Technical Information
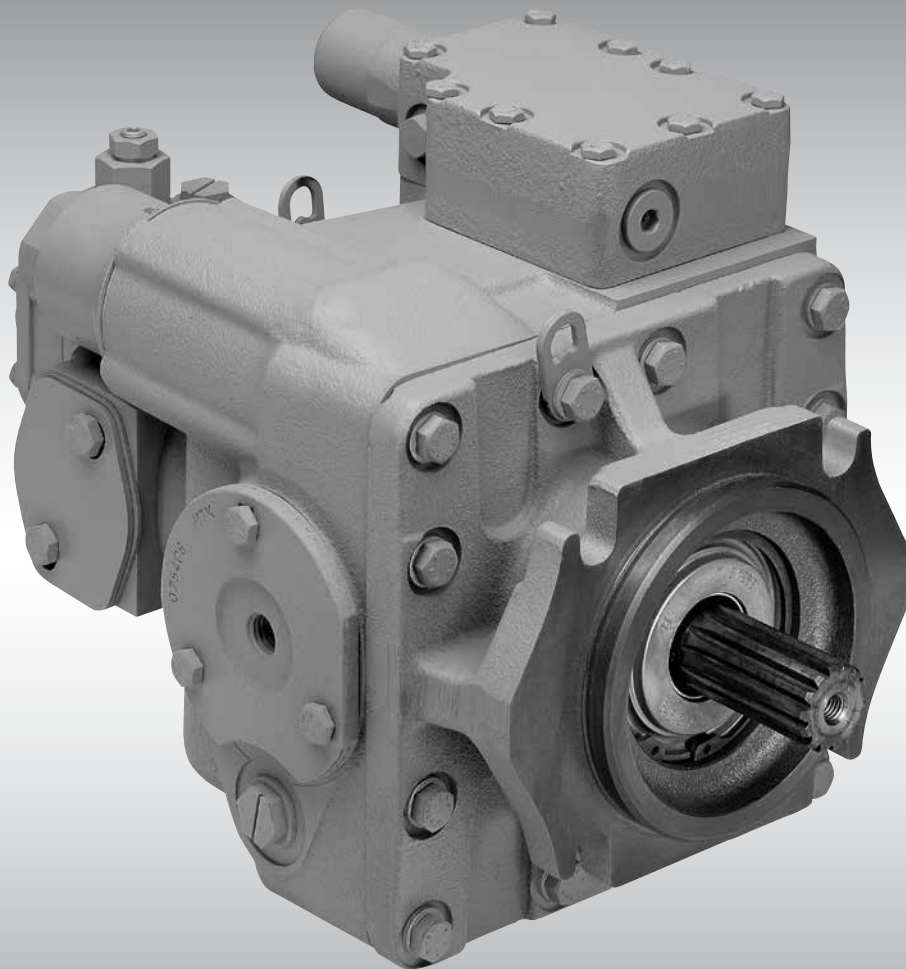
Axial Piston Pumps
Series 20

General Description

Introduction

Danfoss a world leader in hydraulic power systems has developed a family of axial piston pumps.

Description

Danfoss axial piston variable displacement pumps are of swash plate design with variable flow capability suitable for hydrostatic transmissions with closed loop circuit.
Tilting the swash plate to the opposite side of the neutral or zero displacement position reverses flow direction.

Danfoss axial piston variable displacement pumps are well engineered and easy to handle.
The full-length shaft with a highly efficient tapered roller bearing arrangement offers a high loading capacity for external radical forces.
The hydro-mechanical servo displacement control maintains the selected swash plate position and hence pumps displacement.
Upon release of the control handle, the swash plate automatically returns to zero position and the flow reduces to zero.
High case pressures can be achieved without leakage even at the lowest temperatures by using suitable shaft seals.
The servo valve arrangement offers the facility to incorporate function regulators and remote control systems.
Axial piston units are designed for easy servicing. Complete dismantling and reassembly can be carried out with standard hand tools, and all components or sub-assemblies are replaceable.
Axial piston variable displacement pumps of the Danfoss pattern are made by licensed producers worldwide, providing consistent service and fully interchangeable parts.

Typical markets

- Industrial
- Mining
- Transit Mixer
- Utility Vehicles

Front cover illustrations: F005 209

Contents

General Description

Axial Piston Variable Displacement Pump

Sectional View

Swash plate   Control handle   Servo valve (control valve)

Charge pump

Design 1

Input shaft

Charge check valve

Shaft seal

Cylinder block assembly   Servo cylinder

P005 121E

Design 2

General Description

Pump and Motor Circuit Description

HEAT EXCHANGER BYPASS VALVE
RESERVOIR
CONTROL HANDLE
VACUUM GAUGE
HEAT EXCHANGER
REVERSIBLE VARIABLE DISPLACEMENT PUMP
SERVO CONTROL CYLINDER
PUMP SWASHPLATE
SERVO PRESSURE RELIEF VALVES
PURGE RELIEF VALVE
FIXED DISPLACEMENT MOTOR
CHARGE PRESSURE RELIEF VALVE
INPUT SHAFT
LOOP FLUSHING VALVE
OUTPUT SHAFT
SERVO CONTROL CYLINDER
MOTOR SWASHPLATE

| WORKING LOOP (HIGH PRESSURE) | WORKING LOOP (LOW PRESSURE) | CONTROL FLUID | SUCTION LINE | CASE DRAIN FLUID |

P000 027E

Above figure shows schematically the function of a hydrostatic transmission using an axial piston variable displacement pump and a fixed displacement motor.

