

ENGINEERING TOMORROW

Technical Information

Hydraulic Fan Drive Systems



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Revision history

Table of revisions

| Date | Changed | Rev |
|---------------|---|------|
| Sept 2018 | Rebrand to Engineering Tomorrow | 0403 |
| June 2015 | Danfoss layout - update product information | DA |
| November 2010 | new back page | сс |
| February 2010 | Fix Osaka address | СВ |
| July 2009 | updated manual adding new products | CA |
| June 2008 | deletions and illustration modifications | BA |
| April 2008 | added special tools part numbers | AC |
| March 2008 | minor edits and corrections | AB |
| | First edition | AA |



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Market Leading Experience

Over a number of years, Danfoss has built up a wealth of experience with fan drive applications for vehicles and machines operating on and off the highway. This knowledge has been gained by providing system solutions which integrate our market leading hydraulic pumps, motors, valves and electro-hydraulic controllers.

Danfoss Hydraulic Fan Drive Systems Provide:

- On-Off and fully modulating controls
- Increased engine reliability
- Decreased fan noise
- Flexible cooling pack positioning
- Vehicle fuel savings
- Design flexibility with multiple inputs for the electro-hydraulic controllers plus CAN bus per SAEJ 1939
- Integrated systems
- Lower operating costs
- Ability to downsize the engine while maintaining system productivity
- Ability to provide engine anti-stall and overspeed protection

Typical Applications

Due to the versatility, flexibility and reliability of Danfoss fan drive systems, they may be applied in numerous applications, including the following.

Agriculture Machinery

- On-Off and fully modulating controls
- Increased engine reliability
- Automatic or On-demand reversing

Construction Machinery

- Backhoe loaders
- Crawler dozer Crawler loader
- Wheel loaders
- Dump trucks Haulers
- Excavators
- Skid steer loaders

Material Handling Vehicles

- Fork lift trucks
- Rough terrain trucks
- Telehandlers

Road Building Vehicles

- Pavers
- Graders
- Road rollers
- Crawlers

Forestry Machinery

- Feller bunchers
- Forwarders
- Harvesters
- Log skidders

On Highway Vehicles

- Buses
- RV motorhomes
- Garbage trucks
- Sweepers

High Power Specialty Vehicles

- Marine
- Oil and Gas drilling/Fracking
- Mining

Reduced Power Consumption

Danfoss hydraulic fan drive systems allow cooling fan power consumption to be tailored to cooling requirements. Our systems provide a precise, modulated cooling flow for a given set of monitored conditions.

The power to drive a cooling fan rises as a cubic function of fan speed (doubling the fan speed requires an eight-fold increase of input power). However, engine power and cooling demand decrease at higher speeds. Because of this inverse relationship, a direct drive cooling fan must be sized to meet cooling requirement at a relatively low engine speed and is therefore significantly oversized for cooling requirements at higher speeds. Hydraulic fan drive systems allow fan speed to be trimmed so the fan can be properly sized at low engine speeds without drawing excessive power at high speeds.



Power vs Engine Speed Curve

Fan systems are sized to provide required air flow at all engine speeds and operating conditions. Directdrive fans consume a great deal of power at higher engine speeds, without any advantage.

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Trimmed and Standby Fan Speed

Under full cooling demand, maximum fan speed increases with engine speed, up to the *set point* of the fan drive system (the point where further increase in speed yields no further gain). Beyond this point fan speed does not increase, allowing greatly reduced power consumption compared to an untrimmed fan.

Under minimum cooling demand, standby fan speed can be set to provide very low, or minimal air flow.





The upper curves represent maximum cooling conditions; maximum fan speed is trimmed at the set point. The lowest curve represents the standby condition; fan speed is maintained at a minimum value.

| Flexible Mounting | |
|--------------------------|---|
| | Hydraulic fan drives make it is possible to mount the radiator and fan just about anywhere on the vehicle. This is advantageous in space conscious designs. |
| Wide Range of Components | |
| | A fan drive system is sized to provide the required fan torque and speed. Danfoss has a wide range of pumps, motors, controls, and sensors to meet your unique fan drive system needs. |
| Basic Operation | |
| | In simplest terms, fan speed is controlled by regulating the amount of hydraulic oil passing through the fan motor. The greater the flow, the greater the fan speed. The amount of flow is regulated based on one or more inputs from the power system. Typically, engine coolant temperature is the main controlling factor. Other system inputs may include hydraulic fluid temperature, charge air temperature and various signals or switches. As inputs indicate a change in cooling demand, the system adjusts flow to the motor. |
| Intelligent Control | |
| | At the core of the Danfoss Fan Drive System is a controller that monitors relevant cooling parameters and adjusts fan speed accordingly. |
| | Fan Drive Controller |
| | The Danfoss fan drive control system monitors cooling parameter inputs and provides an electronic signal to a proportional hydraulic valve. The proportional valve relays a hydraulic signal either to the |



bypass valve on the motor or the displacement control of a variable displacement pump. Possible inputs to the fan drive control system include engine coolant temperature, charge air temperature, engine or transmission oil temperature, compartment temperature, ambient temperature, and various other signals and switches. Also, many engine control systems provide a fan controlling signal or CAN message which can serve as a cooling parameter input.

Balanced Fan Speed and Heat Generation

When an input, such as engine coolant temperature, rises above a predetermined level, signalling an increase in cooling demand; fan speed is gradually increased. Coolant temperature and fan speed continue to rise until heat generation and cooling are balanced. Under most conditions, this balance occurs at a level below the maximum capability of the system.

Maximum fan speed is reached only under simultaneous conditions of maximum ambient temperature and maximum engine load. These parameters are set as part of the cooling system design criteria.



Fan Speed Vs. Engine Temperature

Fan speed is increased as monitored temperature increases until balance is reached.



Fan Drive Systems

Modulating Fan Drive Systems

Monitoring various cooling system parameters enables the Danfoss modulating fan drive systems to increase fan speed as required. As a modulating system, it ramps fan speed only to the level required, providing only as much air flow as needed to maintain balance between heat generation and cooling.

Gear Pump with Gear Motor and PLUS+1[™] Fan Drive Controller

The pump receives oil directly from the reservoir through the inlet line. The output of the pump is directed to a gear motor with an integral proportional relief valve.

The setting of the valve determines the maximum pressure in the system by bypassing oil (around the motor's gear set) directly to the return port of the motor. The proportional valve is normally closed and requires the application of a PWM signal to reduce the bypass pressure. In a hydraulic fan drive system, the pre-determined maximum pressure setting determines the maximum pressure to the motor, and the maximum trim speed of the fan.

Applying a PWM signal to the valve allows the fan to run at speeds below its maximum trim speed, regardless of the flow supplied by the pump.

Oil exiting the motor is directed back to the reservoir through a filter and a heat exchanger. Oil returning to the reservoir must enter the reservoir well below the fluid level so air will not be entrained in the fluid. The oil is diffused as it enters the reservoir to decelerate it to an acceptable level, to mix it with the fluid in the reservoir, and to prevent the oil from flowing immediately back to the pump inlet. The return oil should remain in the reservoir long enough to allow any entrained air in the fluid to rise to the surface and dissipate back into the atmosphere. An anti-cavitation check valve prevents damage to the fan motor in case of overrun. Fan overrun can occur when fan speed exceeds the speed commanded by the system due to the fan windmilling in the vehicle's air stream.

