risk of personal injury or equipment damage.

- Use only thermistors with reinforced or double insulation to meet PELV insulation requirements.

		Parameters	
		Function	Setting
	+24 V	12	
	+24 V	13	
	D IN	18	
	D IN	19	
	COM	20	
	D IN	27	
	D IN	29	
	D IN	32	
	D IN	33	
	D IN	37	
	+10 V	50	
	A IN	53	
	A IN	54	
	COM	55	
A OUT	42		
COM	39		
		* = Default value	
		Notes/comments: If only a warning is required, set <i>parameter 1-90 Motor Thermal Protection</i> to [1] Thermistor warning. D IN 37 is an option.	

Table 6.1 Motor Thermistor

6.1.2 Mechanical Brake Control

6

		Parameters																																																					
		Function	Setting																																																				
<table border="1"> <tr><td colspan="2">FC</td></tr> <tr><td>+24 V</td><td>12</td></tr> <tr><td>+24 V</td><td>13</td></tr> <tr><td>D IN</td><td>18</td></tr> <tr><td>D IN</td><td>19</td></tr> <tr><td>COM</td><td>20</td></tr> <tr><td>D IN</td><td>27</td></tr> <tr><td>D IN</td><td>29</td></tr> <tr><td>D IN</td><td>32</td></tr> <tr><td>D IN</td><td>33</td></tr> <tr><td>D IN</td><td>37</td></tr> <tr><td colspan="2"> </td></tr> <tr><td>+10 V</td><td>50</td></tr> <tr><td>A IN</td><td>53</td></tr> <tr><td>A IN</td><td>54</td></tr> <tr><td>COM</td><td>55</td></tr> <tr><td>A OUT</td><td>42</td></tr> <tr><td>COM</td><td>39</td></tr> <tr><td colspan="2"> </td></tr> <tr><td>R1</td><td>01</td></tr> <tr><td></td><td>02</td></tr> <tr><td></td><td>03</td></tr> <tr><td colspan="2"> </td></tr> <tr><td>R2</td><td>04</td></tr> <tr><td></td><td>05</td></tr> <tr><td></td><td>06</td></tr> </table>	FC		+24 V	12	+24 V	13	D IN	18	D IN	19	COM	20	D IN	27	D IN	29	D IN	32	D IN	33	D IN	37			+10 V	50	A IN	53	A IN	54	COM	55	A OUT	42	COM	39			R1	01		02		03			R2	04		05		06	130BB841.10	Parameter 5-40 F unction Relay	[32] Mech. brake ctrl.
	FC																																																						
	+24 V	12																																																					
	+24 V	13																																																					
	D IN	18																																																					
	D IN	19																																																					
	COM	20																																																					
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	+10 V	50																																																					
A IN	53																																																						
A IN	54																																																						
COM	55																																																						
A OUT	42																																																						
COM	39																																																						
R1	01																																																						
	02																																																						
	03																																																						
R2	04																																																						
	05																																																						
	06																																																						
		Parameter 5-10 T erminal 18 Digital Input	[8] Start*																																																				
		Parameter 5-11 T erminal 19 Digital Input	[11] Start reversing																																																				
		Parameter 1-71 S tart Delay	0.2																																																				
		Parameter 1-72 S tart Function	[5] VVC ⁺ /FLUX Clockwise																																																				
		Parameter 1-76 S tart Current	I _{m,n}																																																				
		Parameter 2-20 R elease Brake Current	Application dependent																																																				
		Parameter 2-21 A ctivate Brake Speed [RPM]	Half of nominal slip of the motor																																																				
		*=-Default Value																																																					
		Notes/comments: -																																																					

Table 6.2 Mechanical Brake Control

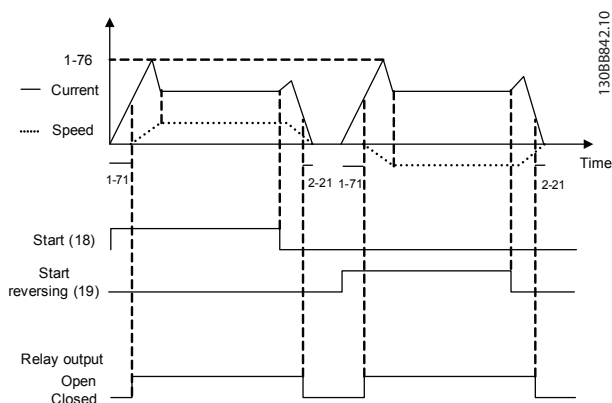


Figure 6.1 Mechanical Brake Control

7 Maintenance, Diagnostics, and Troubleshooting

7.1 Maintenance and Service

Under normal operating conditions and load profiles, the frequency converter is maintenance-free throughout its designed lifetime. To prevent breakdown, danger, and damage, examine the frequency converter for terminal connections tightness, dust entry, and so on at regular intervals depending on the operating conditions. Replace worn or damaged parts with original spare parts or standard parts. For service and support, contact the local Danfoss supplier.

⚠ WARNING

UNINTENDED START

When the frequency converter is connected to AC mains, DC supply, or load sharing, the motor may start at any time. Unintended start during programming, service, or repair work can result in death, serious injury, or property damage. The motor can start via an external switch, a fieldbus command, an input reference signal from the LCP, or after a cleared fault condition.

To prevent unintended motor start:

- Disconnect the frequency converter from the mains.
- Press [Off/Reset] on the LCP before programming parameters.
- Completely wire and assemble the frequency converter, motor, and any driven equipment before connecting the frequency converter to AC mains, DC supply, or load sharing.

7.2 Warning and Alarm Types

Warnings

A warning is issued when an alarm condition is impending, or when an abnormal operating condition is present and may result in the frequency converter issuing an alarm. A warning clears by itself when the abnormal condition ceases.

Alarms

An alarm indicates a fault that requires immediate attention. The fault always triggers a trip or a trip lock. Reset the system after an alarm.

Trip

An alarm is issued when the frequency converter is tripped, meaning that the frequency converter suspends operation to prevent frequency converter or system damage. The motor coasts to a stop. The frequency converter logic continues to operate and monitor the frequency converter status. After the fault condition is remedied, the frequency converter can be reset. It is then ready to start operation again.

Resetting the frequency converter after trip/trip lock

A trip can be reset in any of 4 ways:

- Press [Reset] on the LCP.
- Digital reset input command.
- Serial communication reset input command.
- Auto reset.

Trip lock

Input power is cycled. The motor coasts to a stop. The frequency converter continues to monitor the frequency converter status. Remove input power to the frequency converter, correct the cause of the fault, and reset the frequency converter.

Warning and alarm displays

- A warning is shown in the LCP along with the warning number.
- An alarm flashes along with the alarm number.

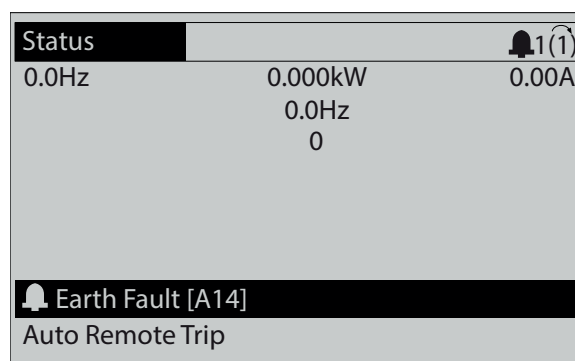
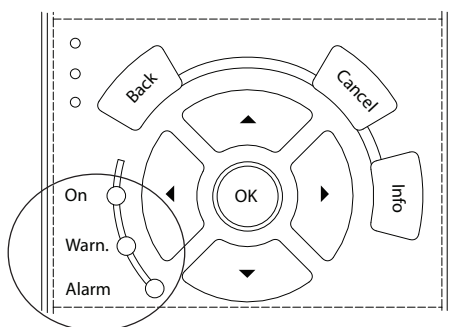


Figure 7.1 Alarm Example

In addition to the text and alarm code in the LCP there are 3 status indicator lights.



130BB467.11

	Warning indicator light	Alarm indicator light
Warning	On	Off
Alarm	Off	On (flashing)
Trip lock	On	On (flashing)

Figure 7.2 Status Indicator Lights

7.3 List of Warnings and Alarms

The following warning and alarm information defines each warning or alarm condition, provides the probable cause for the condition, and details a remedy or troubleshooting procedure.

WARNING 1, 10 Volts low

The control card voltage is less than 10 V from terminal 50. Remove some of the load from terminal 50, as the 10 V supply is overloaded. Maximum 15 mA or minimum 590 Ω.

A short circuit in a connected potentiometer or incorrect wiring of the potentiometer can cause this condition.

Troubleshooting

- Remove the wiring from terminal 50. If the warning clears, the problem is with the wiring. If the warning does not clear, replace the control card.

WARNING/ALARM 2, Live zero error

This warning or alarm only appears if programmed by the user in *parameter 6-01 Live Zero Timeout Function*. The signal on 1 of the analog inputs is less than 50% of the minimum value programmed for that input. Broken wiring or faulty device sending the signal can cause this condition.

Troubleshooting

Check connections on all the analog input terminals. Control card terminals 53 and 54 for signals, terminal 55 common. VLT® General Purpose I/O MCB 101 terminals 11 and 12 for signals, terminal 10 common. VLT® Analog I/O

MCB 109 terminals 1, 3, 5 for signals, terminals 2, 4, 6 common.

Check that the frequency converter programming and switch settings match the analog signal type.

Perform Input Terminal Signal Test.

WARNING/ALARM 3, No motor

No motor is connected to the output of the frequency converter.

WARNING/ALARM 4, Mains phase loss

A phase is missing on the supply side, or the mains voltage imbalance is too high. This message also appears for a fault in the input rectifier. Options are programmed in *parameter 14-12 Response to Mains Imbalance*.

Troubleshooting

- Check the supply voltage and supply currents to the frequency converter.

WARNING 5, DC link voltage high

The DC-link voltage is higher than the high-voltage warning limit. The limit depends on the frequency converter voltage rating. The unit is still active.

WARNING 6, DC link voltage low

The DC-link voltage is lower than the low-voltage warning limit. The limit depends on the frequency converter voltage rating. The unit is still active.

WARNING/ALARM 7, DC overvoltage

If the DC-link voltage exceeds the limit, the frequency converter trips after some time.

Troubleshooting

- Connect a brake resistor.
- Extend the ramp time.
- Change the ramp type.
- Activate the functions in *parameter 2-10 Brake Function*.
- Increase *parameter 14-26 Trip Delay at Inverter Fault*.

WARNING/ALARM 8, DC under voltage

If the DC-link voltage drops below the undervoltage limit, the frequency converter checks if a 24 V DC back-up supply is connected. If no 24 V DC back-up supply is connected, the frequency converter trips after a fixed time delay. The time delay varies with unit size.

Troubleshooting

- Check that the supply voltage matches the frequency converter voltage.
- Perform an input voltage test.
- Perform a soft charge circuit test.

WARNING/ALARM 9, Inverter overload

The frequency converter has run with more than 100% overload for too long and is about to cut out. The counter for electronic thermal inverter protection issues a warning at 98% and trips at 100% with an alarm. The frequency converter cannot be reset until the counter is below 90%.

Troubleshooting

- Compare the output current shown on the LCP with the frequency converter rated current.
- Compare the output current shown on the LCP with the measured motor current.
- Show the thermal frequency converter load on the LCP and monitor the value. When running above the frequency converter continuous current rating, the counter increases. When running below the frequency converter continuous current rating, the counter decreases.

WARNING/ALARM 10, Motor overload temperature

According to the electronic thermal protection (ETR), the motor is too hot.

Select 1 of these options:

- The frequency converter issues a warning or an alarm when the counter is >90% if *parameter 1-90 Motor Thermal Protection* is set to warning options.
- The frequency converter trips when the counter reaches 100% if *parameter 1-90 Motor Thermal Protection* is set to trip options.

The fault occurs when the motor runs with more than 100% overload for too long.

Troubleshooting

- Check for motor overheating.
- Check if the motor is mechanically overloaded.
- Check that the motor current set in *parameter 1-24 Motor Current* is correct.
- Ensure that the motor data in *parameters 1-20 to 1-25* is set correctly.
- If an external fan is in use, check that it is selected in *parameter 1-91 Motor External Fan*.
- Running AMA in *parameter 1-29 Automatic Motor Adaptation (AMA)* tunes the frequency converter to the motor more accurately and reduces thermal loading.

WARNING/ALARM 11, Motor thermistor overtemp

Check whether the thermistor is disconnected. Select whether the frequency converter issues a warning or an alarm in *parameter 1-90 Motor Thermal Protection*.

Troubleshooting

- Check for motor overheating.
- Check if the motor is mechanically overloaded.
- When using terminal 53 or 54, check that the thermistor is connected correctly between either terminal 53 or 54 (analog voltage input) and terminal 50 (+10 V supply). Also check that the terminal switch for 53 or 54 is set for voltage. Check that *parameter 1-93 Thermistor Resource* selects terminal 53 or 54.
- When using terminal 18, 19, 31, 32, or 33 (digital inputs), check that the thermistor is connected correctly between the digital input terminal used (digital input PNP only) and terminal 50. Select the terminal to use in *parameter 1-93 Thermistor Resource*.

WARNING/ALARM 12, Torque limit

The torque has exceeded the value in *parameter 4-16 Torque Limit Motor Mode* or the value in *parameter 4-17 Torque Limit Generator Mode*. *Parameter 14-25 Trip Delay at Torque Limit* can change this warning from a warning-only condition to a warning followed by an alarm.

Troubleshooting

- If the motor torque limit is exceeded during ramp-up, extend the ramp-up time.
- If the generator torque limit is exceeded during ramp-down, extend the ramp-down time.
- If torque limit occurs while running, increase the torque limit. Make sure that the system can operate safely at a higher torque.
- Check the application for excessive current draw on the motor.

WARNING/ALARM 13, Over current

The inverter peak current limit (approximately 200% of the rated current) is exceeded. The warning lasts approximately 1.5 s, then the frequency converter trips and issues an alarm. Shock loading or quick acceleration with high-inertia loads can cause this fault. If the acceleration during ramp-up is quick, the fault can also appear after kinetic back-up. If extended mechanical brake control is selected, a trip can be reset externally.

Troubleshooting

- Remove the power and check if the motor shaft can be turned.
- Check that the motor size matches the frequency converter.
- Check that the motor data is correct in *parameters 1-20 to 1-25*.

ALARM 14, Earth (ground) fault

There is current from the output phase-to-ground, either in the cable between the frequency converter and the motor, or in the motor itself. The current transducers detect the ground fault by measuring current going out from the frequency converter and current going into the frequency converter from the motor. Ground fault is issued if the deviation of the 2 currents is too large. The current going out of the frequency converter must be the same as the current going into the frequency converter.

Troubleshooting

- Remove power to the frequency converter and repair the ground fault.
- Check for ground faults in the motor by measuring the resistance to ground of the motor cables and the motor with a megohmmeter.
- Reset any potential individual offset in the 3 current transducers in the frequency converter. Perform the manual initialization or perform a complete AMA. This method is most relevant after changing the power card.

ALARM 15, Hardware mismatch

A fitted option is not operational with the present control card hardware or software.

Record the value of the following parameters and contact Danfoss.

- *Parameter 15-40 FC Type.*
- *Parameter 15-41 Power Section.*
- *Parameter 15-42 Voltage.*
- *Parameter 15-43 Software Version.*
- *Parameter 15-45 Actual Typecode String.*
- *Parameter 15-49 SW ID Control Card.*
- *Parameter 15-50 SW ID Power Card.*
- *Parameter 15-60 Option Mounted.*
- *Parameter 15-61 Option SW Version (for each option slot).*

ALARM 16, Short circuit

There is short-circuiting in the motor or motor wiring.

Troubleshooting

- Remove the power to the frequency converter and repair the short circuit.

▲WARNING**HIGH VOLTAGE**

Frequency converters contain high voltage when connected to AC mains input, DC supply, or load sharing. Failure to use qualified personnel to install, start up, and maintain the frequency converter can result in death or serious injury.

- **Disconnect power before proceeding.**

WARNING/ALARM 17, Control word timeout

There is no communication to the frequency converter. The warning is only active when *parameter 8-04 Control Word Timeout Function* is NOT set to [0] Off.

If *parameter 8-04 Control Word Timeout Function* is set to [5] Stop and trip, a warning appears, and the frequency converter ramps down to a stop and shows an alarm.

Troubleshooting

- Check the connections on the serial communication cable.
- Increase *parameter 8-03 Control Word Timeout Time*.
- Check the operation of the communication equipment.
- Verify that proper EMC installation was performed.

WARNING/ALARM 20, Temp. input error

The temperature sensor is not connected.

WARNING/ALARM 21, Parameter error

The parameter is out of range. The parameter number is shown in the display.

Troubleshooting

- Set the affected parameter to a valid value.

WARNING/ALARM 22, Hoist mechanical brake

The value of this warning/alarm shows the type of warning/alarm.

0 = The torque reference was not reached before timeout (*parameter 2-27 Torque Ramp Time*).

1 = Expected brake feedback was not received before timeout (*parameter 2-23 Activate Brake Delay*, *parameter 2-25 Brake Release Time*).

WARNING 23, Internal fan fault

The fan warning function is a protective function that checks if the fan is running/mounted. The fan warning can be disabled in *parameter 14-53 Fan Monitor ([0] Disabled)*.

There is a feedback sensor mounted in the fan. If the fan is commanded to run and there is no feedback from the sensor, this alarm appears. This alarm also shows if there is a communication error between the fan power card and the control card.

Check the alarm log (see *chapter 5.2 Local Control Panel Operation*) for the report value associated with this warning.

If the report value is 2, there is a hardware problem with 1 of the fans. If the report value is 12, there is a communication problem between the fan power card and the control card.

Fan troubleshooting

- Cycle power to the frequency converter and check that the fan operates briefly at start-up.
- Check for proper fan operation. Use *parameter group 43-**Unit Readouts* to show the speed of each fan.

Fan power card troubleshooting

- Check the wiring between the fan power card and the control card.
- Fan power card may need to be replaced.
- Control card may need to be replaced.

WARNING 24, External fan fault

The fan warning function is a protective function that checks if the fan is running/mounted. The fan warning can be disabled in *parameter 14-53 Fan Monitor ([0] Disabled)*.

There is a feedback sensor mounted in the fan. If the fan is commanded to run and there is no feedback from the sensor, this alarm appears. This alarm also shows if there is a communication error between the power card and the control card.

Check the alarm log (see *chapter 5.2 Local Control Panel Operation*) for the report value associated with this warning.

If the report value is 1, there is a hardware problem with 1 of the fans. If the report value is 11, there is a communication problem between the power card and the control card.

Fan troubleshooting

- Cycle power to the frequency converter and check that the fan operates briefly at start-up.
- Check for proper fan operation. Use *parameter group 43-**Unit Readouts* to show the speed of each fan.

Power card troubleshooting

- Check the wiring between the power card and the control card.
- Power card may need to be replaced.
- Control card may need to be replaced.

WARNING 25, Brake resistor short circuit

The brake resistor is monitored during operation. If a short circuit occurs, the brake function is disabled and the warning appears. The frequency converter is still operational, but without the brake function.

Troubleshooting

- Remove the power to the frequency converter and replace the brake resistor (refer to *parameter 2-15 Brake Check*).

WARNING/ALARM 26, Brake resistor power limit

The power transmitted to the brake resistor is calculated as an average value over the last 120 s of run-time. The calculation is based on the DC-link voltage and the brake resistor value set in *parameter 2-16 AC brake Max. Current*. The warning is active when the dissipated braking power is higher than 90% of the brake resistor power. If option [2] *Trip* is selected in *parameter 2-13 Brake Power Monitoring*, the frequency converter trips when the dissipated braking power reaches 100%.

WARNING/ALARM 27, Brake chopper fault

The brake transistor is monitored during operation, and if a short circuit occurs, the brake function is disabled, and a warning is issued. The frequency converter is still operational, but since the brake transistor has short-circuited, substantial power is transmitted to the brake resistor, even if it is inactive.

Troubleshooting

- Remove power to the frequency converter and remove the brake resistor.

WARNING/ALARM 28, Brake check failed

The brake resistor is not connected or not working.

Troubleshooting

- Check *parameter 2-15 Brake Check*.

ALARM 29, Heat sink temp

The maximum temperature of the heat sink is exceeded. The temperature fault is not reset until the temperature drops below a defined heat sink temperature. The trip and reset points are different based on the frequency converter power size.

Troubleshooting

Check for the following conditions:

- The ambient temperature is too high.
- The motor cables are too long.
- Incorrect airflow clearance above and below the frequency converter.
- Blocked airflow around the frequency converter.
- Damaged heat sink fan.
- Dirty heat sink.

ALARM 30, Motor phase U missing

Motor phase U between the frequency converter and the motor is missing.

⚠ WARNING**HIGH VOLTAGE**

Frequency converters contain high voltage when connected to AC mains input, DC supply, or load sharing. Failure to use qualified personnel to install, start up, and maintain the frequency converter can result in death or serious injury.

- Disconnect power before proceeding.

Troubleshooting

- Remove the power from the frequency converter and check motor phase U.

ALARM 31, Motor phase V missing

Motor phase V between the frequency converter and the motor is missing.

⚠ WARNING**HIGH VOLTAGE**

Frequency converters contain high voltage when connected to AC mains input, DC supply, or load sharing. Failure to use qualified personnel to install, start up, and maintain the frequency converter can result in death or serious injury.

- Disconnect power before proceeding.

Troubleshooting

- Remove the power from the frequency converter and check motor phase V.

ALARM 32, Motor phase W missing

Motor phase W between the frequency converter and the motor is missing.

⚠ WARNING**HIGH VOLTAGE**

Frequency converters contain high voltage when connected to AC mains input, DC supply, or load sharing. Failure to use qualified personnel to install, start up, and maintain the frequency converter can result in death or serious injury.

- Disconnect power before proceeding.

Troubleshooting

- Remove the power from the frequency converter and check motor phase W.

ALARM 33, Inrush fault

Too many power-ups have occurred within a short time period.

Troubleshooting

- Let the unit cool to operating temperature.

WARNING/ALARM 34, Fieldbus communication fault

The fieldbus on the communication option card is not working.

WARNING/ALARM 35, Option fault

An option alarm is received. The alarm is option-specific. The most likely cause is a power-up or a communication fault.

WARNING/ALARM 36, Mains failure

This warning/alarm is only active if the supply voltage to the frequency converter is lost and *parameter 14-10 Mains Failure* is NOT set to [0] No Function. Check the fuses to the frequency converter and mains power supply to the unit.

ALARM 37, Phase imbalance

There is a current imbalance between the power units.

ALARM 38, Internal fault

When an internal fault occurs, a code number defined in *Table 7.1* is shown.

Troubleshooting

- Cycle power.
- Check that the option is properly installed.
- Check for loose or missing wiring.

It may be necessary to contact the Danfoss supplier or service department. Note the code number for further troubleshooting directions

Number	Text
0	The serial port cannot be initialized. Contact the Danfoss supplier or Danfoss service department.
256–258	The power EEPROM data is defective or too old. Replace the power card.
512–519	Internal fault. Contact the Danfoss supplier or Danfoss service department.
783	Parameter value outside of minimum/maximum limits.
1024–1284	Internal fault. Contact the Danfoss supplier or Danfoss service department.
1299	The option software in slot A is too old.
1300	The option software in slot B is too old.
1302	The option software in slot C1 is too old.
1315	The option software in slot A is not supported/allowed.
1316	The option software in slot B is not supported/allowed.
1318	The option software in slot C1 is not supported/allowed.
1379–2819	Internal fault. Contact the Danfoss supplier or Danfoss service department.
1792	Hardware reset of digital signal processor.
1793	Motor-derived parameters not transferred correctly to the digital signal processor.
1794	Power data not transferred correctly at power-up to the digital signal processor.
1795	The digital signal processor has received too many unknown SPI telegrams. The frequency converter also uses this fault code if the MCO does not power up correctly. This situation can occur due to poor EMC protection or improper grounding.
1796	RAM copy error.
2561	Replace the control card.
2820	LCP stack overflow.
2821	Serial port overflow.
2822	USB port overflow.
3072–5122	Parameter value is outside its limits.
5123	Option in slot A: Hardware incompatible with the control board hardware.
5124	Option in slot B: Hardware incompatible with the control board hardware.
5125	Option in slot C0: Hardware incompatible with the control board hardware.
5126	Option in slot C1: Hardware incompatible with the control board hardware.
5376–6231	Internal fault. Contact the Danfoss supplier or Danfoss service department.

Table 7.1 Internal Fault Codes

ALARM 39, Heat sink sensor

No feedback from the heat sink temperature sensor.

The signal from the IGBT thermal sensor is not available on the power card. The problem could be on the power card, on the gatedrive card, or the ribbon cable between the power card and gatedrive card.

WARNING 40, Overload of digital output terminal 27

Check the load connected to terminal 27 or remove the short-circuit connection. Check *parameter 5-00 Digital I/O Mode* and *parameter 5-01 Terminal 27 Mode*.

WARNING 41, Overload of digital output terminal 29

Check the load connected to terminal 29 or remove the short-circuit connection. Also check *parameter 5-00 Digital I/O Mode* and *parameter 5-02 Terminal 29 Mode*.

WARNING 42, Overload of digital output on X30/6 or overload of digital output on X30/7

For terminal X30/6, check the load connected to terminal X30/6 or remove the short-circuit connection. Also check *parameter 5-32 Term X30/6 Digi Out (MCB 101)* (VLT[®] General Purpose I/O MCB 101).