Pump Circuit Schematic

Designation:
1 = Variable displacement pump
2 = Charge pump
3 = Servo control valve
4 = Charge check valve
5 = Charge relief valve
6 = Filter
7 = Heat exchanger

Ports:
A, B = Main pressure ports (working loop)
S = Suction port - charge pump
L1 , L2 = Drain ports
M = Gauge port - charge pressure

P000 012

Technical Specification

Technical Parameters

Design
Axial piston pump of swash plate design, with variable displacement.

Type of mounting
SAE four bolt flanges.

Pipe connections
Main pressure ports: SAE split flange
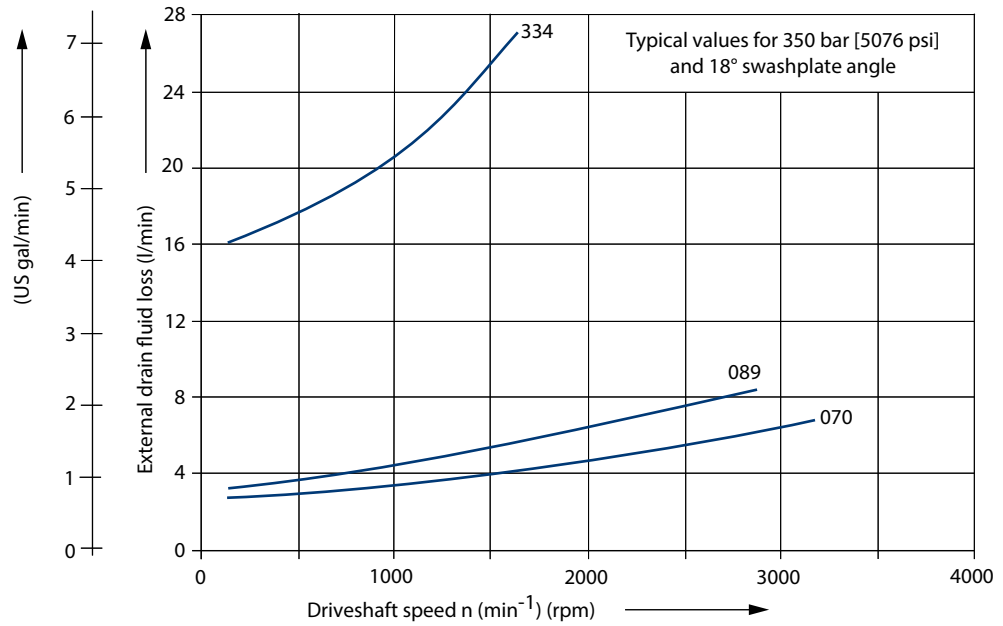Remaining ports: SAE O-ring boss

Direction of rotation
Clockwise or counterclockwise (viewing from the input shaft).

Installation position
Optional; pump housing must be always filled with hydraulic fluid.

External drain fluid loss

P005 105E

Technical Specification

Hydraulic Parameters

System pressure range, input p_1
Variable displacement pump:
Charge pressure nominal: 13 bar [189 psi] above case pressure
Charge pressure minimum: 8 bar [116 psi], intermittent only

Charge pump input pressure:
Min. allowable pressure, continuous   =   0.75 bar [10.9 psi] absolute
Min. allowable pressure, intermittent   =   0.50 bar [7.3 psi] absolute (for cold start)

Charge pump output pressure:
Max. operating pressure = 35 bar [508 psi] above case pressure

System pressure range, output p_2
Pressure on port A or B: Max. operating pressure $\Delta p = 420$ bar [6092 psi]
                                        Max. high pressure setting $\Delta p = 460$ bar[1] [6672 psi]

[1]only with POR-valve

Case pressure
Max. rated pressure   =   2.5 bar [36.3 psi]
Intermittent   =   5.0 bar [72.5 psi]

Hydraulic fluids
Refer to Danfoss publications *Hydraulic Fluids and Lubricants,* **520L0463** and *Experience with Biodegradable Hydraulic Fluids,* **520L0465**.

Temperature range

ϑ_{min} = - 40 °C [- 40 °F]

ϑ_{max} =   95 °C [203 °F]

Viscosity range

ν_{min} = 7 mm^2/s [49 SUS*]

ν_{max} = 1000 mm^2/s [4630 SUS*] (intermittent cold start)
Recommended viscosity range: 12 - 60 mm^2/s [66 - 280 SUS*]

*SUS (Saybolt Universal Second)

Filtration
Required cleanliness level: ISO 4406 - 1999 Code 22/18/13 or better. Refer to Danfoss publication *Hydraulic Fluids and Lubricants,* **520L0463** and *Design Guideline for Hydraulic Fluid Cleanliness,* **520L0467**.

Shaft load
The pump will accept radial and axial loads on its shaft, the maximum capacity being determined by direction and point of application of the load. Please contact your Danfoss representative.

Technical Specification

Hydraulic Parameters (continued)

Technical Data

Parameter		Units	Frame size		
			070	**089**	**334**
Max. displacement		cm³ [in³]	69.8 [4.26]	89.0 [5.43]	333.7 [20.36]
Charge pump displacement	options	cm³ [in³]	18.03 [1.10]		65.50 [4.00]
			12.30 [0.75]		–
Minimum speed		min⁻¹ (rpm)	500		
Rated speed 1		min⁻¹ (rpm)	3200	2900	1900
Maximum swash plate angle		degree	±18		
Mass moment of inertia of rotating group (without charge pump)		kg m² · 10⁻³ [lbf ft² · 10⁻³]	12.34 [292.8]	17.77 [421.7]	161.40 [3830.0]
Weight		kg [lb]	63 [139]	78 [172]	270 [595]

¹ for higher speeds contact your Sauer–Danfoss representative.