Gear Pump with PLUS+1[™] Controller





Fan Drive Systems

Variable Displacement Pump with Fan Drive Control

The variable displacement pump sends flow to the fan motor. Based on sensor and other inputs, the microcontroller adjusts the proportional relief valve to regulate the pressure in the pilot port of the pump's load sensing control. Higher pressure in the pilot line results in increased flow to the fan motor. The control has a pressure compensator feature which can be used to limit the fan's trim speed. Trim speed can also be set by software in the microcontroller.

Fan Drive Control System Illustration



Variable Displacement Pump and HIC Cartridge Valve

The system shown below is the same as the previous system with the addition of an electronically controlled HIC cartridge valve between the pump and motor.

The HIC cartridge valve reverses the hydraulic flow to the motor, thus reversing the rotation of the fan. This feature is commonly used to clean out the radiator if it becomes clogged with debris.

Variable Pump with HIC Cartridge Valve



P107 985E



Fan Drive Systems

Closed Circuit System with Microcontroller

The variable displacement axial piston pump sends flow to the fixed displacement piston fan motor. Based on temperature sensor and other inputs, the microcontroller regulates the displacement of the axial piston pump. Higher coolant temperature results in increased flow to the fan motor. The pumps displacement control has a pressure compensator feature which can be used to limit the maximum fan trim speed in either direction. Trim speed can also be set by software in the microcontroller. The nature of the closed-loop system prevents fan overrun. Zero fan speed is available on demand.

Variable Pump with Fixed Piston Motor



P107 983E

Gear Pumps

Danfoss offers gear pumps in a variety of models, sizes, capacities, and configurations. Integral priority flow dividers are available which supply a constant flow for power assisted steering with the remainder driving the fan drive motor.

Model Sizes and Capacities

Danfoss gear pumps are available in the following models and sizes.

Aluminum construction

Group 2

4 to 25 cm3/rev [0.24 to 1.53 in3/rev] displacement

• Group 3

22 to 90 cm3/rev [1.34 to 5.49 in3/rev]

Cast iron construction

• Group 2.5 (D Series)

7 to 45 cm3/rev [0.43 to 2.75 in3/rev]

Configurations

- Single pump
- Single pump with priority flow divider for power steering assist
- Tandem pumps
- Tandem pumps with priority flow divider for power steering assist
- Multiple pumps (triple, quadruple, etc.)
- Quadra-Flow pumps (digital displacement)

D Series pumps (single and tandem) are available with load sense and discrete flow options.

Group 2 aluminum gear pump



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Group 2.5 D Series gear pump



Quadra-Flow gear pump





Series 45 Variable Displacement Axial Piston Pumps

Danfoss offers a complete family of variable displacement, open circuit, axial piston pumps. The Series 45 family offers a wide range of shafts, flanges, and porting options. Through drives are also available for auxiliary pump drives. Load sensing (LS), pressure compensating (PC), remote pressure compensating (RPC) and electro-proportional fan drive controls are available.

Frame K/L

- 25, 30, 38 and 45 cm3/rev [1.53, 1.83, 2.32, 2.75 in3/rev]
- Operating pressures up to 260 bar [3770 psi]
- Speeds to 3200 min-1(rpm)

Frame J

- 45, 51, 60, 65 and 75 cm3/rev [2.75 3.11, 3.66, 3.97, and 4.57 in3/rev]
- Operating pressures to 310 bar [4495 psi]
- Speeds to 2800 min-1(rpm)

Frame F

- 74 and 90 cm3/rev [4.52 and 5.49 in3/rev]
- Operating pressures to 310 bar [4495 psi]
- Speeds to 2400 min-1(rpm)

Frame E

- 100, 130, and 147 cm3/rev [6.10, 7.93 and 8.97 in3/rev]
- Operating pressures to 310 bar [4495 psi]
- Speeds to 2450 min-1(rpm)

Frame J





Frame K/L



Series 45 Fan Drive Control

The Series 45 fan drive control is an electric proportional control for Series 45 pumps. It controls the pump based on various machine operating parameters. In a fan drive system, coolant temperature forms the basis for pump control.

When the solenoid is de-energized, the pump operates in the high pressure standby (pressure compensation) mode; when the solenoid is fully energized, the pump returns to the low pressure standby mode of operation. This allows the system to minimize energy loss when the cooling system does not require cooling fan operation, potentially using existing system control components (temperature sensor or micro-controller).

The control is proportional. As the current applied to the solenoid increases, the regulated system pressure gradually decreases until the full current is applied, achieving low standby pressure.





D Series Motor

D series fan drive motors are available in displacements from 17 cm³/rev [1.04 in³/rev]to 45 cm³/rev [2.75 in³/rev].

D series fan motors are PLUS+1 compliant.



D Series Motor



D Series Motor Technical Data

| Ratings | Units | 17 | 19 | 21 | 23 | 25 | 29 | 32 | 36 | 38 | 41 | 45 |
|---|---|------|------|------|------|------|-------|-------|-------|-------|-------|-------|
| Displacement | cm ³ /rev | 17.0 | 19.0 | 20.5 | 22.5 | 25.4 | 29.0 | 31.8 | 36.1 | 38.0 | 41.0 | 45.0 |
| | in ³ /rev | 1.04 | 1.16 | 1.25 | 1.37 | 1.55 | 1.77 | 1.94 | 2.20 | 2.32 | 2.50 | 2.75 |
| Rated pressure | bar | 276 | 276 | 276 | 276 | 276 | 276 | 276 | 276 | 276 | 241 | 210 |
| | psi | 4000 | 4000 | 4000 | 4000 | 4000 | 4000 | 4000 | 4000 | 4000 | 3495 | 3045 |
| Peak pressure | bar | 303 | 303 | 303 | 303 | 303 | 303 | 303 | 303 | 303 | 265 | 231 |
| | psi | 4400 | 4400 | 4400 | 4400 | 4400 | 4400 | 4400 | 4400 | 4400 | 3843 | 3350 |
| Speed at rated pressure | maximum | 3400 | 3400 | 3400 | 3400 | 3400 | 3400 | 3400 | 3400 | 3400 | 3000 | 3000 |
| | minimum* | 600 | 600 | 600 | 600 | 600 | 600 | 600 | 600 | 600 | 600 | 600 |
| Minimum shaft speed at 69 bar [1000 PSI] | rpm | 400 | 400 | 400 | 400 | 400 | 400 | 400 | 400 | 400 | 400 | 400 |
| Standard Weight | kg | 8.53 | 8.66 | 8.80 | 8.94 | 9.07 | 9.38 | 9.53 | 9.84 | 9.93 | 10.16 | 10.43 |
| | lb | 18.8 | 19.1 | 19.4 | 19.7 | 20.0 | 20.7 | 21.0 | 21.7 | 21.9 | 22.4 | 23.0 |
| Mass moment of inertia of internal rotating | x10 ⁻⁶ kg•m ² | 127 | 138 | 146 | 156 | 172 | 191 | 206 | 228 | 239 | 255 | 276 |
| components | x10 ⁻⁶ slug•ft ² | 94 | 102 | 107 | 115 | 127 | 141 | 152 | 168 | 176 | 188 | 204 |
| Theoretical torque at rated pressure | N•m | 65.7 | 73.4 | 79.2 | 87.0 | 98.2 | 112.1 | 122.9 | 139.6 | 146.9 | 138.4 | 132.4 |
| | lbf•ft | 48.5 | 54.2 | 58.4 | 64.2 | 72.4 | 82.7 | 90.7 | 102.9 | 108.3 | 102.1 | 97.6 |
| Theoretical power at rated speed | kW | 23.4 | 26.1 | 28.2 | 31.0 | 35.0 | 39.9 | 43.8 | 49.7 | 46.1 | 43.5 | 41.6 |
| | hp | 31.2 | 34.9 | 37.6 | 41.3 | 46.6 | 53.2 | 58.4 | 66.3 | 61.1 | 58.0 | 55.5 |