For terminal X30/7, check the load connected to terminal X30/7 or remove the short-circuit connection. Check *parameter 5-33 Term X30/7 Digi Out (MCB 101)* (VLT[®] General Purpose I/O MCB 101).

ALARM 43, Ext. supply

VLT[®] Extended Relay Option MCB 113 is mounted without external 24 V DC. Either connect a 24 V DC external supply or specify that no external supply is used via *parameter 14-80 Option Supplied by External 24VDC, [0] No.* A change in *parameter 14-80 Option Supplied by External 24VDC* requires a power cycle.

ALARM 45, Earth fault 2

Ground fault.

Troubleshooting

- Check for proper grounding and loose connections.
- Check for proper wire size.
- Check the motor cables for short circuits or leakage currents.

ALARM 46, Power card supply

The supply on the power card is out of range. Another reason can be a defective heat sink fan.

There are 3 supplies generated by the switch mode supply (SMPS) on the power card:

- 24 V.
- 5 V.
- ±18 V.

When powered with VLT® 24 V DC Supply MCB 107, only the 24 V and 5 V supplies are monitored. When powered with 3-phase mains voltage, all 3 supplies are monitored.

Troubleshooting

- Check for a defective power card.
- Check for a defective control card.
- Check for a defective option card.
- If a 24 V DC supply is used, verify proper supply power.
- Check for a defective heat sink fan.

WARNING 47, 24 V supply low

The supply on the power card is out of range.

There are 3 supplies generated by the switch mode supply (SMPS) on the power card:

- 24 V.
- 5 V.
- ± 18 V.

Troubleshooting

- Check for a defective power card.

WARNING 48, 1.8 V supply low

The 1.8 V DC supply used on the control card is outside of the allowable limits. The supply is measured on the control card.

Troubleshooting

- Check for a defective control card.
- If an option card is present, check for overvoltage.

WARNING 49, Speed limit

The warning is shown when the speed is outside of the specified range in *parameter 4-11 Motor Speed Low Limit [RPM]* and *parameter 4-13 Motor Speed High Limit [RPM]*. When the speed is below the specified limit in *parameter 1-86 Trip Speed Low [RPM]* (except when starting or stopping), the frequency converter trips.

ALARM 50, AMA calibration failed

Contact the Danfoss supplier or Danfoss Service Department.

ALARM 51, AMA check U_{nom} and I_{nom}

The settings for motor voltage, motor current, and motor power are wrong.

Troubleshooting

- Check the settings in *parameters 1-20 to 1-25*.

ALARM 52, AMA low I_{nom}

The motor current is too low.

Troubleshooting

- Check the settings in *parameter 1-24 Motor Current*.

ALARM 53, AMA motor too big

The motor is too large for the AMA to operate.

ALARM 54, AMA motor too small

The motor is too small for the AMA to operate.

ALARM 55, AMA parameter out of range

The AMA cannot run because the parameter values of the motor are outside of the acceptable range.

ALARM 56, AMA interrupted by user

The AMA is manually interrupted.

ALARM 57, AMA internal fault

Try to restart the AMA. Repeated restarts can overheat the motor.

ALARM 58, AMA Internal fault

Contact the Danfoss supplier.

WARNING 59, Current limit

The current is higher than the value in *parameter 4-18 Current Limit*. Ensure that the motor data in *parameters 1-20 to 1-25* is set correctly. Increase the current limit if necessary. Ensure that the system can operate safely at a higher limit.

WARNING 60, External interlock

A digital input signal indicates a fault condition external to the frequency converter. An external interlock has commanded the frequency converter to trip.

Troubleshooting

- Clear the external fault condition.
- To resume normal operation, apply 24 V DC to the terminal programmed for external interlock.
- Reset the frequency converter.

WARNING/ALARM 61, Feedback error

An error between calculated speed and speed measurement from feedback device.

Troubleshooting

- Check the settings for warning/alarm/disabling in *parameter 4-30 Motor Feedback Loss Function*.
- Set the tolerable error in *parameter 4-31 Motor Feedback Speed Error*.
- Set the tolerable feedback loss time in *parameter 4-32 Motor Feedback Loss Timeout*.

WARNING 62, Output frequency at maximum limit

If the output frequency reaches the value set in *parameter 4-19 Max Output Frequency*, the frequency converter issues a warning. The warning ceases when the output drops below the maximum limit. If the frequency converter is unable to limit the frequency, it trips and issues an alarm. The latter may happen in the flux mode if the frequency converter loses control of the motor.

Troubleshooting

- Check the application for possible causes.
- Increase the output frequency limit. Ensure that the system can operate safely at a higher output frequency.

ALARM 63, Mechanical brake low

The actual motor current has not exceeded the release brake current within the start delay time window.

WARNING 64, Voltage Limit

The load and speed combination demands a motor voltage higher than the actual DC-link voltage.

WARNING/ALARM 65, Control card over temperature

The cutout temperature of the control card is 85 °C (185 °F).

Troubleshooting

- Check that the ambient operating temperature is within the limits.
- Check for clogged filters.
- Check the fan operation.
- Check the control card.

WARNING 66, Heat sink temperature low

The frequency converter is too cold to operate. This warning is based on the temperature sensor in the IGBT module. Increase the ambient temperature of the unit. Also, a trickle amount of current can be supplied to the frequency converter whenever the motor is stopped by setting *parameter 2-00 DC Hold/Preheat Current* to 5% and *parameter 1-80 Function at Stop*.

ALARM 67, Option module configuration has changed

One or more options have either been added or removed since the last power-down. Check that the configuration change is intentional and reset the unit.

ALARM 68, Safe Stop activated

Safe Torque Off (STO) has been activated. To resume normal operation, apply 24 V DC to terminal 37, then send a reset signal (via bus, digital I/O, or by pressing [Reset]).

ALARM 69, Power card temperature

The temperature sensor on the power card is either too hot or too cold.

Troubleshooting

- Check that the ambient operating temperature is within limits.
- Check for clogged filters.
- Check fan operation.
- Check the power card.

ALARM 70, Illegal FC configuration

The control card and power card are incompatible. To check compatibility, contact the Danfoss supplier with the type code from the unit nameplate and the part numbers of the cards.

ALARM 71, PTC 1 safe stop

STO has been activated from the VLT® PTC Thermistor Card MCB 112 (motor too warm). Normal operation can be resumed when the MCB 112 applies 24 V DC to terminal 37 again (when the motor temperature reaches an acceptable level), and when the digital input from the MCB 112 is deactivated. When that happens, send a reset signal (via bus or digital I/O, or press [Reset]).

ALARM 72, Dangerous failure

STO with trip lock. An unexpected combination of STO commands has occurred:

- VLT® PTC Thermistor Card MCB 112 enables X44/10, but STO is not enabled.
- MCB 112 is the only device using STO (specified through selection [4] *PTC 1 alarm* or [5] *PTC 1 warning* in *parameter 5-19 Terminal 37 Safe Stop*), STO is activated, and X44/10 is not activated.

WARNING 73, Safe Stop auto restart

STO activated. With automatic restart enabled, the motor can start when the fault is cleared.

ALARM 74, PTC Thermistor

Alarm related to VLT® PTC Thermistor Card MCB 112. The PTC is not working.

ALARM 75, Illegal profile sel.

Do not write the parameter value while the motor is running. Stop the motor before writing the MCO profile to *parameter 8-10 Control Word Profile*.

WARNING 77, Reduced power mode

The frequency converter is operating in reduced power mode (less than the allowed number of inverter sections). This warning is generated on power cycle when the frequency converter is set to run with fewer inverters and remains on.

ALARM 78, Tracking error

The difference between setpoint value and actual value exceeds the value in *parameter 4-35 Tracking Error*.

Troubleshooting

- Disable the function or select an alarm/warning in *parameter 4-34 Tracking Error Function*.
- Investigate the mechanics around the load and motor. Check feedback connections from motor encoder to frequency converter.
- Select motor feedback function in *parameter 4-30 Motor Feedback Loss Function*.
- Adjust the tracking error band in *parameter 4-35 Tracking Error* and *parameter 4-37 Tracking Error Ramping*.

ALARM 79, Illegal power section configuration

The scaling card has an incorrect part number or is not installed. The MK102 connector on the power card could not be installed.

ALARM 80, Drive initialised to default value

Parameter settings are initialized to default settings after a manual reset. To clear the alarm, reset the unit.

ALARM 81, CSIV corrupt

CSIV file has syntax errors.

ALARM 82, CSIV parameter error

CSIV failed to initialize a parameter.

ALARM 83, Illegal option combination

The mounted options are incompatible.

ALARM 84, No safety option

The safety option was removed without applying a general reset. Reconnect the safety option.

ALARM 88, Option detection

A change in the option layout is detected.

Parameter 14-89 Option Detection is set to [0] *Frozen configuration* and the option layout has been changed.

- To apply the change, enable option layout changes in *parameter 14-89 Option Detection*.
- Alternatively, restore the correct option configuration.

WARNING 89, Mechanical brake sliding

The hoist brake monitor detects a motor speed exceeding 10 RPM.

ALARM 90, Feedback monitor

Check the connection to encoder/resolver option and, if necessary, replace VLT® Encoder Input MCB 102 or VLT® Resolver Input MCB 103.

ALARM 91, Analog input 54 wrong settings

Set switch S202 in position OFF (voltage input) when a KTY sensor is connected to analog input terminal 54.

ALARM 99, Locked rotor

The rotor is blocked.

WARNING/ALARM 104, Mixing fan fault

The fan is not operating. The fan monitor checks that the fan is spinning at power-up or whenever the mixing fan is turned on. The mixing-fan fault can be configured as a warning or an alarm trip in *parameter 14-53 Fan Monitor*.

Troubleshooting

- Cycle power to the frequency converter to determine if the warning/alarm returns.

WARNING/ALARM 122, Mot. rotat. unexp.

The frequency converter performs a function that requires the motor to be at standstill, for example DC hold for PM motors.

WARNING 163, ATEX ETR cur.lim.warning

The frequency converter has run above the characteristic curve for more than 50 s. The warning is activated at 83% and deactivated at 65% of the allowed thermal overload.

ALARM 164, ATEX ETR cur.lim.alarm

Operating above the characteristic curve for more than 60 s within a period of 600 s activates the alarm, and the frequency converter trips.

WARNING 165, ATEX ETR freq.lim.warning

The frequency converter is running for more than 50 s below the allowed minimum frequency (*parameter 1-98 ATEX ETR interpol. points freq.*).

ALARM 166, ATEX ETR freq.lim.alarm

The frequency converter has operated for more than 60 s (in a period of 600 s) below the allowed minimum frequency (*parameter 1-98 ATEX ETR interpol. points freq.*).

WARNING 250, New spare part

A component in the drive system has been replaced.

Troubleshooting

- Reset the drive system to restore normal operation.

WARNING 251, New typecode

The power card or other components are replaced, and the type code has changed.

8 Specifications

8.1 Electrical Data

8.1.1 Mains Supply 200–240 V

Type designation	PK25	PK37	PK55	PK75	P1K1	P1K5	P2K2	P3K0	P3K7
Typical shaft output [kW/(hp)], high overload	0.25 (0.34)	0.37 (0.5)	0.55 (0.75)	0.75 (1.0)	1.1 (1.5)	1.5 (2.0)	2.2 (3.0)	3.0 (4.0)	3.7 (5.0)
Enclosure protection rating IP20 (FC 301 only)	A1	A1	A1	A1	A1	A1	–	–	–
Enclosure protection rating IP20, IP21	A2	A2	A2	A2	A2	A2	A2	A3	A3
Enclosure protection rating IP55, IP66	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A5	A5
Output current									
Continuous (200–240 V) [A]	1.8	2.4	3.5	4.6	6.6	7.5	10.6	12.5	16.7
Intermittent (200–240 V) [A]	2.9	3.8	5.6	7.4	10.6	12.0	17.0	20.0	26.7
Continuous kVA (208 V) [kVA]	0.65	0.86	1.26	1.66	2.38	2.70	3.82	4.50	6.00
Maximum input current									
Continuous (200–240 V) [A]	1.6	2.2	3.2	4.1	5.9	6.8	9.5	11.3	15.0
Intermittent (200–240 V) [A]	2.6	3.5	5.1	6.6	9.4	10.9	15.2	18.1	24.0
Additional specifications									
Maximum cable cross-section ^{2),5)} for mains, motor, brake, and load sharing [mm ²] ([AWG])	4, 4, 4 (12,12,12) (minimum 0.2 (24))								
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	6, 4, 4 (10,12,12)								
Estimated power loss at rated maximum load [W] ³⁾	21	29	42	54	63	82	116	155	185
Efficiency ⁴⁾	0.94	0.94	0.95	0.95	0.96	0.96	0.96	0.96	0.96

Table 8.1 Mains Supply 200–240 V, PK25–P3K7

Type designation	P5K5		P7K5		P11K	
	HO	NO	HO	NO	HO	NO
High/normal overload ¹⁾						
Typical shaft output [kW/(hp)]	5.5 (7.5)	7.5 (10)	7.5 (10)	11 (15)	11 (15)	15 (20)
Enclosure protection rating IP20	B3		B3		B4	
Enclosure protection rating IP21, IP55, IP66	B1		B1		B2	
Output current						
Continuous (200–240 V) [A]	24.2	30.8	30.8	46.2	46.2	59.4
Intermittent (60 s overload) (200–240 V) [A]	38.7	33.9	49.3	50.8	73.9	65.3
Continuous kVA (208 V) [kVA]	8.7	11.1	11.1	16.6	16.6	21.4
Maximum input current						
Continuous (200–240 V) [A]	22.0	28.0	28.0	42.0	42.0	54.0
Intermittent (60 s overload) (200–240 V) [A]	35.2	30.8	44.8	46.2	67.2	59.4
Additional specifications						
IP20 maximum cable cross-section ^{2),5)} for mains, brake, motor, and load sharing [mm ²] ([AWG])	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35,-,- (2,-,-)	
IP21 maximum cable cross-section ^{2),5)} for mains, brake, and load sharing [mm ²] ([AWG])	16,10,16 (6, 8, 6)		16,10,16 (6, 8, 6)		35,-,- (2,-,-)	
IP21 maximum cable cross-section ^{2),5)} for motor [mm ²] ([AWG])	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35,25,25 (2, 4, 4)	
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	16,10,10 (6, 8, 8)					
Estimated power loss at rated maximum load [W] ³⁾	239	310	371	514	463	602
Efficiency ⁴⁾	0.96		0.96		0.96	

Table 8.2 Mains Supply 200–240 V, P5K5–P11K

Type designation	P15K		P18K		P22K		P30K		P37K	
High/normal overload ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical shaft output [kW/(hp)]	15 (20)	18.5 (25)	18.5 (25)	22 (30)	22 (30)	30 (40)	30 (40)	37 (50)	37 (50)	45 (60)
Enclosure protection rating IP20	B4		C3		C3		C4		C4	
Enclosure protection rating IP21, IP55, IP66	C1		C1		C1		C2		C2	
Output current										
Continuous (200–240 V) [A]	59.4	74.8	74.8	88.0	88.0	115	115	143	143	170
Intermittent (60 s overload) (200–240 V) [A]	89.1	82.3	112	96.8	132	127	173	157	215	187
Continuous kVA (208 V) [kVA]	21.4	26.9	26.9	31.7	31.7	41.4	41.4	51.5	51.5	61.2
Maximum input current										
Continuous (200–240 V) [A]	54.0	68.0	68.0	80.0	80.0	104	104	130	130	154
Intermittent (60 s overload) (200–240 V) [A]	81.0	74.8	102	88.0	120	114	156	143	195	169
Additional specifications										
IP20 maximum cable cross-section ⁵⁾ for mains, brake, motor, and load sharing [mm ²] ([AWG])	35 (2)		50 (1)		50 (1)		150 (300 MCM)		150 (300 MCM)	
IP21, IP55, IP66 maximum cable cross-section ⁵⁾ for mains and motor [mm ²] ([AWG])	50 (1)		50 (1)		50 (1)		150 (300 MCM)		150 (300 MCM)	
IP21, IP55, IP66 maximum cable cross-section ⁵⁾ for brake and load sharing [mm ²] ([AWG])	50 (1)		50 (1)		50 (1)		95 (3/0)		95 (3/0)	
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	50, 35, 35 (1, 2, 2)						95, 70, 70 (3/0, 2/0, 2/0)		185, 150, 120 (350 MCM, 300 MCM, 4/0)	
Estimated power loss at rated maximum load [W] ³⁾	624	737	740	845	874	1140	1143	1353	1400	1636
Efficiency ⁴⁾	0.96		0.97		0.97		0.97		0.97	

Table 8.3 Mains Supply 200–240 V, P15K–P37K

8.1.2 Mains Supply 380–500 V

Type designation	PK37	PK55	PK75	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5
Typical shaft output [kW/(hp)], high overload	0.37 (0.5)	0.55 (0.75)	0.75 (1.0)	1.1 (1.5)	1.5 (2.0)	2.2 (3.0)	3.0 (4.0)	4.0 (5.0)	5.5 (7.5)	7.5 (10)
Enclosure protection rating IP20 (FC 301 only)	A1	A1	A1	A1	A1	–	–	–	–	–
Enclosure protection rating IP20, IP21	A2	A2	A2	A2	A2	A2	A2	A2	A3	A3
Enclosure protection rating IP55, IP66	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A4/A5	A5	A5
Output current high overload 160% for 1 minute										
Shaft output [kW/(hp)]	0.37 (0.5)	0.55 (0.75)	0.75 (1.0)	1.1 (1.5)	1.5 (2.0)	2.2 (3.0)	3.0 (4.0)	4.0 (5.0)	5.5 (7.5)	7.5 (10)
Continuous (380–440 V) [A]	1.3	1.8	2.4	3.0	4.1	5.6	7.2	10	13	16
Intermittent (380–440 V) [A]	2.1	2.9	3.8	4.8	6.6	9.0	11.5	16	20.8	25.6
Continuous (441–500 V) [A]	1.2	1.6	2.1	2.7	3.4	4.8	6.3	8.2	11	14.5
Intermittent (441–500 V) [A]	1.9	2.6	3.4	4.3	5.4	7.7	10.1	13.1	17.6	23.2
Continuous kVA (400 V) [kVA]	0.9	1.3	1.7	2.1	2.8	3.9	5.0	6.9	9.0	11
Continuous kVA (460 V) [kVA]	0.9	1.3	1.7	2.4	2.7	3.8	5.0	6.5	8.8	11.6
Maximum input current										
Continuous (380–440 V) [A]	1.2	1.6	2.2	2.7	3.7	5.0	6.5	9.0	11.7	14.4
Intermittent (380–440 V) [A]	1.9	2.6	3.5	4.3	5.9	8.0	10.4	14.4	18.7	23
Continuous (441–500 V) [A]	1.0	1.4	1.9	2.7	3.1	4.3	5.7	7.4	9.9	13
Intermittent (441–500 V) [A]	1.6	2.2	3.0	4.3	5.0	6.9	9.1	11.8	15.8	20.8
Additional specifications										
IP20, IP21 maximum cable cross-section ^{2),5)} for mains, motor, brake, and load sharing [mm ²] ([AWG])	4, 4, 4 (12,12,12) (minimum 0.2(24))									
IP55, IP66 maximum cable cross-section ^{2),5)} for mains, motor, brake, and load sharing [mm ²] ([AWG])	4, 4, 4 (12,12,12)									
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	6, 4, 4 (10,12,12)									
Estimated power loss at rated maximum load [W] ³⁾	35	42	46	58	62	88	116	124	187	255
Efficiency ⁴⁾	0.93	0.95	0.96	0.96	0.97	0.97	0.97	0.97	0.97	0.97

Table 8.4 Mains Supply 380–500 V (FC 302), 380–480 V (FC 301), PK37–P7K5

Type designation	P11K		P15K		P18K		P22K	
High/normal overload ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO
Typical shaft output [kW/(hp)]	11 (15)	15 (20)	15 (20)	18.5 (25)	18.5 (25)	22 (30)	22 (30)	30 (40)
Enclosure protection rating IP20	B3		B3		B4		B4	
Enclosure protection rating IP21, IP55, IP66	B1		B1		B2		B2	
Output current								
Continuous (380–440 V) [A]	24	32	32	37.5	37.5	44	44	61
Intermittent (60 s overload) (380–440 V) [A]	38.4	35.2	51.2	41.3	60	48.4	70.4	67.1
Continuous (441–500 V) [A]	21	27	27	34	34	40	40	52
Intermittent (60 s overload) (441–500 V) [A]	33.6	29.7	43.2	37.4	54.4	44	64	57.2
Continuous kVA (400 V) [kVA]	16.6	22.2	22.2	26	26	30.5	30.5	42.3
Continuous kVA (460 V) [kVA]	–	21.5	–	27.1	–	31.9	–	41.4
Maximum input current								
Continuous (380–440 V) [A]	22	29	29	34	34	40	40	55
Intermittent (60 s overload) (380–440 V) [A]	35.2	31.9	46.4	37.4	54.4	44	64	60.5
Continuous (441–500 V) [A]	19	25	25	31	31	36	36	47
Intermittent (60 s overload) (441–500 V) [A]	30.4	27.5	40	34.1	49.6	39.6	57.6	51.7
Additional specifications								
IP21, IP55, IP66 maximum cable cross-section ^{2),5)} for mains, brake, and load sharing [mm ²] ([AWG])	16, 10, 16 (6, 8, 6)		16, 10, 16 (6, 8, 6)		35,-,-(2,-,-)		35,-,-(2,-,-)	
IP21, IP55, IP66 maximum cable cross-section ^{2),5)} for motor [mm ²] ([AWG])	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35, 25, 25 (2, 4, 4)		35, 25, 25 (2, 4, 4)	
IP20 maximum cable cross-section ^{2),5)} for mains, brake, motor, and load sharing [mm ²] ([AWG])	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35,-,-(2,-,-)		35,-,-(2,-,-)	
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	16, 10, 10 (6, 8, 8)							
Estimated power loss at rated maximum load [W] ³⁾	291	392	379	465	444	525	547	739
Efficiency ⁴⁾	0.98		0.98		0.98		0.98	

Table 8.5 Mains Supply 380–500 V (FC 302), 380–480 V (FC 301), P11K–P22K

Type designation	P30K		P37K		P45K		P55K		P75K	
	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
High/normal overload ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical shaft output [kW/(hp)]	30 (40)	37 (50)	37 (50)	45 (60)	45 (60)	55 (75)	55 (75)	75 (100)	75 (100)	90 (125)
Enclosure protection rating IP20	B4		C3		C3		C4		C4	
Enclosure protection rating IP21, IP55, IP66	C1		C1		C1		C2		C2	
Output current										
Continuous (380–440 V) [A]	61	73	73	90	90	106	106	147	147	177
Intermittent (60 s overload) (380–440 V) [A]	91.5	80.3	110	99	135	117	159	162	221	195
Continuous (441–500 V) [A]	52	65	65	80	80	105	105	130	130	160
Intermittent (60 s overload) (441–500 V) [A]	78	71.5	97.5	88	120	116	158	143	195	176
Continuous kVA (400 V) [kVA]	42.3	50.6	50.6	62.4	62.4	73.4	73.4	102	102	123
Continuous kVA (460 V) [kVA]	–	51.8	–	63.7	–	83.7	–	104	–	128
Maximum input current										
Continuous (380–440 V) [A]	55	66	66	82	82	96	96	133	133	161
Intermittent (60 s overload) (380–440 V) [A]	82.5	72.6	99	90.2	123	106	144	146	200	177
Continuous (441–500 V) [A]	47	59	59	73	73	95	95	118	118	145
Intermittent (60 s overload) (441–500 V) [A]	70.5	64.9	88.5	80.3	110	105	143	130	177	160
Additional specifications										
IP20 maximum cable cross-section ⁵⁾ for mains and motor [mm ²] ([AWG])	35 (2)		50 (1)		50 (1)		150 (300 MCM)		150 (300 MCM)	
IP20 maximum cable cross-section ⁵⁾ for brake and load sharing [mm ²] ([AWG])	35 (2)		50 (1)		50 (1)		95 (4/0)		95 (4/0)	
IP21, IP55, IP66 maximum cable cross-section ⁵⁾ for mains and motor [mm ²] ([AWG])	50 (1)		50 (1)		50 (1)		150 (300 MCM)		150 (300 MCM)	
IP21, IP55, IP66 maximum cable cross-section ⁵⁾ for brake and load sharing [mm ²] ([AWG])	50 (1)		50 (1)		50 (1)		95 (3/0)		95 (3/0)	
Maximum cable cross-section ^{2),5)} for mains disconnect [mm ²] ([AWG])			50, 35, 35 (1, 2, 2)				95, 70, 70 (3/0, 2/0, 2/0)		185, 150, 120 (350 MCM, 300 MCM, 4/0)	
Estimated power loss at rated maximum load [W] ³⁾	570	698	697	843	891	1083	1022	1384	1232	1474
Efficiency ⁴⁾	0.98		0.98		0.98		0.98		0.99	