Determination of Nominal Pump Sizes

Use these formulae to determine the nominal pump size for a specific application:

Based on SI units

Based on US units

Output flow:

$$Q = \frac{V_g \cdot n \cdot \eta_v}{1000} \quad \text{l/min}$$

$$Q = \frac{V_g \cdot n \cdot \eta_v}{231} \quad \text{[US gal/min]}$$

Input torque:

$$M = \frac{V_g \cdot \Delta p}{20 \cdot \pi \cdot \eta_m} \quad \text{N·m}$$

$$M = \frac{V_g \cdot \Delta p}{2 \cdot \pi \cdot \eta_m} \quad \text{[lbf·in]}$$

Input power:

$$P = \frac{M \cdot n}{9550} = \frac{Q \cdot \Delta p}{600 \cdot \eta_t} \quad \text{kW}$$

$$P = \frac{M \cdot n}{63.025} = \frac{Q \cdot \Delta p}{1714 \cdot \eta_t} \quad \text{[hp]}$$

Variables: SI units [US units]

V_g = Displacement per rev.   cm³/rev [in³/rev]
p_{HD} = Outlet pressure   bar [psi]
p_{ND} = Inlet pressure   bar [psi]
$\Delta p = p_{HD} - p_{ND}$ bar [psi]
n = Speed   min⁻¹ (rpm)
η_v = Volumetric efficiency
η_m = Mechanical (torque) efficiency
η_t = Overall efficiency ($\eta_v \cdot \eta_m$)

Technical Specification

Servo Displacement Control (linear response)

Regulated by the control handle on the servo valve, the swash plate can be infinitely varied in both directions with the help of the servo system. The pump displacement resulting from any control handle position can be established using the figures on this page.
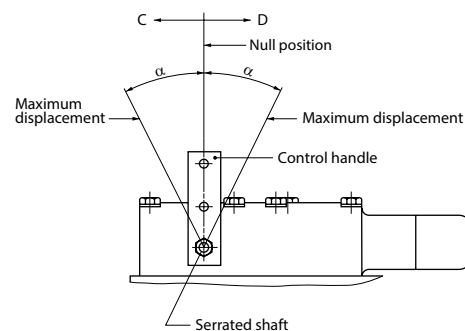
The angle of the control handle for stroke initiation and for the final position of the stroke can vary from unit to unit within the range of the tolerance band.

The inter-relation of flow direction, rotation of the pump and the control handle movement is shown below.
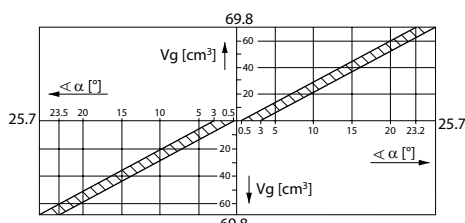
Pump flow direction

Flow direction changes with the direction of rotation and the control handle movement (see *besides*).

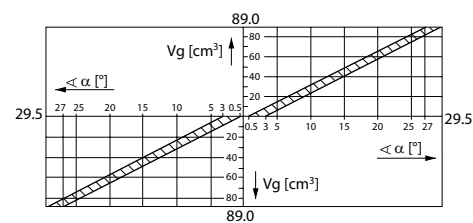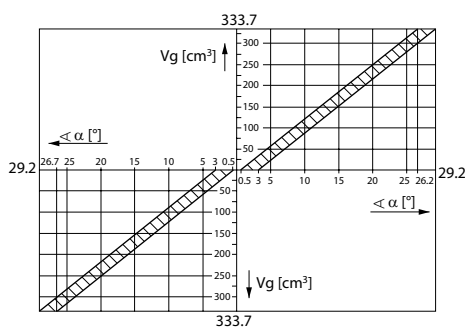| Pump rotation	Movement of control handle in direction	Pressure port OUT	Pressure port IN
CCW (Left)	C	B	A
	D	A	B
CW (Right)	C	A	B
	D	B	A

P000 013E

SPV2/070

P000 016

SPV2/089

P000 017

SPV2/334

P000 021

Technical Specification

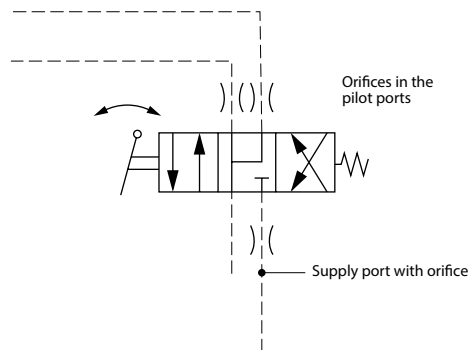**Servo Displacement Control (linear response) (continued)**

Reversing time

Time for the directional change of the flow from Q_{max}, across zero to Q_{max}, depending on the size of the control orifice fitted in the supply port to the servo valve (see *below*).

The values given assume movement of the control handle directly from one end position to the other.