D Series Motor Technical Data (continued)

| Ratings | Units | 17 | 19 | 21 | 23 | 25 | 29 | 32 | 36 | 38 | 41 | 45 |
|---------------------|-------|------|------|------|------|------|------|------|------|------|------|------|
| Case drain pressure | bar | 5.0 | 5.0 | 5.0 | 5.0 | 5.0 | 5.0 | 5.0 | 5.0 | 5.0 | 5.0 | 5.0 |
| | psi | 72.5 | 72.5 | 72.5 | 72.5 | 72.5 | 72.5 | 72.5 | 72.5 | 72.5 | 72.5 | 72.5 |

* minimum speed at maximum pressure

SGM2Y Motor

Group 2 fan drive motors are available in displacements from 8.4 cm³/rev [0.51 in³/rev]to 25 cm³/rev [1.54 in³/rev].

Configurations include European and SAE flanges; taper 1:8, 1:5, and straight shafts Ø15.875 mm [0.62 in].

Group 2 fan drive motors are PLUS+1 compliant.

SGM2Y Motor



SGM2Y technical data

| | Units | | Frame size | | | | | | |
|--|---|--------------|--------------|----------------|------------------|-------------------|--------------|-------------|--|
| | | 8.0 | 011 | 014 | 017 | 019 | 022 | 025 | |
| Displacement | cm ³ /rev [in ³ /rev] | 8.4 [0.51] | 10.8 [0.66] | 14.4 [0.88] | 16.8 [1.03] | 19.2 [1.17] | 22.8 [1.39] | 25.2 [1.54] | |
| Peak pressure | bar [psi] | 270 [3916] | 270 [3916] | 270 [3916] | 250 [3626] | 230 [3336] | 200 [2900] | 180 [2610] | |
| Rated pressure |] | 250 [3626] | 250 [3626] | 250 [3626] | 230 [3336] | 210 [3046] | 180 [2610] | 160 [2320] | |
| Back pressure | | 150 [2176] | 150 [2176] | 150 [2176] | 150 [2176] | 130 [1885] | 100 [1450] | 100 [1450] | |
| Maximum speed | min-1 [rpm] | 3500 | 3500 | 3500 | 3500 | 3500 | 3500 | 3500 | |
| Weight | kg [lb] | 4.73 [10.43] | 4.83 [10.65] | 5.03 [11.1] | 5.18 [11.42] | 5.23 [11.53] | 5.33 [11.75] | 5.53 [12.2] | |
| Moment of inertia of rotating components | x 10-6 kg•m ² [x 10-6 lbf•ft ²] | 32.4 [796] | 38.4 [911] | 47.3 [1122] | 53.3 [1265] | 59.2 [1405] | 68.1 [1616] | 74.1 [1758] | |
| Electrical connector | model | | Deutsch | DT 04-2P conne | ctors (Protectio | n rate IP 69K DII | N 400050) | | |
| Electrical current signal | А | | 0 to 1.1 A | @ 12VDC, with | coil resistance | of 7.2 ohms @ 2 | 0°C [68°F] | | |
| | | | 0 to 0.55 A | @ 24VDC, with | coil resistance | of 28.8 ohms @ 3 | 20°C [68°F] | | |
| PWM frequency | Hz | | | | from 100 to 200 |) | | | |

SGM3Y Motor

Group 3 fan drive motor available in displacements from 22.1 cm³/rev [1.34 in³/rev]to 44.1 cm³/rev [2.69 in³/rev].

Group 3 fan drive motors are PLUS+1 compliant.



SGM3Y Motor



SGM3Y technical data

| | Units | | Frame size | | | | | | | |
|--|---|-----------------|-------------------|---------------------|---------------------|--------------|--|--|--|--|
| | | 022 | 026 | 033 | 038 | 044 | | | | |
| Displacement | cm ³ /rev [in ³ /rev] | 22.1 [1.34] | 26.2 [1.60] | 33.1 [2.02] | 37.9 [2.31] | 44.1 [2.69] | | | | |
| Peak pressure | bar [psi] | 210 [3046] | 210 [3046] | 210 [3046] | 210 [3046] | 210 [3046] | | | | |
| Rated pressure | | 190 [2756] | 190 [2756] | 190 [2756] | 190 [2756] | 190 [2756] | | | | |
| Back pressure | | 120 [1740] | 120 [1740] | 120 [1740] | 120 [1740] | 120 [1740] | | | | |
| Maximum speed | min ⁻¹ [rpm] | 3500 | 2500 | 2500 | 2500 | 2500 | | | | |
| Weight | kg [lb] | 9.12 [20.11] | 9.22 [20.33] | 9.32 [20.55] | 9.38 [20.68] | 9.52 [21.0] | | | | |
| Moment of inertia of rotating components | x 10 ⁻⁶ kg•m ² [x 10 ⁻⁶ lbf•ft ²] | 198 [4699] | 216 [5126] | 246 [5838] | 267.2 [6341] | 294.2 [6981] | | | | |
| Electrical connector | model | Deutsc | h DT 04-2P conne | ectors (Protectior | n rate IP 69K DIN 4 | 400050) | | | | |
| Electrical current | А | 0 to 1.1 | A @ 12VDC, with | n coil resistance o | of 7.2 ohms @ 20° | C [68°F] | | | | |
| signal | | 0 to 0.55 | 5 A @ 24VDC, with | n coil resistance o | f 28.8 ohms @ 20 | °C [68°F] | | | | |
| PWM frequency | Hz | from 100 to 200 | | | | | | | | |

L/K Frame Axial Piston Motors

For higher power applications, Danfoss offers the L and K frame two position, axial piston motor. The KV and LV motors can operate at two different displacements. Minimum displacement can be used when high fan speed is required at low engine speed and maximum displacement can be used at high engine speed. The K and L frame motors can also be used as single displacement motors.

This short, compact motor is configured ideally for installations requiring compact packaging and optimized plumbing. All hydraulic ports are on one face of the motor. Axial or radial configurations are available.

