

### 3-Phase Bridge Rectifier + IGBT braking chopper

SKD116/...-L140

#### **Features**

- Compact design
- Two screws mounting
- Heat transfer and isolation through direct copper bonded aluminium oxide ceramic (DCB)
- High surge currents
- Up to 1600V reverse voltage
- IGBT Trench4 inside; max T<sub>i</sub>=175°C
- CAL4F inside, max Tj=175°C
- $I_{CM}/I_{FM} = 3xI_{C,nom}/I_{F,nom}$ Rectifier diode, max Tj=150°C

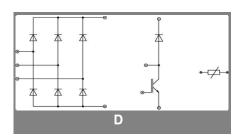
#### Typical Applications\*

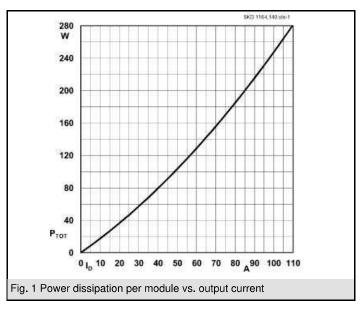
- DC drives
- Controlled filed rectifiers for DC motors
- Controlled battery charger

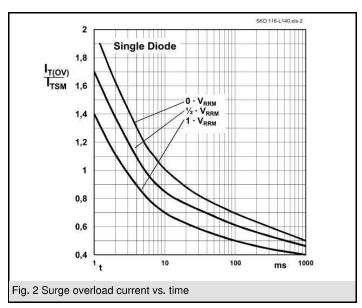
V <sub>RSM</sub>	V <sub>RRM</sub> , V <sub>DRM</sub>	I <sub>D</sub> = 110 A (maximum value for continuous operation)			
V	V	(T <sub>s</sub> = 85 °C)			
1300	1200	SKD 116/12-L140			
1700	1600	SKD116/16-L140			

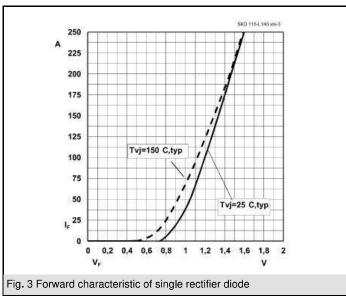
<b>Absolute Maximum Ratings</b> $T_s = 25$ °C, unless otherwise specifie							
Symbol	Conditions	Values	Units				
Bridge - Rectifier							
I <sub>D</sub>	T <sub>s</sub> = 85 °C; inductive load	110	Α				
I <sub>FSM</sub> /I <sub>TSM</sub>	$t_p = 10 \text{ ms}; \sin 180^\circ; T_{jmax}$	1050	Α				
i²t	t <sub>p</sub> = 10 ms; sin 180°; T <sub>jmax</sub>	5500	A²s				
IGBT - Chopper							
V <sub>CES</sub> /V <sub>GES</sub>		1200 / 20	V				
I <sub>C</sub>	$T_s = 25 (70) ^{\circ}C$	150 (120)	Α				
I <sub>CM</sub>	$t_p = 1 \text{ ms}; T_s = 25 (70) ^{\circ}\text{C}$	520	Α				
Freewheeling - CAL Diode							
$V_{RRM}$		1200	V				
I <sub>F</sub>	$T_s = 25 (70) ^{\circ}C$	130 (105)	Α				
I <sub>FM</sub>	$t_p = 1 \text{ ms; } T_s = 25 (70) \text{ °C}$	450	Α				
T <sub>vi</sub>	Diode & IGBT (Thyristor)	- 40 + 175 (-40+ 125)	°C				
T <sub>stg</sub>		- 40 + 125	°C				
T <sub>solder</sub>	terminals, 10 s	260	°C				
V <sub>isol</sub>	a.c. (50) Hz, RMS 1 min. / 1 s	3000 / 3600	V				