Adjustment time of handle:	< minimum reserving time
Operating pressure:	Δp_2 = 210 bar [3046 psi]
Speed:	n = 1450 min^{-1} (rpm)
System temperature:	50 °C [122 °F]
Viscosity:	35 mm^2/s [164 SUS]

Frame size	Minimum reversing time (s) without orifice	Maximum reversing time (s) with orifice Ø 0.66 in supply port
070	1.0	9.3
089	1.1	9.0
334	5.6	43.8

Schematic diagram of servo valve with alternative orifice positions

Orifices in the pilot ports
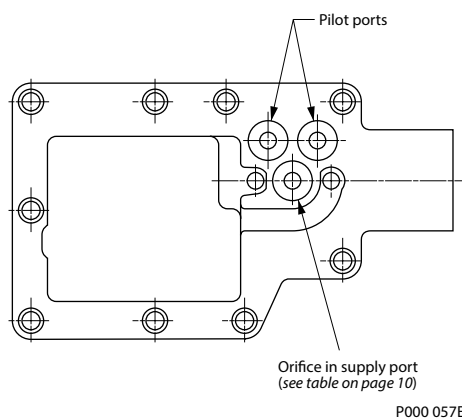
Supply port with orifice

P000 056E

Technical Specification

Servo Displacement Control (linear response) (continued)

Reset time

Time for reducing the flow from either flow direction from Q_{max} to 0 releasing the control handle. Assuming no mechanical blockage of the control handle's free return and assuming no orifices in the pilot ports:

Operating pressure: Δp_2 = 210 bar [3046 psi]
System temperature: 50 °C [122 ° F]
Viscosity: 35 mm²/s [164 SUS]

Changing reversing and reset time

Servo valve counter bored recesses for orifice insert

Pilot ports

Orifice in supply port
(*see table on page 10*)

P000 057E

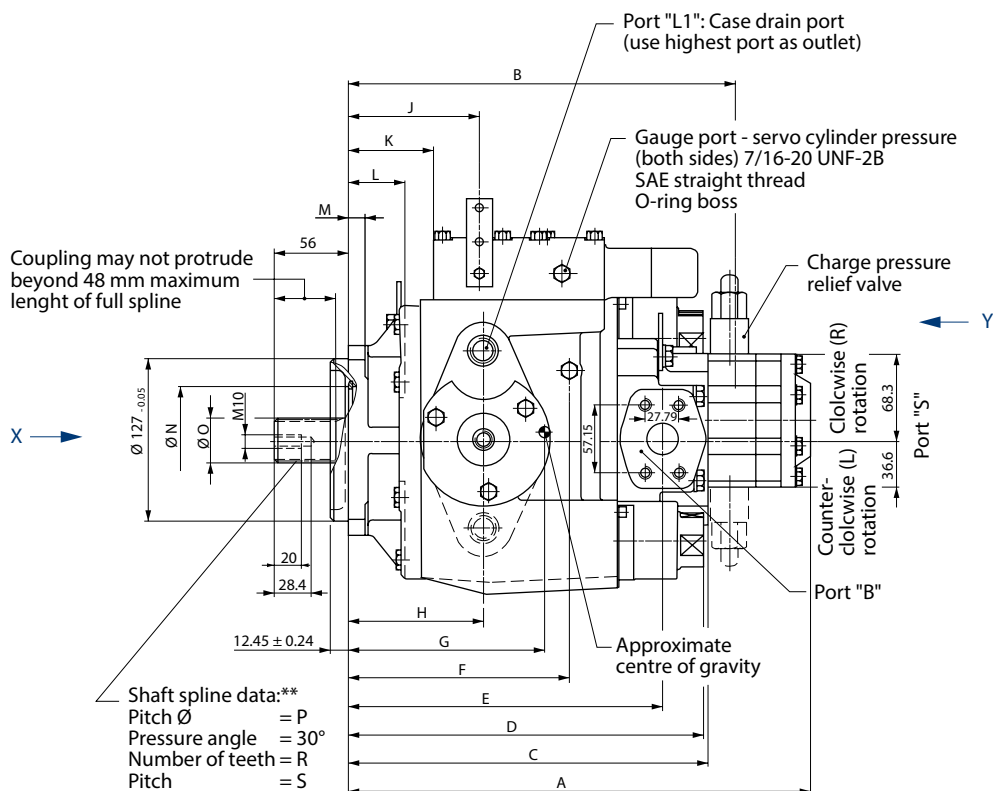| Frame size	Minimum reset time (s)
070	3.0
089	
334	5.4

Inserting one orifice in each of the pilot ports can extend the reversing time. The reset time will also be extended.

Inserting an orifice in one of the pilot ports only can extend the reversing time in one flow direction. The reset time will be extended only for this flow direction.

Dimensions
– Frame Size 070 and 089 cm³

Configuration PS,
displacement control VML 1

P005 106E

* Minimum and maximum angle α, (see section *Servo displacement control*).
** Shaft spline data: spline shaft with involute spline, according to SAE handbook, 1963, class 1, fillet root side fit.