Mounting

• SAE B-2 bolt and Danfoss cartridge

Shaft

SAE 0.875 diameter cylindrical and 1:8 taper keyed shafts

System Ports



• SAE O-ring boss, axial or twin radial locations

Specifications

- 25, 30, 38 and 45 cm3/rev [1.52, 1.83, 2.14, 2.32 and 2.75 in³/rev] maximum displacements
- Operating pressure up to 415 bar [6000 psi]
- Speeds up to 5500 min-1(rpm)

Control

- Direct acting single line hydraulic displacement control
- 10 to 241 bar [150 to 3500 psi] shift pressure
- Reverse Displacement Control (electric or hydraulic)

Options

- Speed sensor
- Maximum displacement limiter
- Integral over-pressure and anti-cavitation protection

LV Motor



Danfoss



LC Motor



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PLUS+1<sup>™</sup> Controllers
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12 Pin Microcontroller





24 Pin Microcontroller



PLUS+1TM controllers and input/output expansion modules are designed to provide flexible, expandable, powerful, and cost effective total machine management systems for off-highway vehicles. These modules communicate with one another and other intelligent systems over a machine CAN (Controller Area Network) data bus. PLUS+1TM hardware products are designed to be equally effective in a distributed CAN network system, with intelligence in every node, or as stand-alone control for smaller machine systems. PLUS+1TM systems are incrementally expandable: Additional modules can be easily added to the machine CAN network to increase system capabilities or computational power.

Inputs

Each input pin allows one or more of these functional types. For pins with multiple functions, input parameters are user programmable using PLUS+1[™] GUIDE templates.

- Digital (DIN)
- Digital or Analog (DIN/AIN)
- Digital or Analog or Frequency (DIN/AIN/FreqIN)
- Analog or Temperature or Rheostat (AIN/Temp/Rheo)
- Fixed Range Analog or CAN shield (AIN/CAN shield)

Outputs

PLUS+1TM control modules feature user-configurable universal output circuits. Output parameters are configured using PLUS+1TM GUIDE templates. Refer to product data sheets for maximum current ratings of individual modules. The following output types are supported:

- Digital (DOUT)
- PWM (PWMOUT)
- Analog voltage suitable for driving Danfoss PVG valves (PVEOUT)

CAN Ports

All PLUS+1[™] modules have CAN ports that conform to CAN 2.0b specifications, including CAN shield.

Temperature Sensors

The Danfoss family of analog temperature sensors is designed to operate in conjunction with Danfoss Fan Drive Controls. The PLUS+1TM compliant sensors are thermistor-type temperature sensors.



Temperature sensors



Models

Two models are available: An air sensor typically used to measure engine charge air temperature, and a liquid sensor typically used to measure engine coolant or oil temperature.

Features

- Integrated connector and sensor body
- Brass body construction
- Anti-fouling air temperature sensor design
- 50° C to 125° C operating temperature
- range, FDC software configurable

For proper operation, the air temperature sensor must be mounted at the top of the manifold pipe with the sensor tip facing down.

Temperature versus resistance limits

| Measured Temp, ° C | Resistance, Ohms | | | | | | |
|--------------------|------------------|-----------|--|--|--|--|--|
| ["F] | Nominal | Tolerance | | | | | |
| 50 [122] | 810.9 | ±5% | | | | | |
| 80 [176] | 283.0 | ±5% | | | | | |
| 100 [212] | 152.9 | ±8% | | | | | |
| 125 [257] | 76.9 | ±8% | | | | | |

PLUS+1 [™] Compliance

The Danfoss temperature sensors are compliant with the larger microprocessors (for example the MC050). The MC050 microprocessor has internal resistance in its four temperature inputs.

If you are using the Danfoss temperature sensors with the smaller microprocessors (for example the MC012 and MC024), you will need to connect the sensors in series with an external resistor (Rv) as shown in the following illustration.



Analog sensor voltage



For assistance in configuring the temperature sensors contact your Danfoss representative.

Sizing Equations

Equations

Pumps

Based on SI units

Based on English units

Based on English units

| Output flow Q = | $\frac{V_{g} \cdot n \cdot \eta_{v}}{1000}$ | (l/min) | Output flow $Q =$ | $\frac{V_{g} \cdot n \cdot \eta_{v}}{231}$ (US | gal/min) |
|-----------------|--|---------|-------------------|---|----------|
| Input torque M= | $\frac{V_g \cdot \Delta p}{20 \cdot \pi \cdot \eta_m}$ | (N•m) | Input torque M= | $\frac{V_g \cdot \Delta p}{2 \cdot \pi \cdot \eta_m}$ | (lbf•in) |
| Input power P = | V _g • n• Δp 600 000 • η _m | (kW) | Input power P = | V _g • n• Δp 396 000 • η _m | (hp) |

Motors

Based on SI units

| Output torque M | = | $\frac{V_g \cdot \Delta p \cdot \eta_m}{20 \cdot \pi}$ | (N•m) | Output torque M | = | $\frac{V_{g} \cdot \Delta p \cdot \eta_{m}}{2 \cdot \pi}$ | (lbf•in) |
|-----------------|---|--|-------|-----------------|---|---|----------|
| Output power P | = | $\frac{Q \cdot \Delta p \cdot \eta_t}{600}$ | (kW) | Output power P | = | <u>Q•Δp•η_t</u> 1714 | (hp) |

Variables

SI units [English units]

V_g = Displacement per revolution cm³/rev [in³/rev]

p_O = Outlet pressure bar [psi]

p_i = Inlet pressure bar [psi]

 $\Delta p = pO - pi$ (system pressure) bar [psi]

n = Speed min-1 (rpm)

 $\eta_v =$ Volumetric efficiency

 $\eta_m = Mechanical \ efficiency$

 $\eta_t = \text{Overall efficiency} (\eta_v \cdot \eta_m)$

SI unit formulas are based on cm³, bar, N, N•m, W.

English formulas are based on in³, psi, lbf•in, hp.





System Design Data Form

Print this form. Fill in all the fields and check the appropriate check boxes. Fax the filled out form to your Danfoss Power Solutions Technical Sales Representative.

Engine details

| Manufacturer _ | Model or Series |
|-------------------------------------|--|
| Pump Drive | Engine PTO Ratio:1 Input torque Belt Drive (engine to pump) limit: |
| Pump Rotation | Clockwise, Right hand Counterclockwise, Anti-clockwise, Left hand |
| Speeds | Low IdleRPM (rated) GovernedRPM (rated) High IdleRPM (max speed) |
| | Power steering |
| | |
| Controlled Flov | w Requirement US gal/min 🗌 1/min 🔲 |
| Steering Pressu (maximum) | psi bar |
| | P104 376E |



Fan information

| Manufacturer | _ Model or Series |
|--|--|
| Fan Diameter | _ in 🔲 mm 🔲 |
| Fan Input Power | _ HP kW At speed rpm |
| Fan Rotation (viewed on motor shaft, see illustration) Fan Trim Speed rpm | Clockwise Counterclockwise |
| Set Point at Fan Trim Speed | rpm |
| (engine speed where max heat load occurs) | |
| Coolant Temperature at Fan Trim Speed | d°F°C |
| (coolant temp where max fan speed is requ | ured) |
| Note: To properly size and specify a fan drive system, i can be determined from fan curves supplied by the man on heat loads. Air flow information must include accu | fan power requirements must be stated as accurately as possible. Fan power requirements nufacturer. Radiator and cooler manufacturers will supply air flow requirements based rate air flow and static pressure to determine correct fan power requirements. |