Table 8.6 Mains Supply 380–500 V (FC 302), 380–480 V (FC 301), P30K–P75K

8.1.3 Mains Supply 525–600 V (FC 302 only)

Type designation	PK75	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5
Typical shaft output [kW/(hp)]	0.75 (1)	1.1 (1.5)	1.5 (2.0)	2.2 (3.0)	3 (4.0)	4 (5.0)	5.5 (7.5)	7.5 (10)
Enclosure protection rating IP20, IP21	A3	A3	A3	A3	A3	A3	A3	A3
Enclosure protection rating IP55	A5	A5	A5	A5	A5	A5	A5	A5
Output current								
Continuous (525–550 V) [A]	1.8	2.6	2.9	4.1	5.2	6.4	9.5	11.5
Intermittent (525–550 V) [A]	2.9	4.2	4.6	6.6	8.3	10.2	15.2	18.4
Continuous (551–600 V) [A]	1.7	2.4	2.7	3.9	4.9	6.1	9.0	11.0
Intermittent (551–600 V) [A]	2.7	3.8	4.3	6.2	7.8	9.8	14.4	17.6
Continuous kVA (525 V) [kVA]	1.7	2.5	2.8	3.9	5.0	6.1	9.0	11.0
Continuous kVA (575 V) [kVA]	1.7	2.4	2.7	3.9	4.9	6.1	9.0	11.0
Maximum input current								
Continuous (525–600 V) [A]	1.7	2.4	2.7	4.1	5.2	5.8	8.6	10.4
Intermittent (525–600 V) [A]	2.7	3.8	4.3	6.6	8.3	9.3	13.8	16.6
Additional specifications								
Maximum cable cross-section ^{2),5)} for mains, motor, brake, and load sharing [mm ²] ([AWG])	4, 4, 4 (12,12,12) (minimum 0.2 (24))							
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	6, 4, 4 (10,12,12)							
Estimated power loss at rated maximum load [W] ³⁾	35	50	65	92	122	145	195	261
Efficiency ⁴⁾	0.97	0.97	0.97	0.97	0.97	0.97	0.97	0.97

Table 8.7 Mains Supply 525–600 V (FC 302 only), PK75–P7K5

Type designation	P11K		P15K		P18K		P22K		P30K	
	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
High/normal load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical shaft output [kW/(hp)]	11 (15)	15 (20)	15 (20)	18.5 (25)	18.5 (25)	22 (30)	22 (30)	30 (40)	30 (40)	37 (50)
Enclosure protection rating IP20	B3		B3		B4		B4		B4	
Enclosure protection rating IP21, IP55, IP66	B1		B1		B2		B2		C1	
Output current										
Continuous (525–550 V) [A]	19	23	23	28	28	36	36	43	43	54
Intermittent (525–550 V) [A]	30	25	37	31	45	40	58	47	65	59
Continuous (551–600 V) [A]	18	22	22	27	27	34	34	41	41	52
Intermittent (551–600 V) [A]	29	24	35	30	43	37	54	45	62	57
Continuous kVA (550 V) [kVA]	18.1	21.9	21.9	26.7	26.7	34.3	34.3	41.0	41.0	51.4
Continuous kVA (575 V) [kVA]	17.9	21.9	21.9	26.9	26.9	33.9	33.9	40.8	40.8	51.8
Maximum input current										
Continuous at 550 V [A]	17.2	20.9	20.9	25.4	25.4	32.7	32.7	39	39	49
Intermittent at 550 V [A]	28	23	33	28	41	36	52	43	59	54
Continuous at 575 V [A]	16	20	20	24	24	31	31	37	37	47
Intermittent at 575 V [A]	26	22	32	27	39	34	50	41	56	52
Additional specifications										
IP20 maximum cable cross-section ^{2),5)} for mains, brake, motor, and load sharing [mm ²] ([AWG])	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35,-,-(2,-,-)		35,-,-(2,-,-)		35,-,-(2,-,-)	
IP21, IP55, IP66 maximum cable cross-section ^{2),5)} for mains, brake, and load sharing [mm ²] ([AWG])	16, 10, 10 (6, 8, 8)		16, 10, 10 (6, 8, 8)		35,-,-(2,-,-)		35,-,-(2,-,-)		50,-,- (1,-,-)	
IP21, IP55, IP66 maximum cable cross-section ^{2),5)} for motor [mm ²] ([AWG])	10, 10,- (8, 8,-)		10, 10,- (8, 8,-)		35, 25, 25 (2, 4, 4)		35, 25, 25 (2, 4, 4)		50,-,- (1,-,-)	
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	16, 10, 10 (6, 8, 8)								50, 35, 35 (1, 2, 2)	
Estimated power loss at rated maximum load [W] ³⁾	220	300	300	370	370	440	440	600	600	740
Efficiency ⁴⁾	0.98		0.98		0.98		0.98		0.98	

Table 8.8 Mains Supply 525–600 V (FC 302 only), P11K–P30K

Type designation	P37K		P45K		P55K		P75K	
High/normal load ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO
Typical shaft output [kW/(hp)]	37 (50)	45 (60)	45 (60)	55 (75)	55 (75)	75 (100)	75 (100)	90 (125)
Enclosure protection rating IP20	C3	C3	C3		C4		C4	
Enclosure protection rating IP21, IP55, IP66	C1	C1	C1		C2		C2	
Output current								
Continuous (525–550 V) [A]	54	65	65	87	87	105	105	137
Intermittent (525–550 V) [A]	81	72	98	96	131	116	158	151
Continuous (551–600 V) [A]	52	62	62	83	83	100	100	131
Intermittent (551–600 V) [A]	78	68	93	91	125	110	150	144
Continuous kVA (550 V) [kVA]	51.4	61.9	61.9	82.9	82.9	100.0	100.0	130.5
Continuous kVA (575 V) [kVA]	51.8	61.7	61.7	82.7	82.7	99.6	99.6	130.5
Maximum input current								
Continuous at 550 V [A]	49	59	59	78.9	78.9	95.3	95.3	124.3
Intermittent at 550 V [A]	74	65	89	87	118	105	143	137
Continuous at 575 V [A]	47	56	56	75	75	91	91	119
Intermittent at 575 V [A]	70	62	85	83	113	100	137	131
Additional specifications								
IP20 maximum cable cross-section ⁵⁾ for mains and motor [mm ²] ([AWG])	50 (1)				150 (300 MCM)			
IP20 maximum cable cross-section ⁵⁾ for brake and load sharing [mm ²] ([AWG])	50 (1)				95 (4/0)			
IP21, IP55, IP66 maximum cable cross-section ⁵⁾ for mains and motor [mm ²] ([AWG])	50 (1)				150 (300 MCM)			
IP21, IP55, IP66 maximum cable cross-section ⁵⁾ for brake and load sharing [mm ²] ([AWG])	50 (1)				95 (4/0)			
Maximum cable cross-section ^{2),5)} for mains disconnect [mm ²] ([AWG])	50, 35, 35 (1, 2, 2)				95, 70, 70 (3/0, 2/0, 2/0)		185, 150, 120 (350 MCM, 300 MCM, 4/0)	
Estimated power loss at rated maximum load [W] ³⁾	740	900	900	1100	1100	1500	1500	1800
Efficiency ⁴⁾	0.98		0.98		0.98		0.98	

Table 8.9 Mains Supply 525–600 V P37K–P75K (FC 302 only), P37K–P75K

For fuse ratings, see chapter 8.7 Fuses and Circuit Breakers.

1) High overload=150% or 160% torque for a duration of 60 s. Normal overload=110% torque for a duration of 60 s.

2) The 3 values for the maximum cable cross-section are for single core, flexible wire, and flexible wire with sleeve, respectively.

3) Applies to dimensioning of frequency converter cooling. If the switching frequency is higher than the default setting, the power losses may increase. LCP and typical control card power consumptions are included. For power loss data according to EN 50598-2, refer to drives.danfoss.com/knowledge-center/energy-efficiency-directive/#/

4) Efficiency measured at nominal current. For energy efficiency class, see chapter 8.4 Ambient Conditions. For part load losses, see drives.danfoss.com/knowledge-center/energy-efficiency-directive/#/.

5) Cable cross-section is regarded for copper cables.

8.1.4 Mains Supply 525–690 V (FC 302 only)

Type designation	P1K1	P1K5	P2K2	P3K0	P4K0	P5K5	P7K5
High/normal overload ¹⁾	HO/NO	HO/NO	HO/NO	HO/NO	HO/NO	HO/NO	HO/NO
Typical shaft output [kW/(hp)]	1.1 (1.5)	1.5 (2.0)	2.2 (3.0)	3.0 (4.0)	4.0 (5.0)	5.5 (7.5)	7.5 (10)
Enclosure protection rating IP20	A3	A3	A3	A3	A3	A3	A3
Output current							
Continuous (525–550 V) [A]	2.1	2.7	3.9	4.9	6.1	9.0	11.0
Intermittent (525–550 V) [A]	3.4	4.3	6.2	7.8	9.8	14.4	17.6
Continuous (551–690 V) [A]	1.6	2.2	3.2	4.5	5.5	7.5	10.0
Intermittent (551–690 V) [A]	2.6	3.5	5.1	7.2	8.8	12.0	16.0
Continuous kVA 525 V	1.9	2.5	3.5	4.5	5.5	8.2	10.0
Continuous kVA 690 V	1.9	2.6	3.8	5.4	6.6	9.0	12.0
Maximum input current							
Continuous (525–550 V) [A]	1.9	2.4	3.5	4.4	5.5	8.1	9.9
Intermittent (525–550 V) [A]	3.0	3.9	5.6	7.0	8.8	12.9	15.8
Continuous (551–690 V) [A]	1.4	2.0	2.9	4.0	4.9	6.7	9.0
Intermittent (551–690 V) [A]	2.3	3.2	4.6	6.5	7.9	10.8	14.4
Additional specifications							
Maximum cable cross-section ^{2),5)} for mains, motor, brake, and load sharing [mm ²] ([AWG])	4, 4, 4 (12, 12, 12) (minimum 0.2 (24))						
Maximum cable cross-section ^{2),5)} for disconnect [mm ²] ([AWG])	6, 4, 4 (10, 12, 12)						
Estimated power loss at rated maximum load (W) ³⁾	44	60	88	120	160	220	300
Efficiency ⁴⁾	0.96	0.96	0.96	0.96	0.96	0.96	0.96

Table 8.10 A3 Enclosure, Mains Supply 525–690 V IP20/Protected Chassis, P1K1–P7K5

Type designation	P11K		P15K		P18K		P22K	
High/normal overload ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO
Typical shaft output at 550 V [kW/(hp)]	7.5 (10)	11 (15)	11 (15)	15 (20)	15 (20)	18.5 (25)	18.5 (25)	22 (30)
Typical shaft output at 690 V [kW/(hp)]	11 (15)	15 (20)	15 (20)	18.5 (25)	18.5 (25)	22 (30)	22 (30)	30 (40)
Enclosure protection rating IP20	B4		B4		B4		B4	
Enclosure protection rating IP21, IP55	B2		B2		B2		B2	
Output current								
Continuous (525–550 V) [A]	14.0	19.0	19.0	23.0	23.0	28.0	28.0	36.0
Intermittent (60 s overload) (525–550 V) [A]	22.4	20.9	30.4	25.3	36.8	30.8	44.8	39.6
Continuous (551–690 V) [A]	13.0	18.0	18.0	22.0	22.0	27.0	27.0	34.0
Intermittent (60 s overload) (551–690 V) [A]	20.8	19.8	28.8	24.2	35.2	29.7	43.2	37.4
Continuous kVA (at 550 V) [kVA]	13.3	18.1	18.1	21.9	21.9	26.7	26.7	34.3
Continuous kVA (at 690 V) [kVA]	15.5	21.5	21.5	26.3	26.3	32.3	32.3	40.6
Maximum input current								
Continuous (at 550 V) [A]	15.0	19.5	19.5	24.0	24.0	29.0	29.0	36.0
Intermittent (60 s overload) (at 550 V) [A]	23.2	21.5	31.2	26.4	38.4	31.9	46.4	39.6
Continuous (at 690 V) [A]	14.5	19.5	19.5	24.0	24.0	29.0	29.0	36.0
Intermittent (60 s overload) (at 690 V) [A]	23.2	21.5	31.2	26.4	38.4	31.9	46.4	39.6
Additional specifications								
Maximum cable cross-section ^{2),5)} for mains/motor, load share, and brake [mm ²] ([AWG])	35, 25, 25 (2, 4, 4)							
Maximum cable cross-section ^{2),5)} for mains disconnect [mm ²] ([AWG])	16, 10, 10 (6, 8, 8)							
Estimated power loss at rated maximum load (W) ³⁾	150	220	220	300	300	370	370	440
Efficiency ⁴⁾	0.98		0.98		0.98		0.98	

Table 8.11 B2/B4 Enclosure, Mains Supply 525–690 V IP20/IP21/IP55 - Chassis/NEMA 1/NEMA 12 (FC 302 only), P11K–P22K

Type designation	P30K		P37K		P45K		P55K		P75K	
High/normal overload ¹⁾	HO	NO	HO	NO	HO	NO	HO	NO	HO	NO
Typical shaft output at 550 V [kW/(hp)]	22 (30)	30 (40)	30 (40)	37 (50)	37 (50)	45 (60)	45 (60)	55 (75)	55 (75)	75 (100)
Typical shaft output at 690 V [kW/(hp)]	30 (40)	37 (50)	37 (50)	45 (60)	45 (60)	55 (75)	55 (75)	75 (100)	75 (100)	90 (125)
Enclosure protection rating IP20	B4		C3		C3		D3h		D3h	
Enclosure protection rating IP21, IP55	C2		C2		C2		C2		C2	
Output current										
Continuous (525–550 V) [A]	36.0	43.0	43.0	54.0	54.0	65.0	65.0	87.0	87.0	105
Intermittent (60 s overload) (525–550 V) [A]	54.0	47.3	64.5	59.4	81.0	71.5	97.5	95.7	130.5	115.5
Continuous (551–690 V) [A]	34.0	41.0	41.0	52.0	52.0	62.0	62.0	83.0	83.0	100
Intermittent (60 s overload) (551–690 V) [A]	51.0	45.1	61.5	57.2	78.0	68.2	93.0	91.3	124.5	110
Continuous kVA (at 550 V) [kVA]	34.3	41.0	41.0	51.4	51.4	61.9	61.9	82.9	82.9	100
Continuous kVA (at 690 V) [kVA]	40.6	49.0	49.0	62.1	62.1	74.1	74.1	99.2	99.2	119.5
Maximum input current										
Continuous (at 550 V) [A]	36.0	49.0	49.0	59.0	59.0	71.0	71.0	87.0	87.0	99.0
Intermittent (60 s overload) (at 550 V) [A]	54.0	53.9	72.0	64.9	87.0	78.1	105.0	95.7	129	108.9
Continuous (at 690 V) [A]	36.0	48.0	48.0	58.0	58.0	70.0	70.0	86.0	–	–
Intermittent (60 s overload) (at 690 V) [A]	54.0	52.8	72.0	63.8	87.0	77.0	105	94.6	–	–
Additional specifications										
Maximum cable cross-section ⁵⁾ for mains and motor [mm ²] ([AWG])	150 (300 MCM)									
Maximum cable cross-section ⁵⁾ for load share and brake [mm ²] ([AWG])	95 (3/0)									
Maximum cable cross-section ^{2),5)} for mains disconnect [mm ²] ([AWG])	95, 70, 70 (3/0, 2/0, 2/0)						185, 150, 120 (350 MCM, 300 MCM, 4/0)		–	
Estimated power loss at rated maximum load [W] ³⁾	600	740	740	900	900	1100	1100	1500	1500	1800
Efficiency ⁴⁾	0.98		0.98		0.98		0.98		0.98	

Table 8.12 B4, C2, C3 Enclosure, Mains Supply 525–690 V IP20/IP21/IP55 – Chassis/NEMA 1/NEMA 12 (FC 302 only), P30K–P75K

For fuse ratings, see chapter 8.7 Fuses and Circuit Breakers.

1) High overload=150% or 160% torque for a duration of 60 s. Normal overload=110% torque for a duration of 60 s.

2) The 3 values for the maximum cable cross-section are for single core, flexible wire, and flexible wire with sleeve, respectively.

3) Applies to dimensioning of frequency converter cooling. If the switching frequency is higher than the default setting, the power losses may increase. LCP and typical control card power consumptions are included. For power loss data according to EN 50598-2, refer to drives.danfoss.com/knowledge-center/energy-efficiency-directive/#/

4) Efficiency measured at nominal current. For energy efficiency class, see chapter 8.4 Ambient Conditions. For part load losses, see drives.danfoss.com/knowledge-center/energy-efficiency-directive/#/.

5) Cable cross-section is regarded for copper cables.

8.2 Mains Supply

Mains supply

Supply terminals (6-pulse)	L1, L2, L3
Supply terminals (12-pulse)	L1-1, L2-1, L3-1, L1-2, L2-2, L3-2
Supply voltage	200–240 V ±10%
Supply voltage	FC 301: 380–480 V/FC 302: 380–500 V ±10%
Supply voltage	FC 302: 525–600 V ±10%
Supply voltage	FC 302: 525–690 V ±10%

Mains voltage low/mains dropout:

During low mains voltage or a mains dropout, the frequency converter continues until the DC-link voltage drops below the minimum stop level, which corresponds typically to 15% below the frequency converter's lowest rated supply voltage. Power-up and full torque cannot be expected at mains voltage lower than 10% below the frequency converter's lowest rated supply voltage.

Supply frequency	50/60 Hz ±5%
Maximum imbalance temporary between mains phases	3.0% of rated supply voltage
True power factor (λ)	≥0.9 nominal at rated load
Displacement power factor ($\cos \phi$)	Near unity (>0.98)
Switching on input supply L1, L2, L3 (power-ups) ≤7.5 kW (10 hp)	Maximum twice per minute.
Switching on input supply L1, L2, L3 (power-ups) 11–75 kW (15–101 hp)	Maximum once per minute.
Switching on input supply L1, L2, L3 (power-ups) ≥90 kW (121 hp)	Maximum once per 2 minutes.
Environment according to EN60664-1	Overvoltage category III/pollution degree 2

The unit is suitable for use on a circuit capable of delivering not more than 100000 RMS symmetrical Amperes, 240/500/600/690 V maximum.

8.3 Motor Output and Motor Data

Motor output (U, V, W)

Output voltage	0–100% of supply voltage
Output frequency	0–590 Hz ¹⁾
Output frequency in flux mode	0–300 Hz
Switching on output	Unlimited
Ramp times	0.01–3600 s

1) Dependent on voltage and power.

Torque characteristics

Starting torque (constant torque)	Maximum 160% for 60 s ¹⁾ once in 10 minutes
Starting/overload torque (variable torque)	Maximum 110% up to 0.5 s ¹⁾ once in 10 minutes
Torque rise time in flux (for 5 kHz f_{sw})	1 ms
Torque rise time in VVC ⁺ (independent of f_{sw})	10 ms

1) Percentage relates to the nominal torque.

8.4 Ambient Conditions

Environment	
Enclosure	IP20/Chassis, IP21/Type 1, IP55/Type 12, IP66/Type 4X
Vibration test	1.0 g
Maximum THD _v	10%
Maximum relative humidity	5–93% (IEC 721-3-3; Class 3K3 (non-condensing) during operation
Aggressive environment (IEC 60068-2-43) H ₂ S test	Class Kd
Ambient temperature ¹⁾	Maximum 50 °C (122 °F) (24-hour average maximum 45 °C (113 °F))
Minimum ambient temperature during full-scale operation	0 °C (32 °F)
Minimum ambient temperature at reduced performance	-10 °C (14 °F)
Temperature during storage/transport	-25 to +65/70 °C (-13 to +149/158 °F)
Maximum altitude above sea level without derating ¹⁾	1000 m (3280 ft)
EMC standards, Emission	EN 61800-3
EMC standards, Immunity	EN 61800-3
Energy efficiency class ²⁾	IE2

1) See special conditions in the design guide for:

- Derating for high ambient temperature.
- Derating for high altitude.

2) Determined according to EN 50598-2 at:

- Rated load.
- 90% rated frequency.
- Switching frequency factory setting.
- Switching pattern factory setting.

8.5 Cable Specifications

Cable lengths and cross-sections for control cables¹⁾

Maximum motor cable length, shielded	FC 301: 50 m (164 ft)/FC 302: 150 m (492 ft)
Maximum motor cable length, unshielded	FC 301: 75 m (246 ft)/FC 302: 300 m (984 ft)
Maximum cross-section to control terminals, flexible/rigid wire without cable end sleeves	1.5 mm ² /16 AWG
Maximum cross-section to control terminals, flexible wire with cable end sleeves	1 mm ² /18 AWG
Maximum cross-section to control terminals, flexible wire with cable end sleeves with collar	0.5 mm ² /20 AWG
Minimum cross-section to control terminals	0.25 mm ² /24 AWG

1) For power cables, see electrical tables in chapter 8.1 Electrical Data.

8.6 Control Input/Output and Control Data

Digital inputs	
Programmable digital inputs	FC 301: 4 (5) ¹⁾ /FC 302: 4 (6) ¹⁾
Terminal number	18, 19, 27 ¹⁾ , 29 ¹⁾ , 32, 33
Logic	PNP or NPN
Voltage level	0–24 V DC
Voltage level, logic 0 PNP	<5 V DC
Voltage level, logic 1 PNP	>10 V DC
Voltage level, logic 0 NPN ²⁾	>19 V DC
Voltage level, logic 1 NPN ²⁾	<14 V DC
Maximum voltage on input	28 V DC
Pulse frequency range	0–110 kHz

(Duty cycle) minimum pulse width	4.5 ms
Input resistance, R_i	Approximately 4 k Ω

- 1) Terminals 27 and 29 can also be programmed as output.
- 2) Except STO input terminal 37.

STO terminal 37^{1, 2)} (terminal 37 is fixed PNP logic)

Voltage level	0–24 V DC
Voltage level, logic 0 PNP	<4 V DC
Voltage level, logic 1 PNP	>20 V DC
Maximum voltage on input	28 V DC
Typical input current at 24 V	50 mA rms
Typical input current at 20 V	60 mA rms
Input capacitance	400 nF

All digital inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

- 1) See chapter 4.7.1 Safe Torque Off (STO) for further information about terminal 37 and STO.
- 2) When using a contactor with a DC coil inside in combination with STO, it is important to make a return way for the current from the coil when turning it off. This can be done by using a freewheel diode (or, alternatively, a 30 V or 50 V MOV for quicker response time) across the coil. Typical contactors can be bought with this diode.

Analog inputs

Number of analog inputs	2
Terminal number	53, 54
Modes	Voltage or current
Mode select	Switch S201 and switch S202
Voltage mode	Switch S201/switch S202 = OFF (U)
Voltage level	-10 V to +10 V (scaleable)
Input resistance, R_i	Approximately 10 k Ω
Maximum voltage	± 20 V
Current mode	Switch S201/switch S202 = ON (I)
Current level	0/4 to 20 mA (scaleable)
Input resistance, R_i	Approximately 200 Ω
Maximum current	30 mA
Resolution for analog inputs	10 bit (+ sign)
Accuracy of analog inputs	Maximum error 0.5% of full scale
Bandwidth	100 Hz

The analog inputs are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

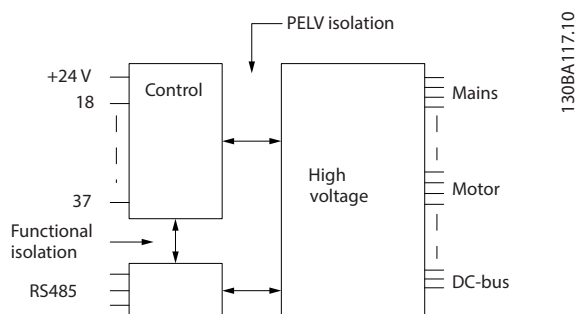


Figure 8.1 PELV Isolation

Pulse/encoder inputs

Programmable pulse/encoder inputs	2/1
Terminal number pulse/encoder	29 ¹⁾ , 33 ²⁾ /32 ³⁾ , 33 ³⁾
Maximum frequency at terminal 29, 32, 33	110 kHz (Push-pull driven)
Maximum frequency at terminal 29, 32, 33	5 kHz (Open collector)

Minimum frequency at terminal 29, 32, 33	4 Hz
Voltage level	See parameter group 5-1* Digital Inputs in the programming guide.
Maximum voltage on input	28 V DC
Input resistance, R_i	Approximately 4 k Ω
Pulse input accuracy (0.1–1 kHz)	Maximum error: 0.1% of full scale
Encoder input accuracy (1–11 kHz)	Maximum error: 0.05% of full scale

The pulse and encoder inputs (terminals 29, 32, 33) are galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

- 1) FC 302 only.
- 2) Pulse inputs are 29 and 33.
- 3) Encoder inputs: 32=A, 33=B.

Digital output

Programmable digital/pulse outputs	2
Terminal number	27, 29 ¹⁾
Voltage level at digital/frequency output	0–24 V
Maximum output current (sink or source)	40 mA
Maximum load at frequency output	1 k Ω
Maximum capacitive load at frequency output	10 nF
Minimum output frequency at frequency output	0 Hz
Maximum output frequency at frequency output	32 kHz
Accuracy of frequency output	Maximum error: 0.1% of full scale
Resolution of frequency outputs	12 bit

1) Terminal 27 and 29 can also be programmed as input.

The digital output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Analog output

Number of programmable analog outputs	1
Terminal number	42
Current range at analog output	0/4 to 20 mA
Maximum load GND - analog output less than	500 Ω
Accuracy on analog output	Maximum error: 0.5% of full scale
Resolution on analog output	12 bit

The analog output is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, 24 V DC output

Terminal number	12, 13
Output voltage	24 V +1, -3 V
Maximum load	200 mA

The 24 V DC supply is galvanically isolated from the supply voltage (PELV), but has the same potential as the analog and digital inputs and outputs.