Dimensions - mm [in]

Frame size	B	C	D	E	F	G	H	J	K	L	M	Ø N
070	315 [12.402]	294 [11.575]	305 [12.008]	259 [10.197]	188 [7.402]	146 [5.748]	112 [4.409]	120 [4.724]	84 [3.307]	48 [1.890]	16 [0.630]	84 [3.307]
089	328 [12.913]	307 [12.087]	312 12.283]	271 [10.669]	195 [7.677]	140 [5.512]	118 [4.646]	129 [5.079]	91 [3.583]	49 [1.929]	17.5 [0.689]	98 [3.858]

Frame size	A[1]		Shaft spline				Bore Ø for shaft coupling
	Charge pump		Ø O	Ø P	R	S	
	12 cm³	**18** cm³					
070	372 [14.646]	381 [15.000]	34.50 $_{-0.17}$ [1.358 $_{-0.0067}$]	33.338 [1.313]	21 [0.827]	16/32	31.75 $^{+0.062}$ [1.250 $^{+0.0024}$]
089	358 [14.094]	394 [15.512]	37.68 $_{-0.17}$ [1.483 $_{-0.0067}$]	36.513 [1.438]	23 [0.906]	16/32	34.95 $^{+0.062}$ [1.376 $^{+0.0024}$]

[1] Short version available on request. Please contact your local Danfoss representative.
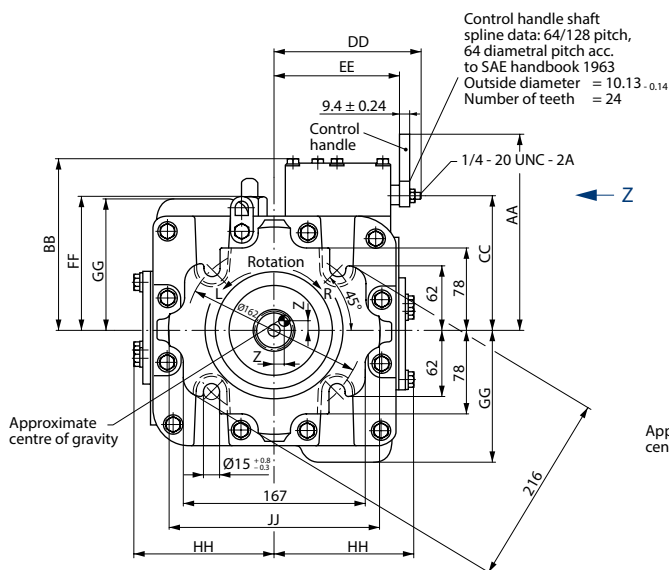
Dimensions - mm [in]

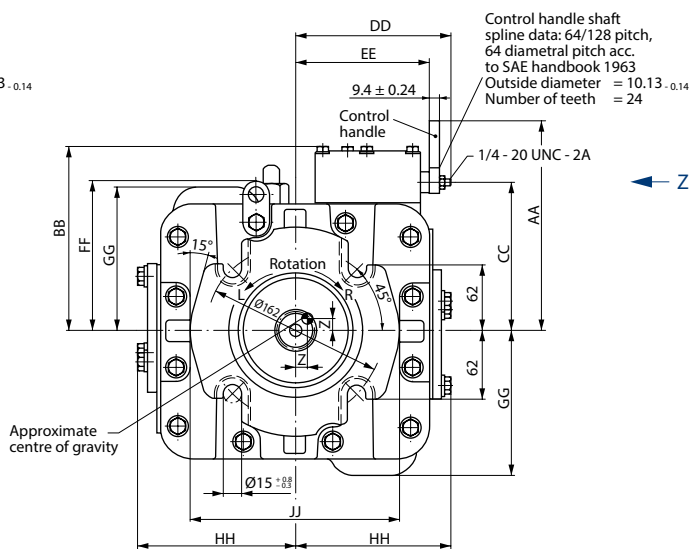| Frame size	T	U	V	W	X	Y	Z
070	71.4 [2.811]	112.7 [4.437]	105 [4.134]	108 [4.252]	60.5 [2.382]	85.8 [3.378]	9.5 [0.374]
089	77.7 [3.059]	128.7 [5.067]	115 [4.528]	119 [4.685]	65 [2.559]	95.2 [3.748]	12.7 [0.500]