Control preference

| Electro-H Sir | Iydraulic Modulating ngle Input | Electro-Hydraulic ON/OFF | |
|--------------------|---|--------------------------|-----------|
| Mu Reservoir | Iltiple Inputs | | P104 377E |
| Reservoir Capacity | US gal | liter | P104 378E |



| Hydraulic Fluid Type _ Viscosity | at 40 | 0° C [104°F] □ 00° C [212°F] | cSt SUS | |
|-------------------------------------|--|---------------------------------|--|-----------|
| Viscosity | at 40 | 0° C [104°F] | cSt SUS | |
| | at 10 | 00° C [212°F] | | |
| | | | | |
| Maximum Fluid Tempe | erature | | °F | P104 379E |
| Filtra | tion | | | |
| Filter Position | Inlet Line Pressure Line Return Line recommended | Filter Flow | Full Flow | |
| Filter Rating | micron lge inside the reservoir. This r | x rati | io acity and reduces the dwell time (the time the oil | |



Pumps

Pump Drives

Where possible, avoid radial and axial loads on the pump drive.

For in-line drives, place a suitable drive coupling between the prime mover (e.g. engine) and the pump input shaft to remove radial and axial load potential. For belt driven pump applications an outrigger bearing may be required to relieve the pump of radial loads. Outrigger bearings are available with ball or roller bearing support for such applications. For Power Take Off (PTO) drives (where an external gear is assembled to the pump), and for belt driven pump applications, consult your Danfoss representative.

In many applications the limiting factor for driving a pump is available torque. Pump drive shafts have a torque limit based on material, design and system pressure. Likewise, pump drives such as air compressors with PTOs also have torque limits. When planning to drive a pump on the back of an air compressor, first check with the compressor supplier to understand their product torque limitations. Most compressors do not have a constant torque capability across their speed range. Typically, the torque capability of a compressor is lower at low engine speeds and increases to a speed where the capability remains constant.

A number of pump drive shafts are generally available across the Danfoss product range. Consider driveshaft selection carefully.

Pump Inlet

When designing the inlet portion of the hydraulic circuit, it is important to keep the pump inlet pressure within published limits. To reduce the chances of inlet cavitation problems, observe the following guidelines:

- Position reservoir outlet above the pump inlet level whenever possible.
- Make the inlet line (hose and fittings) as straight and as short as possible without inducing bending or stress loads onto the inlet port.
- Size the inlet line to keep fluid velocities and inlet pressure within the limits published in the individual product literature.
- To reduce the chances of port fitting leakage, we recommend using SAE split flange or O-ring boss ports whenever possible.

Pump Outlet

- Make the outlet line (hose and fittings) as straight and as short as possible without inducing bending
 or stress loads onto the outlet port.
- Ensure the outlet line is sized to keep fluid velocities within the limits published in the individual product literature.
- To reduce the chances of port-fitting leakage we recommend using SAE split flange or O-ring boss ports whenever possible.

Motors

SGM2YN and SGM3YN Fan Drive Motors

SGM2Y and SGM3Y fan drive motors have the proportional solenoid bypass relief valve built into the rear cover. Electrical connector is Deutsch DT 04-2P. Mount the motor so the relief valve is below the reservoir oil level. Keep the relief valve in a horizontal position.

D Series Fan Drive Motors

D series fan drive motors are available with an integrated proportional or standard relief valve. Mount the motor so the relief valve is below the reservoir oil level. Keep the relief valve in a horizontal position.



L and K Variable Motors

L and K variable motors do not have over-pressure protection or an anti-cavitation valve integrated into the motor. Both valve functions need to be provided externally.

L and K variable motors may be applied in open circuit systems without external back-pressure valves, as long as the motor case pressure does not exceed the outlet pressure by more than 0.5 bar [7 psi].

Typically the motor's maximum displacement is used when the system is sized for maximum cooling when the engine is at <u>Full Load High Idle</u> speed. The motor's minimum displacement is selected to provide improved cooling when the engine is at its low idle speed.

Reverse Displacement Motors

The Reverse Displacement Motor is a unique design variation of the L and K variable motors.

It has been designed to reverse the direction of fan rotation without using an externally mounted fourway directional control valve.

The motor is switched from maximum displacement in the forward direction to maximum displacement in the reverse direction with an integrated solenoid valve.

Over-pressure protection and an anti-cavitation valve are integrated into the motors endcap.

Series 40 Fixed Displacement Motors

Series 40 motors are available with over-pressure protection and an anti-cavitation valve in a unidirectional open circuit configuration.

They may be applied in open circuit systems without external back-pressure valves as long as the motor case pressure does not exceed the outlet port pressure by more than 0.5 bar [7.0 psi].

Bi-directional open circuit operation is available, provided that a four-way directional control valve is located between the pump and the motor.

Series 90 Fixed Displacement Motors

Series 90 fixed displacement motors are available without over-pressure protection or an anti-cavitation valve in an open circuit configuration.

They may be applied in open circuit systems without external back-pressure valves, but <u>specific</u> axial thrust, case pressure, and maximum shaft speed limits must be respected. (Consult your Danfoss Technical Sales Representative for assistance when specifying a Series 90 fixed displacement motor in an open circuit application.

Controls

PLUS+1[™] controller

The Plus+1TM controller is designed to control many different hydraulic devices. Mount the Plus+1TM controller in a convenient, out of the way, location. A diagnostic connector is required to connect to the Plus+1TM controller. Mount the connector in an easily accessible location in the operators cabin. Follow the wiring guidelines found in Plus+1TM module technical literature.

Series 45 Fan Drive Controls

In Danfoss open circuit fan drives, fan speed is regulated by controlling the system pressure differential across the fan motor. In Series 45 pumps, this is provided by using the Electric Proportional Control variation. The Electric Proportional Control consists of a proportional solenoid integrated into the Remote Pressure Compensated control housing. This control provides an output pressure proportional to the current supplied to the solenoid and allows the pump to be operated at any pressure limit between the load sense and pressure compensation settings by varying the current sent to the solenoid. Both Normally Closed and Normally Open control configurations are available. The Normally Closed configuration is usually applied in system cooling fan installations. It is desireable that the fan fail to full speed if there is an interruption of the electrical command to the solenoid, for any reason.

H1 Pump with Fan Drive Control

A fan drive control option is available for the H1 family of high power, closed circuit, variable displacement pumps. The H1 Fan Drive Control is compatible with the PLUS+1TM controller and the fan drive application block. The Fan Drive Control is designed with a single solenoid and uses a single control input to regulate both the fan speed and direction of rotation.

When the pump speed is at the design set point, fan speed required for the desired cooling capacity is determined by the pump's displacement. In many systems, the fan's speed at this condition may be close to its maximum design speed. If the pump speed increases beyond the set point and the pump is commanded to maximum displacement; then the fan speed will increase in proportion to the pump speed ratio and the pressure drop across the fan motor will increase in proportion to the square of the pump speed ratio. To prevent this from happening, the system designer is encouraged to limit the maximum fan speed in each direction of rotation by adjusting the set pressure of the Pressure Limiters for both directions of rotation.