Control card, 10 V DC output

Terminal number	± 50
Output voltage	10.5 V ± 0.5 V
Maximum load	15 mA

The 10 V DC supply is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

Control card, RS485 serial communication

Terminal number	68 (P, TX+, RX+), 69 (N, TX-, RX-)
Terminal number 61	Common for terminals 68 and 69

The RS485 serial communication circuit is functionally separated from other central circuits and galvanically isolated from the supply voltage (PELV).

Control card, USB serial communication

USB standard	1.1 (full speed)
USB plug	USB type B plug

Connection to PC is carried out via a standard host/device USB cable.

The USB connection is galvanically isolated from the supply voltage (PELV) and other high-voltage terminals.

The USB ground connection is not galvanically isolated from protective earth. Use only an isolated laptop as PC connection to the USB connector on the frequency converter.

Relay outputs

Programmable relay outputs	FC 301 all kW: 1/FC 302 all kW: 2
Relay 01 terminal number	1-3 (break), 1-2 (make)
Maximum terminal load (AC-1) ¹⁾ on 1-3 (NC), 1-2 (NO) (resistive load)	240 V AC, 2 A
Maximum terminal load (AC-15) ¹⁾ (inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Maximum terminal load (DC-1) ¹⁾ on 1-2 (NO), 1-3 (NC) (resistive load)	60 V DC, 1 A
Maximum terminal load (DC-13) ¹⁾ (inductive load)	24 V DC, 0.1 A
Relay 02 (FC 302 only) terminal number	4-6 (break), 4-5 (make)
Maximum terminal load (AC-1) ¹⁾ on 4-5 (NO) (resistive load) ^{2), 3)} overvoltage cat. II	400 V AC, 2 A
Maximum terminal load (AC-15) ¹⁾ on 4-5 (NO) (inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Maximum terminal load (DC-1) ¹⁾ on 4-5 (NO) (resistive load)	80 V DC, 2 A
Maximum terminal load (DC-13) ¹⁾ on 4-5 (NO) (inductive load)	24 V DC, 0.1 A
Maximum terminal load (AC-1) ¹⁾ on 4-6 (NC) (resistive load)	240 V AC, 2 A
Maximum terminal load (AC-15) ¹⁾ on 4-6 (NC) (inductive load @ cosφ 0.4)	240 V AC, 0.2 A
Maximum terminal load (DC-1) ¹⁾ on 4-6 (NC) (resistive load)	50 V DC, 2 A
Maximum terminal load (DC-13) ¹⁾ on 4-6 (NC) (inductive load)	24 V DC, 0.1 A
Minimum terminal load on 1-3 (NC), 1-2 (NO), 4-6 (NC), 4-5 (NO)	24 V DC 1 mA, 24 V AC 20 mA
Environment according to EN 60664-1	Overvoltage category III/pollution degree 2

1) IEC 60947 part 4 and 5

The relay contacts are galvanically isolated from the rest of the circuit by reinforced isolation (PELV).

2) Overvoltage Category II.

3) UL applications 300 V AC 2 A.

Control card performance

Scan interval	1 ms
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Control characteristics

Resolution of output frequency at 0-590 Hz	±0.003 Hz
Repeat accuracy of precise start/stop (terminals 18, 19)	≤±0.1 ms
System response time (terminals 18, 19, 27, 29, 32, 33)	≤2 ms
Speed control range (open loop)	1:100 of synchronous speed
Speed control range (closed loop)	1:1000 of synchronous speed
Speed accuracy (open loop)	30-4000 RPM: Error ±8 RPM
Speed accuracy (closed loop), depending on resolution of feedback device	0-6000 RPM: Error ±0.15 RPM
Torque control accuracy (speed feedback)	Maximum error ±5% of rated torque

All control characteristics are based on a 4-pole asynchronous motor.

8.7 Fuses and Circuit Breakers

Use recommended fuses and/or circuit breakers on the supply side as protection if there is component break-down inside the frequency converter (first fault).

NOTICE!

Use of fuses on the supply side is mandatory for IEC 60364 (CE) and NEC 2009 (UL) compliant installations.

Recommendations

- gG type fuses.
- Moeller type circuit breakers. For other circuit breaker types, ensure that the energy into the frequency converter is equal to or lower than the energy provided by Moeller types.

Use of recommended fuses and circuit breakers ensures that possible damage to the frequency converter is limited to damage inside the unit. For further information, see *Application Note Fuses and Circuit Breakers*.

The fuses in *chapter 8.7.1 CE Compliance* to *chapter 8.7.2 UL Compliance* are suitable for use on a circuit capable of delivering 100000 A_{rms} (symmetrical), depending on the frequency converter voltage rating. With the proper fusing, the frequency converter short-circuit current rating (SCCR) is 100000 A_{rms}.

8.7.1 CE Compliance

200–240 V

Enclosure	Power [kW (hp)]	Recommended fuse size	Recommended maximum fuse	Recommended circuit breaker Moeller	Maximum trip level [A]
A1	0.25–1.5 (0.34–2.0)	gG-10	gG-25	PKZM0-16	16
A2	0.25–1.5 (0.34–2.0)	gG-10	gG-25	PKZM0-25	25
	2.2 (3.0)	gG-16			
A3	3.0 (4.0)	gG-16	gG-32	PKZM0-25	25
	3.7 (5.0)	gG-20			
A4	0.25–1.5 (0.34–2.0)	gG-10	gG-32	PKZM0-25	25
	2.2 (3.0)	gG-16			
A5	0.25–1.5 (0.34–2.0)	gG-10	gG-32	PKZM0-25	25
	2.2–3.0 (3.0–4.0)	gG-16			
	3.7 (5.0)	gG-20			
B1	5.5 (7.5)	gG-25	gG-80	PKZM4-63	63
	7.5 (10.0)	gG-32			
B2	11.0 (15.0)	gG-50	gG-100	NZMB1-A100	100
B3	5.5 (7.5)	gG-25	gG-63	PKZM4-50	50
B4	7.5 (10.0)	gG-32	gG-125	NZMB1-A100	100
	11.0 (15.0)	gG-50			
	15.0 (20.0)	gG-63			
C1	15.0 (20.0)	gG-63	gG-160	NZMB2-A200	160
	18.5 (25.0)	gG-80			
	22.0 (30.0)	gG-100	aR-160		
C2	30.0 (40.0)	aR-160	aR-200	NZMB2-A250	250
	37.0 (50.0)	aR-200	aR-250		
C3	18.5 (25.0)	gG-80	gG-150	NZMB2-A200	150
	22.0 (30.0)	aR-125	aR-160		
C4	30.0 (40.0)	aR-160	aR-200	NZMB2-A250	250
	37.0 (50.0)	aR-200	aR-250		

Table 8.13 200–240 V, Enclosure Sizes A, B, and C

380–500 V

Enclosure	Power [kW (hp)]	Recommended fuse size	Recommended maximum fuse	Recommended circuit breaker Moeller	Maximum trip level [A]
A1	0.37–1.5 (0.5–2.0)	gG-10	gG-25	PKZM0-16	16
A2	0.37–3.0 (0.5–4.0)	gG-10	gG-25	PKZM0-25	25
	4.0 (5.0)	gG-16			
A3	5.5–7.5 (7.5–10.0)	gG-16	gG-32	PKZM0-25	25
A4	0.37–3.0 (0.5–4.0)	gG-10	gG-32	PKZM0-25	25
	4.0 (5.0)	gG-16			
A5	0.37–3.0 (0.5–4.0)	gG-10	gG-32	PKZM0-25	25
	4.0–7.5 (5.0–10.0)	gG-16			
B1	11–15 (15.0–20.0)	gG-40	gG-80	PKZM4-63	63
B2	18.5 (25.0)	gG-50	gG-100	NZMB1-A100	100
	22.0 (30.0)	gG-63			
B3	11–15 (15.0–20.0)	gG-40	gG-63	PKZM4-50	50
B4	18.5 (25.0)	gG-50	gG-125	NZMB1-A100	100
	22.0 (30.0)	gG-63			
	30.0 (40.0)	gG-80			
C1	30.0 (40.0)	gG-80	gG-160	NZMB2-A200	160
	37.0 (50.0)	gG-100			
	45.0 (60.0)	gG-160			
C2	55.0 (75.0)	aR-200	aR-250	NZMB2-A250	250
	75.0 (100.0)	aR-250			
C3	37.0 (50.0)	gG-100	gG-150	NZMB2-A200	150
	45.0 (60.0)	gG-160	gG-160		
C4	55.0 (75.0)	aR-200	aR-250	NZMB2-A250	250
	75.0 (100.0)	aR-250			

Table 8.14 380–500 V, Enclosure Sizes A, B, and C

525–600 V

Enclosure	Power [kW (hp)]	Recommended fuse size	Recommended maximum fuse	Recommended circuit breaker Moeller	Maximum trip level [A]
A2	0-75-4.0 (1.0–5.0)	gG-10	gG-25	PKZM0-25	25
A3	5.5 (7.5)	gG-10	gG-32	PKZM0-25	25
	7.5 (10.0)	gG-16			
A5	5.5 (7.5)	gG-10	gG-32	PKZM0-25	25
	7.5 (10.0)	gG-16			
B1	11.0 (15.0)	gG-25	gG-80	PKZM4-63	63
	15.0 (20.0)	gG-32			
	18.5 (25.0)	gG-40			
B2	22.0 (30.0)	gG-50	gG-100	NZMB1-A100	100
	30.0 (40.0)	gG-63			
B3	11.0 (15.0)	gG-25	gG-63	PKZM4-50	50
	15.0 (20.0)	gG-32			
B4	18.5 (25.0)	gG-40	gG-125	NZMB1-A100	100
	22.0 (30.0)	gG-50			
	30.0 (40.0)	gG-63			
C1	37.0 (50.0)	gG-63	gG-160	NZMB2-A200	160
	45.0 (60.0)	gG-100			
	55.0 (60.0)	aR-160	aR-250		
C2	75.0 (100.0)	aR-200	aR-250	NZMB2-A250	250
C3	37.0 (50.0)	gG-63	gG-150	NZMB2-A200	150
	45.0 (60.0)	gG-100	gG-150	NZMB2-A200	
C4	55.0 (75.0)	aR-160	aR-250	NZMB2-A250	250
	75.0 (100.0)	aR-200			

Table 8.15 525–600 V, Enclosure Sizes A, B, and C

525–690 V

Enclosure	Power [kW (hp)]	Recommended fuse size	Recommended maximum fuse	Recommended circuit breaker Moeller	Maximum trip level [A]
A3	1.1 (1.5)	gG-6	gG-25	PKZM0-16	16
	1.5 (2.0)	gG-6	gG-25		
	2.2 (3.0)	gG-6	gG-25		
	3.0 (4.0)	gG-10	gG-25		
	4.0 (5.0)	gG-10	gG-25		
	5.5 (7.5)	gG-16	gG-25		
	7.5 (10.0)	gG-16	gG-25		
B2/B4	11.0 (15.0)	gG-25	gG-63	-	-
	15.0 (20.0)	gG-32			
	18.5 (25.0)	gG-32			
	22.0 (30.0)	gG-40			
B4/C2	30.0 (40.0)	gG-63	gG-80	-	-
C2/C3	37.0 (50.0)	gG-63	gG-100	-	-
	45.0 (60.0)	gG-80	gG-125		
C2	55.0 (75.0)	gG-100	gG-160	-	-
	75.0 (100.0)	gG-125			

Table 8.16 525–690 V, Enclosure Sizes A, B, and C

8.7.2 UL Compliance

200–240 V

Power [kW (hp)]	Recommended maximum fuse					
	Bussmann Type RK1 ¹⁾	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC
0.25–0.37 (0.34–0.5)	KTN-R-05	JKS-05	JJN-05	FNQ-R-5	KTK-R-5	LP-CC-5
0.55–1.1 (0.75–1.5)	KTN-R-10	JKS-10	JJN-10	FNQ-R-10	KTK-R-10	LP-CC-10
1.5 (2.0)	KTN-R-15	JKS-15	JJN-15	FNQ-R-15	KTK-R-15	LP-CC-15
2.2 (3.0)	KTN-R-20	JKS-20	JJN-20	FNQ-R-20	KTK-R-20	LP-CC-20
3.0 (4.0)	KTN-R-25	JKS-25	JJN-25	FNQ-R-25	KTK-R-25	LP-CC-25
3.7 (5.0)	KTN-R-30	JKS-30	JJN-30	FNQ-R-30	KTK-R-30	LP-CC-30
5.5 (7.5)	KTN-R-50	KS-50	JJN-50	–	–	–
7.5 (10.0)	KTN-R-60	JKS-60	JJN-60	–	–	–
11.0 (15.0)	KTN-R-80	JKS-80	JJN-80	–	–	–
15–18.5 (20.0–25.0)	KTN-R-125	JKS-125	JJN-125	–	–	–
22.0 (30.0)	KTN-R-150	JKS-150	JJN-150	–	–	–
30.0 (40.0)	KTN-R-200	JKS-200	JJN-200	–	–	–
37.0 (50.0)	KTN-R-250	JKS-250	JJN-250	–	–	–

Table 8.17 200–240 V, Enclosure Sizes A, B, and C

Power [kW (hp)]	Recommended maximum fuse							
	SIBA Type RK1	Littelfuse Type RK1	Ferraz- Shawmut Type CC	Ferraz- Shawmut Type RK1 ³⁾	Bussmann Type JFHR2 ²⁾	Littelfuse JFHR2	Ferraz- Shawmut JFHR2 ⁴⁾	Ferraz- Shawmut J
0.25–0.37 (0.34–0.5)	5017906-005	KLN-R-05	ATM-R-05	A2K-05-R	FWX-5	–	–	HSJ-6
0.55–1.1 (0.75–1.5)	5017906-010	KLN-R-10	ATM-R-10	A2K-10-R	FWX-10	–	–	HSJ-10
1.5 (2.0)	5017906-016	KLN-R-15	ATM-R-15	A2K-15-R	FWX-15	–	–	HSJ-15
2.2 (3.0)	5017906-020	KLN-R-20	ATM-R-20	A2K-20-R	FWX-20	–	–	HSJ-20
3.0 (4.0)	5017906-025	KLN-R-25	ATM-R-25	A2K-25-R	FWX-25	–	–	HSJ-25
3.7 (5.0)	5012406-032	KLN-R-30	ATM-R-30	A2K-30-R	FWX-30	–	–	HSJ-30
5.5 (7.5)	5014006-050	KLN-R-50	–	A2K-50-R	FWX-50	–	–	HSJ-50
7.5 (10.0)	5014006-063	KLN-R-60	–	A2K-60-R	FWX-60	–	–	HSJ-60
11.0 (15.0)	5014006-080	KLN-R-80	–	A2K-80-R	FWX-80	–	–	HSJ-80
15–18.5 (20.0–25.0)	2028220-125	KLN-R-125	–	A2K-125-R	FWX-125	–	–	HSJ-125
22.0 (30.0)	2028220-150	KLN-R-150	–	A2K-150-R	FWX-150	L25S-150	A25X-150	HSJ-150
30.0 (40.0)	2028220-200	KLN-R-200	–	A2K-200-R	FWX-200	L25S-200	A25X-200	HSJ-200
37.0 (50.0)	2028220-250	KLN-R-250	–	A2K-250-R	FWX-250	L25S-250	A25X-250	HSJ-250

Table 8.18 200–240 V, Enclosure Sizes A, B, and C

1) KTS fuses from Bussmann may substitute KTN for 240 V frequency converters.

2) FWH fuses from Bussmann may substitute FWX for 240 V frequency converters.

3) A6KR fuses from Ferraz Shawmut may substitute A2KR for 240 V frequency converters.

4) A50X fuses from Ferraz Shawmut may substitute A25X for 240 V frequency converters.

380–500 V

Power [kW (hp)]	Recommended maximum fuse					
	Bussmann Type RK1	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC
0.37–1.1 (0.5–1.5)	KTS-R-6	JKS-6	JJS-6	FNQ-R-6	KTK-R-6	LP-CC-6
1.5–2.2 (2.0–3.0)	KTS-R-10	JKS-10	JJS-10	FNQ-R-10	KTK-R-10	LP-CC-10
3.0 (4.0)	KTS-R-15	JKS-15	JJS-15	FNQ-R-15	KTK-R-15	LP-CC-15
4.0 (5.0)	KTS-R-20	JKS-20	JJS-20	FNQ-R-20	KTK-R-20	LP-CC-20
5.5 (7.5)	KTS-R-25	JKS-25	JJS-25	FNQ-R-25	KTK-R-25	LP-CC-25
7.5 (10.0)	KTS-R-30	JKS-30	JJS-30	FNQ-R-30	KTK-R-30	LP-CC-30
11.0 (15.0)	KTS-R-40	JKS-40	JJS-40	–	–	–
15.0 (20.0)	KTS-R-50	JKS-50	JJS-50	–	–	–
18.5 (25.0)	KTS-R-60	JKS-60	JJS-60	–	–	–
22.0 (30.0)	KTS-R-80	JKS-80	JJS-80	–	–	–
30.0 (40.0)	KTS-R-100	JKS-100	JJS-100	–	–	–
37.0 (50.0)	KTS-R-125	JKS-125	JJS-125	–	–	–
45.0 (60.0)	KTS-R-150	JKS-150	JJS-150	–	–	–
55.0 (75.0)	KTS-R-200	JKS-200	JJS-200	–	–	–
75.0 (100.0)	KTS-R-250	JKS-250	JJS-250	–	–	–

Table 8.19 380–500 V, Enclosure Sizes A, B, and C

Power [kW (hp)]	Recommended maximum fuse							
	SIBA Type RK1	Littelfuse Type RK1	Ferraz Shawmut Type CC	Ferraz Shawmut Type RK1	Bussmann JFHR2	Ferraz Shawmut JFerraz Shawmut J	Ferraz Shawmut JFHR2 ¹⁾	Littelfuse JFHR2
0.37–1.1 (0.5–1.5)	5017906-006	KLS-R-6	ATM-R-6	A6K-6-R	FWH-6	HSJ-6	–	–
1.5–2.2 (2.0–3.0)	5017906-010	KLS-R-10	ATM-R-10	A6K-10-R	FWH-10	HSJ-10	–	–
3.0 (4.0)	5017906-016	KLS-R-15	ATM-R-15	A6K-15-R	FWH-15	HSJ-15	–	–
4.0 (5.0)	5017906-020	KLS-R-20	ATM-R-20	A6K-20-R	FWH-20	HSJ-20	–	–
5.5 (7.5)	5017906-025	KLS-R-25	ATM-R-25	A6K-25-R	FWH-25	HSJ-25	–	–
7.5 (10.0)	5012406-032	KLS-R-30	ATM-R-30	A6K-30-R	FWH-30	HSJ-30	–	–
11.0 (15.0)	5014006-040	KLS-R-40	–	A6K-40-R	FWH-40	HSJ-40	–	–
15.0 (20.0)	5014006-050	KLS-R-50	–	A6K-50-R	FWH-50	HSJ-50	–	–
18.5 (25.0)	5014006-063	KLS-R-60	–	A6K-60-R	FWH-60	HSJ-60	–	–
22.0 (30.0)	2028220-100	KLS-R-80	–	A6K-80-R	FWH-80	HSJ-80	–	–
30.0 (40.0)	2028220-125	KLS-R-100	–	A6K-100-R	FWH-100	HSJ-100	–	–
37.0 (50.0)	2028220-125	KLS-R-125	–	A6K-125-R	FWH-125	HSJ-125	–	–
45.0 (60.0)	2028220-160	KLS-R-150	–	A6K-150-R	FWH-150	HSJ-150	–	–
55.0 (75.0)	2028220-200	KLS-R-200	–	A6K-200-R	FWH-200	HSJ-200	A50-P-225	L50-S-225
75.0 (100.0)	2028220-250	KLS-R-250	–	A6K-250-R	FWH-250	HSJ-250	A50-P-250	L50-S-250

Table 8.20 380–500 V, Enclosure Sizes A, B, and C

1) Ferraz Shawmut A50QS fuses may substitute for A50P fuses.

525–600 V

Power [kW (hp)]	Recommended maximum fuse									
	Bussmann Type RK1	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC	SIBA Type RK1	Littelfuse Type RK1	Ferraz Shawmut Type RK1	Ferraz Shawmut J
0.75– 1.1 (1.0– 1.5)	KTS-R-5	JKS-5	JJS-6	FNQ-R-5	KTK-R-5	LP-CC-5	5017906-005	KLS-R-005	A6K-5-R	HSJ-6
1.5–2.2 (2.0– 3.0)	KTS-R-10	JKS-10	JJS-10	FNQ-R-10	KTK-R-10	LP-CC-10	5017906-010	KLS-R-010	A6K-10-R	HSJ-10
3.0 (4.0)	KTS-R15	JKS-15	JJS-15	FNQ-R-15	KTK-R-15	LP-CC-15	5017906-016	KLS-R-015	A6K-15-R	HSJ-15
4.0 (5.0)	KTS-R20	JKS-20	JJS-20	FNQ-R-20	KTK-R-20	LP-CC-20	5017906-020	KLS-R-020	A6K-20-R	HSJ-20
5.5 (7.5)	KTS-R-25	JKS-25	JJS-25	FNQ-R-25	KTK-R-25	LP-CC-25	5017906-025	KLS-R-025	A6K-25-R	HSJ-25
7.5 (10.0)	KTS-R-30	JKS-30	JJS-30	FNQ-R-30	KTK-R-30	LP-CC-30	5017906-030	KLS-R-030	A6K-30-R	HSJ-30
11 (15.0)	KTS-R-35	JKS-35	JJS-35	–	–	–	5014006-040	KLS-R-035	A6K-35-R	HSJ-35
15.0 (20.0)	KTS-R-45	JKS-45	JJS-45	–	–	–	5014006-050	KLS-R-045	A6K-45-R	HSJ-45
18.5 (25.0)	KTS-R-50	JKS-50	JJS-50	–	–	–	5014006-050	KLS-R-050	A6K-50-R	HSJ-50
22.0 (30.0)	KTS-R-60	JKS-60	JJS-60	–	–	–	5014006-063	KLS-R-060	A6K-60-R	HSJ-60
30.0 (40.0)	KTS-R-80	JKS-80	JJS-80	–	–	–	5014006-080	KLS-R-075	A6K-80-R	HSJ-80
37.0 (50.0)	KTS-R-100	JKS-100	JJS-100	–	–	–	5014006-100	KLS-R-100	A6K-100-R	HSJ-100
45.0 (60.0)	KTS-R-125	JKS-125	JJS-125	–	–	–	2028220-125	KLS-R-125	A6K-125-R	HSJ-125
55.0 (75.0)	KTS-R-150	JKS-150	JJS-150	–	–	–	2028220-150	KLS-R-150	A6K-150-R	HSJ-150
75.0 (100.0)	KTS-R-175	JKS-175	JJS-175	–	–	–	2028220-200	KLS-R-175	A6K-175-R	HSJ-175

Table 8.21 525–600 V, Enclosure Sizes A, B, and C

525–690 V

Power [kW (hp)]	Recommended maximum fuse					
	Bussmann Type RK1	Bussmann Type J	Bussmann Type T	Bussmann Type CC	Bussmann Type CC	Bussmann Type CC
1.1 (1.5)	KTS-R-5	JKS-5	JJS-6	FNQ-R-5	KTK-R-5	LP-CC-5
1.5–2.2 (2.0–3.0)	KTS-R-10	JKS-10	JJS-10	FNQ-R-10	KTK-R-10	LP-CC-10
3.0 (4.0)	KTS-R15	JKS-15	JJS-15	FNQ-R-15	KTK-R-15	LP-CC-15
4.0 (5.0)	KTS-R20	JKS-20	JJS-20	FNQ-R-20	KTK-R-20	LP-CC-20
5.5 (7.5)	KTS-R-25	JKS-25	JJS-25	FNQ-R-25	KTK-R-25	LP-CC-25
7.5 (10.0)	KTS-R-30	JKS-30	JJS-30	FNQ-R-30	KTK-R-30	LP-CC-30
11.0 (15.0)	KTS-R-35	JKS-35	JJS-35	–	–	–
15.0 (20.0)	KTS-R-45	JKS-45	JJS-45	–	–	–
18.5 (25.0)	KTS-R-50	JKS-50	JJS-50	–	–	–
22.0 (30.0)	KTS-R-60	JKS-60	JJS-60	–	–	–
30.0 (40.0)	KTS-R-80	JKS-80	JJS-80	–	–	–
37.0 (50.0)	KTS-R-100	JKS-100	JJS-100	–	–	–
45.0 (60.0)	KTS-R-125	JKS-125	JJS-125	–	–	–
55.0 (75.0)	KTS-R-150	JKS-150	JJS-150	–	–	–
75.0 (100.0)	KTS-R-175	JKS-175	JJS-175	–	–	–