**Dimensions
– Frame Size 070 and 089 cm³**

**Configuration PS,
displacement control VML 1
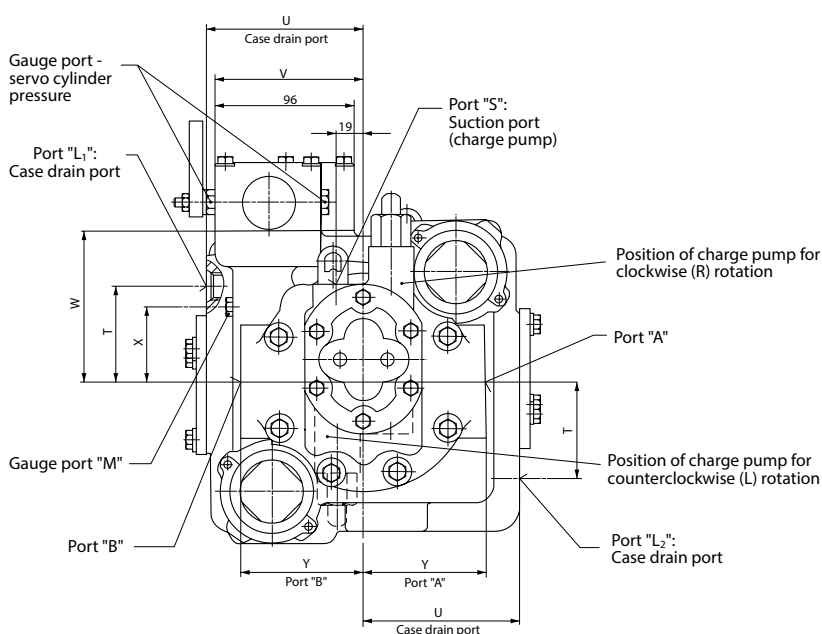(continued)**

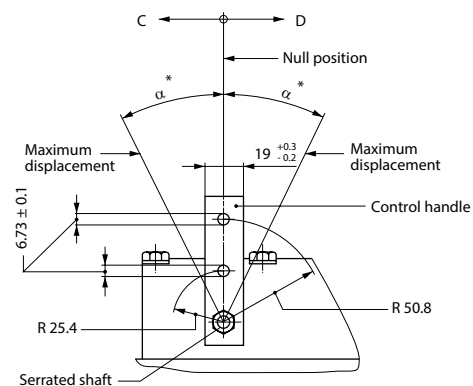View X (for SPV 2/070 only)   View X (for SPV 2/089 only)

P005 108E

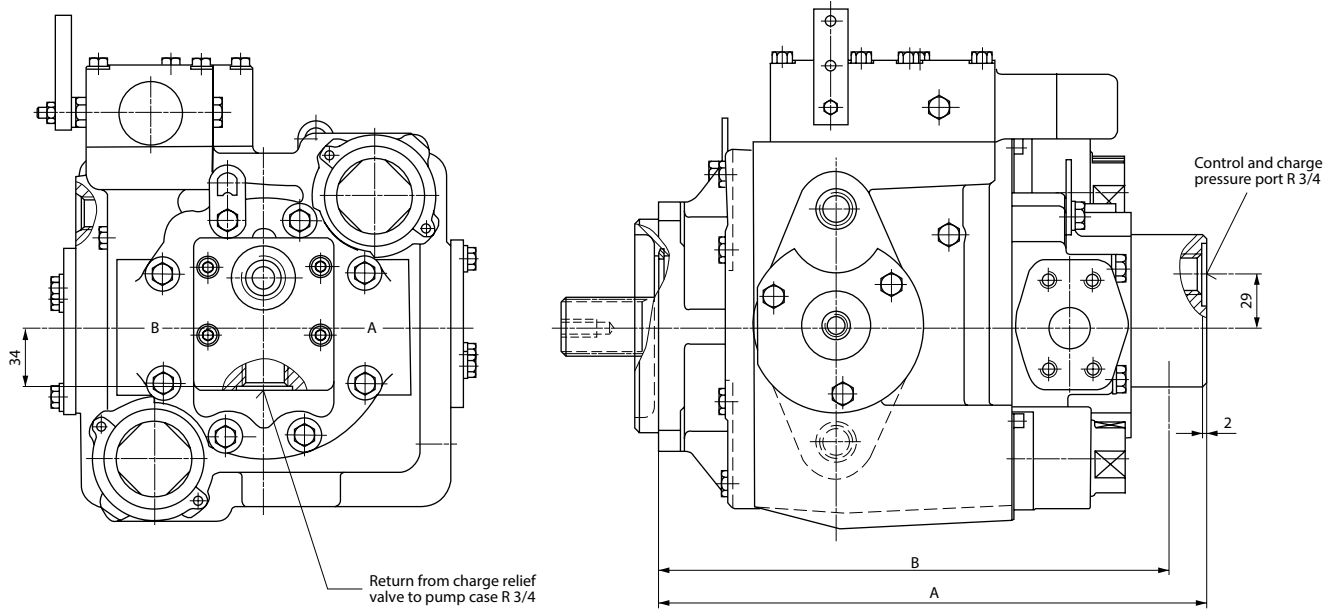| Frame size	AA	BB	CC	DD	EE	FF	GG	HH	JJ
070	187.6 [7.386]	162 [6.378]	128.6 [5.063]	133 [5.236]	113 [4.449]	126 [4.961]	123 [4.843]	130 [5.118]	194 [7.638]
089	198.6 [7.819]	173 [6.811]	139.6 [5.496]	144 [5.669]	123 [4.843]	140 [5.512]	134 [5.276]	148 [5.827]	194 [7.638]

View Y   View Z

P005 107E

P000 022E

Dimensions
– Frame Size 070 and 089 cm³

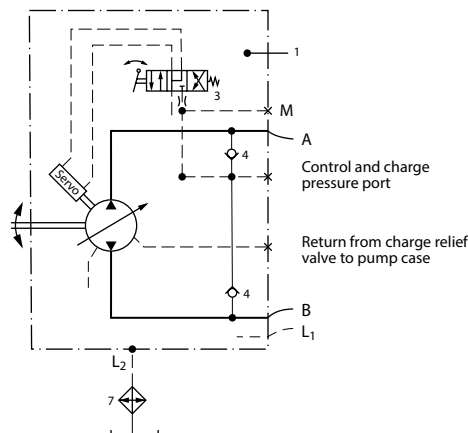**Configuration AA 010,**
displacement control VML 1

Control and charge
pressure port R 3/4

29

2

Return from charge relief
valve to pump case R 3/4

B

A

P000 009E

Dimensions - mm [in]

Frame Size	A	B	Weight kg [lb]
070	339 [13.346]	316 [12.441]	63.5 [140]
089	352 [13.858]	329 [12.953]	78.5 [173]