The Fan Drive Control (FDC) has limitations on the maximum servo delta pressure developed, compared to other types of controls, and so there are limitations to the operating conditions which can be achieved in the various frame size H1 pumps. Typical fan drive systems are unusual in that they achieve peak pressure only at high flows, so it is important that FDC equipped pumps not be applied beyond the specified limits. (Refer to *Fan Drive Design Guidelines* **520L0926**, Appendix H, for additional information, or contact your Danfoss Technical Sales Representative for assistance.)

Fan drives are sized with reserve pump capacity so that peak fan speed can be maintained even when engine speed is reduced, as illustrated below. This is a feature that is unique to the Danfoss H1 Fan Drive Control; it allows the system to maintain a nearly constant fan speed without the need for additional control algorithms in the fan drive controller. In this example, representing an engine lugging condition (engine speed change of 20%), there was no significant reduction in fan speed.





Prime Mover Speed Change (2500 - 2000 - 2500 rpm)



System

Filtration

To prevent premature wear, it is imperative that only clean fluid enters the pump and hydraulic circuit. A filter capable of controlling the fluid cleanliness to class 22/18/13 (per ISO 4406-1999) or better, under normal operating conditions, is recommended. At initial start up, the system can be at Class 25/22/17 but should not be run at high speed or pressure until the Class 22/18/13 is achieved through filtration. Since the filter must be changed at regular intervals, the filter housing should be located in an accessible area. Appropriate filter change intervals may be determined by test or by gauges indicating excessive pressure drop across the filter element.

For more information refer to *Design Guideline for Hydraulic Fluid Cleanliness, Technical Information* **520L0467**.

Operating Temperatures

With Buna seals and normal operating conditions, the system temperature should not exceed 82 °C [180 °F] except for short periods to 93 °C [200 °F]. With optional Viton elastomer, the system may be operated at continuous temperatures up to 107°C [225°F] without damage to the hydraulic components.

Caution

Operation in excess of 107 °C [225 °F] may cause external leakage or premature unit failure.

Fluids

A mineral based fluid is recommended that includes additives to resist corrosion, oxidation and foaming. The oil should have a maximum viscosity commensurate with system pressure drop and pump suction pressures. Since the fluid serves as a system lubricant, as well as transmitting power, careful selection of the fluid is important for proper operation and satisfactory life of the hydraulic components. Hydraulic



fluids should be changed at appropriate intervals determined by test, supplier, or by change in color, or odor, of the fluid.

Every 10°C [18°F] rise in continuous reservoir temperature over 80°C [176 °F] decreases the life of the oil by $\frac{1}{2}$.

For additional technical information on hydraulic fluids refer to *Hydraulic Fluids and Lubricants* **520L0463** Technical Information Bulletin and specific product technical bulletins.

For information relating to biodegradable fluids, see Danfoss publication *Experience with Biodegradable Hydraulic Fluids* **520L0465** or consult the Danfoss Technical Services Department.



D Series Pumps

D Series pump counterclockwise (CCW) rotation



For specifications and measurements for A, B, C, and D, refer to the folowing table.





D Series Pump Clockwise (CW) Rotation



(SAE B mount available)

P106 104E

| Nominal pump displacement cm ³ /rev [in ³ /rev] | Maximum continuous pressure bar [psi] | Maximum pressure bar [psi] | Maximum speed min-1 (rpm) | A mm [in] | B mm [in] | C mm [in] | D mm [in] |
|--|--|----------------------------------|------------------------------|--------------|--------------|--------------|--------------|
| 7.0 [0.43] | 276 [4000] | 303 [4400] | 3400 | 80.5 [3.17] | 92.0 [3.62] | 94.5 [3.72] | 116.1 [4.57] |
| 9.5 [0.58] | 276 [4000] | 303 [4400] | 3400 | 82.9 [3.27] | 94.4 [3.72] | 96.9 [3.82] | 118.5 [4.67] |
| 12.6 [0.77] | 276 [4000] | 303 [4400] | 3400 | 86.1 [3.39] | 97.5 [3.84] | 100.1 [3.94] | 121.7 [4.79] |
| 14.3 [0.87] | 276 [4000] | 303 [4400] | 3400 | 87.8 [3.46] | 99.2 [3.91] | 101.7 [4.01] | 123.3 [4.86] |
| 17.0 [1.04] | 276 [4000] | 303 [4400] | 3400 | 90.4 [3.56] | 101.9 [4.01] | 104.4 [4.11] | 126.0 [4.96] |



| Nominal pump displacement cm ³ /rev [in ³ /rev] | Maximum continuous pressure bar [psi] | Maximum pressure bar [psi] | Maximum speed min-1 (rpm) | A mm [in] | B mm [in] | C mm [in] | D mm [in] |
|--|--|----------------------------------|------------------------------|--------------|--------------|--------------|--------------|
| 19.0 [1.16] | 276 [4000] | 303 [4400] | 3400 | 92.5 [3.64] | 103.9 [4.09] | 106.4 [4.19] | 128.0 [5.04] |
| 20.5 [1.25] | 276 [4000] | 303 [4400] | 3400 | 94.0 [3.70] | 105.4 [4.15] | 108.0 [4.25] | 129.6 [5.10] |
| 22.5 [1.37] | 276 [4000] | 303 [4400] | 3400 | 95.8 [3.77] | 107.3 [4.22] | 109.8 [4.32] | 131.4 [5.17] |
| 25.4 [1.55] | 276 [4000] | 303 [4400] | 3400 | 98.8 [3.89] | 110.2 [4.34] | 112.8 [4.44] | 134.4 [5.29] |
| 29.0 [1.77] | 276 [4000] | 303 [4400] | 3200 | 102.4 [4.03] | 113.8 [4.48] | 116.4 [4.58] | 138.0 [5.43] |
| 31.8 [1.94] | 276 [4000] | 303 [4400] | 3000 | 105.2 [4.14] | 116.6 [4.59] | 119.1 [4.69] | 140.7 [5.54] |
| 36.0 [2.20] | 241 [3500] | 265 [3850] | 2750 | 109.4 [4.31] | 120.9 [4.76] | 123.4 [4.86] | 145.0 [5.71] |
| 38.0 [2.32] | 228 [3300] | 250 [3630] | 2750 | 111.4 [4.39] | 122.8 [4.84] | 125.4 [4.94] | 147.0 [5.79] |
| 41.0 [2.50] | 207 [3000] | 228 [3300] | 2500 | 114.4 [4.50] | 125.8 [4.95] | 128.4 [5.05] | 150.0 [5.90] |
| 45.1 [2.75] | 190 [2750] | 209 [3025] | 2500 | 118.6 [4.67] | 130.1 [5.12] | 132.6 [5.22] | 154.2 [6.07] |

Quadra-Flow Pump









P108899







D Series Pump with Load Sensing Schematic



P107897





Quadra-Flow Schematic



D Series Gear Motor

D Series Motor Dimensions



| Dimensions | Units | 17 | 19 | 21 | 23 | 25 | 29 | 32 | 36 | 38 | 41 | 45 |
|-------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| Dimension | mm | 88.9 | 90.9 | 92.5 | 94.2 | 97.3 | 100.8 | 103.6 | 107.7 | 109.7 | 112.8 | 117.1 |
| A | in | 3.50 | 3.58 | 3.64 | 3.71 | 3.83 | 3.97 | 4.08 | 4.24 | 4.32 | 4.44 | 4.61 |
| Dimension B | mm | 91.7 | 93.8 | 95.3 | 97.0 | 100.1 | 103.6 | 106.4 | 110.7 | 112.5 | 115.6 | 119.9 |
| | in | 3.61 | 3.69 | 3.75 | 3.82 | 3.94 | 4.08 | 4.19 | 4.36 | 4.43 | 4.55 | 4.72 |
| Dimension C | mm | 154.4 | 156.5 | 158.0 | 160.0 | 162.8 | 166.4 | 169.2 | 173.5 | 175.5 | 178.6 | 182.6 |
| | in | 6.08 | 6.18 | 6.22 | 6.30 | 6.41 | 6.55 | 6.66 | 6.83 | 6.91 | 7.03 | 7.19 |

Dimensions in table are maximum dimensions.