Table 8.22 525–690 V, Enclosure Sizes A, B, and C

Power [kW (hp)]	Maximum pre-fuse	Recommended maximum fuse						
		Bussmann E52273 RK1/JDDZ	Bussmann E4273 J/JDDZ	Bussmann E4273 T/JDDZ	SIBA E180276 RK1/JDDZ	Littelfuse E81895 RK1/JDDZ	Ferraz Shawmut E163267/ E2137 RK1/JDDZ	Ferraz Shawmut E2137 J/HSJ
11.0 (15.0)	30 A	KTS-R-30	JKS-30	JKJS-30	5017906-030	KLS-R-030	A6K-30-R	HST-30
15–18.5 (20.0–25.0)	45 A	KTS-R-45	JKS-45	JJS-45	5014006-050	KLS-R-045	A6K-45-R	HST-45
22.0 (30.0)	60 A	KTS-R-60	JKS-60	JJS-60	5014006-063	KLS-R-060	A6K-60-R	HST-60
30.0 (40.0)	80 A	KTS-R-80	JKS-80	JJS-80	5014006-080	KLS-R-075	A6K-80-R	HST-80
37.0 (50.0)	90 A	KTS-R-90	JKS-90	JJS-90	5014006-100	KLS-R-090	A6K-90-R	HST-90
45.0 (60.0)	100 A	KTS-R-100	JKS-100	JJS-100	5014006-100	KLS-R-100	A6K-100-R	HST-100
55.0 (75.0)	125 A	KTS-R-125	JKS-125	JJS-125	2028220-125	KLS-150	A6K-125-R	HST-125
75.0 (100.0)	150 A	KTS-R-150	JKS-150	JJS-150	2028220-150	KLS-175	A6K-150-R	HST-150

Table 8.23 525–690 V, Enclosure Sizes B, and C

8.8 Connection Tightening Torques

Enclosure Size	200–240 V [kW (hp)]	380–500 V [kW (hp)]	525–690 V [kW (hp)]	Purpose	Tightening torque [Nm] ([in-lb])
A2	0.25–2.2 (0.34–3.0)	0.37–4 (0.5–5.0)	–	Mains, brake resistor, load sharing, motor cables.	0.5–0.6 (4.4–5.3)
A3	3–3.7 (4.0–5.0)	5.5–7.5 (7.5–10.0)	1.1–7.5 (1.5–10.0)		
A4	0.25–2.2 (0.34–3.0)	0.37–4 (0.5–5.0)	–		
A5	3–3.7 (4.0–5.0)	5.5–7.5 (7.5–10.0)	–		
B1	5.5–7.5 (7.5–10.0)	11–15 (15–20)	–	Mains, brake resistor, load sharing, motor cables.	1.8 (15.9)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)
B2	11 (15)	18.5–22 (25–30)	11–22 (15–30)	Mains, brake resistor, load sharing cables.	4.5 (39.8)
				Motor cables.	4.5 (39.8)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)
B3	5.5–7.5 (7.5–10.0)	11–15 (15–20)	–	Mains, brake resistor, load sharing, motor cables.	1.8 (15.9)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)
B4	11–15 (15–20)	18.5–30 (25–40)	11–30 (15–40)	Mains, brake resistor, load sharing, motor cables.	4.5 (39.8)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)
C1	15–22 (20–30)	30–45 (40–60)	–	Mains, brake resistor, load sharing cables.	10 (89)
				Motor cables.	10 (89)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)
C2	30–37 (40–50)	55–75 (75–100)	30–75 (40–100)	Mains, motor cables.	14 (124) (up to 95 mm ² (3 AWG)) 24 (212) (over 95 mm ² (3 AWG))
				Load sharing, brake cables.	14 (124)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)
C3	18.5–22 (25–30)	30–37 (40–50)	37–45 (50–60)	Mains, brake resistor, load sharing, motor cables.	10 (89)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)
C4	37–45 (50–60)	55–75 (75–100)	11–22 (15–30)	Mains, motor cables.	14 (124) (up to 95 mm ² (3 AWG)) 24 (212) (over 95 mm ² (3 AWG))
				Load sharing, brake cables.	14 (124)
				Relay.	0.5–0.6 (4.4–5.3)
				Ground.	2–3 (17.7–26.6)

Table 8.24 Tightening Torque for Cables

8.9 Power Ratings, Weight, and Dimensions

Enclosure size	A1	A2	A3	A4	A5
Rated power [kW (hp)]	0.25-1.5 (0.34-2)	0.25-2.2 (0.34-3)	3-3.7 (4-5)	0.25-2.2 (0.34-3)	0.25-3.7 (0.34-5)
380-480/500 V	0.37-1.5 (0.5-2)	0.37-4 (0.5-5)	5.5-7.5 (7.5-10)	0.37-4 (0.5-5)	0.37-7.5 (0.5-10)
525-600 V	-	-	0.75-7.5 (1-10)	-	0.75-7.5 (1-10)
525-690 V	-	-	1.1-7.5 (1.5-10)	-	-
IP	20	20	20	21	55/66
NEMA	Chassis	Chassis	Chassis	Type 1	Type 12/4X
Height [mm (in)]					
Height of mounting plate	200 (7.9)	268 (10.6)	268 (10.6)	375 (14.8)	390 (15.4)
Height with ground termination plate for fieldbus cables	316 (12.4)	374 (14.7)	374 (14.7)	-	-
Distance between mounting holes	190 (7.5)	257 (10.1)	257 (10.1)	350 (13.8)	401 (15.8)
Width [mm (in)]					
Width of mounting plate	75 (3)	90 (3.5)	130 (5.1)	130 (5.1)	200 (7.9)
Width of mounting plate with 1 C option	-	130 (5.1)	170 (6.7)	170 (6.7)	242 (9.5)
Width of mounting plate with 2 C options	-	150 (5.9)	190 (7.5)	190 (7.5)	242 (9.5)
Distance between mounting holes	60 (2.4)	70 (2.8)	110 (4.3)	110 (4.3)	171 (6.7)
Depth [mm (in)]					
Depth without option A/B	207 (8.1)	205 (8.1)	205 (8.1)	207 (8.1)	200 (7.9)
With option A/B	222 (8.7)	220 (8.7)	220 (8.7)	222 (8.7)	200 (7.9)
Screw holes [mm (in)]					
c	6.0 (0.24)	8.0 (0.31)	8.0 (0.31)	8.0 (0.31)	8.25 (0.32)
d	ø8 (ø0.31)	ø11 (ø0.43)	ø11 (ø0.43)	ø11 (ø0.43)	ø12 (ø0.47)
e	ø5 (ø0.2)	ø5.5 (ø0.22)	ø5.5 (ø0.22)	ø5.5 (ø0.22)	ø6.5 (ø0.26)
f	5 (0.2)	9 (0.35)	6.5 (0.26)	6.5 (0.26)	9 (0.35)
Maximum weight [kg (lb)]	2.7 (6)	4.9 (10.8)	6.6 (14.6)	7 (15.4)	13.5/14.2 (30/31)
Front cover tightening torque [Nm (in-lb)]					
Plastic cover (low IP)	Click	Click	Click	Click	-

Enclosure size		A1	A2	A3	A4	A5
Rated power [kW (hp)]	200-240 V	0.25-1.5 (0.34-2)	0.25-2.2 (0.34-3)	3-3.7 (4-5)	0.25-2.2 (0.34-3)	0.25-3.7 (0.34-5)
	380-480/500 V	0.37-1.5 (0.5-2)	0.37-4 (0.5-5)	5.5-7.5 (7.5-10)	0.37-4 (0.5-5)	0.37-7.5 (0.5-10)
	525-600 V	-	-	0.75-7.5 (1-10)	-	0.75-7.5 (1-10)
	525-690 V	-	-	1.1-7.5 (1.5-10)	-	-
Metal cover (IP55/66)		-	-	-	1.5 (13.3)	1.5 (13.3)

1) See Figure 8.2 and Figure 8.3 for top and bottom mounting holes.

Table 8.25 Power Ratings, Weight, and Dimensions, Enclosure Sizes A1-A5

Enclosure size	B1	B2	B3	B4
Rated power [kW (hp)]	5.5-7.5 (7.5-10)	15	5.5-7.5 (7.5-10)	11-15 (15-20)
	11-15 (15-20)	18.5-22 (25-30)	11-15 (15-20)	18.5-30 (25-40)
	11-15 (15-20)	18.5-22 (25-30)	11-15 (15-20)	18.5-30 (25-40)
	-	11-22 (15-30)	-	11-30 (15-40)
IP	21/55/66	21/55/66	20	20
NEMA	Type 1/12/4X	Type 1/12/4X	Chassis	Chassis
Height [mm (in)]				
Height of mounting plate	480 (18.9)	650 (25.6)	399 (15.7)	520 (20.5)
Height with ground termination plate for fieldbus cables	A	-	420 (16.5)	595 (23.4)
Distance between mounting holes	a	624 (24.6)	380 (15)	495 (19.5)
Width [mm (in)]				
Width of mounting plate	B	242 (9.5)	165 (6.5)	230 (9.1)
Width of mounting plate with 1 C option	B	242 (9.5)	205 (8.1)	230 (9.1)
Width of mounting plate with 2 C options	B	242 (9.5)	225 (8.9)	230 (9.1)
Distance between mounting holes	b	210 (8.3)	140 (5.5)	200 (7.9)
Depth [mm (in)]				
Depth without option A/B	C	260 (10.2)	249 (9.8)	242 (9.5)
With option A/B	C	260 (10.2)	262 (10.3)	242 (9.5)
Screw holes [mm (in)]				
	c	12 (0.47)	8 (0.31)	-
	d	ø19 (ø0.75)	12 (0.47)	-
	e	ø9 (ø0.35)	6.8 (0.27)	8.5 (0.33)
	f	9 (0.35)	7.9 (0.31)	15 (0.59)
Maximum weight [kg (lb)]		23 (51)	12 (26.5)	23.5 (52)
Front cover tightening torque [Nm (in-lb)]				
Plastic cover (low IP)	Click	Click	Click	Click
Metal cover (IP55/66)	2.2 (19.5)	2.2 (19.5)	-	-





Enclosure size	B1	B2	B3	B4
Rated power [kW (hp)]				
200–240 V	5.5–7.5 (7.5–10)	15	5.5–7.5 (7.5–10)	11–15 (15–20)
380–480/500 V	11–15 (15–20)	18.5–22 (25–30)	11–15 (15–20)	18.5–30 (25–40)
525–600 V	11–15 (15–20)	18.5–22 (25–30)	11–15 (15–20)	18.5–30 (25–40)
525–690 V	-	11–22 (15–30)	-	11–30 (15–40)

1) See Figure 8.2 and Figure 8.3 for top and bottom mounting holes.

Table 8.26 Power Ratings, Weight, and Dimensions, Enclosure Sizes B1–B4

Enclosure size		C1	C2	C3	C4	D3h
Rated power [kW (hp)]	200–240 V	15–22 (20–30)	30–37 (40–50)	18.5–22 (25–30)	30–37 (40–50)	–
	380–480/500 V	30–45 (40–60)	55–75 (75–100)	37–45 (50–60)	55–75 (75–100)	–
	525–600 V	30–45 (40–60)	55–90 (75–125)	37–45 (50–60)	55–90 (75–125)	–
	525–690 V	–	30–75 (40–100)	37–45 (50–60)	37–45 (50–60)	55–75 (75–100)
IP NEMA	–	21/55/66 Type 1/12/4X	21/55/66 Type 1/12/4X	20 Chassis	20 Chassis	20 Chassis
Height [mm (in)]						
Height of mounting plate	A ¹⁾	680 (26.8)	770 (30.3)	550 (21.7)	660 (26)	909 (35.8)
Height with ground termination plate for fieldbus cables	A	–	–	630 (24.8)	800 (31.5)	–
Distance between mounting holes	a	648 (25.5)	739 (29.1)	521 (20.5)	631 (24.8)	–
Width [mm (in)]						
Width of mounting plate	B	308 (12.1)	370 (14.6)	308 (12.1)	370 (14.6)	250 (9.8)
Width of mounting plate with 1 C option	B	308 (12.1)	370 (14.6)	308 (12.1)	370 (14.6)	–
Width of mounting plate with 2 C options	B	308 (12.1)	370 (14.6)	308 (12.1)	370 (14.6)	–
Distance between mounting holes	b	272 (10.7)	334 (13.1)	270 (10.6)	330 (13)	–
Depth [mm (in)]						
Depth without option A/B	C	310 (12.2)	335 (13.2)	333 (13.1)	333 (13.1)	375 (14.8)
With option A/B	C	310 (12.2)	335 (13.2)	333 (13.1)	333 (13.1)	375 (14.8)
Screw holes [mm (in)]						
	c	12.5 (0.49)	12.5 (0.49)	–	–	–
	d	ø19 (ø0.75)	ø19 (ø0.75)	–	–	–
	e	ø9 (ø0.35)	ø9 (ø0.35)	8.5 (0.33)	8.5 (0.33)	–
	f	9.8 (0.39)	9.8 (0.39)	17 (0.67)	17 (0.67)	–
Maximum weight [kg (lb)]		45 (99)	65 (143)	35 (77)	50 (110)	62 (137)
Front cover tightening torque [Nm (in-lb)]						
Plastic cover (low IP)		Click	Click	2 (17.7)	2 (17.7)	–
Metal cover (IP55/66)		2.2 (19.5)	2.2 (19.5)	2 (17.7)	2 (17.7)	–
1) See <i>Figure 8.2</i> and <i>Figure 8.3</i> for top and bottom mounting holes.						

Table 8.27 Power Ratings, Weight, and Dimensions, Enclosure Sizes C1–C4 and D3h

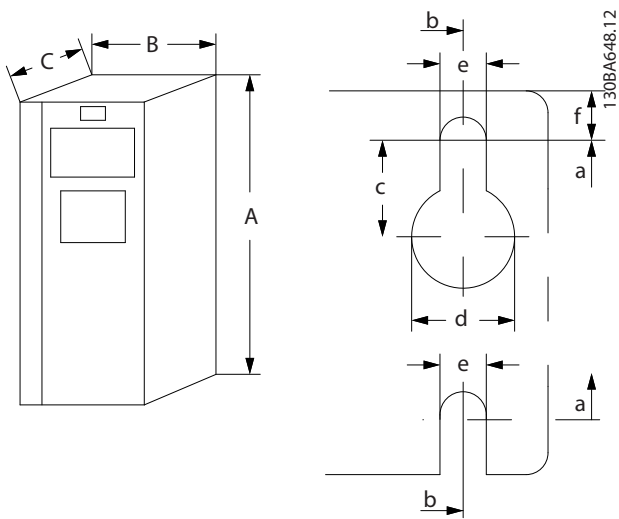


Figure 8.2 Top and Bottom Mounting Holes (See chapter 8.9 Power Ratings, Weight, and Dimensions)

8

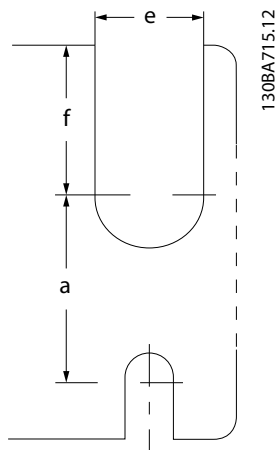


Figure 8.3 Top and Bottom Mounting Holes (B4, C3, and C4)

9 Appendix

9.1 Symbols, Abbreviations, and Conventions

°C	Degrees Celsius
°F	Degrees Fahrenheit
AC	Alternating current
AEO	Automatic energy optimization
AWG	American wire gauge
AMA	Automatic motor adaptation
DC	Direct current
EMC	Electro-magnetic compatibility
ETR	Electronic thermal relay
$f_{M,N}$	Nominal motor frequency
FC	Frequency converter
I_{INV}	Rated inverter output current
I_{LIM}	Current limit
$I_{M,N}$	Nominal motor current
$I_{VLT,MAX}$	Maximum output current
$I_{VLT,N}$	Rated output current supplied by the frequency converter
IP	Ingress protection
LCP	Local control panel
MCT	Motion control tool
n_s	Synchronous motor speed
$P_{M,N}$	Nominal motor power
PELV	Protective extra low voltage
PCB	Printed circuit board
PM Motor	Permanent magnet motor
PWM	Pulse width modulation
RPM	Revolutions per minute
Regen	Regenerative terminals
T_{LIM}	Torque limit
$U_{M,N}$	Nominal motor voltage

Table 9.1 Symbols and Abbreviations

Conventions

Numbered lists indicate procedures. Bullet lists indicate other information.

Italicized text indicates:

- Cross-reference.
- Link.
- Parameter name.
- Parameter group name.
- Parameter option.
- Footnote.

All dimensions in drawings are in [mm] (in).

9.2 Parameter Menu Structure

9.2.1 Software 8.10

Code	Operation / Display	Parameter	Description	Parameter	Description	Parameter	Description
0-0*	Basic Settings	0-79	Clock Fault	1-54	Voltage reduction in fieldweakening	2-16	AC brake Max. Current
0-01	Language	0-81	Working Days	1-55	U/f Characteristic - U	2-17	Over-voltage Control
0-02	Motor Speed Unit	0-82	Additional Non-Working Days	1-56	Brake Check Condition	2-18	Brake Check Condition
0-03	Regional Settings	0-83	Time for Fieldbus	1-58	Flying Start Test Pulses Current	2-19	Over-voltage Gain
0-04	Operating State at Power-up (Hand)	0-84	Summer Time Start for Fieldbus	1-6*	Flying Start Test Pulses Frequency	2-2*	Mechanical Brake
0-05	Performance Monitor	0-85	Summer Time End for Fieldbus	1-60	Load Depen. Setting	2-20	Release Brake Current
0-09	Set-up Operations	0-86	Date and Time Readout	1-61	Low Speed Load Compensation	2-21	Activate Brake Speed [RPM]
0-1*	Active Set-up	0-87	Load and Motor	1-62	High Speed Load Compensation	2-22	Activate Brake Speed [Hz]
0-10	Edit Set-up	0-88	General Settings	1-63	Slip Compensation Time Constant	2-23	Activate Brake Delay
0-11	This Set-up Linked to	0-89	Configuration Mode	1-64	Resonance Damping	2-24	Stop Delay
0-12	Readout: Linked Set-ups	1-0*	Motor Control Principle	1-65	Min. Current at Low Speed	2-25	Torque Ref
0-13	Readout: Edit Set-ups / Channel	1-01	Flux Motor Feedback Source	1-66	Torque Release Time	2-26	Torque Ramp Up Time
0-14	Readout: actual setup	1-02	Torque Characteristics	1-67	Motor Inertia	2-27	Quick Stop Ramp Time
0-15	Display Line 1.1 Small	1-03	Local Mode Configuration	1-68	System Inertia	2-28	Quick Stop Ramp Type
0-2*	LCP Display	1-04	Clockwise Direction	1-69	Start Adjustments	2-29	Quick Stop S-ramp Ratio at Decel.
0-20	Display Line 1.2 Small	1-05	Motor Angle Offset Adjust	1-7*	Start Mode	2-3*	Adv. Mech Brake
0-21	Display Line 1.3 Small	1-06	Special Settings	1-70	Start Delay	2-30	Position P Start Proportional Gain
0-22	Display Line 2 Large	1-07	Motor Construction	1-71	Start Function	2-31	Speed PID Start Proportional Gain
0-23	Display Line 3 Large	1-08	Damping Gain	1-72	Flying Start	2-32	Speed PID Start Integral Time
0-24	My Personal Menu	1-09	Low Speed Filter Time Const.	1-73	Start Speed [RPM]	2-33	Speed PID Start Lowpass Filter Time
0-25	LCP Custom Readout	1-10	High Speed Filter Time Const.	1-74	Start Speed [Hz]	3-0*	Reference / Ramps
0-30	Unit for User-defined Readout	1-11	Voltage filter time const.	1-75	Start Current	3-0*	Reference Range
0-31	Min Value of User-defined Readout	1-12	Min. Current at No Load	1-76	Start Speed [Hz]	3-01	Reference/Feedback Unit
0-32	Max Value of User-defined Readout	1-13	Motor Data	1-8*	Stop Adjustments	3-02	Minimum Reference
0-33	Source for User-defined Readout	1-14	Motor Power [kW]	1-80	Function at Stop	3-03	Maximum Reference
0-37	Display Text 1	1-15	Motor Voltage	1-81	Min. Speed for Function at Stop [RPM]	3-04	Reference Function
0-38	Display Text 2	1-16	Motor Power [HP]	1-82	Min Speed for Function at Stop [Hz]	3-10	Preset Reference
0-39	Display Text 3	1-17	Motor Voltage	1-83	Precise Stop Function	3-11	Jog Speed [Hz]
0-4*	LCP Keypad	1-18	Motor Frequency	1-84	Precise Stop Counter Value	3-12	Catch up/slow Down Value
0-40	[Hand on] Key on LCP	1-19	Motor Current	1-85	Precise Stop Speed Compensation	3-13	Reference Site
0-41	[Off] Key on LCP	1-20	Motor Nominal Speed	1-9*	Motor Temperature	3-15	Preset Relative Reference
0-42	[Auto on] Key on LCP	1-21	Motor Cont. Rated Torque	1-90	Motor Thermal Protection	3-16	Reference Resource 1
0-43	[Reset] Key on LCP	1-22	Automatic Motor Adaptation (AMA)	1-91	Motor External Fan	3-17	Reference Resource 2
0-44	[Off/Reset] Key on LCP	1-23	Adv. Motor Data	1-94	ATEX ETR cur.lim. speed reduction	3-18	Reference Resource 3
0-45	[Drive Bypass] Key on LCP	1-24	Stator Resistance (Rs)	1-95	Thermistor Resource	3-19	Relative Scaling Reference Resource
0-5*	Copy/Save	1-25	Rotor Resistance (Rr)	1-96	Thermistor Sensor Type	3-4*	Ramp 1
0-50	LCP Copy	1-26	Rotor Leakage Reactance (X1)	1-97	Thermistor Threshold level	3-40	Ramp 1 Type
0-51	Set-up Copy	1-27	Rotor Leakage Reactance (X2)	1-98	ATEX ETR interpol. points freq.	3-41	Ramp 1 Ramp Up Time
0-6*	Password	1-28	Main Reactance (Xh)	1-99	ATEX ETR interpol. points current	3-42	Ramp 1 Ramp Down Time
0-60	Main Menu Password	1-29	Iron Loss Resistance (Rfe)	2-*	Brakes	3-43	Ramp 1 S-ramp Ratio at Accel. Start
0-61	Access to Main Menu w/o Password	1-30	q-axis Inductance (Ld)	2-0*	DC-Brake	3-44	Ramp 1 S-ramp Ratio at Decel. Start
0-65	Quick Menu Password	1-31	q-axis Inductance (Lq)	2-00	DC Hold Current	3-45	Ramp 1 S-ramp Ratio at Decel. End
0-66	Access to Quick Menu w/o Password	1-32	Motor Poles	2-01	DC Brake Current	3-5*	Ramp 2
0-67	Bus Password Access	1-33	Back EMF at 1000 RPM	2-02	DC Brake Time	3-50	Ramp 2 Type
0-68	Safety Parameters Password	1-34	Motor Angle Offset	2-03	DC Braking Time	3-51	Ramp 2 Ramp Up Time
0-69	Password Protection of Safety Parameters	1-35	d-axis Inductance Sat. (LdSat)	2-04	DC Brake Cut In Speed [Hz]	3-52	Ramp 2 Ramp Down Time
0-7*	Clock Settings	1-36	Position Detection Gain	2-05	Maximum Reference	3-53	Ramp 2 S-ramp Ratio at Accel. Start
0-70	Date and Time	1-37	Torque Calibration	2-06	Parking Current	3-54	Ramp 2 S-ramp Ratio at Accel. End
0-71	Date Format	1-38	Inductance Sat. Point	2-07	Parking Time	3-55	Tracking Error Function
0-72	Time Zone Offset	1-39	q-Axis Inductance Saturation Point	2-1*	Brake Energy Funct.	3-56	Tracking Error
0-73	Time Zone Offset	1-40	Motor Magnetising at Zero Speed [RPM]	2-10	Brake Function	3-57	Tracking Error Timeout
0-74	DST/Summertime Start	1-41	Min Speed Normal Magnetising	2-11	Brake Resistor (ohm)	3-6*	Tracking Error Ramping
0-76	DST/Summertime End	1-42	Motor Magnetising [Hz]	2-12	Brake Power Limit (kW)	3-60	Tracking Error After Ramping
0-77	DST/Summertime End	1-43	Model Shift Frequency	2-13	Brake Power Monitoring	3-61	Timeout
		1-44		2-15	Brake Check	3-62	Speed Monitor
		1-45				3-63	Motor Speed Monitor Function
		1-46				3-65	Motor Speed Monitor Max