Circuit schematic

Control and charge
pressure port

Return from charge relief
valve to pump case

Designation:
1 = Variable Displacement pump
3 = Servo control valve
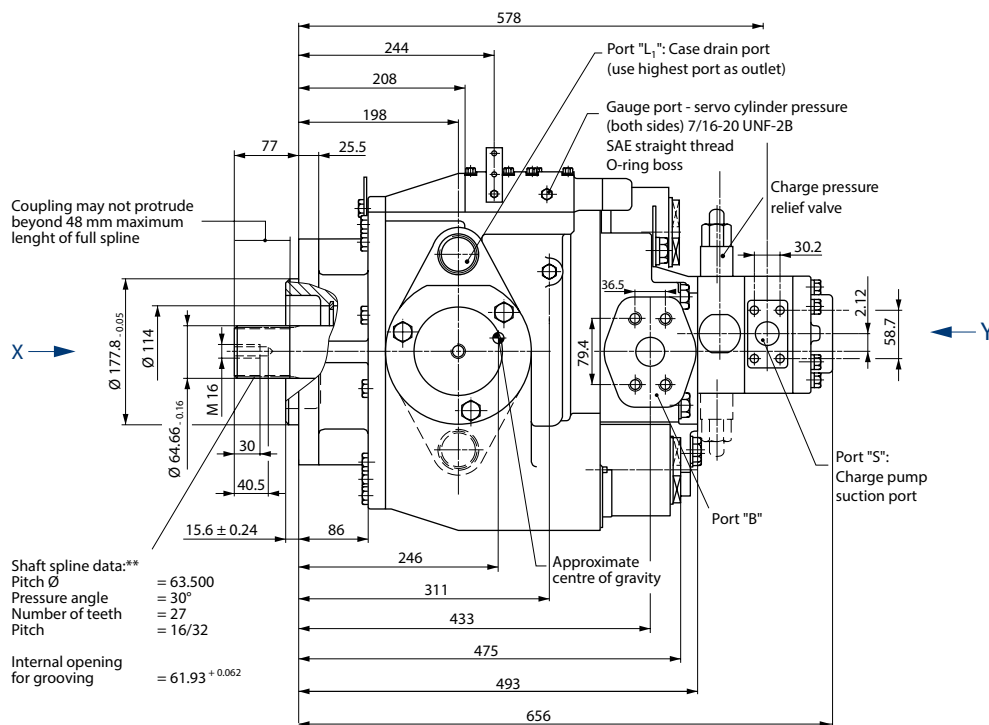4 = Charge check valve
7 = Heat exchanger

Ports:
A, B = Main pressure ports (working loop)
L1, L2 = Drain ports
M = Gauge port - charge pressure

P000 058E

Dimensions
– Frame Size 334 cm³

Configuration PS,
displacement control VML 1

Port "L₁": Case drain port
(use highest port as outlet)

Gauge port - servo cylinder pressure
(both sides) 7/16-20 UNF-2B
SAE straight thread
O-ring boss

Charge pressure
relief valve

Coupling may not protrude
beyond 48 mm maximum
lenght of full spline

Port "S":
Charge pump
suction port

Port "B"

Approximate
centre of gravity

Shaft spline data:**
Pitch Ø   = 63.500
Pressure angle   = 30°
Number of teeth   = 27
Pitch   = 16/32

Internal opening
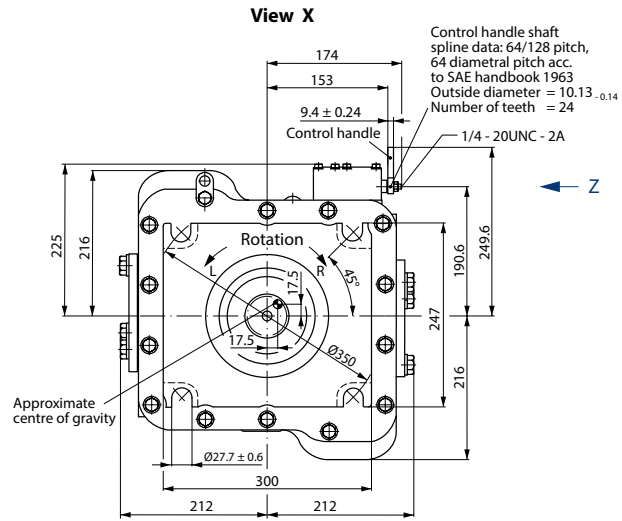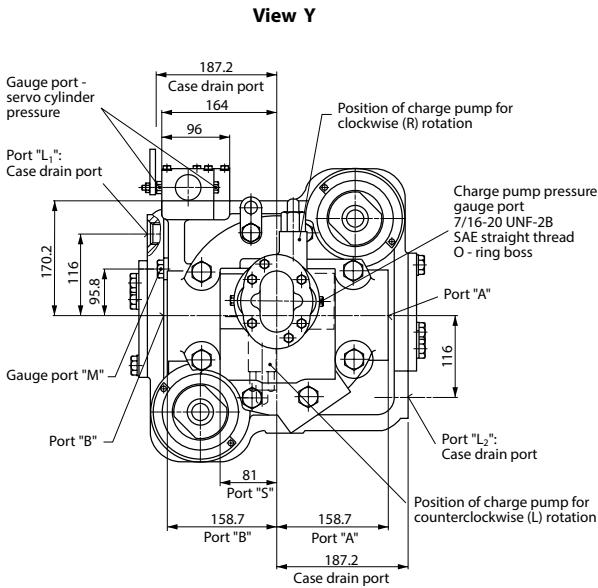for grooving   = 61.93 $^{+0.062}$