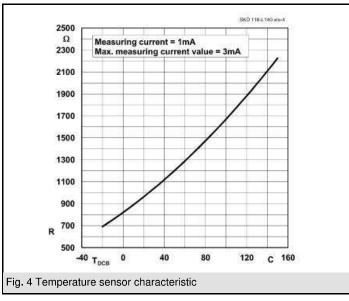
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Characteristics		T <sub>s</sub> = 25 °C,	T <sub>s</sub> = 25 °C, unless otherwise specified			
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	Symbol	Conditions	min.	typ.	max.	Units	
$ \begin{array}{ c c c c }\hline R_{th(j-s)} & per  diode & 1 & K/W \\ \hline \textbf{IGBT - Chopper} \\ V_{CE(sat)} & I_C = 140  \text{A, T}_j = 25  ^{\circ}\text{C;} & 1,85 & 2,1 & V \\ \hline R_{th(j-s)} & per  IGBT & 0,38 & K/W \\ \hline t_{d(on)} /  t_r & valid  for  all  values: & 97 / 185 & ns \\ \hline t_{d(off)} /  t_f & V_{CC} = 600  V;  V_{GE} = 15  V; & 443 / 82 & ns \\ \hline I_C = 140  \text{A; T}_j = 150  ^{\circ}\text{C;} & 443 / 82 & ns \\ \hline I_C = 140  \text{A; T}_j = 150  ^{\circ}\text{C;} & 63,3 & mJ \\ \hline \textbf{CAL - Diode - Freewheeling} \\ \hline V_{T(TO)} /  r_t & T_j = 150  ^{\circ}\text{C} & 0,9 / 7,8 & 1,1 / 8,6 & V/m\Omega \\ \hline R_{RRM} & valid  for  all  values: & 30 & A \\ \hline Q_{rr} & I_F = 140  \text{A; } V_R = -600  \text{V;} & 9 & \mu \text{C} \\ \hline \textbf{Temperature Sensor} \\ \hline R_{TS} & T = 25  (100)  ^{\circ}\text{C;} & 1000  (1670) & \Omega \\ \hline \end{array} $	-						
$ \begin{array}{ c c c c } \hline \textbf{IGBT - Chopper} \\ V_{CE(sat)} &   _{L} = 140 \text{ A, } T_{j} = 25 \text{ °C}; \\ V_{GE} = 15 \text{ V} \\ \hline \\ R_{th(j-s)} & \text{per IGBT} \\ \hline \\ t_{d(on)} / t_{r} & \text{valid for all values:} \\ t_{d(off)} / t_{f} &   _{V_{CC}} = 600 \text{ V; } V_{GE} = 15 \text{ V; } \\ I_{C} = 140 \text{ A; } T_{j} = 150 \text{ °C;} \\ \hline \\ E_{on} + E_{off} &   _{T_{j}} = 150 \text{ °C; } R_{G} = 4 \Omega; \\ &   _{inductive load} \\ \hline \hline \\ \hline $	$V_{TO}$ / $r_{t}$	T <sub>j</sub> = 125 °C		0,8 / 7		V / mΩ	
$ \begin{array}{ c c c c } \hline \textbf{IGBT - Chopper} \\ V_{CE(sat)} &   _{L} = 140 \text{ A, } T_{j} = 25 \text{ °C}; \\ V_{GE} = 15 \text{ V} \\ \hline \\ R_{th(j-s)} & \text{per IGBT} \\ \hline \\ t_{d(on)} / t_{r} & \text{valid for all values:} \\ t_{d(off)} / t_{f} &   _{V_{CC}} = 600 \text{ V; } V_{GE} = 15 \text{ V; } \\ I_{C} = 140 \text{ A; } T_{j} = 150 \text{ °C;} \\ \hline \\ E_{on} + E_{off} &   _{T_{j}} = 150 \text{ °C; } R_{G} = 4 \Omega; \\ &   _{inductive load} \\ \hline \hline \\ \hline $	R <sub>th(j-s)</sub>	per diode			1	K/W	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		opper					
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	V <sub>CE(sat)</sub>	I <sub>C</sub> = 140 A, T <sub>j</sub> = 25 °C; V <sub>GE</sub> = 15 V		1,85	2,1	V	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	R <sub>th(j-s)</sub>	per IGBT		0,38		K/W	
$ \begin{array}{llllllllllllllllllllllllllllllllllll$		valid for all values:		97 / 185		ns	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		$V_{CC}$ = 600 V; $V_{GE}$ = 15 V; $I_{C}$ = 140 A; $T_{i}$ = 150 °C;		443 / 82		ns	
	$E_{on}+E_{off}$	$T_{i} = 150 ^{\circ}\text{C};  R_{G} = 4 \Omega;$		63,3		mJ	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$		inductive load					
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$	CAL - Diode - Freewheeling						
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$V_{T(TO)} / r_t$	T <sub>j</sub> = 150 °C		0,9 / 7,8	1,1 / 8,6	V / mΩ	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	R <sub>th(j-s)</sub>	per diode		0,56		K/W	
$E_{off}$ $V_{GE} = 0 \text{ V}; T_j = 150 \text{ °C}$ 7,92       mJ         Temperature Sensor         R <sub>TS</sub> T = 25 (100) °C;       1000 (1670)       Ω	I <sub>RRM</sub>			30		Α	
Temperature Sensor $R_{TS}$ $T = 25 (100) ^{\circ}C;$ $1000 (1670)$ $\Omega$	Q <sub>rr</sub>	$I_F = 140 \text{ A}; V_R = -600 \text{ V};$ $dI_F/dt = -1700 \text{ A}/\mu\text{s}$		9		μC	
$R_{TS}$ $T = 25 (100) ^{\circ}C;$	E <sub>off</sub>	$V_{GE} = 0 \text{ V}; T_j = 150 ^{\circ}\text{C}$		7,92		mJ	
19	Temperature Sensor						
Mechanical data	-	1		1000 (1670)		Ω	
1 1	Mechanical data						
M <sub>S</sub> mounting Torque 2,55 3,45 Nm	M <sub>S</sub>	mounting Torque	2,55		3,45	Nm	