SGM2YN Gear Motor

02AA



P005 400E

| Frame size 8 | | 8.0 | 011 [0.67] | 014 [0.95] | 017 [1.04] | 019 [1.16] | 022 [1.34] | 025 [1.53] |
|--------------|---|-----------------|-----------------|-----------------|----------------|------------------|-----------------|-----------------|
| Dimension | Α | 47 [1.85] | 49 [1.93] | 52 [2.05] | 54 [2.13] | 56 [2.17] | 59 [2.32] | 61 [2.40] |
| mm [in] | В | 95.5 [3.76] | 99.5 [3.91] | 105.5 [4.15] | 109.5 [4.31] | 113.5 [4.47] | 119.5 [4.70] | 123.5 [4.86] |
| | c | 118.5 [4.66] | 122.5 [4.83] | 128.5 [5.05] | 132.5 [5.22] | 136.5 [5.37] | 142.5 [5.61] | 146.5 [5.77] |
| Inlet port | D | 7 | 7/8-14 UNF-2I | B (SAE J1926/ | 1 O-ring boss) |); 16.7 [0.66] r | nin. full threa | d |





SGM2YN - 02AA dimensions (continued)

| Frame si | ze | 8.0 | 011 [0.67] | 014 [0.95] | 017 [1.04] | 019 [1.16] | 022 [1.34] | 025 [1.53] | | | | | | |
|-------------|----|------|-------------|---|------------|------------|------------|------------|--|-----------|--|--|--|--|
| Outlet port | E | 15 [| 0.59] | 20 [0.79] | | | | | | 20 [0.79] | | | | |
| | F | 35 [| 1.38] | 40 [1.57] | | | | | | | | | | |
| | G | | | M6-6H; 12[0.47] min. full thread | | | | | | | | | | |
| Drain po | rt | 9 | /16 18UNF-2 | 3 (SAE J1925/1 O-ring boss) 12.7 [0.50] min. full threads | | | | | | | | | | |



For more information regarding SGM2Y gear motors, refer to SGM2Y and SGM3Y Fan Drive Motors Technical Information **11040345**.



06BA



P005 402E

| SGIVIZT - UODA UITTIETISIOTIS |
|-------------------------------|
|-------------------------------|

| Frame si | ze | 8.0 | 011 [0.67] | 014 [0.95] | 017 [1.04] | 019[1.16] | 022 [1.34] | 025 [1.53] |
|-------------|-----|-------------|---|-----------------|---------------|------------------|-----------------|-----------------|
| Dimension | A | 47 [1.85] | 49 [1.93] | 52 [2.05] | 54 [2.13] | 56 [2.17] | 59 [2.32] | 61 [2.40] |
| mm [in] | В | 95.5 [3.76] | 99.5 [3.91] | 105.5 [4.15] | 109.5 [4.31] | 113.5 [4.47] | 119.5 [4.70] | 123.5 [4.86] |
| | С | 116 [4.57] | 120 [4.72] | 126 [4.96] | 130 [5.11] | 134 [5.28] | 140 [5.51] | 144 [5.67] |
| Inlet port | D | 7 | 7/8-14 UNF-2I | B (SAE J1926/ | 1 O-ring boss |); 16.7 [0.66] r | nin. full threa | d |
| Outlet port | E | | 7/8-14 | UNF-2B | | 1 | 1/16-12 UN-2 | 2B |
| | F | | 16.7 [0.66] min. full thread 19 [0.75] min. full thread | | | | | |
| Drain po | ort | 9 | /16 18UNF-2 | B (SAE J1925/ | 1 O-ring boss |) 12.7 [0.50] n | nin. full threa | ds |





For more information regarding SGM2Y gear motors, refer to SGM2Y and SGM3Y Fan Drive Motors Technical Information **11040345**.



06GB



P005 404E

SGM2YN - 06GB dimensions

| Frame si | ze | 8.0 | 011 [0.67] | 014 [0.95] | 017 [1.04] | 019[1.16] | 022 [1.34] | 025 [1.53] |
|-------------|----|-------------|---|-----------------|----------------|------------------|-----------------|-----------------|
| Dimension | Α | 47 [1.85] | 49 [1.93] | 52 [2.05] | 54 [2.13] | 56 [2.17] | 59 [2.32] | 61 [2.40] |
| mm [in] | В | 95.5 [3.76] | 99.5 [3.91] | 105.5 [4.15] | 109.5 [4.31] | 113.5 [4.47] | 119.5 [4.70] | 123.5 [4.86] |
| | с | 116 [4.57] | 120 [4.72] | 126 [4.96] | 130 [5.11] | 134 [5.28] | 140 [5.51] | 144 [5.67] |
| Inlet port | D | 7 | 7/8-14 UNF-28 | 3 (SAE J1926/ | 1 O-ring boss) |); 16.7 [0.66] r | nin. full threa | d |
| Outlet port | E | | 7/8-14 UNF-2B 1 1/16-12-UN-2B | | | | | |
| | F | | 16.7 [0.66] min. full thread 19 [0.75] min. full thread | | | | | |
| Drain po | rt | 9 | /16 18UNF-2 | 3 (SAE J1925/ | 1 O-ring boss) |) 12.7 [0.50] m | nin. full threa | ds |





For more information regarding SGM2Y gear motors, refer to SGM2Y and SGM3Y Fan Drive Motors Technical Information **11040345**.







SGM3YN - 07BC dimensions

| Frame size | | 022 | 026 | 033 | 038 | 044 |
|-------------|---|---|------------|------------|------------|------------|
| Dimension | A | 63 | 64.5 | 67 | 68.8 | 71 |
| mm [in] | В | 127.1 | 130.1 | 135.1 | 138.6 | 143 |
| | С | 20 [0.787] | 20 [0.787] | 27 [1.063] | 27 [1.063] | 27 [1.063] |
| Inlet port | D | 1-1/16-12UN-2B | | | | |
| Outlet port | E | 1-1/16-12UN-2B | | | | |
| | F | 19 [0.75] min. full thread | | | | |
| Drain port | | 9/16 18UNF-2B (SAE J1925/1 O-ring boss) 12.7 [0.50] min. full threads | | | | |





For more information regarding SGM3Y gear motors, refer to SGM2Y and SGM3Y Fan Drive Motors Technical Information **11040345**.