4-45	Motor Speed Monitor Timeout	5-40	Function Relay	6-36	Term. X30/11 Filter Time Constant	7-31	Process PID Anti Windup	8-47	BTM Timeout
4-50	Adj. Warnings	5-41	On Delay, Relay	6-4*	Analog Input 4	7-32	Process PID Start Speed	8-48	BTM Maximum Errors
4-51	Warning Current Low	5-42	Off Delay, Relay	6-41	Terminal X30/12 Low Voltage	7-33	Process PID Proportional Gain	8-49	BTM Error Log
4-52	Warning Current High	5-5*	Pulse Input	6-40	Terminal X30/12 High Voltage	7-34	Process PID Integral Time	8-5*	Digital/Bus
4-53	Warning Speed Low	5-50	Term. 29 Low Frequency	6-44	Term. X30/12 Low Ref./Feedb. Value	7-35	Process PID Differentiation Time	8-50	Coasting Select
4-54	Warning Speed High	5-51	Term. 29 High Frequency	6-45	Term. X30/12 High Ref./Feedb. Value	7-36	Process PID Diff. Gain Limit	8-51	Quick Stop Select
4-55	Warning Reference Low	5-52	Term. 29 High Ref./Feedb. Value	6-46	Term. X30/12 Filter Time Constant	7-38	Process PID Feed Forward Factor	8-52	DC Brake Select
4-56	Warning Reference High	5-53	Term. 29 High Ref./Feedb. Value	6-5*	Analog Output 1	7-39	On Reference Bandwidth	8-53	Start Select
4-57	Warning Feedback Low	5-54	Pulse Filter Time Constant #29	6-50	Terminal 42 Output	7-4*	Adv. Process PID I	8-54	Reversing Select
4-58	Warning Feedback High	5-55	Term. 33 Low Frequency	6-51	Terminal 42 Output Min Scale	7-40	Process PID I-part Reset	8-55	Set-up Select
4-59	Missing Motor Phase Function	5-56	Term. 33 High Frequency	6-52	Terminal 42 Output Max Scale	7-41	Process PID Output Neg. Clamp	8-56	Preset Reference Select
4-60	Motor Check At Start	5-57	Term. 33 Low Ref./Feedb. Value	6-53	Term. 42 Output Bus Ctrl	7-42	Process PID Output Pos. Clamp	8-57	Profidrive OFF2 Select
4-61	Speed Bypass	5-58	Term. 33 High Ref./Feedb. Value	6-54	Terminal 42 Output Timeout Preset	7-43	Process PID Gain Scale at Min. Ref.	8-58	Profidrive OFF3 Select
4-62	Bypass Speed From [RPM]	5-59	Pulse Filter Time Constant #33	6-5*	Analog Output 2	7-44	Process PID Gain Scale at Max. Ref.	8-8*	FC Port Diagnostics
4-63	Bypass Speed To [RPM]	5-60	Terminal 27 Pulse Output Variable	6-6*	Terminal X30/8 Output	7-45	Process PID Feed Fwd Resource	8-80	Bus Message Count
4-64	Bypass Speed To [Hz]	5-61	Pulse Output Max Freq #27	6-61	Terminal X30/8 Min. Scale	7-46	Bus Error Count	8-81	Bus Error Count
4-65	Bypass Speed To [Hz]	5-62	Terminal 29 Pulse Output Variable	6-62	Terminal X30/8 Max. Scale	7-48	Slave Messages Rcvd	8-82	Slave Messages Rcvd
4-8*	Power Limit	5-63	Pulse Output Max Freq #29	6-63	Terminal X30/8 Bus Control	7-49	Slave Error Count	8-83	Slave Error Count
4-81	Power Limit Func. Motor Mode	5-66	Terminal X30/6 Pulse Output Variable	6-64	Terminal X30/8 Output Timeout Preset	7-5*	Bus Jog	8-9*	Bus Jog
4-82	Power Limit Motor Mode	5-68	Pulse Output Max Freq #X30/6	6-7*	Analog Output 3	7-50	Bus Jog 1 Speed	8-90	Bus Jog 1 Speed
4-83	Power Limit Generator Mode	5-7*	24V Encoder Input	6-70	Terminal X45/1 Output	7-51	Bus Jog 2 Speed	8-91	Bus Jog 2 Speed
4-9*	Directional Limits	5-70	Term. 32/33 Pulses Per Revolution	6-71	Terminal X45/1 Min. Scale	7-52	PROFIBUS	9-0*	PROFIBUS
4-90	Directional Limit Mode	5-71	Term. 32/33 Encoder Direction	6-72	Terminal X45/1 Max. Scale	7-53	Setpoint	9-00	Setpoint
4-91	Positive Speed Limit [RPM]	5-8*	I/O Options	6-73	Terminal X45/1 Bus Control	7-56	Actual Value	9-07	Actual Value
4-92	Positive Speed Limit [Hz]	5-80	AHF Cap Reconnect Delay	6-74	Terminal X45/1 Output Timeout Preset	7-57	PCD Write Configuration	9-15	PCD Write Configuration
4-93	Negative Speed Limit [RPM]	5-9*	Bus Controlled	6-8*	Analog Output 4	8-0*	PCD Read Configuration	9-16	PCD Read Configuration
4-94	Negative Speed Limit [Hz]	5-90	Digital & Relay Bus Control	6-81	Terminal X45/3 Output	8-01	Node Address	9-18	Node Address
4-95	Positive Torque limit	5-93	Pulse Out #27 Bus Control	6-82	Terminal X45/3 Min. Scale	8-02	Drive Unit System Number	9-19	Drive Unit System Number
4-96	Negative Torque limit	5-95	Pulse Out #29 Bus Control	6-83	Terminal X45/3 Max. Scale	8-03	Telegram Selection	9-22	Telegram Selection
5-0*	Digital In/Out	5-96	Pulse Out #29 Timeout Preset	6-84	Terminal X45/3 Bus Control	8-04	Parameters for Signals	9-23	Parameters for Signals
5-01	Digital I/O Mode	5-97	Pulse Out #X30/6 Bus Control	6-84	Terminal X45/3 Output Timeout Preset	8-05	Parameter Edit	9-27	Parameter Edit
5-02	Terminal 29 Mode	6-0*	Analog In/Out	7-0*	Controllers	8-06	Process Control	9-28	Process Control
5-10	Terminal 18 Digital Input	6-00	Analog I/O Mode	7-01	Speed PID Ctrl.	8-07	End-of-Timeout Function	9-44	Fault Message Counter
5-11	Terminal 19 Digital Input	6-01	Live Zero Timeout Function	7-02	Speed PID Feedback Source	8-08	Reset Control Word Timeout	9-45	Fault Code
5-12	Terminal 20 Digital Input	6-1*	Analog Input 1	7-03	Speed PID Droop	8-08	Diagnosis Trigger	9-47	Fault Number
5-13	Terminal 21 Digital Input	6-10	Terminal 53 Low Voltage	7-04	Speed PID Integral Time	8-10	Readout Filtering	9-52	Fault Situation Counter
5-14	Terminal 32 Digital Input	6-11	Terminal 53 High Voltage	7-05	Speed PID Differentiation Time	8-11	Ctrl. Word Settings	9-53	Profibus Warning Word
5-15	Terminal 33 Digital Input	6-12	Terminal 53 Low Current	7-06	Speed PID Filter Time	8-13	Control Word Profile	9-63	Actual Baud Rate
5-16	Terminal X30/2 Digital Input	6-13	Terminal 53 High Current	7-07	Speed PID Lowpass Filter Time	8-14	Configurable Status Word STW	9-64	Device Identification
5-17	Terminal X30/3 Digital Input	6-14	Terminal 53 Low Ref./Feedb. Value	7-08	Speed PID Feedback Gear Ratio	8-17	Configurable Control Word CTW	9-65	Profile Number
5-18	Terminal X30/4 Digital Input	6-15	Terminal 53 High Ref./Feedb. Value	7-09	Speed PID Error Correction w/ Ramp	8-19	Configurable Alarm and Warningword	9-67	Control Word 1
5-19	Terminal 37 Safe Stop	6-16	Analog Input 2	7-10	Torque PI Ctrl.	8-33	Product Code	9-68	Status Word 1
5-20	Terminal X46/1 Digital Input	6-2*	Terminal 54 Low Voltage	7-11	Terminal 54 High Voltage	8-33	FC Port Settings	9-71	Profibus Save Data Values
5-21	Terminal X46/3 Digital Input	6-21	Terminal 54 High Voltage	7-12	Terminal 54 Low Current	8-34	Protocol	9-72	ProfibusDriveReset
5-22	Terminal X46/5 Digital Input	6-22	Terminal 54 Low Current	7-13	Terminal 54 High Current	8-34	Parity / Stop Bits	9-75	DO Identification
5-23	Terminal X46/7 Digital Input	6-23	Terminal 54 High Current	7-14	Terminal 54 Low Ref./Feedb. Value	8-35	FC Port Baud Rate	9-80	Defined Parameters (1)
5-24	Terminal X46/9 Digital Input	6-24	Terminal 54 High Ref./Feedb. Value	7-15	Terminal 54 High Ref./Feedb. Value	8-36	Parity / Stop Bits	9-81	Defined Parameters (2)
5-25	Terminal X46/11 Digital Input	6-25	Terminal 54 Low Ref./Feedb. Value	7-16	Terminal 54 Low Ref./Feedb. Value	8-37	Estimated cycle time	9-82	Defined Parameters (3)
5-26	Terminal X46/13 Digital Input	6-26	Terminal 54 Filter Time Constant	7-17	Terminal 54 Filter Time Constant	8-4*	Minimum Response Delay	9-83	Defined Parameters (4)
5-3*	Digital Outputs	6-3*	Analog Input 3	7-18	Terminal 54 High Ref./Feedb. Value	8-40	Max Inter-Char Delay	9-84	Defined Parameters (5)
5-30	Terminal 27 Digital Output	6-30	Terminal X30/11 Low Voltage	7-19	Terminal 54 Filter Time Constant	8-41	FC MC protocol set	9-90	Changed Parameters (1)
5-31	Terminal 29 Digital Output	6-31	Terminal X30/11 High Voltage	7-20	Process CL Feedback 1 Resource	8-42	Telegram Selection	9-91	Changed Parameters (2)
5-32	Term X30/6 Digi Out (MCB 101)	6-32	Terminal X30/11 Low Voltage	7-22	Process CL Feedback 2 Resource	8-43	Parameters for Signals	9-92	Changed Parameters (3)
5-33	Term X30/7 Digi Out (MCB 101)	6-34	Term. X30/11 High Ref./Feedb. Value	7-3*	Process PID Ctrl.	8-45	PCD Write Configuration	9-93	Changed Parameters (4)
5-4*	Relays	6-35	Term. X30/11 High Ref./Feedb. Value	7-30	Process PID Normal/ Inverse Control	8-46	PCD Read Configuration	9-94	Changed Parameters (5)
							BTM Transaction Command	9-99	Profibus Revision Counter
							BTM Transaction Status		



10-0* CAN Fieldbus	12-3* EtherNet/IP	13-4* Logic Rules	14-56 Capacitance Output Filter	15-6* Option Ident
10-00 Common Settings	12-30 Warning Parameter	13-40 Logic Rule Boolean 1	14-57 Inductance Output Filter	15-60 Option Mounted
10-01 CAN Protocol	12-31 Net Reference	13-41 Logic Rule Operator 1	14-59 Actual Number of Inverter Units	15-61 Option SW Version
10-01 Baud Rate Select	12-32 Net Control	13-42 Logic Rule Boolean 2	14-6* Auto Derate	15-62 Option Ordering No
10-02 MAC ID	12-33 CIP Revision	13-43 Logic Rule Operator 2	14-60 Function at Over Temperature	15-63 Option Serial No
10-05 Readout Transmit Error Counter	12-34 CIP Product Code	13-44 Logic Rule Boolean 3	14-61 Function at Inverter Overload	15-70 Option in Slot A
10-06 Readout Receive Error Counter	12-35 EDS Parameter	13-5* States	14-62 Inv. Overload Derate Current	15-71 Slot A Option SW Version
10-07 Readout Bus Off Counter	12-37 COS Inhibit Timer	13-51 SL Controller Event	14-7* Compatibility	15-72 Option in Slot B
10-1* DeviceNet	12-38 COS Filter	13-52 SL Controller Action	14-72 Legacy Alarm Word	15-73 Slot B Option SW Version
10-10 Process Data Type Selection	12-4* Modbus TCP	13-9* User Defined Alerts	14-73 Legacy Warning Word	15-74 Option in Slot C0/E0
10-11 Process Data Config Write	12-40 Status Parameter	13-90 Alert Trigger	14-74 Leg. Ext. Status Word	15-75 Slot C0/E0 Option SW Version
10-12 Process Data Config Read	12-41 Slave Message Count	13-91 Alert Action	14-8* Options	15-76 Option in Slot C1/E1
10-13 Warning Parameter	12-42 Slave Exception Message Count	13-92 Alert Text	14-80 Option Supplied by External 24VDC	15-77 Slot C1/E1 Option SW Version
10-14 Net Reference	12-5* EtherCAT	13-9* User Defined Readouts	14-88 Option Data Storage	15-8* Operating Data II
10-15 Net Control	12-50 Configured Station Alias	13-97 Alert Alarm Word	14-89 Option Detection	15-80 Fan Running Hours
10-2* COS Filters	12-51 Configured Station Address	13-98 Alert Warning Word	14-9* Fault Settings	15-81 Preset Fan Running Hours
10-20 COS Filter 1	12-59 EtherCAT Status	13-99 Alert Status Word	14-90 Fault Level	15-89 Configuration Change Counter
10-21 COS Filter 2	12-6* Ethernet PowerLink	14-0* Special Functions	15-0* Drive Information	15-9* Parameter Info
10-22 COS Filter 3	12-60 Node ID	14-00 Inverter Switching	15-00 Operating Data	15-92 Defined Parameters
10-23 COS Filter 4	12-62 SDO Timeout	14-00 Switching Pattern	15-00 Operating hours	15-93 Modified Parameters
10-3* Parameter Access	12-63 Basic Ethernet Timeout	14-01 Switching Frequency	15-01 Running Hours	15-98 Drive Identification
10-30 Array Index	12-66 Threshold	14-03 Overmodulation	15-02 kWh Counter	15-99 Parameter Metadata
10-31 Store Data Values	12-67 Threshold Counters	14-04 Acoustic Noise Reduction	15-03 Power Up's	16-0* Data Readouts
10-32 Devicenet Revision	12-68 Cumulative Counters	14-06 Dead Time Compensation	15-04 Over Temp's	16-0* General Status
10-33 Store Always	12-69 Cumulative Counters	14-1* Mains Failure	15-05 Over Volt's	16-00 Control Word
10-34 DeviceNet Product Code	12-69 Ethernet PowerLink Status	14-10 Mains Failure	15-06 Reset kWh Counter	16-01 Reference [Unit]
10-39 Devicenet F Parameters	12-8* Other Ethernet Services	14-11 Mains Fault Voltage Level	15-07 Reset Running Hours Counter	16-02 Reference %
10-5* CANopen	12-80 FTP Server	14-12 Response to Mains Imbalance	15-1* Data Log Settings	16-03 Status Word
10-50 Process Data Config Write.	12-81 HTTP Server	14-14 Kin. Back-up Time-out	15-10 Logging Source	16-05 Main Actual Value [%]
10-51 Process Data Config Read.	12-82 SMTP Service	14-15 Kin. Back-up Trip Recovery Level	15-11 Logging Interval	16-06 Actual Position
12-0* Ethernet	12-84 Address Conflict Detection	14-16 Kin. Back-up Gain	15-12 Trigger Event	16-09 Custom Readout
12-0* IP Settings	12-85 ACD Last Conflict	14-2* Trip Reset	15-13 Logging Mode	16-1* Motor Status
12-00 IP Address Assignment	12-88 Transparent Socket Channel Port	14-20 Reset Mode	15-14 Samples Before Trigger	16-10 Power [kW]
12-01 IP Address	12-9* Advanced Ethernet Services	14-21 Automatic Restart Time	15-2* Historic Log	16-11 Power [hp]
12-02 Subnet Mask	12-90 Cable Diagnostic	14-22 Operation Mode	15-20 Historic Log: Event	16-12 Motor Voltage
12-03 Default Gateway	12-91 Auto Cross Over	14-23 Typecode Setting	15-21 Historic Log: Value	16-13 Frequency
12-04 DHCP Server	12-92 IGMP Snooping	14-24 Trip Delay at Current Limit	15-22 Historic Log: Time	16-14 Motor current
12-05 Lease Expires	12-93 Cable Error Length	14-25 Trip Delay at Torque Limit	15-3* Fault Log	16-15 Frequency [%]
12-06 Name Servers	12-94 Broadcast Storm Protection	14-26 Trip Delay at Inverter Fault	15-30 Fault Log: Error Code	16-16 Torque [Nm]
12-07 Domain Name	12-95 Inactivity timeout	14-28 Production Settings	15-31 Fault Log: Value	16-17 Speed [RPM]
12-08 Host Name	12-96 Port Config	14-3* Current Limit Ctr.	15-32 Fault Log: Time	16-18 Motor Thermal
12-09 Physical Address	12-97 QoS Priority	14-30 Current Lim Ctr, Proportional Gain	15-33 Fault log: Date and Time	16-19 Thermistor Sensor Temperature
12-1* Ethernet Link Parameters	12-98 Interface Counters	14-31 Current Lim Ctr, Integration Time	15-4* Drive Identification	16-20 Motor Angle
12-10 Link Status	12-99 Media Counters	14-32 Current Lim Ctr, Filter Time	15-40 FC Type	16-21 Torque [%] High Res.
12-11 Link Duration	13-0* Smart Logic	14-33 Stall Protection	15-41 Power Section	16-22 Torque [%]
12-12 Auto Negotiation	13-0* SLC Settings	14-36 Field-weakening Function	15-42 Voltage	16-23 Motor Shaft Power [kW]
12-13 Link Speed	13-00 SL Controller Mode	14-37 Fieldweakening Speed	15-43 Software Version	16-24 Calibrated Stator Resistance
12-14 Link Duplex	13-01 Start Event	14-4* Energy Optimising	15-44 Ordered Typecode String	16-25 Torque [Nm] High
12-18 Supervisor MAC	13-02 Stop Event	14-40 VT Level	15-45 Actual Typecode String	16-3* Drive Status
12-19 Supervisor IP Addr.	13-03 Reset SLC	14-41 AEO Minimum Magnetisation	15-46 Frequency Converter Ordering No	16-30 DC Link Voltage
12-2* Process Data	13-1* Comparators	14-42 Minimum AEO Frequency	15-47 Power Card Ordering No	16-31 System Temp.
12-20 Control Instance	13-10 Comparator Operand	14-43 Motor Cosphi	15-48 LCP Id No	16-32 Brake Energy /s
12-21 Process Data Config Write	13-11 Comparator Operator	14-5* Environment	15-49 SW ID Control Card	16-33 Brake Energy Average
12-22 Process Data Config Read	13-12 Comparator Value	14-50 RFI Filter	15-50 SW ID Power Card	16-34 Heatsink Temp.
12-23 Process Data Config Write Size	13-1* RS Flip Flops	14-51 DC-Link Compensation	15-51 Frequency Converter Serial Number	16-35 Inverter Thermal
12-24 Process Data Config Read Size	13-15 RS-FF Operand S	14-52 Fan Control	15-53 Power Card Serial Number	16-36 Inv. Nom. Current
12-27 Master Address	13-16 RS-FF Operand R	13-2* Timers	15-54 Config File Name	16-37 Inv. Max. Current
12-28 Store Data Values	13-20 SL Controller Timer	14-55 Output Filter	15-58 Smart Setup Filename	16-38 SL Controller State
12-29 Store Always			15-59 Filename	16-39 Control Card Temp.

16-40	Logging Buffer Full	17-22	Multiturn Revolutions	23-0*	Timed Actions	30-97	Wifi Timeout Action	32-72	Size of the Control Window (Deactiv)
16-41	Performance Measurements	17-24	SSI Data Length	23-01	ON Time	31-**	Bypass Option	32-73	Integral limit filter time
16-42	Service Log Counter	17-25	Clock Rate	23-02	OFF Time	31-00	Bypass Mode	32-74	Position error filter time
16-43	Timed Actions Status	17-26	SSI Data Format	23-02	OFF Action	31-01	Bypass Start Time Delay	32-8*	Velocity & Accel.
16-45	Motor Phase U Current	17-34	HIPERFACE Baudrate	23-03	OFF Action	31-02	Bypass Trip Time Delay	32-80	Maximum Velocity (Encoder)
16-46	Motor Phase V Current	17-5*	Resolver Interface	23-04	Occurrence	31-03	Test Mode Activation	32-81	Shortest Ramp
16-47	Motor Phase W Current	17-50	Poles	23-0*	Timed Actions Settings	31-10	Bypass Status Word	32-82	Ramp Type
16-48	Speed Ref. After Ramp [RPM]	17-51	Input Voltage	23-08	Timed Actions Mode	31-11	Bypass Running Hours	32-83	Velocity Resolution
16-49	Current Fault Source	17-52	Input Frequency	23-09	Timed Actions Reactivation	31-19	Remote Bypass Activation	32-84	Default Velocity
16-5*	Ref. & Feedb.	17-53	Transformation Ratio	23-1*	Maintenance	32-**	MCO Basic Settings	32-85	Default Acceleration
16-50	External Reference	17-56	Encoder Sim. Resolution	23-10	Maintenance Item	32-0*	Encoder 2	32-86	Acc. up for limited jerk
16-51	Pulse Reference	17-59	Resolver Interface	23-11	Maintenance Action	32-00	Incremental Signal Type	32-87	Acc. down for limited jerk
16-52	Feedback[Unit]	17-6*	Monitoring and App.	23-12	Maintenance Time Base	32-01	Incremental Resolution	32-88	Dec. up for limited jerk
16-53	Digi Pot Reference	17-60	Feedback Direction	23-13	Maintenance Time Interval	32-02	Absolute Protocol	32-89	Dec. down for limited jerk
16-57	Feedback [RPM]	17-61	Feedback Signal Monitoring	23-14	Maintenance Date and Time	32-03	Absolute Resolution	32-9*	Development
16-6*	Inputs & Outputs	17-7*	Position Scaling	23-1*	Maintenance Reset	32-04	Absolute Encoder Baudrate X55	32-90	Debug Source
16-60	Digital Input	17-70	Position Unit	23-15	Reset Maintenance Word	32-05	Absolute Encoder Data Length	33-**	MCO Adv. Settings
16-61	Terminal 53 Switch Setting	17-71	Position Unit Scale	23-16	Maintenance Text	32-06	Absolute Encoder Clock Frequency	33-0*	Home Motion
16-62	Analog Input 53	17-72	Position Unit Numerator	30-**	Special Features	32-07	Absolute Encoder Cable Generation	33-01	Force HOME
16-63	Terminal 54 Switch Setting	17-73	Position Unit Denominator	30-0*	Wobbler	32-08	Absolute Encoder Cable Length	33-01	Zero Point Offset from Home Pos.
16-64	Analog Input 54	17-74	Position Offset	30-00	Wobble Mode	32-09	Encoder Monitoring	33-02	Ramp for Home Motion
16-65	Analog Output 42 [mA]	18-**	Data Readouts 2	30-01	Wobble Delta Frequency [Hz]	32-10	Rotational Direction	33-03	Velocity of Home Motion
16-66	Digital Output [bin]	18-0*	Maintenance Log	30-02	Wobble Delta Frequency [%]	32-11	User Unit Denominator	33-04	Behaviour during HomeMotion
16-67	Freq. Input #29 [Hz]	18-00	Maintenance Log: Item	30-03	Wobble Delta Freq. Scaling Resource	32-12	User Unit Numerator	33-1*	Synchronization
16-68	Freq. Input #29 [Hz]	18-01	Maintenance Log: Action	30-04	Wobble Delta Freq. Frequency [Hz]	32-13	Enc.2 Control	33-10	Sync Factor Master
16-69	Pulse Output #27 [Hz]	18-02	Maintenance Log: Time	30-05	Wobble Jump Frequency [%]	32-14	Enc.2 node ID	33-11	Sync Factor Slave
16-70	Pulse Output #29 [Hz]	18-03	Maintenance Log: Date and Time	30-06	Wobble Jump Time	32-15	Enc.2 CAN guard	33-12	Position Offset for Synchronization
16-71	Relay Output [bin]	18-2*	Motor Readouts	30-07	Wobble Sequence Time	32-3*	Encoder 1	33-13	Accuracy Window for Position Sync.
16-72	Counter A	18-27	Safe Opt. Est. Speed	30-08	Wobble Up/ Down Time	32-30	Incremental Signal Type	33-14	Relative Slave Velocity Limit
16-73	Counter B	18-28	Safe Opt. Meas. Speed	30-09	Wobble Random Function	32-31	Incremental Resolution	33-15	Marker Number for Master
16-74	Prec. Stop Counter	18-29	Safe Opt. Speed Error	30-10	Wobble Ratio	32-32	Absolute Protocol	33-16	Marker Number for Slave
16-75	Analog In X30/11	18-3*	Analog Readouts	30-11	Wobble Random Ratio Max.	32-33	Absolute Resolution	33-17	Master Marker Distance
16-76	Analog In X30/12	18-36	Analog Input X48/2 [mA]	30-12	Wobble Random Ratio Min.	32-35	Absolute Encoder Data Length	33-18	Slave Marker Distance
16-77	Analog Out X30/8 [mA]	18-37	Temp. Input X48/4	30-19	Wobble Delta Freq. Scaled	32-36	Absolute Encoder Clock Frequency	33-19	Master Marker Type
16-78	Analog Out X45/1 [mA]	18-38	Temp. Input X48/7	30-2*	Adv. Start Adjust	32-37	Absolute Encoder Clock Generation	33-20	Slave Marker Type
16-79	Analog Out X45/3 [mA]	18-39	Temp. Input X48/10	30-20	High Starting Torque Time [s]	32-38	Absolute Encoder Cable Length	33-21	Master Marker Tolerance Window
16-8*	Fieldbus & FC Port	18-4*	PGIO Data Readouts	30-21	High Starting Torque Current [%]	32-39	Encoder Monitoring	33-22	Slave Marker Tolerance Window
16-80	Fieldbus CTW 1	18-43	Analog Out X49/7	30-22	Locked Rotor Protection	32-40	Encoder Termination	33-23	Start Behaviour for Marker Sync
16-82	Fieldbus REF 1	18-44	Analog Out X49/9	30-23	Locked Rotor Detection Time [s]	32-43	Enc.1 Control	33-24	Marker Number for Fault
16-84	Comm. Option STW	18-45	Analog Out X49/11	30-24	Locked Rotor Detection Speed Error [%]	32-44	Enc.1 node ID	33-25	Marker Number for Ready
16-85	FC Port CTW 1	18-5*	Active Alarms/Warnings	30-25	Light Load Delay [s]	32-45	Enc.1 CAN guard	33-26	Velocity Filter
16-86	FC Port REF 1	18-55	Active Alarm Numbers	30-26	Light Load Current [%]	32-5*	Feedback Source	33-27	Offset Filter Time
16-87	Bus Readout Alarm/Warning	18-56	Active Warning Numbers	30-27	Light Load Speed [%]	32-50	Source Slave	33-28	Marker Filter Configuration
16-89	Configurable Alarm/Warning Word	18-6*	Inputs & Outputs 2	30-27	Light Load Speed [%]	32-51	MCO 302 Last Will	33-29	Filter Time for Marker Filter
16-9*	Diagnosis Readouts	18-60	Digital Input 2	30-5*	Unit Configuration	32-52	Source Master	33-30	Maximum Marker Correction
16-90	Alarm Word	18-7*	Rectifier Status	30-50	Heat Sink Fan Mode	32-6*	PID Controller	33-31	Synchronisation Type
16-91	Alarm Word 2	18-70	Mains Voltage	30-8*	Compatibility (I)	32-60	Proportional factor	33-32	Feed Forward Velocity Adaptation
16-92	Warning Word	18-71	Mains Frequency	30-80	d-axis Inductance (Ld)	32-61	Derivative factor	33-33	Velocity Filter Window
16-93	Warning Word 2	18-72	Mains Imbalance	30-81	Brake Resistor (ohm)	32-62	Integral factor	33-34	Slave Marker filter time
16-94	Ext. Status Word	18-75	Rectifier DC Volt.	30-83	Speed PID Proportional Gain	32-63	Limit Value for Integral Sum	33-4*	Limit Handling
16-95	Ext. Status Word 2	18-9*	PID Readouts	30-84	Process PID Proportional Gain	32-64	PID Bandwidth	33-40	Behaviour atEnd Limit Switch
16-96	Maintenance Word	18-90	Process PID Error	30-9*	Wifi LCP	32-65	Velocity Feedforward	33-41	Negative Software End Limit
17-7*	Position Feedback	18-91	Process PID Output	30-90	SSID	32-66	Acceleration Feed-Forward	33-42	Positive Software End Limit
17-1*	Inc. Enc. Interface	18-92	Process PID Clamped Output	30-91	Channel	32-67	Max. Tolerated Position Error	33-43	Negative Software End Limit Active
17-10	Signal Type	18-93	Process PID Gain Scaled Output	30-92	Password	32-68	Reverse Behavior for Slave	33-44	Positive Software End Limit Active
17-11	Resolution (PPR)	22-**	Appl. Functions	30-93	Security type	32-69	Sampling Time for PID Control	33-45	Time in Target Window
17-2*	Abs. Enc. Interface	22-0*	Miscellaneous	30-94	IP address	32-70	Scan Time for Profile Generator	33-46	Target Window LimitValue
17-20	Protocol Selection	23-**	Time-based Functions	30-95	Submask	32-71	Size of the Control Window (Activation)	33-47	Size of Target Window
17-21	Resolution (Positions/Rev)	30-96	Port						