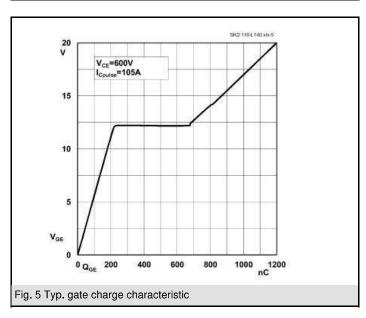


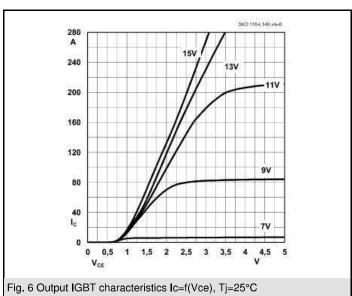


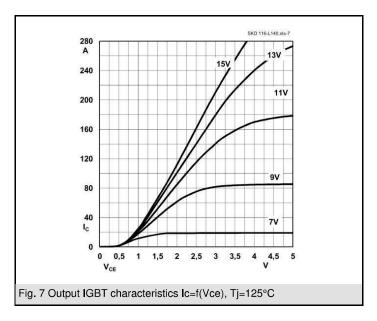


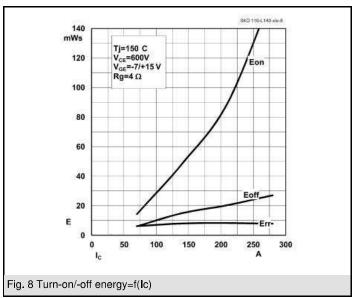


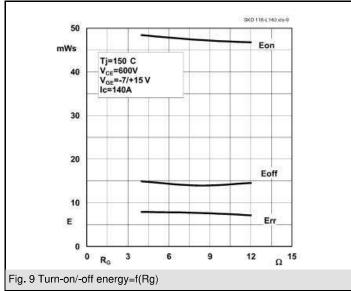


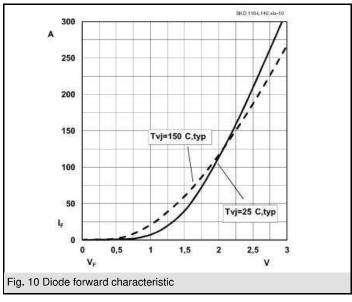




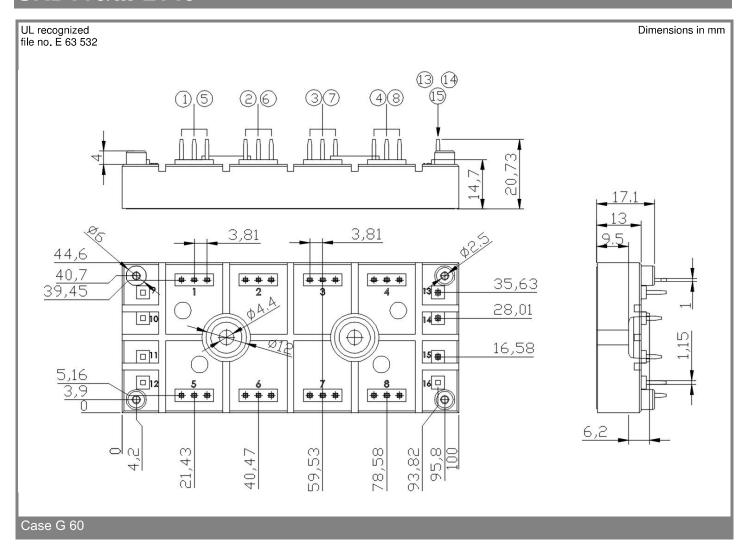


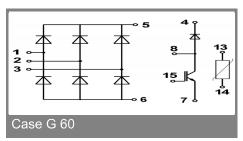






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This is an electrostatic discharge sensitive device (ESDS), international standard IEC 60747-1, chapter IX.

#### \*IMPORTANT INFORMATION AND WARNINGS

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