P005 115E

* Minimum and maximum angle α, (see section *servo displacement control*).
** Shaft spline data: spline shaft with involute spline, according to SAE handbook, 1963, class 1, fillet root side fit.
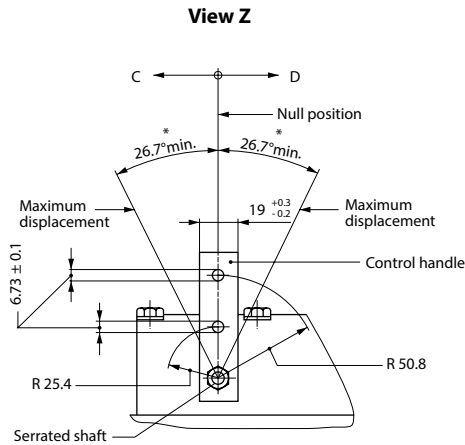
**Dimensions
– Frame Size 334 cm³**

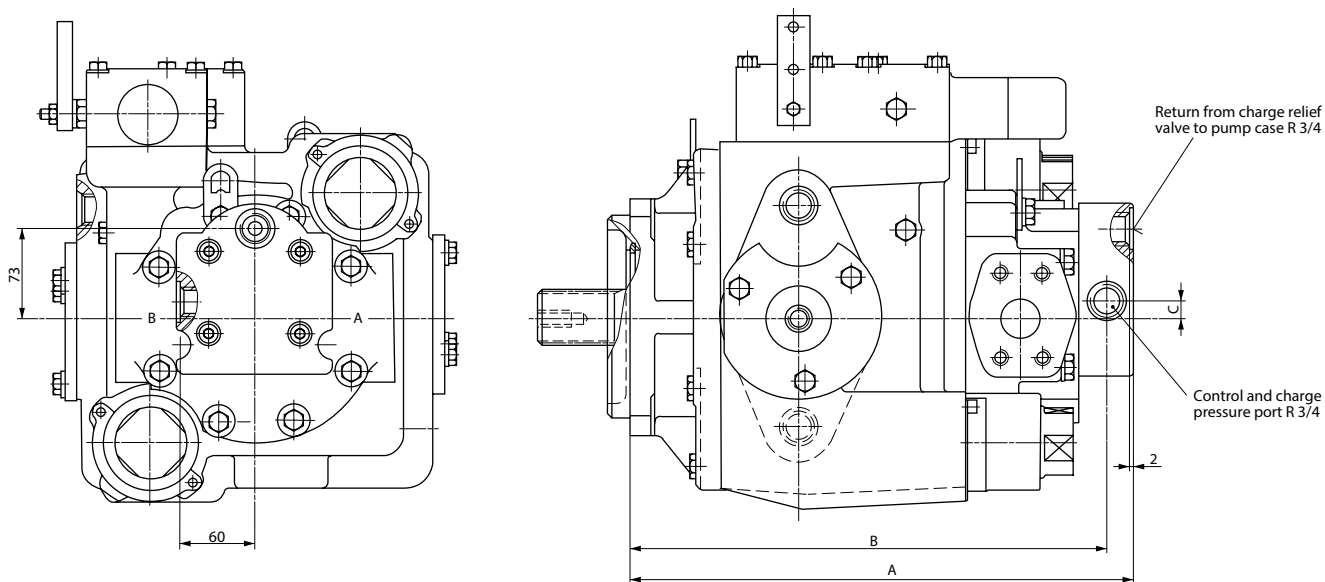**Configuration PS,
displacement control VML 1
(continued)**

View Y

View X

Control handle shaft spline data: 64/128 pitch, 64 diametral pitch acc. to SAE handbook 1963
Outside diameter = 10.13 -0.14
Number of teeth = 24

P005 111E

View Z

P000 026E

Port A and B:	SAE flange, size 1 1/2 SAE split flange boss, 6000 psi, 4 threads, 5/8-11 UNC-2B, 35 deep
Port L1, L2:	1 7/8-12 UNF-2B, SAE straight thread, O-ring boss
Port S:	SAE flange, 1 1/4 SAE split flange boss, 3000 psi, 4 threads, 7/16-14 UNC-2B, 28 deep
Port M:	7/16-20 UNF-2B, SAE straight thread, O-ring boss

**Dimensions
– Frame Size 334 cm³**

**Configuration AA 010,
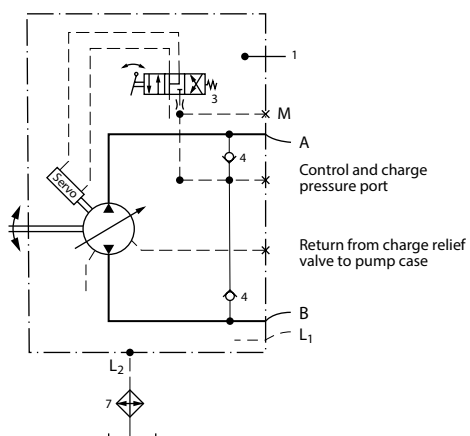displacement control VML 1**

P000 010E

Dimensions - mm [in]

Frame size	A	B	C	Weight kg [lb]
334	546 [21.496]	520 [20.472]	21 [0.827]	264.5 [583]

Circuit schematic

Designation:
1 = Variable Displacement pump
3 = Servo control valve
4 = Charge check valve
7 = Heat exchanger

Ports:
A, B = Main pressure ports (working loop)
L1, L2 = Drain ports
M = Gauge port - charge pressure

P000 058E

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