07GB



SGM3YN - 07GB dimensions

| Frame size | | 022 | 026 | 033 | 038 | 044 |
|-------------|---|---|------------|------------|------------|------------|
| Dimension | A | 61 | 63 | 64.5 | 66.5 | 69.5 |
| mm [in] | В | 132.5 | 135.5 | 140.5 | 144.0 | 148.5 |
| | С | 20 [0.787] | 20 [0.787] | 27 [1.063] | 27 [1.063] | 27 [1.063] |
| Inlet port | D | 1 1/16-12UN-2B | | | | |
| Outlet port | E | 1 1/16-12UN-2B | | | | |
| | F | 19 [0.748] min. full thread | | | | |
| Drain port | | 9/16 18UNF-2B (SAE J1925/1 O-ring boss) 12.7 [0.50] min. full threads | | | | |





For more information regarding SGM3Y gear motors, refer to SGM2Y and SGM3Y Fan Drive Motors Technical Information **11040345**.

PRV10-IS2 Valve for SGM2Y







PRV12-IS2 Valve for SGM3Y







Reverse Displacement Motors (RDM)

Cartridge Motor







P108915

Recommended mounting hardware

| Bolt size | Grade | Torque N•m [lbf•ft] | Mounting circle diameter | |
|---|-------|---------------------|--------------------------|--|
| 1/2 inch | 5 | 86 [64] | 160 mm [6.299 in] | |
| | 8 | 122 [90] | | |
| Use hardened washer under each bolt head. | | | | |



Port locations and gauge installation

Pressure measurements can be obtained by installing tee fittings to the connections at the locations listed in the table below. Recommended gauge sizes are listed.

Twin radial port locations





P108844

Port information

| Port identifier | Metric | Inch | Pressure obtained | Gauge size, bar [psi] |
|-----------------|------------------------|------------------------|--------------------|-----------------------|
| X1 | ISO 6941-1, M 18x1.5 | ISO 11926-1, 3/4-16 | Control signal | 600 [10 000] |
| L1 | ISO 6941-1, M 14x1.5 | ISO 11926-1, 9/16-18 | Case drain | 10 [100] |
| A/B | ISO 6941-1, M 27x2 | ISO 11926-1, 1-1/16-12 | System pressure | 600 [10 000] |
| MA/MB | ISO 11926-1, 7/16 - 20 | | System gauge port | 600 [10,000] |
| F | ISO 11926-1, 7/16-20 | | Brake release port | - |





L and K Frame Variable Motor





Motor Rotation

L and K Frame variable motors are fully bidirectional. The table gives the direction of rotation with respect to flow direction through the motor.

Rotation by Flow Direction

| Mount | SAE-B | Cartridge |
|----------|-------|-----------|
| Flow A→B | CCW | CW |
| Flow B→A | CW | CCW |

Schematics

Motor schematic, single line control



Motor schematic, dual line control



Series 40 Fixed Motors



M35/M44 MF: mounting flange



*All ports are SAE straight thread o-ring ports per SAE J514, unless otherwise specified.

Shaft rotation is determined by viewing motor from output shaft end.

Contact Danfoss Application Engineering for specific installation drawings.

M35/M44 MF: axial ports, twin ports, loop flushing, speed sensor

Flow direction

| Motor shaft rotation | Port A | Port B |
|----------------------|--------|--------|
| Clockwise | In | Out |
| Counterclockwise | Out | In |



M35-M44 MF dimensions



*All ports are SAE straight thread o-ring ports per SAE J514, unless otherwise specified. Shaft rotation is determined by viewing motor from output shaft end. Contact Danfoss Application Engineering for specific installation drawings.

Series 90 Fixed Motors



90K55 Fixed Motor Cartridge Mount



All SAE straight thread O-rings ports per SAE J1926 (fittings per SAE 514). Shaft rotation is determined by viewing motor from output shaft end. Contact your Danfoss representative for specific installation drawings



Splined output shaft options

| Output shaft option | Shaft diameter T | Full spline length U | Major diameter V | Pitch diameter W | Number of teeth Y | Pitch Z |
|---------------------|------------------|-------------------------|---------------------|---------------------|----------------------|---------|
| S1 | 24.9 [0.98] | 27.9 [1.10] | 31.13 [1.2258] | 29.634 [1.1667] | 14 | 12/24 |
| C6 | 29 [1.14] | 32.5 [1.28] | 34.42 [1.3550] | 33.338 [1.3125] | 21 | 16/32 |

Flow direction

| Shaft rotation | Flow direction | | |
|------------------------|----------------|----------|--|
| | Port "A" | Port "B" | |
| Clockwise (CW) | Out | In | |
| Counterclockwise (CCW) | In | Out | |











PLUS+1TM Microcontroller

Installation Drawings

Fan Drive Control Schematic



S45 Frame J pump with PRV control

P108870



Schematics

Fan Drive System Schematics

Gear Motor (with proportional control) Schematic



S45 Fan Drive Controller Schematic





Fan Drive System Related Literature

Overview

Fan drive systems may consist of a variety of pump, motor, valve and control combinations. The product codes shown on the following pages are for components that have been designed specifically for fan drive systems. Refer to the literature listed below for product code information and specifications for other Danfoss components that may be utilized in a fan drive system.

Gear Pumps

- SNP 2 (group 2) Gear Pumps 520L0560
- D Series Gear Pumps 520L0781
- Group 1 thru 3 Gear Pumps and Motors 520L0557
- SNP 3 (group 3) Gear Pumps 520L0569

Open Circuit Piston Pumps

• Series 45 Open Circuit Axial Piston Pumps 520L0519

Closed Circuit Piston Pumps

- Series 42 Variable Piston Pumps **11022637**
- Series 90 Axial Piston Pumps and Motors 520L0603
- H1 Pumps with Fan Drive Control (045-100 cm³) **11062168**

Gear Motors

- SGM2Y and SGM3Y Fan Drive Gear Motors **11040345**
- D Series Gear Motors Including Fan Drive **11044656**

Open Circuit Piston Motors

- L and K Frame Variable Motors 520L0627
- Series 40 Axial Piston Motors 520L0636
- Series 90 Axial Piston Motors 520L0604
- RDM Motors L1424445

Controllers

- Fan Drive Control Temperature Sensors **BLN-95-9063**
- Electronic Fan Drive Controller (FDC) **11005336**
- Electronic Fan Drive Controller Assembly (FDCA) 11005337
- PLUS+1TM Controller Family **520L0719**

System Guidelines

- Design Guidelines for Hydraulic Fluid Cleanliness 520L0467
- Design Guidelines for Hydraulic Fan Drive Systems 520L0926











Products we offer:

- DCV directional control valves
- Electric converters
- **Electric machines**
- **Electric motors**
- Hydrostatic motors
- Hydrostatic pumps
- Orbital motors
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- PLUS+1[®] joysticks and pedals
- PLUS+1[®] operator interfaces
- PLUS+1[®] sensors
- PLUS+1[®] software
- PLUS+1[®] software services, support and training
- Position controls and sensors
- PVG proportional valves
- Steering components and systems
- Telematics

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