33-5*	I/O Configuration	34-30	PCD 10 Read from MCO	36-4*	Output X49/7	42-44	Deceleration Rate
33-50	Terminal X57/1 Digital Input	34-40	Inputs & Outputs	36-40	Terminal X49/7 Analogue Output	42-45	Delta V
33-51	Terminal X57/2 Digital Input	34-41	Digital Outputs	36-42	Terminal X49/7 Min. Scale	42-46	Zero Speed
33-52	Terminal X57/3 Digital Input	34-42	Digital Outputs	36-43	Terminal X49/7 Max. Scale	42-47	Ramp Time
33-53	Terminal X57/4 Digital Input	34-5*	Process Data	36-44	Terminal X49/7 Bus Control	42-48	S-ramp Ratio at Decel. Start
33-54	Terminal X57/5 Digital Input	34-50	Actual Position	36-45	Terminal X49/7 Timeout Preset	42-49	S-ramp Ratio at Decel. End
33-55	Terminal X57/6 Digital Input	34-51	Commanded Position	36-5*	Output X49/9	42-5*	SLS
33-56	Terminal X57/7 Digital Input	34-52	Actual Master Position	36-50	Terminal X49/9 Analogue Output	42-50	Cut Off Speed
33-57	Terminal X57/8 Digital Input	34-53	Slave Index Position	36-52	Terminal X49/9 Min. Scale	42-51	Speed Limit
33-58	Terminal X57/9 Digital Input	34-54	Master Index Position	36-53	Terminal X49/9 Max. Scale	42-52	Fail Safe Reaction
33-59	Terminal X57/10 Digital Input	34-55	Curve Position	36-54	Terminal X49/9 Bus Control	42-53	Start Ramp
33-60	Terminal X59/1 and X59/2 Mode	34-56	Track Error	36-55	Terminal X49/9 Timeout Preset	42-54	Ramp Down Time
33-61	Terminal X59/1 Digital Input	34-57	Synchronizing Error	36-6*	Output X49/11	42-6*	Safe Fieldbus
33-62	Terminal X59/2 Digital Input	34-58	Actual Velocity	36-60	Terminal X49/11 Analogue Output	42-60	Telegram Selection
33-63	Terminal X59/1 Digital Output	34-59	Actual Master Velocity	36-62	Terminal X49/11 Min. Scale	42-61	Destination Address
33-64	Terminal X59/2 Digital Output	34-60	Synchronizing Status	36-63	Terminal X49/11 Max. Scale	42-8*	Status
33-65	Terminal X59/3 Digital Output	34-61	Axis Status	36-64	Terminal X49/11 Bus Control	42-80	Safe Option Status
33-66	Terminal X59/4 Digital Output	34-62	Program Status	36-65	Terminal X49/11 Timeout Preset	42-81	Safe Option Status 2
33-67	Terminal X59/5 Digital Output	34-64	MCO 302 Status	40-3*	Special Settings	42-82	Safe Control Word
33-68	Terminal X59/6 Digital Output	34-65	MCO 302 Control	40-4*	Extend. Fault Log	42-83	Safe Status Word
33-69	Terminal X59/7 Digital Output	34-66	SPI Error Counter	40-41	Fault Log: Ext. Reference	42-85	Active Safe Func.
33-70	Terminal X59/8 Digital Output	34-7*	Diagnosis readouts	40-42	Fault Log: Frequency	42-86	Safe Option Info
33-8*	Global Parameters	34-70	MCO Alarm Word 1	40-43	Fault Log: Current	42-87	Time Until Manual Test
33-80	Activated Program Number	34-71	MCO Alarm Word 2	40-44	Fault Log: Voltage	42-88	Supported Customization File Version
33-81	Power-up State	35-0*	Sensor Input Option	40-45	Fault Log: DC Link Voltage	42-89	Customization File Version
33-82	Drive Status Monitoring	35-0*	Temp. Input Mode	40-46	Fault Log: Control Word	42-90	Special
33-83	Behaviour afterEsc.	35-00	Term. X48/4 Temperature Unit	40-46	Fault Log: Status Word	42-90	Restart Safe Option
33-84	Behaviour afterEsc.	35-01	Term. X48/4 Input Type	40-5*	Advanced Control Settings	43-3*	Unit Readouts
33-85	MCO Supplied by External 24VDC	35-02	Term. X48/7 Temperature Unit	40-50	Flux Sensorless Model Shift	43-0*	Component Status
33-86	Terminal at alarm	35-03	Term. X48/7 Input Type	40-51	Flux Sensorless Corr. Gain	43-00	Component Temp.
33-87	Terminal state at alarm	35-04	Term. X48/10 Temperature Unit	42-1*	Safety Functions	43-01	Auxiliary Temp.
33-88	Status word at alarm	35-05	Term. X48/10 Input Type	42-1*	Speed Monitoring	43-02	Component SW ID
33-9*	MCO Port Settings	35-06	Temperature Sensor Alarm Function	42-10	Measured Speed Source	43-1*	Power Card Status
33-90	X62 MCO CAN node ID	35-1*	Temp. Input X48/4	42-11	Encoder Resolution	43-10	HS Temp. ph.U
33-91	X62 MCO CAN baud rate	35-14	Term. X48/4 Filter Time Constant	42-12	Encoder Direction	43-11	HS Temp. ph.V
33-94	X60 MCO RS485 serial termination	35-15	Term. X48/4 Temp. Monitor	42-13	Gear Ratio	43-12	HS Temp. ph.W
33-95	X60 MCO RS485 serial baud rate	35-16	Term. X48/4 Low Temp. Limit	42-14	Feedback Type	43-13	PC Fan A Speed
34-3*	MCO Data Readouts	35-17	Term. X48/4 High Temp. Limit	42-15	Feedback Filter	43-14	PC Fan B Speed
34-0*	PCD Write Par.	35-2*	Temp. Input X48/7	42-17	Tolerance Error	43-15	PC Fan C Speed
34-01	PCD 1 Write to MCO	35-24	Term. X48/7 Filter Time Constant	42-18	Zero Speed Error	43-2*	Fan Pow/Card Status
34-02	PCD 2 Write to MCO	35-25	Term. X48/7 Temp. Monitor	42-19	Zero Speed Limit	43-20	FPC Fan A Speed
34-03	PCD 3 Write to MCO	35-26	Term. X48/7 Low Temp. Limit	42-2*	Safe Input	43-21	FPC Fan B Speed
34-04	PCD 4 Write to MCO	35-27	Term. X48/7 High Temp. Limit	42-20	Safe Function	43-22	FPC Fan C Speed
34-05	PCD 5 Write to MCO	35-3*	Temp. Input X48/10	42-21	Type	43-23	FPC Fan D Speed
34-06	PCD 6 Write to MCO	35-34	Term. X48/10 Filter Time Constant	42-22	Discrepancy Time	43-24	FPC Fan E Speed
34-07	PCD 7 Write to MCO	35-35	Term. X48/10 Temp. Monitor	42-23	Stable Signal Time	43-25	FPC Fan F Speed
34-08	PCD 8 Write to MCO	35-36	Term. X48/10 Low Temp. Limit	42-24	Restart Behaviour	600-*	PROFIsafe
34-09	PCD 9 Write to MCO	35-37	Term. X48/10 High Temp. Limit	42-30	General	600-22	PROFIdrive/Safe Tel. Selected
34-10	PCD 10 Write to MCO	35-4*	Analog Input X48/2	42-31	Reset Source	600-44	Fault Message Counter
34-2*	PCD Read Par.	35-42	Term. X48/2 Low Current	42-33	Parameter Set Name	600-47	Fault Number
34-21	PCD 1 Read from MCO	35-43	Term. X48/2 High Current	42-33	S-Param Set Value	601-*	PROFIdrive 2
34-22	PCD 2 Read from MCO	35-44	Term. X48/2 Low Ref./Feedb. Value	42-36	Level 1 Password	601-22	PROFIdrive Safety Channel Tel. No.
34-23	PCD 3 Read from MCO	35-45	Term. X48/2 High Ref./Feedb. Value	42-37	Level 1 Password Buffer		
34-24	PCD 4 Read from MCO	36-*	Programmable I/O Option	42-4*	SS1		
34-25	PCD 5 Read from MCO	36-0*	I/O Mode	42-40	Type		
34-26	PCD 6 Read from MCO	36-03	Terminal X49/7 Mode	42-41	Ramp Profile		
34-27	PCD 7 Read from MCO	36-04	Terminal X49/9 Mode	42-42	Delay Time		
34-28	PCD 8 Read from MCO	36-05	Terminal X49/11 Mode	42-43	Delta T		
34-29	PCD 9 Read from MCO						

9.2.2 Software 48.2X

1-06	Clockwise Direction	1-72	Start Function	3-0*	Reference Limits	3-72	Ramp 4 Ramp Down Time
1-07	Motor Angle Offset Adjust	1-73	Flying Start	3-00	Reference Range	3-75	Ramp 4 S-ramp Ratio at Accel. Start
1-1*	Special Settings	1-74	Start Speed [RPM]	3-01	Reference/Feedback Unit	3-76	Ramp 4 S-ramp Ratio at Accel. End
1-10	Motor Construction	1-75	Start Speed [Hz]	3-02	Minimum Reference	3-77	Ramp 4 S-ramp Ratio at Decel. Start
1-11	Motor Model	1-76	Start Current	3-03	Maximum Reference	3-78	Ramp 4 S-ramp Ratio at Decel. End
1-18	Min. Current at No Load	1-8*	Stop Adjustments	3-04	Reference Function	3-8*	Other Ramps
1-2*	Motor Data	1-80	Function at Stop	3-05	On Reference Window	3-80	Jog/Homing Ramp Time
1-20	Motor Power [kW]	1-81	Min Speed for Function at Stop [RPM]	3-06	Minimum Position	3-81	Quick Stop Ramp Time
1-21	Motor Power [HP]	1-82	Min Speed for Function at Stop [Hz]	3-07	Maximum Position	3-82	Quick Stop Ramp Type
1-22	Motor Voltage	1-9*	Motor Temperature	3-08	On Target Window	3-83	Quick Stop S-ramp Ratio at Decel. Start
1-23	Motor Frequency	1-90	Motor Thermal Protection	3-1*	References	3-84	Quick Stop S-ramp Ratio at Decel. End
1-24	Motor Current	1-91	Motor External Fan	3-10	Preset Reference	3-89	Ramp Lowpass Filter Time
1-25	Motor Nominal Speed	1-93	Thermistor Resource	3-11	Jog Speed [Hz]	3-9*	Digital Pot.Meter
1-26	Motor Cont. Rated Torque	1-94	ATEX ETR curlim. speed reduction	3-12	Catch up/slow Down Value	3-90	Step Size
1-29	Automatic Motor Adaptation (AMA)	1-95	KTY Sensor Type	3-13	Reference Site	3-91	Ramp Time
1-3*	Adv. Motor Data	1-96	KTY Thermistor Resource	3-14	Preset Relative Reference	3-92	Power Restore
1-30	Stator Resistance (Rs)	1-97	KTY Threshold level	3-15	Reference Resource 1	3-93	Maximum Limit
1-31	Rotor Resistance (Rr)	1-98	ATEX ETR interpol. points freq.	3-16	Reference Resource 2	3-94	Minimum Limit
1-33	Stator Leakage Reactance (X1)	2-*	Brakes	3-17	Reference Resource 3	3-95	Ramp Delay
1-34	Rotor Leakage Reactance (X2)	2-0*	DC-Brake	3-18	Relative Scaling Reference Resource	4-*	Limits / Warnings
1-35	Main Reactance (Xh)	2-00	DC Hold Current	3-2*	References II	4-1*	Motor Limits
1-36	Iron Loss Resistance (Rfe)	2-01	DC Brake Current	3-20	Preset Target	4-10	Motor Speed Direction
1-37	d-axis Inductance (Ld)	2-02	DC Braking Time	3-21	Touch Target	4-11	Motor Speed Low Limit [RPM]
1-38	q-axis Inductance (Lq)	2-03	DC Brake Cut In Speed [RPM]	3-22	Master Scale Numerator	4-12	Motor Speed Low Limit [Hz]
1-39	Motor Poles	2-04	DC Brake Cut In Speed [Hz]	3-23	Master Scale Denominator	4-13	Motor Speed High Limit [RPM]
1-40	Back EMF at 1000 RPM	2-05	Maximum Reference	3-24	Master Lowpass Filter Time	4-14	Motor Speed High Limit [Hz]
1-41	Motor Angle Offset	2-06	Parking Current	3-25	Master Bus Resolution	4-16	Torque Limit Motor Mode
1-42	d-axis Inductance Sat. (LdSat)	2-07	Parking Time	3-26	Master Offset	4-17	Torque Limit Generator Mode
1-44	d-axis Inductance Sat. (LqSat)	2-1*	Brake Energy Funct.	3-27	Virtual Master Max Ref	4-18	Current Limit
1-45	q-axis Inductance Sat. (LqSat)	2-10	Brake Function	3-28	Master Offset Speed Ref	4-19	Max Output Frequency
1-46	Position Detection Gain	2-11	Brake Resistor (ohm)	3-4*	Ramp 1	4-2*	Limit Factors
1-47	Torque Calibration	2-12	Brake Power Limit (kW)	3-40	Ramp 1 Type	4-20	Torque Limit Factor Source
1-48	d-axis Inductance Sat. Point	2-13	Brake Power Monitoring	3-41	Ramp 1 Ramp Up Time	4-21	Speed Limit Factor Source
1-49	q-axis Inductance Sat. Point	2-15	Brake Check	3-42	Ramp 1 Ramp Down Time	4-23	Brake Check Limit Factor Source
1-5*	Load Indep. Setting	2-16	AC brake Max. Current	3-45	Ramp 1 S-ramp Ratio at Accel. Start	4-24	Brake Check Limit Factor
1-50	Motor Magnetisation at Zero Speed [RPM]	2-17	Over-voltage Control	3-46	Ramp 1 S-ramp Ratio at Decel. End	4-3*	Motor Speed Mon.
1-51	Min Speed Normal Magnetising [Hz]	2-18	Brake Check Condition	3-47	Ramp 1 S-ramp Ratio at Decel. Start	4-30	Motor Feedback Loss Function
1-52	Min Speed Normal Magnetising [Hz]	2-19	Over-voltage Gain	3-48	Ramp 1 S-ramp Ratio at Decel. End	4-31	Motor Feedback Speed Error
1-53	Model Shift Frequency	2-2*	Mechanical Brake	3-5*	Ramp 2	4-32	Motor Feedback Loss Timeout
1-54	Voltage reduction in fieldweakening	2-20	Release Brake Current	3-50	Ramp 2 Type	4-34	Tracking Error Function
1-55	U/f Characteristic - U	2-21	Activate Brake Speed [RPM]	3-51	Ramp 2 Ramp Up Time	4-35	Tracking Error
1-56	U/f Characteristic - F	2-22	Activate Brake Speed [Hz]	3-52	Ramp 2 Ramp Down Time	4-36	Tracking Error Timeout
1-57	Torque Estimation Time Constant	2-23	Activate Brake Delay	3-55	Ramp 2 S-ramp Ratio at Accel. Start	4-37	Tracking Error Ramping
1-58	Flying Start Test Pulses Current	2-24	Stop Delay	3-56	Ramp 2 S-ramp Ratio at Accel. End	4-38	Tracking Error Ramping Timeout
1-59	Flying Start Test Pulses Frequency	2-25	Brake Release Time	3-57	Ramp 2 S-ramp Ratio at Decel. Start	4-39	Tracking Error After Ramping Timeout
1-6*	Load Depen. Setting	2-26	Torque Ref	3-58	Ramp 3	4-4*	Speed Monitor
1-60	Low Speed Load Compensation	2-27	Torque Ramp Up Time	3-60	Ramp 3 Type	4-43	Motor Speed Monitor Function
1-61	High Speed Load Compensation	2-28	Gain Boost Factor	3-61	Ramp 3 Ramp up Time	4-44	Motor Speed Monitor Max
1-62	Slip Compensation	2-3*	Adv. Mech Brake	3-62	Ramp 3 Ramp down Time	4-45	Motor Speed Monitor Timeout
1-63	Slip Compensation Time Constant	2-30	Position P Start Proportional Gain	3-65	Ramp 3 S-ramp Ratio at Accel. Start	4-5*	Adj. Warnings
1-64	Resonance Damping	2-31	Speed PID Start Proportional Gain	3-66	Ramp 3 S-ramp Ratio at Accel. End	4-50	Warning Current Low
1-65	Resonance Damping Time Constant	2-32	Speed PID Start Integral Time	3-67	Ramp 3 S-ramp Ratio at Decel. Start	4-51	Warning Current High
1-66	Min. Current at Low Speed	2-33	Speed PID Start Lowpass Filter Time	3-68	Ramp 3 S-ramp Ratio at Decel. End	4-52	Warning Speed Low
1-67	Load Type	2-34	Gain	3-7*	Ramp 4	4-53	Warning Speed High
1-68	Motor Inertia	3-*	Reference / Ramps	3-70	Ramp 4 Type	4-54	Warning Reference Low
1-69	System Inertia	3-71	Ramp 4 Ramp up Time	3-71	Ramp 4 Ramp up Time	4-55	Warning Reference High
1-70	PM Start Mode						
1-71	Start Delay						



4-56	Warning Feedback Low	5-60	Terminal 27 Pulse Output Variable	6-6*	Analog Output 2	7-94	Position PI Feedback Scale	9-07	Actual Value
4-57	Warning Feedback High	5-62	Pulse Output Max Freq #27	6-60	Terminal X30/8 Output	7-95	Numerator	9-15	PCD Write Configuration
4-58	Missing Motor Phase Function	5-63	Terminal 29 Pulse Output Variable	6-61	Terminal X30/8 Min. Scale	7-95	Position PI Feedback Scale	9-16	PCD Read Configuration
4-6*	Speed Bypass	5-65	Pulse Output Max Freq #29	6-62	Terminal X30/8 Max. Scale	7-97	Denominator	9-18	Node Address
4-60	Bypass Speed From [RPM]	5-66	Terminal X30/6 Pulse Output Variable	6-63	Terminal X30/8 Bus Control	7-97	Position PI Maximum Speed Above Master	9-19	Drive Unit System Number
4-61	Bypass Speed To [Hz]	5-68	Pulse Output Max Freq #X30/6	6-64	Terminal X30/8 Output Timeout	7-98	Position PI Feed Forward Factor	9-22	Telegram Selection
4-62	Bypass Speed To [RPM]	5-7*	24V Encoder Input	6-7*	Preset	7-99	Position PI Minimum Ramp Time	9-23	Parameters for Signals
4-63	Bypass Speed To [Hz]	5-70	Term 32/33 Pulses Per Revolution	6-7*	Analog Output 3	8-0*	Comm. and Options	9-27	Parameter Edit
4-7*	Position Monitor	5-71	Term 32/33 Encoder Direction	6-70	Terminal X45/1 Output	8-0*	General Settings	9-28	Process Control
4-70	Position Error Function	5-72	Term 32/33 Encoder DType	6-71	Terminal X45/1 Min. Scale	8-0*	Control Site	9-44	Fault Message Counter
4-71	Maximum Position Error	5-8*	I/O Options	6-72	Terminal X45/1 Max. Scale	8-01	Control Word Source	9-45	Fault Code
4-72	Position Error Timeout	5-80	AHF Cap Reconnect Delay	6-73	Terminal X45/1 Bus Control	8-02	Control Word Timeout Time	9-47	Fault Number
4-73	Position Limit Function	5-9*	Bus Controlled	6-74	Terminal X45/1 Output Timeout	8-03	Control Word Timeout Function	9-52	Fault Situation Counter
4-74	Start Fwd/Rcv Function	5-90	Digital & Relay Bus Control	6-8*	Analog Output 4	8-04	End-of-Timeout Function	9-53	Profibus Warning Word
4-75	Touch Timeout	5-94	Pulse Out #27 Bus Control	6-80	Terminal X45/3 Output	8-05	Reset Control Word Timeout	9-64	Actual Baud Rate
5-3*	Digital In/Out	5-95	Pulse Out #29 Bus Control	6-81	Terminal X45/3 Min. Scale	8-06	Diagnosis Trigger	9-64	Device Identification
5-0*	Digital I/O mode	5-96	Pulse Out #29 Timeout Preset	6-82	Terminal X45/3 Max. Scale	8-07	Readout Filtering	9-65	Profile Number
5-00	Digital I/O Mode	5-97	Pulse Out #X30/6 Bus Control	6-83	Terminal X45/3 Bus Control	8-1*	Ctrl. Word Settings	9-67	Control Word 1
5-01	Terminal 27 Mode	5-98	Pulse Out #X30/6 Timeout Preset	6-84	Terminal X45/3 Output Timeout	8-10	Configurable Status Word STW	9-68	Edit Set-up
5-02	Terminal 29 Mode	6-6**	Analog In/Out	7-7*	Controllers	8-13	Configurable Control Word CTW	9-70	Profibus Save Data Values
5-1*	Digital Inputs	6-0*	Analog I/O Mode	7-0*	Speed PID Ctrl.	8-14	Configurable Control Word CTW	9-72	ProfibusDriveReset
5-10	Terminal 18 Digital Input	6-00	Live Zero Timeout Time	7-00	Speed PID Feedback Source	8-17	Configurable Alarm and Warningword	9-75	DO Identification
5-11	Terminal 19 Digital Input	6-01	Live Zero Timeout Function	7-01	Speed PID Droop	8-19	Product Code	9-80	Defined Parameters (1)
5-12	Terminal 27 Digital Input	6-1*	Analog Input 1	7-02	Speed PID Proportional Gain	8-3*	FC Port Settings	9-81	Defined Parameters (2)
5-13	Terminal 29 Digital Input	6-10	Terminal 53 Low Voltage	7-03	Speed PID Integral Time	8-30	Protocol	9-82	Defined Parameters (3)
5-14	Terminal 32 Digital Input	6-11	Terminal 53 High Voltage	7-04	Speed PID Differentiation Time	8-31	Address	9-83	Defined Parameters (4)
5-15	Terminal 33 Digital Input	6-12	Terminal 53 Low Current	7-05	Speed PID Diff. Gain Limit	8-32	FC Port Baud Rate	9-84	Defined Parameters (5)
5-16	Terminal X30/2 Digital Input	6-13	Terminal 53 High Current	7-06	Speed PID Lowpass Filter Time	8-33	Parity / Stop Bits	9-85	Defined Parameters (6)
5-17	Terminal X30/3 Digital Input	6-14	Terminal 53 Low Ref./Feedb. Value	7-07	Speed PID Feedback Gear Ratio	8-34	Estimated cycle time	9-90	Changed Parameters (1)
5-18	Terminal X30/4 Digital Input	6-15	Terminal 53 High Ref./Feedb. Value	7-08	Speed PID Accel. Feed Forward Factor	8-35	Minimum Response Delay	9-91	Changed Parameters (2)
5-19	Terminal 37 Safe Stop	6-16	Terminal 53 Filter Time Constant	7-09	Speed PID Error Correction w/ Ramp	8-36	Max Response Delay	9-92	Changed Parameters (3)
5-20	Terminal X46/1 Digital Input	6-2*	Analog Input 2	7-1*	Torque PI Ctrl.	8-37	Max Inter-Char Delay	9-93	Changed Parameters (4)
5-21	Terminal X46/3 Digital Input	6-20	Terminal 54 Low Voltage	7-10	Torque PI Feedback Source	8-4*	FC MC protocol set	9-94	Changed Parameters (5)
5-22	Terminal X46/5 Digital Input	6-21	Terminal 54 High Voltage	7-11	Torque PI Proportional Gain	8-40	Telegram Selection	10-0*	Profibus Revision Counter
5-23	Terminal X46/7 Digital Input	6-22	Terminal 54 Low Current	7-12	Torque PI Integral Gain	8-41	Parameters for Signals	10-0*	CAN Fieldbus Common Settings
5-24	Terminal X46/9 Digital Input	6-23	Terminal 54 High Current	7-13	Torque PI Integration Time	8-42	PCD Write Configuration	10-00	CAN Protocol
5-25	Terminal X46/11 Digital Input	6-24	Terminal 54 Low Ref./Feedb. Value	7-16	Torque PI Lowpass Filter Time	8-43	PCD Read Configuration	10-01	Baud Rate Select
5-26	Terminal X46/13 Digital Input	6-25	Terminal 54 High Ref./Feedb. Value	7-18	Torque PI Feed Forward Factor	8-5*	Digital/Bus	10-02	MAC ID
5-3*	Digital Outputs	6-26	Terminal 54 Filter Time Constant	7-19	Current Controller Rise Time	8-50	Coasting Select	10-05	Readout Transmit Error Counter
5-30	Terminal 27 Digital Output	6-3*	Analog Input 3	7-2*	Process Ctrl. Feedb	8-51	Quick Stop Select	10-06	Readout Receive Error Counter
5-31	Terminal 29 Digital Output	6-30	Terminal X30/11 Low Voltage	7-20	Process CL Feedback 1 Resource	8-52	DC Brake Select	10-07	Readout Bus Off Counter
5-32	Term X30/6 Digi Out (MCB 101)	6-31	Term. X30/11 High Voltage	7-22	Process CL Feedback 2 Resource	8-53	Start Select	10-1*	DeviceNet
5-33	Term X30/7 Digi Out (MCB 101)	6-32	Term. X30/11 Low Ref./Feedb. Value	7-3*	Process PID Ctrl.	8-54	Reversing Select	10-10	Process Data Type Selection
5-4*	Relays	6-33	Term. X30/11 High Ref./Feedb. Value	7-30	Process PID Normal/ Inverse Control	8-55	Set-up Select	10-11	Process Data Config Write
5-40	Function Relay	6-34	Term. X30/11 Filter Time Constant	7-31	Process PID Anti Windup	8-56	Preset Reference Select	10-12	Process Data Config Read
5-41	On Delay, Relay	6-36	Term. X30/12 Low Voltage	7-32	Process PID Start Speed	8-57	Profidrive OFF2 Select	10-13	Warning Parameter
5-42	Off Delay, Relay	6-37	Term. X30/12 High Voltage	7-33	Process PID Proportional Gain	8-58	Profidrive OFF3 Select	10-14	Net Reference
5-5*	Pulse Input	6-40	Terminal X30/12 Low Voltage	7-34	Process PID Integral Time	8-8*	FC Port Diagnostics	10-15	Net Control
5-50	Term. 29 Low Frequency	6-41	Terminal X30/12 High Voltage	7-35	Process PID Differentiation Time	8-80	Bus Message Count	10-2*	COS Filters
5-51	Term. 29 High Frequency	6-44	Term. X30/12 Low Ref./Feedb. Value	7-36	Process PID Diff. Gain Limit	8-81	Bus Error Count	10-20	COS Filter 1
5-52	Term. 29 Low Ref./Feedb. Value	6-45	Term. X30/12 High Ref./Feedb. Value	7-37	Process PID Filter Time Constant	8-82	Slave Messages Rcvd	10-21	COS Filter 2
5-53	Term. 29 High Ref./Feedb. Value	6-46	Term. X30/12 Filter Time Constant	7-38	Process PID Feed Forward Factor	8-83	Slave Error Count	10-22	COS Filter 3
5-54	Pulse Filter Time Constant #29	6-5*	Analog Output 1	7-39	On Reference Bandwidth	8-9*	Bus Jog	10-23	COS Filter 4
5-55	Term. 33 Low Frequency	6-50	Terminal 42 Output	7-9*	Position PI Ctrl.	8-90	Bus Jog 1 Speed	10-3*	Parameter Access
5-56	Term. 33 High Frequency	6-51	Terminal 42 Output Min Scale	7-90	Position PI Feedback Source	8-91	Bus Jog 2 Speed	10-30	Array Index
5-57	Term. 33 Low Ref./Feedb. Value	6-52	Terminal 42 Output Max Scale	7-91	Position PI Droop	9-9*	PROFIdrive	10-31	Store Data Values
5-58	Term. 33 High Ref./Feedb. Value	6-53	Terminal 42 Output Bus Ctrl	7-92	Position PI Proportional Gain	9-00	Setpoint	10-32	Devicenet Revision
5-59	Pulse Filter Time Constant #33	6-54	Terminal 42 Output Timeout Preset	7-93	Position PI Integral Time				
5-6*	Pulse Output	6-55	Analog Output Filter						

10-33	Store Always	12-80	FTP Server	14-26	Trip Delay at Inverter Fault	15-41	Power Section	16-21	Torque [%] High Res.
10-34	DeviceNet Product Code	12-81	HTTP Server	14-28	Production Settings	15-42	Voltage	16-22	Torque [%]
10-39	DeviceNet F Parameters	12-82	SMTP Service	14-29	Service Code	15-43	Software Version	16-23	Motor Shaft Power [kW]
10-5*	CANopen	12-89	Transparent Socket Channel Port	14-3*	Current Limit Ctrl.	15-44	Ordered Typecode String	16-24	Calibrated Stator Resistance
10-50	Process Data Config Write.	12-9*	Advanced Ethernet Services	14-30	Current Lim Ctrl, Proportional Gain	15-45	Actual Typecode String	16-25	Torque [Nm] High
10-51	Process Data Config Read.	12-90	Cable Diagnostic	14-31	Current Lim Ctrl, Integration Time	15-46	Frequency Converter Ordering No	16-3*	Drive Status
12-2**	Ethernet	12-91	Auto Cross Over	14-32	Current Lim Ctrl, Filter Time	15-47	Power Card Ordering No	16-30	DC Link Voltage
12-0*	IP Settings	12-92	IGMP Snooping	14-35	Stall Protection	15-48	LCP Id No	16-32	Brake Energy /s
12-00	IP Address Assignment	12-93	Cable Error Length	14-36	Fieldweakening Function	15-49	SW ID Control Card	16-33	Brake Energy Average
12-01	IP Address	12-94	Broadcast Storm Protection	14-3*	Energy Optimising	15-50	SW ID Power Card	16-34	Heatsink Temp.
12-02	Subnet Mask	12-95	Broadcast Storm Filter	14-40	VT Level	15-51	Frequency Converter Serial Number	16-35	Inverter Thermal
12-03	Default Gateway	12-96	Port Config	14-41	AEO Minimum Magnetisation	15-53	Power Card Serial Number	16-36	Inv. Nom. Current
12-04	DHCP Server	12-98	Interface Counters	14-42	Minimum AEO Frequency	15-58	Smart Setup Filename	16-37	Inv. Max. Current
12-05	Lease Expires	12-99	Media Counters	14-43	Motor Cosphi	15-59	CSV Filename	16-38	SL Controller State
12-06	Name Servers	13-3**	Smart Logic	14-5*	Environment	15-6*	Option Ident	16-39	Control Card Temp.
12-07	Domain Name	13-0*	SLC Settings	14-50	RFI Filter	15-60	Option Mounted	16-40	Logging Buffer Full
12-08	Host Name	13-00	SL Controller Mode	14-51	DC Link Compensation	15-61	Option SW Version	16-41	LCP Bottom Statusline
12-09	Physical Address	13-01	Start Event	14-52	Fan Control	15-62	Option Ordering No	16-44	Speed Error [RPM]
12-1*	Ethernet Link Parameters	13-02	Stop Event	14-53	Fan Monitor	15-63	Option Serial No	16-45	Motor Phase U Current
12-10	Link Status	13-03	Reset SLC	14-55	Output Filter	15-70	Option in Slot A	16-46	Motor Phase V Current
12-11	Link Duration	13-1*	Comparators	14-56	Capacitance Output Filter	15-71	Slot A Option SW Version	16-47	Motor Phase W Current
12-12	Auto Negotiation	13-10	Comparator Operand	14-57	Inductance Output Filter	15-72	Option in Slot B	16-48	Speed Ref. After Ramp [RPM]
12-13	Link Speed	13-11	Comparator Operator	14-59	Actual Number of inverter Units	15-73	Slot B Option SW Version	16-49	Current Fault Source
12-14	Link Duplex	13-12	Comparator Value	14-7*	Compatibility	15-74	Option in Slot C0/E0	16-5*	Ref. & Feedb.
12-2*	Process Data	13-1*	RS Flip Flops	14-72	Legacy Alarm Word	15-75	Slot C0/E0 Option SW Version	16-50	External Reference
12-20	Control Instance	13-15	RS-FF Operand S	14-73	Legacy Warning Word	15-76	Option in Slot C1/E1	16-51	Pulse Reference
12-21	Process Data Config Write	13-16	RS-FF Operand R	14-74	Leg. Ext. Status Word	15-77	Slot C1/E1 Option SW Version	16-52	Feedback[Unit]
12-22	Process Data Config Read	13-2*	Timers	14-8*	Options	15-8*	Operating Data II	16-53	Digi Pot Reference
12-23	Process Data Config Write Size	13-20	SL Controller Timer	14-80	Option Supplied by External 24VDC	15-80	Fan Running Hours	16-57	Feedback [RPM]
12-24	Process Data Config Read Size	13-4*	Logic Rules	14-88	Option Data Storage	15-81	Preset Fan Running Hours	16-6*	Inputs & Outputs
12-27	Master Address	13-40	Logic Rule Boolean 1	14-89	Option Detection	15-82	Configuration Change Counter	16-60	Digital Input
12-28	Store Data Values	13-41	Logic Rule Operator 1	14-9*	Fault Settings	15-9*	Parameter Info	16-61	Terminal 53 Switch Setting
12-29	Store Always	13-42	Logic Rule Boolean 2	14-90	Fault Level	15-92	Defined Parameters	16-62	Terminal 54 Switch Setting
12-3*	EtherNet/IP	13-43	Logic Rule Operator 2	15-0*	Operating Data	15-98	Drive Identification	16-64	Analog Input 54
12-30	Warning Parameter	13-44	Logic Rule Boolean 3	15-00	Operating hours	15-99	Parameter/Metadata	16-65	Analog Output 42 [mA]
12-31	Net Reference	13-5*	States	15-01	Running Hours	16-0*	General Status	16-66	Digital Output [bin]
12-32	Net Control	13-52	SL Controller Action	15-02	kWh Counter	16-00	Control Word	16-67	Freq. Input #29 [Hz]
12-33	CIP Revision	14-0*	Special Functions	15-03	Power Up's	16-01	Reference [Unit]	16-68	Freq. Input #33 [Hz]
12-34	CIP Product Code	14-00	Inverter Switching	15-04	Over Volt's	16-02	Reference %	16-69	Pulse Output #27 [Hz]
12-35	EDS Parameter	14-01	Switching Pattern	15-05	Over Volt's	16-03	Status Word	16-70	Pulse Output #29 [Hz]
12-37	COS Inhibit Timer	14-03	Overmodulation	15-06	Reset kWh Counter	16-05	Main Actual Value [%]	16-71	Relay Output [bin]
12-38	COS Filter	14-04	PWM Random	15-1*	Data Log Settings	16-06	Actual Position	16-72	Counter A
12-40	Status Parameter	14-06	Dead Time Compensation	15-10	Logging Source	16-07	Target Position	16-73	Counter B
12-41	Slave Message Count	14-1*	Mains On/Off	15-11	Logging Interval	16-08	Position Error	16-75	Analog In X30/11
12-42	Slave Exception Message Count	14-10	Mains Failure	15-12	Trigger Event	16-09	Custom Readout	16-76	Analog In X30/12
12-5*	EtherCAT	14-11	Mains Voltage at Mains Fault	15-13	Logging Mode	16-10	Motor Status	16-77	Analog Out X30/8 [mA]
12-50	Configured Station Alias	14-12	Function at Mains Imbalance	15-14	Samples Before Trigger	16-11	Power [kW]	16-78	Analog Out X45/1 [mA]
12-51	Configured Station Address	14-15	Kin. Backup Time Out	15-2*	Historic Log	16-11	Power [hp]	16-79	Analog Out X45/3 [mA]
12-59	EtherCAT Status	14-16	Kin. Backup Trip Recovery Level	15-20	Historic Log: Event	16-12	Motor Voltage	16-8*	Fieldbus & FC Port
12-60	Node ID	14-2*	Trip Reset	15-21	Historic Log: Value	16-13	Frequency	16-80	Fieldbus REF 1
12-62	SDO Timeout	14-20	Reset Mode	15-22	Historic Log: Time	16-14	Motor current	16-82	Fieldbus REF 2
12-63	Basic Ethernet Timeout	14-21	Automatic Restart Time	15-30	Fault Log	16-15	Frequency [%]	16-84	Comm. Option STW
12-66	Threshold	14-22	Operation Mode	15-31	Fault Log: Error Code	16-16	Torque [Nm]	16-85	FC Port CTW 1
12-67	Threshold Counters	14-23	Typecode Setting	15-32	Fault Log: Value	16-17	Speed [RPM]	16-86	FC Port REF 1
12-68	Cumulative Counters	14-24	Trip Delay at Current Limit	15-4*	Drive Identification	16-18	Motor Thermal	16-87	Bus Readout Alarm/Warning
12-69	Ethernet PowerLink Status	14-25	Trip Delay at Torque Limit	15-40	FC Type	16-19	KTY sensor temperature	16-89	Configurable Alarm/Warning Word
12-8*	Other Ethernet Services								



16-9*	Diagnosis Readouts	18-6*	Inputs & Outputs 2	42-14	Feedback Type
16-90	Alarm Word	18-60	Digital Input 2	42-15	Feedback Filter
16-91	Alarm Word 2	30-**	Special Features	42-17	Tolerance Error
16-92	Warning Word	30-2*	Adv. Start Adjust	42-18	Zero Speed Timer
16-93	Warning Word 2	30-20	High Starting Torque Time [s]	42-19	Zero Speed Limit
16-94	Ext. Status Word	30-21	High Starting Torque Current [%]	42-2*	Safe Input
17-**	Position Feedback	30-22	Locked Rotor Protection	42-20	Safe Function
17-1*	Inc. Enc. Interface	30-23	Locked Rotor Detection Time [s]	42-21	Type
17-10	Signal Type	30-24	Locked Rotor Detection Speed Error [%]	42-22	Discrepancy Time
17-11	Resolution (PPR)	30-8*	Compatibility (I)	42-23	Stable Signal Time
17-2*	Abs. Enc. Interface	30-80	d-axis Inductance (Ld)	42-24	Restart Behaviour
17-20	Protocol Selection	30-81	Brake Resistor (ohm)	42-3*	General
17-21	Resolution (Positions/Rev)	30-83	Speed PID Proportional Gain	42-30	External Failure Reaction
17-22	Multiturn Revolutions	30-84	Process PID Proportional Gain	42-31	Reset Source
17-24	SSI Data Length	31-**	Bypass Option	42-33	Parameter Set Name
17-25	Clock Rate	31-00	Bypass Mode	42-35	S-CRC Value
17-26	SSI Data Format	31-01	Bypass Start Time Delay	42-36	Level 1 Password
17-34	HIPERFACE Baudrate	31-02	Bypass Trip Time Delay	42-4*	SSI
17-5*	Resolver Interface	31-03	Test Mode Activation	42-40	Type
17-50	Poles	31-10	Bypass Status Word	42-41	Ramp Profile
17-51	Input Voltage	31-11	Bypass Running Hours	42-42	Delay Time
17-52	Input Frequency	31-19	Remote Bypass Activation	42-43	Delta T
17-53	Transformation Ratio	35-**	Sensor Input Option	42-44	Deceleration Rate
17-56	Encoder Sim. Resolution	35-0*	Temp. Input Mode	42-45	Delta V
17-59	Resolver Interface	35-00	Term. X48/4 Temperature Unit	42-46	Zero Speed
17-6*	Monitoring and App.	35-01	Term. X48/4 Input Type	42-47	Ramp Time
17-60	Feedback Direction	35-02	Term. X48/7 Temperature Unit	42-48	S-ramp Ratio at Decel. Start
17-61	Feedback Signal Monitoring	35-03	Term. X48/7 Input Type	42-49	S-ramp Ratio at Decel. End
17-7*	Position Scaling	35-04	Term. X48/10 Temperature Unit	42-5*	SLS
17-70	Position Unit	35-05	Term. X48/10 Input Type	42-50	Cut Off Speed
17-71	Position Unit Scale	35-06	Temperature Sensor Alarm Function	42-51	Speed Limit
17-72	Position Unit Numerator	35-1*	Temp. Input X48/4	42-52	Fail Safe Reaction
17-73	Position Unit Denominator	35-14	Term. X48/4 Filter Time Constant	42-53	Start Ramp
17-74	Position Offset	35-15	Term. X48/4 Temp. Monitor	42-54	Ramp Down Time
17-75	Position Recovery at Power-up	35-16	Term. X48/4 Low Temp. Limit	42-6*	Safe Fieldbus
17-76	Position Axis Mode	35-17	Term. X48/4 High Temp. Limit	42-60	Telegram Selection
17-77	Position Feedback Mode	35-2*	Temp. Input X48/7	42-61	Destination Address
17-8*	Position Homing	35-24	Term. X48/7 Filter Time Constant	42-8*	Status
17-80	Homing Function	35-25	Term. X48/7 Temp. Monitor	42-80	Safe Option Status
17-81	Home Sync Function	35-26	Term. X48/7 Low Temp. Limit	42-81	Safe Option Status 2
17-82	Home Position	35-27	Term. X48/7 High Temp. Limit	42-82	Safe Control Word
17-83	Homing Speed	35-3*	Temp. Input X48/10	42-83	Safe Status Word
17-84	Homing Torque Limit	35-34	Term. X48/10 Filter Time Constant	42-85	Active Safe Func.
17-85	Homing Timeout	35-35	Term. X48/10 Temp. Monitor	42-86	Safe Option Info
17-9*	Position Config	35-36	Term. X48/10 Low Temp. Limit	42-88	Supported Customization File Version
17-90	Absolute Position Mode	35-37	Term. X48/10 High Temp. Limit	42-89	Customization File Version
17-91	Relative Position Mode	35-42	Analog Input X48/2	42-9*	Special
17-92	Position Control Selection	35-43	Term. X48/2 Low Current	42-90	Restart Safe Option
17-93	Master Offset Selection	35-44	Term. X48/2 High Current	600-22	PROFIdrive/safe Tel. Selected
17-94	Rotary Absolute Direction	35-45	Term. X48/2 Low Ref./Feedb. Value	600-44	Fault Message Counter
18-3*	Analog Readouts	35-46	Term. X48/2 High Ref./Feedb. Value	600-47	Fault Number
18-36	Analog Input X48/2 [mA]	42-1*	Speed Monitoring	600-52	Fault Situation Counter
18-37	Temp. Input X48/4	42-10	Measured Speed Source	601-22	PROFIdrive Safety Channel Tel. No.
18-38	Temp. Input X48/7	42-11	Encoder Resolution		
18-39	Temp. Input X48/10	42-12	Encoder Direction		
18-5*	Active Alarms/Warnings	42-13	Gear Ratio		
18-55	Active Alarm Numbers				
18-56	Active Warning Numbers				

Index

A

Abbreviation..... 65

AC

 input..... 15

 mains..... 15

Additional resources..... 3

Alarms

 Alarms..... 23

 List of..... 24

AMA

 AMA..... 20

 see also *Automatic motor adaption*

Ambient condition..... 46

Analog

 output..... 48

Analog input..... 24

Analog signal..... 24

Automatic motor adaptation (AMA)

 Warning..... 30

Automatic motor adaption..... 20

Auxiliary equipment..... 17

B

Backplate..... 9

Brake resistor

 Warning..... 27

Burst transient..... 11

C

Cable

 length and cross-section..... 46

 routing..... 17

 specification..... 46

 Motor cable..... 10, 14

Certifications..... 5

Circuit breaker..... 17, 50

Clearance requirements..... 9

Conduct..... 17

Control

 characteristic..... 49

 wiring..... 14, 17

 Wiring..... 10

Control card

 Control card..... 24, 48, 49

 DC Output, 10 V..... 48

 RS485..... 48

 Serial communication..... 48

 USB serial communication..... 49

 Warning..... 31

Convention..... 65

Cooling..... 9

Cooling clearance..... 17

Current

 DC current..... 10

 Input current..... 15

D

DC link..... 24

DC output, 10 V..... 48

Dimension..... 59

Discharge time..... 7

Disconnect switch..... 18

E

Electrical installation..... 0

EMC interference..... 14

EMC-compliant installation..... 10

EN 50598-2..... 46

Energy efficiency..... 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 46

Environment..... 46

Exploded view..... 4

External controller..... 3

F

Fans

 Warning..... 27, 32

Feedback..... 17

Floating delta..... 15

Flux..... 22

Front cover tightening torque..... 59, 61, 63

Fuse..... 10, 17, 28, 50

G

GLCP..... 19

 see also *Graphic local control panel*

Graphic local control panel..... 19

Ground		Motor	
connection.....	17	cable.....	10, 14
wire.....	10	output.....	45
Grounding.....	17	overload protection.....	3
Warning.....	29	power.....	10
Grounded delta.....	15	status.....	3
Grounding.....	14, 15, 18	thermal protection.....	21
		thermistor.....	21
H		wiring.....	14, 17
Heat sink		Output performance (U, V, W).....	45
Warning.....	29, 31	Overheating.....	25
High voltage.....	6, 18	Thermistor.....	21
		Unintended motor rotation.....	7
		Warning.....	25, 28
		Mounting.....	9, 17
I			
IEC 61800-3.....	15	N	
Input		Nameplate.....	8
Analog input.....	47		
Digital input.....	46	O	
disconnect.....	15	Optional equipment.....	14
power.....	10, 14, 15, 17, 23	Output	
power wiring.....	17	Analog output.....	48
signal.....	30	Digital output.....	48
terminal.....	15, 18	power wiring.....	17
Input terminal.....	24	Overcurrent protection.....	10
Installation			
Check list.....	17	P	
environment.....	8	PELV.....	21
Intended use.....	3	Performance.....	49
Interference isolation.....	17	Phase loss.....	24
Items supplied.....	8	Potential equalization.....	11
		Power	
L		Input power.....	18
Leakage current.....	7, 10	connection.....	10
Lifting.....	9	factor.....	17
Load sharing.....	6, 23	rating.....	59
		Power card	
M		Warning.....	31
Mains		Programming.....	24
supply.....	39, 40, 41, 45	Pulse/encoder input.....	47
Maintenance.....	23		
Mechanical brake control.....	15, 22	Q	
Mechanical installation.....	0	Qualified personnel.....	6
		R	
		Reference	
		Reference.....	21
		Relay output.....	49
		Remote command.....	3

Index	Operating Guide
Reset.....	23, 31
RFI filter.....	15
Rotor	
Warning.....	32
RS485	
RS485.....	48
S	
Safe Torque Off	
Safe Torque Off.....	15
Warning.....	31
Safety.....	7
Serial communication	
RS485.....	48
Serial communication.....	48, 49
USB serial communication.....	49
Service.....	23
Shielded cable.....	14, 17
Shock.....	8
Short circuit.....	26
STO.....	15
see also <i>Safe Torque Off</i>	
Storage.....	8
Supply voltage.....	15, 18, 28
Symbol.....	65
System feedback.....	3
System set-up.....	20
T	
Terminal	
Output terminal.....	18
Thermistor	
Warning.....	31
Torque	
Limit.....	25
characteristic.....	45
Trip	
Trip.....	21, 23
lock.....	23
Troubleshooting	
Warnings and alarms.....	24
Type approvals.....	5
U	
Unintended start.....	6, 23
V	
Vibration.....	8
Voltage imbalance.....	24
Voltage level.....	46
W	
Warnings	
List of.....	24
Warnings.....	23
Weight.....	59
Windmilling.....	7
Wire size.....	10, 14
Wiring	
Control wiring.....	14
Motor wiring.....	14
Thermistor control wiring.....	15
schematic.....	13



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